Image Representation

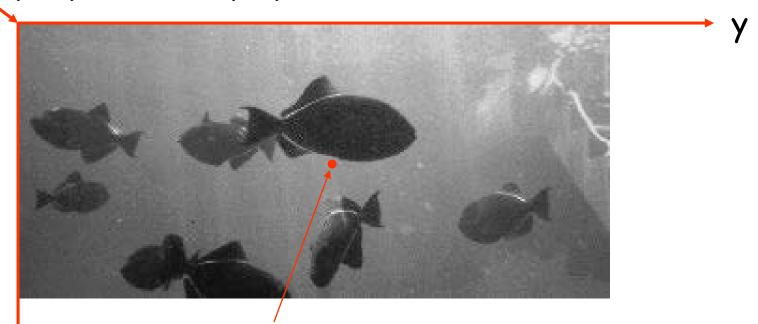
Reference:

[Gonzalez and Woods] Rafael C. Gonzalez and Richard E. Woods, Digital Image Processing, Second Edition, Prentice-Hall, Inc.

http://www.imageprocessingplace.com/

Image representation

origin (0,0) in C, and (1,1) in MATLAB

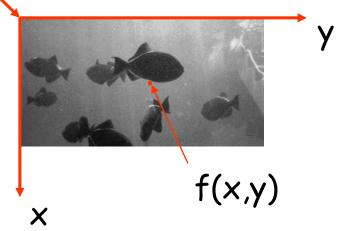


X

f(x,y), a 2D function representing image intensity; (x,y) represents a pair of spatial coordinates

Image representation

origin



- Discretized in both
 - ·Spatial coordinates
 - ·Brightness

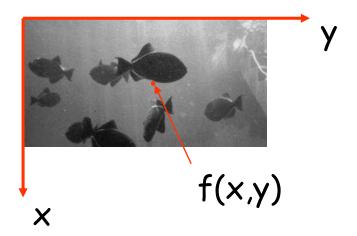
Similar to a matrix in Linear Algebra

Individual elements are called: image elements, picture elements (pixels), (image points)

Image representation (MATLAB convention)

				→ Y
f(x, y)	f(1, 1)	f(1, 2)	f(1, 3)	Dimension 2
	f(2, 1)	f(2, 2)	f(2, 3)	
	f(3, 1)	f(3, 2)	f(3, 3)	
X ,	ension 1			4

Image function, f (intensity)

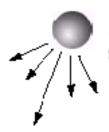


The image function (intensity/color) f can be characterized by two components:

- (1) illumination (light source) and
- (2) reflectance (materials).

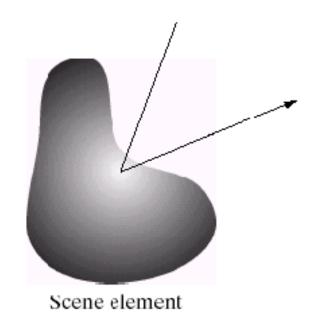
Image intensity is depending on these two factors.

Image function, f (intensity)



Illumination (energy) source

Illumination: the amount of source illumination (energy) incident on the scene being viewed.

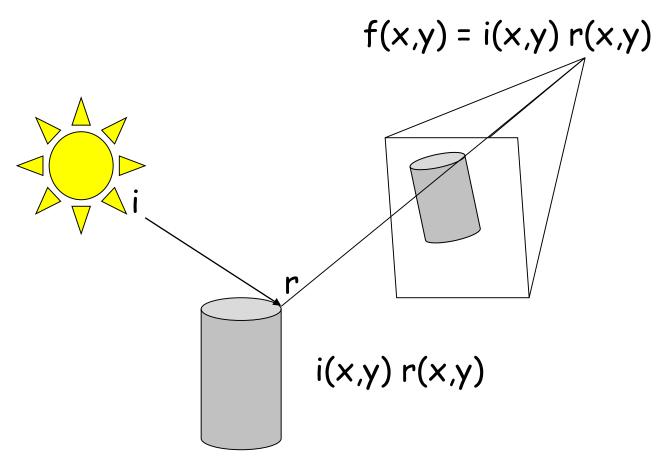


Reflectance: the amount of source illumination (energy) reflected by the objects (or elements) in the scene.

Image model

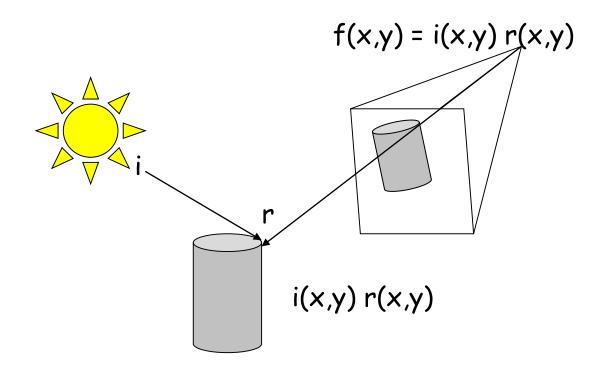
- Basic nature of f(x,y) has two components: f(x,y) = i(x,y) r(x,y)
- i(x,y) is illumination component $0 \le i(x,y) < +infinity$
- r(x,y) is reflectance component
 0 ≤ r(x,y) ≤ 1
 0 = total absorption, 1 = total reflectance.
- f(x,y) is intensity
- $0 \le f(x,y) < +infinity$

Image model

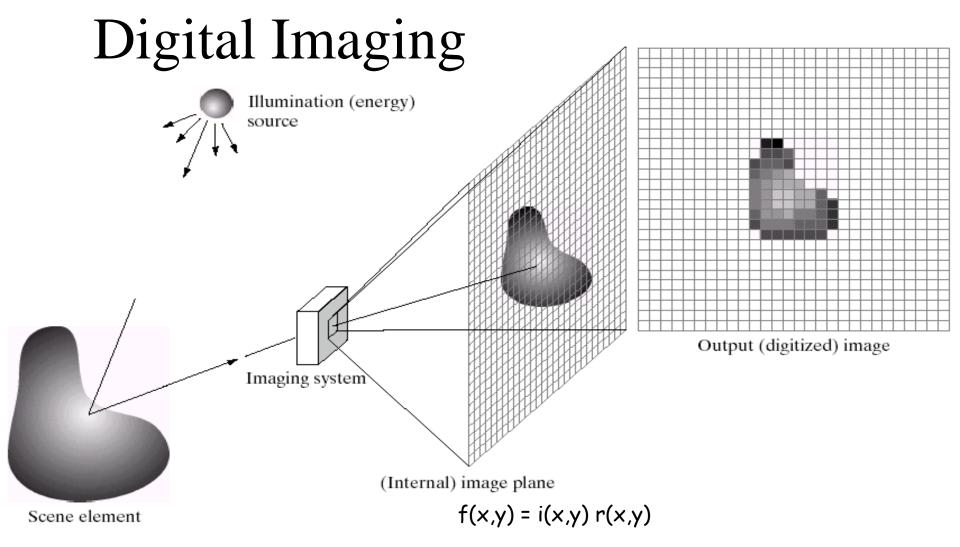


i and r are continuous functions thus f(x,y) can be continuous

Sampling and quantization are affecting the image quality.



i and r are continuous functions thus f(x,y) can be continuous



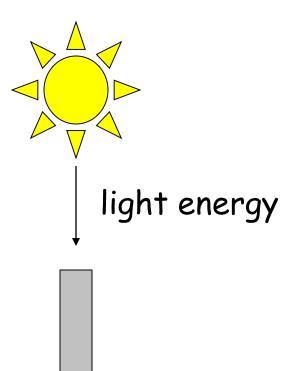
a b c d e

FIGURE 2.15 An example of the digital image acquisition process. (a) Energy ("illumination") source. (b) An element of a scene. (c) Imaging system. (d) Projection of the scene onto the image plane. (e) Digitized image.

Digital Imaging

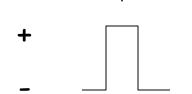
- Charged-Coupled Device (CCD)
 - consists of photosites
 - silicon imaging elements that give a voltage output proportional to the intensity of the incident light
 - linear array (scanner)
 - area array (Camera CCD)
- http://en.wikipedia.org/wiki/Charge-coupled_device

Photosites



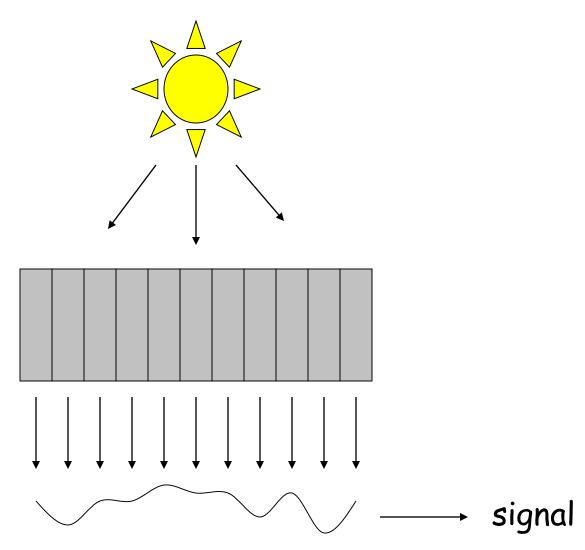
CCD consists of photosites

silicon imaging elements
 that give a voltage output
 proportional to the
 intensity of the incident
 light

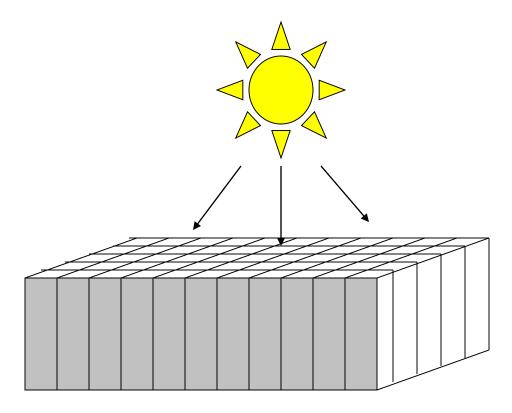


output voltage

Line scan sensor



Area scan sensor



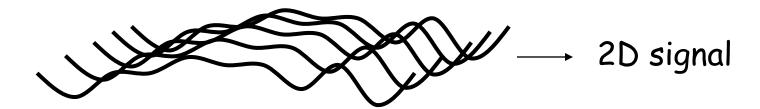
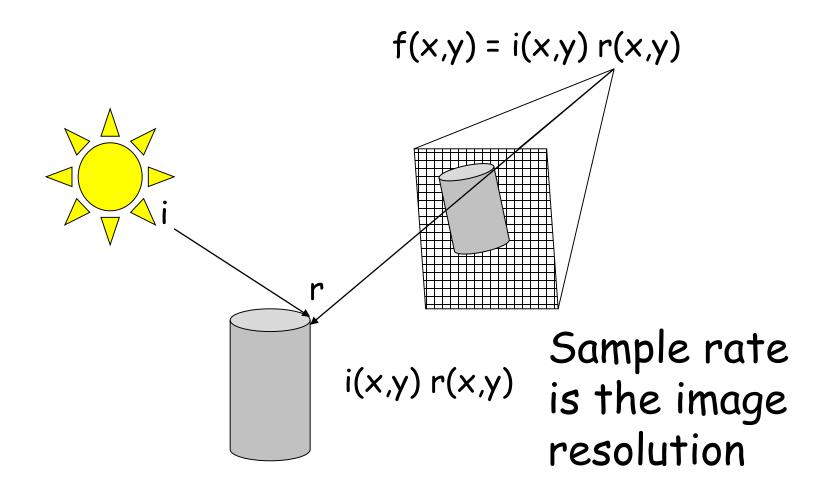
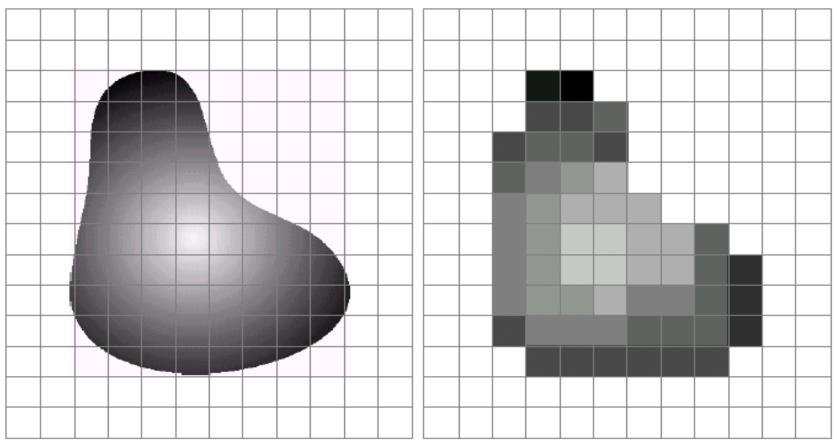


Image sampling/resolution



Spatially discretized



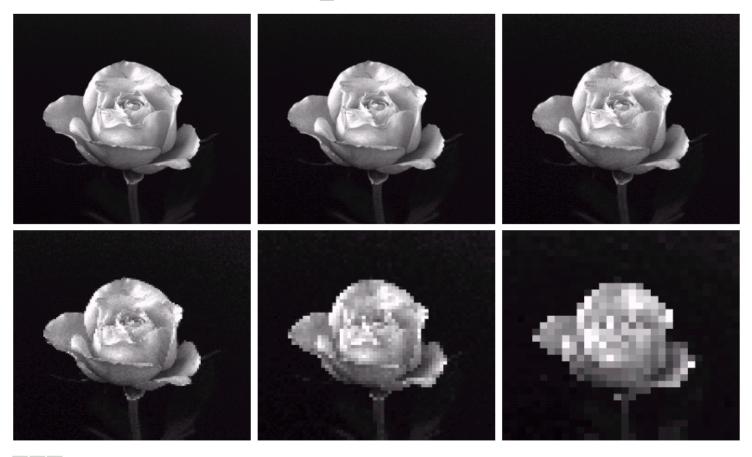
a b

FIGURE 2.17 (a) Continuos image projected onto a sensor array. (b) Result of image sampling and quantization.

A digital image is discrete

A digital image is discrete (MATLAB convention)

Effects of spatial resolution



abc def

FIGURE 2.20 (a) 1024×1024 , 8-bit image. (b) 512×512 image resampled into 1024×1024 pixels by row and column duplication. (c) through (f) 256×256 , 128×128 , 64×64 , and 32×32 images resampled into 1024×1024 pixels.

Effects of spatial resolution





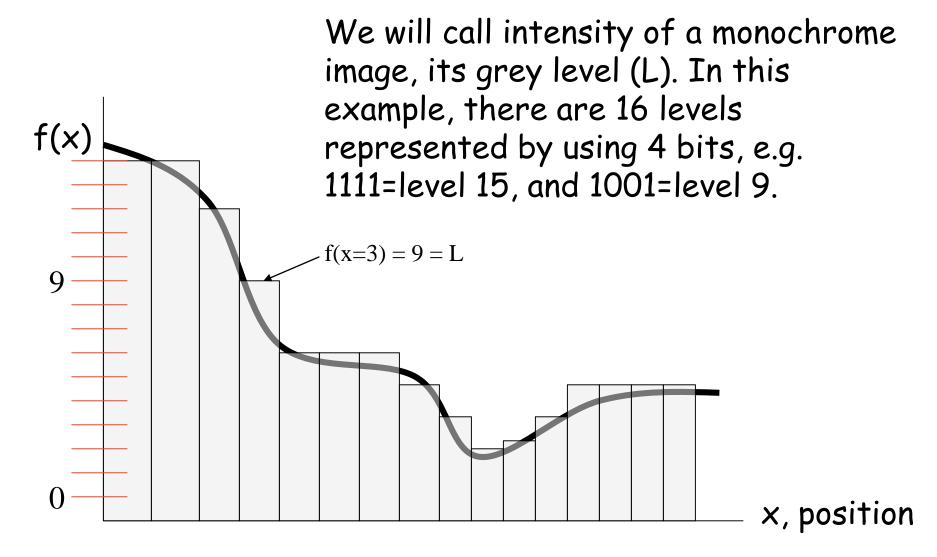








Intensity quantization



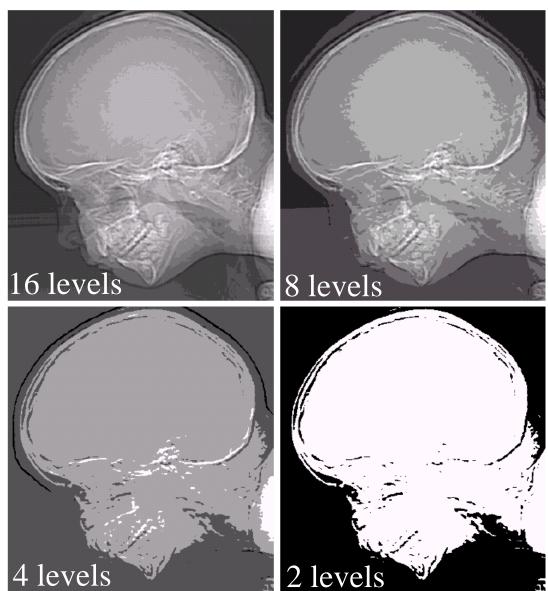
Effects of intensity quantization

e f g h

FIGURE 2.21

(Continued)
(e)–(h) Image
displayed in 16, 8,
4, and 2 gray
levels. (Original
courtesy of
Dr. David
R. Pickens,
Department of
Radiology &
Radiological
Sciences,
Vanderbilt
University
Medical Center.)

Image resolution is fixed but the number of gray levels decreases.



22

Effects of intensity quantization



Storage requirements

M = number of columns, "Width" in MATLAB

Amount of memory needed

M*N*(bits required to represent the grey levels)

N = number of rows, "height" in MATLAB