# LECTURE 10:INFLUENCE MAXIMIZATION IN NETWORKS

## How to Create Big Cascades?

- □ Blogs Information epidemics:
  - Which are the influential blogs?
  - Which blogs create big cascades?
  - □ Where should we advertise?



Which node shall we target?

## Viral Marketing?

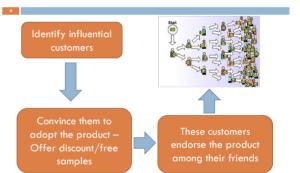
□ We are more influenced by our friends than strangers



- □ 68% of consumers consult friends and family before purchasing home electronics
- □50% do research online before purchasing electronics



### Viral Marketing

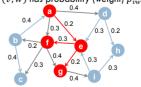


### **Probabilistic Contagion**

- □ Independent Cascade Model
  - $\square$  Directed finite G = (V, E)
  - Say nodes with this behavior are "active"
  - lacksquare Each edge (v,w) has a probability  $p_{vw}$
  - ${\color{red} extbf{ iny I}}$  If node v is active, it gets  $\underline{\text{one}}$  chance to
  - make w active, with probability  $p_{vw}$
  - Each edge fires at most once
- □ Does scheduling matter? No
  - u, v both active, doesn't matter which fires first
  - But the time moves in discrete steps

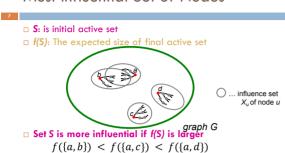
# Independent Cascade Model

- □ Initially some nodes S are active
- lacksquare Each edge (v,w) has probability (weight)  $p_{vw}$

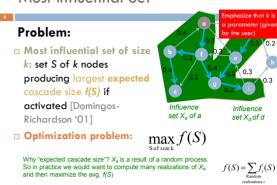


- □ When node v becomes active:
- Activations spread through the network

### Most Influential Set of Nodes



### Most Influential Set

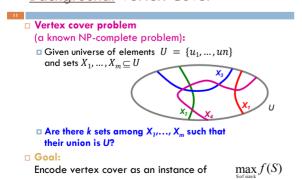


# HOW HARD IS INFLUENCE **MAXIMIZATION?**

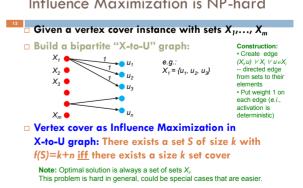
### Most Influential Subset of Nodes

□ Most influential set of k nodes: set S on k nodes producing largest expected cascade size f(S) if activated □ The optimization problem:  $\max_{S} f(S)$ □ How hard is this problem? □ NP-COMPLETE! ■ Show that finding most influential set is at least as hard as a vertex cover

# Background: Vertex Cover



### Influence Maximization is NP-hard



# Summary so Far

### □ Bad news:

- □ Influence maximization is NP-complete
- □ Next, good news:
  - There exists an approximation algorithm!
- □ Consider the Hill Climbing algorithm to find S:
  - - Influence set of each node  $u: X_u = \{v_1, v_2, \dots\}$
    - $\blacksquare$  If we activate u, nodes  $\{v_1, v_2, \dots\}$  will eventually get active
  - $\blacksquare$  **Algorithm:** At each iteration i take the node u that gives best marginal gain:  $\max f(S_{i-1} \cup \{u\})$

 $S_i$  ... Initially active set  $f(S_i)$  ... Size of the union of  $X_u$ ,  $u \in S_i$ 

# (Greedy) Hill Climbing

### Algorithm:

- □ Start with  $S_0 = \{\}$
- $\square$  For  $i = 1 \dots k$ 
  - $\blacksquare$  Take node u that  $\max f(S_{i-1} \cup \{u\})$
  - $\blacksquare$  Let  $S_{i} \_ S_{i-1} \cup \{u\}$

### Example:

- $\square$  Eval.  $f(\{a\}), ..., f(\{e\})$ , pick max of them
- Eval.  $f(\{a,b\}), ..., f(\{a,e\})$ , pick max
- $\square$  Eval. f(a,b,c), ...,  $f(\{a,b,e\})$ , pick max











# **Approximation Guarantee**

# Hill climbing produces a solution S

where:  $f(S) \ge (1-1/e)*OPT$  (f(S)>0.63\*OPT)

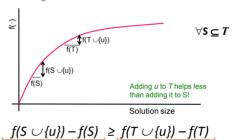
[Nemhauser, Fisher, Wolsey '78, Kempe, Kleinberg, Tardos '03]

- $\Box$  Claim holds for functions  $f(\cdot)$  with 2 properties:
  - ☐ f is monotone: (activating more nodes doesn't hurt) if  $S \subset T$  then  $f(S) \leq f(T)$  and  $f(\{\})=0$
  - fis submodular: (activating each additional node helps less) adding an element to a set gives less improvement than adding it to one of its subsets:  $\forall S \subseteq T$

$$\underbrace{f(S \cup \{u\}) - f(S)}_{\text{Gain of adding a node to a small set}} \ge \underbrace{f(T \cup \{u\}) - f(T)}_{\text{Gain of adding a node to a large set}}$$

# Submodularity—Diminishing returns

□ Diminishing returns:



# Solution Quality

### We just proved:

□ Hill climbing finds solution S which

 $f(S) \ge (1-1/e)*OPT$ i.e.,  $f(S) \ge 0.63*OPT$ 

### □ This is a data independent bound

- □ This is a worst case bound
- □ No matter what is the input data (influence sets), we know that the Hill-Climbing won't never do worse than 0.63\*OPT

# Evaluating f(S)?

### □ How to evaluate f(S)?

- Still an open question of how to compute efficiently
- But: Very good estimates by simulation
  - □ Repeating the diffusion process often enough (polynomial in n;  $1/\epsilon$ )
  - Achieve  $(1 \pm \varepsilon)$ -approximation to f(S)
  - □ Generalization of Nemhauser-Wolsey proof: Greedy algorithm is now a  $(1-1/e-\varepsilon')$ -approximation



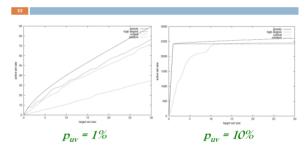
### **Experiment Data**

- □ A collaboration network: co-authorships in papers of the arXiv high-energy physics theory:
  - □ 10,748 nodes
  - □ 53,000 edges
- □ Independent Cascade Model:
  - □ Case 1: Uniform probabilities p on each edge
  - **Case 2:** Edge from v to ω has probability  $1/\deg(ω)$  of activating ω.

# **Experiment Settings**

- □ Simulate the process 10,000 times for each targeted set
  - Every time re-choosing edge outcomes randomly
  - □ Compare with other 3 common heuristics
    - □ Degree centrality,
    - □ Distance centrality
    - □ Random nodes

# Independent Cascade Model



# Independent Cascade Model

