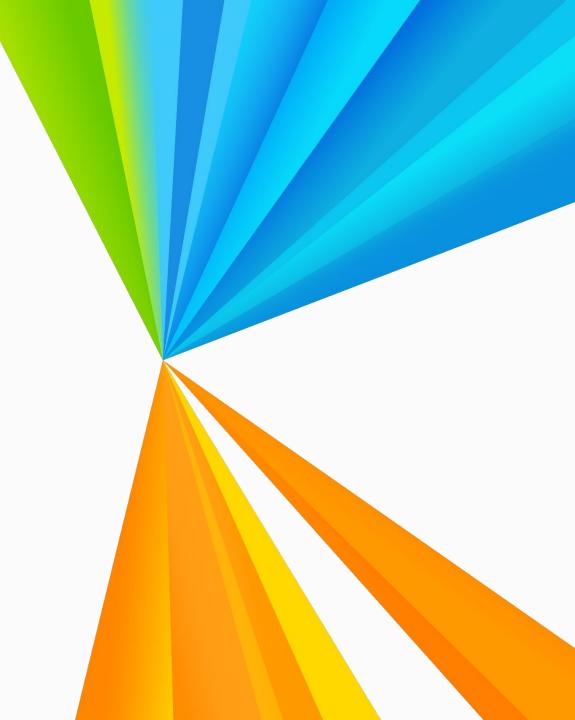


Developing with Zephyr in Visual Studio Code

Hands-on workshop

Derek Snell June 2024

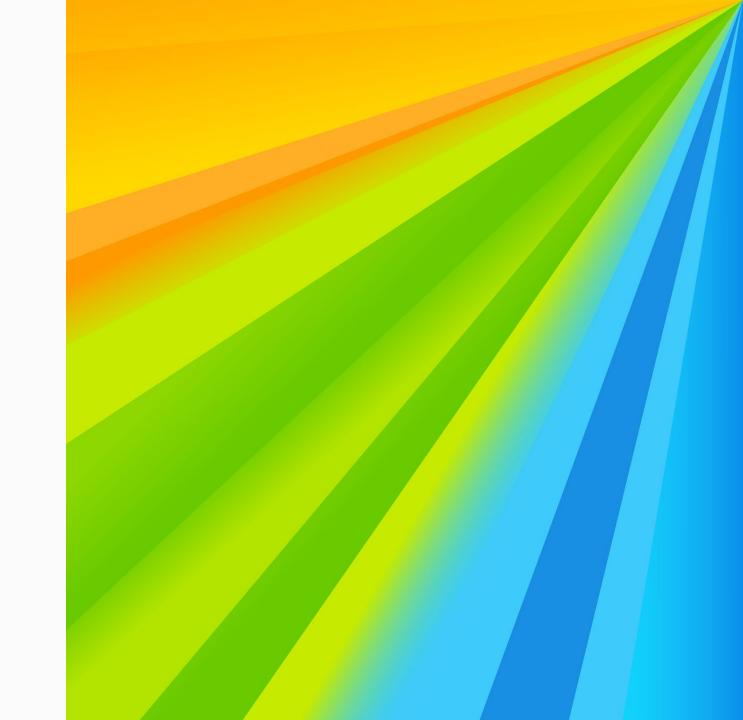


Agenda

• MCUXpresso extension for VS Code

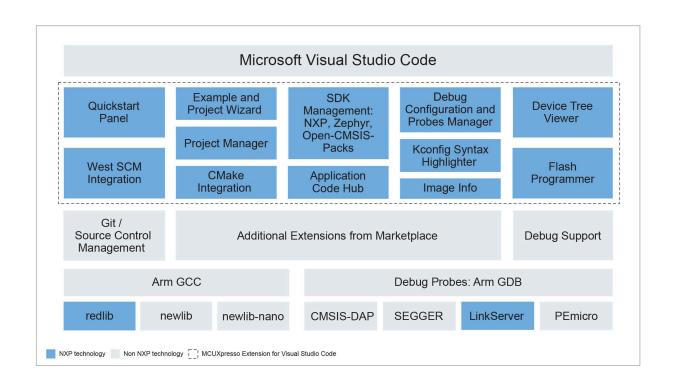
- Zephyr:
- Portability
- Devicetree
- Kconfig
- Hands-on Labs

MCUXpresso for VS Code



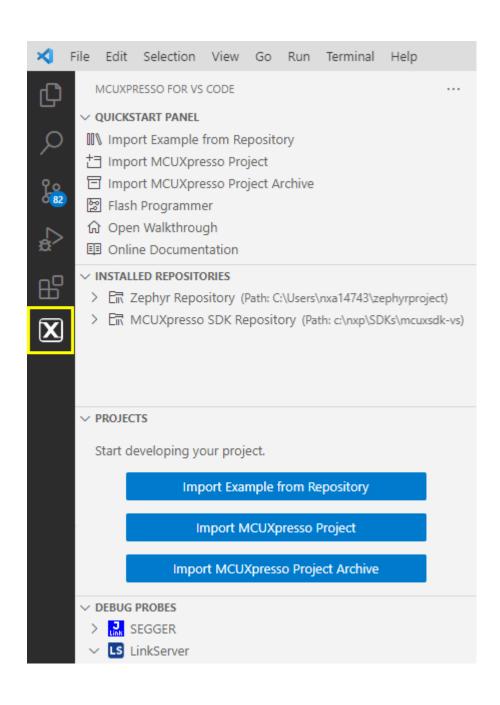
MCUXpresso for Visual Studio Code 🔀

- Free to use
- Optimized for ease-of-use
- Extended for MCUXpresso SDK or Zephyr based development flows
- Based on Arm GCC compiler
- Compatible with standalone
 MCUXpresso Configuration tools



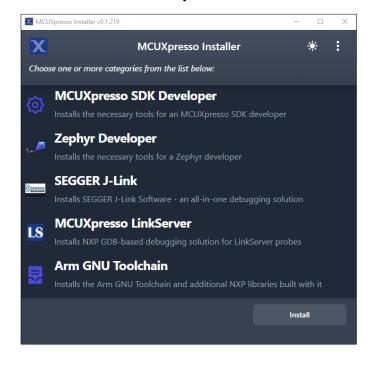
Introduction to Visual Studio Code

- NXP developed MCUXpresso Extension
 - Installed from VS Code Extensions Marketplace
 - Improves NXP development experience
- Featured Improvements:
 - MCUXpresso Installer
 - Quickstart Panel
 - Zephyr & MCUXpresso Applications Importer
 - Editing
 - Build & Debug



MCUXpresso for VS Code: Installation

- Installer handles toolchain dependencies
 - Git
 - Python
 - West
 - Segger
 - LinkServer
 - Arm® GNU
 - Zephyr SDK
 - Cmake
 - Ninja
 - Devicetree compiler
 - other Zephyr dependencies



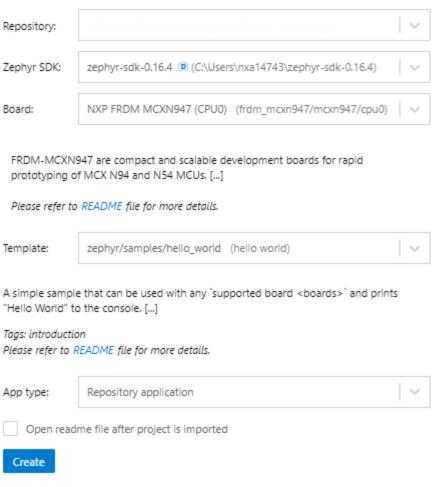


MCUXpresso for VS Code: Zephyr Applications

- Imports Zephyr and dependency repositories
- Imports Zephyr sample applications
 - Choose board to target
- Device Tree Viewer
- Zephyr debugger features:
 - Thread Awareness
 - Stack usage



Import Example from Repository



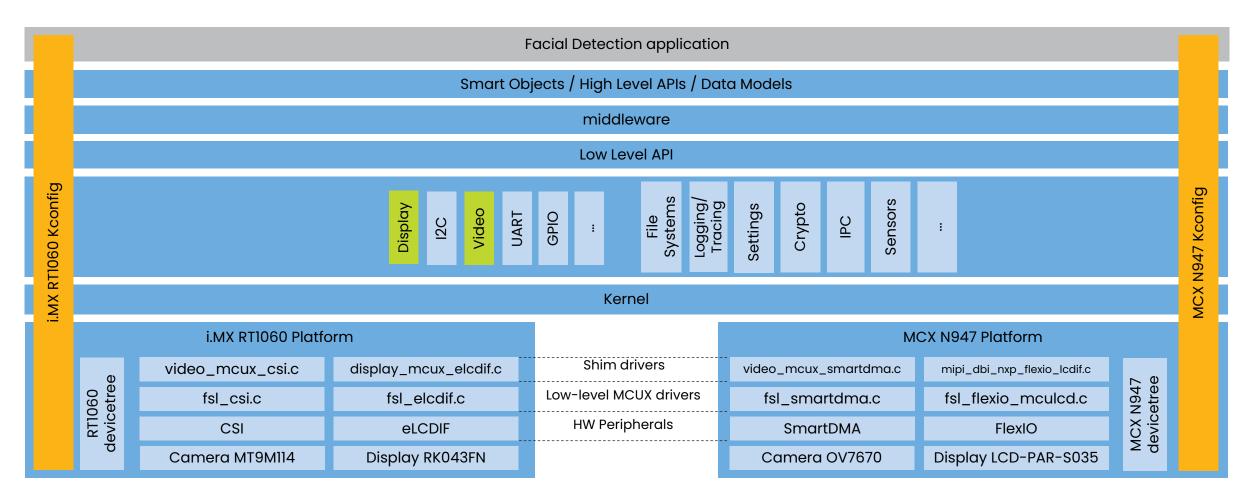
Zephyr Portability





Hardware Abstraction with devicetree and Kconfig

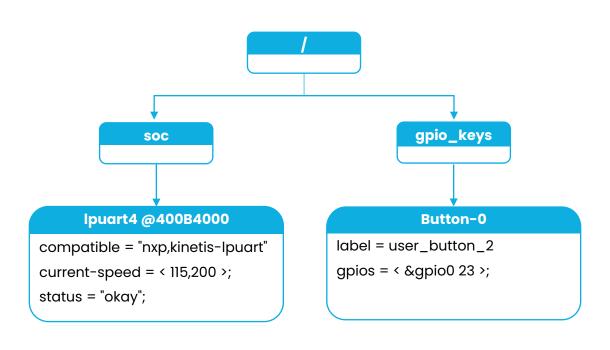
- Application on both mimxrt1060_evk and frdm_mcxn947 boards
 - Same application, same kernel and upper layers, but different HAL controlled by device tree and Kconfig settings



DeviceTree Overview - from FRDM-MCXN947 board

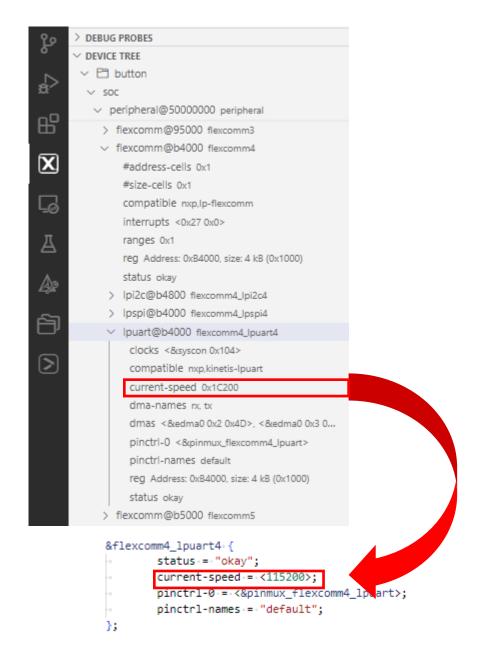
- Nodes correspond to some hardware component
 - Nodes are hierarchical, and can reflect the hardware's physical layout
- Properties will describe or configure the hardware node, such as a UART's baud rate

```
/dts-v1/;
/ {
    soc {
        flexcomm4 lpuart4: lpuart@b4000 {
                compatible = "nxp,kinetis-lpuart";
                reg = < 0xb4000 0x1000 >;
                status = "okay";
                current-speed = < 115200 >;
                pinctrl-0 = < &pinmux_flexcomm4_lpuart >;
                pinctrl-names = "default";
        };
    };
    gpio keys {
        compatible = "gpio-keys";
        user button 2: button 0 {
                label = "User SW2";
                gpios = < &gpio0 23 (GPIO ACTIVE LOW | GPIO PULL UP)>;
                status = "okay";
        };
};
10 | NXP | Confidential
```



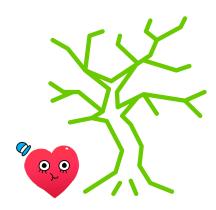
MCUXpresso Device Tree Viewer

- VS Code extension includes a Device Tree Viewer
- Displays all nodes and properties included in the application build
- Clicking a node or property in the Viewer finds the location in the source file



Advantages of using Device Tree

- Fully describes all enabled HW in system for the application
 - Describes dependencies between nodes, HW hierarchy fully described
- Application does not need to include HW-specific files, or call HW-specific APIs
- No overhead
 - Uses preprocessor macros to bind Device Tree to drivers
 - No additional memory footprint used over the device driver model



Kconfig – Kernel Configuration system

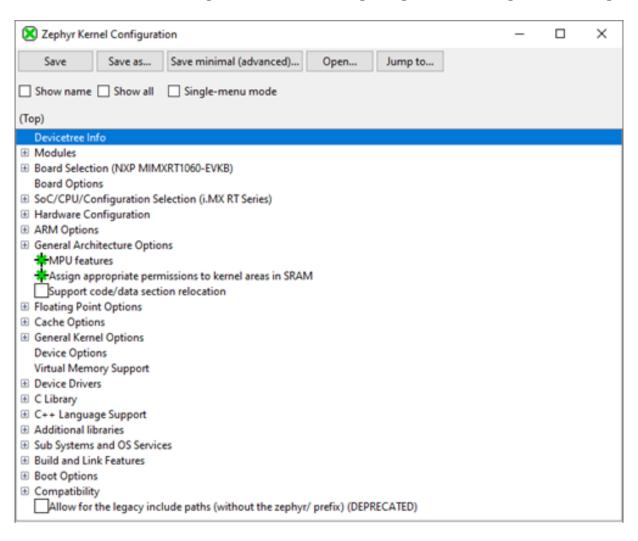
- Zephyr uses the same configuration system used by the Linux kernel
- The goal is to support configuration without having to change any source code
- For this compiler optimization example:
 - Applications are given a choice of options
 - Application selects for size like this: CONFIG SIZE OPTIMIZATIONS=y
- Another example:
 - App can set stack size for Main thread:

```
CONFIG MAIN STACK SIZE=1024
```

```
choice COMPILER OPTIMIZATIONS
        prompt "Optimization level"
config SIZE OPTIMIZATIONS
        bool "Optimize for size"
        help
          Compiler optimizations will be set to -Os.
config SPEED OPTIMIZATIONS
        bool "Optimize for speed"
        help
          Compiler optimizations will be set to -02.
config DEBUG OPTIMIZATIONS
        bool "Optimize debugging experience"
        help
          Compiler optimizations will be set to -Og.
config NO OPTIMIZATIONS
        bool "Optimize nothing"
        help
          Compiler optimizations will be set to -00.
endchoice
```

Interactive Config tools

Guiconfig is optional tool for viewing and changing Kconfig settings:

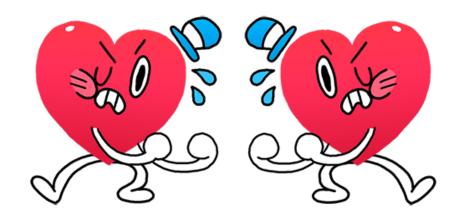


Guiconfig helps browse and explore the Kconfig settings

When to configure using Devicetree or Kconfig

Whether to use devicetree or Kconfig for a particular purpose:

- Use devicetree to describe hardware and boot-time configuration
 - Peripherals on a board, boot-time clock frequencies, interrupt lines, etc.
- Use Kconfig to configure software support to build into the final image
 - Where to add network support, which drivers are needed
- Kconfig for software, devicetree for hardware
- An example, a device with 10/100 Ethernet MAC
 - devicetree:
 - Describe the presence of the Ethernet MAC
 - Compatible drivers
 - Hardware configuration, such as IEEE1588 support and interrupts
 - Kconfig:
 - Determines which software features should be built, such as selecting the Networking stack and supported protocols



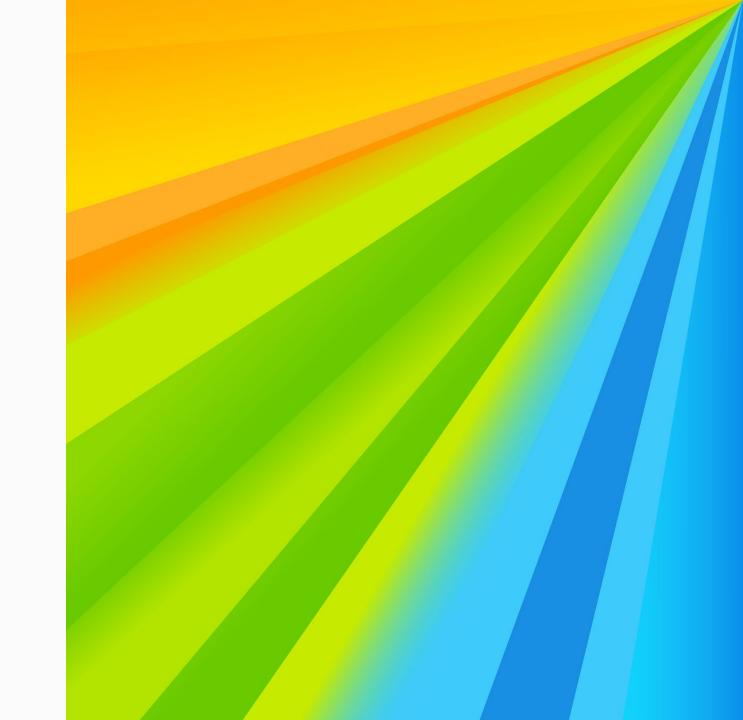
Summary of Zephyr build steps

VS Code calls these build tools when a project is built

- Scripts merge device tree for build
 - Uses sources from board and SOC, plus overlay files
- Scripts merge kernel config (Kconfig) options
 - From sources: board-specific config, application config, and CMake entries
- Generates build files using Cmake
- Compiles source code
- Links all libraries, and then final application

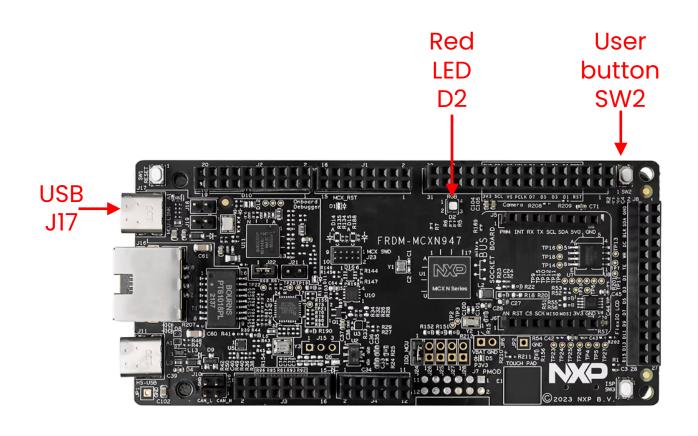


Hands-On Labs



Lab Pre-Requisites

- Hardware
 - FRDM-MCXN947
 - USB Type-C cable
 - On-board MCU-Link debugger
- Software and Tools:
 - Zephyr post v3.6.0 release (main branch)
 - VS Code with MCUXpresso extension
 - See AMF-ENT-T4788 Hands-On Pre-requisite Developing with Zephyr in Visual Studio Code.pdf



Zephyr Hands-on Lab Guides



- Hello_World
 - Import sample, build, debug

Kconfig

- Explore and modify Kconfigs, guiconfig tool
- Debugging with VS Code
 - Thread Awareness, Stack Usage, thread call stack
- Devicetree
 - MCUXpresso Device Tree Viewer, board overlay files, modifying hardware configuration

Zephyr On-Demand Webinar Series www.nxp.com/zephyr Training

- Series of customer webinars introducing Zephyr and highlighting NXP-supported platforms
- Includes demonstrations (but not hands-on training or lab tutorials)
 - NXP and Zephyr OS: Unlocking Innovation with an Open Source RTOS
 - Maureen Helm (NXP)
 - Kate Stewart (Zephyr Project)

- Application Portability with Zephyr OS and NXP
- Derek Snell, Senior Systems Engineer (NXP)

- Accelerate Development with Zephyr OS **Features and Modules**
- Derek Snell, Senior Systems Engineer (NXP)

- •NXP and SEGGER: Debug, Visualize and Analyze **Zephyr OS Applications with Ease**
- •Derek Snell, Senior Systems Engineer (NXP)
- Axel Wolf (SEGGER)
- Should I Care About Zephyr OS?
- Real Experiences of an RTOS Expert
- •Brendon Slade, MCU Ecosystem Director (NXP)
- •Eli Hughes, Pro Support Engineer
- •OTA Device Management with Golioth Cloud Platform **Using Zephyr RTOS and NXP i.MX RT**
- •Mike Szczys, Developer Relations Engineer (Golioth)
- Derek Snell, Senior Systems Engineer (NXP)
- Designing for Low Power Using Zephyr® Project: A **Smartwatch Example**
- Derek Snell, Senior Systems Engineer (NXP)

Additional Resources - Zephyr

Zephyr:

- NXP Zephyr page
- Zephyr Getting Started web page
- Zephyr Community and Support
- GitHub
- Zephyr's Board Porting Guide
- <u>Samples and Demos</u>
- <u>Supported boards</u>
- Beyond the Getting Started Guide
- Zephyr Documentation

Kconfig:

- Zephyr Kconfig documentation
- guiconfig and menuconfig interactive
 Kconfig tools
- Sources of Kconfig symbols, and how they are merged

• Devicetree:

- <u>Zephyr Devicetree documentation</u>
- Zephyr Devicetree HOWTOs
- <u>Devicetree specifications</u>

Additional Resources – MCUXpresso and VS Code

- MCUXpresso for VS Code
 - Wiki pages
 - Community Support Forum
- MCUXpresso Ecosystem

- VS Code
 - Download
 - <u>Debugging</u>
 - <u>Embedded Tooling RTOS View</u>



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