

Feedback Vertex Set with Bounded Cycle Length: Approximation, Tractability and Beyond the Worst-Case Analysis

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Outline

- 1 Problem Overview
- 2 Approximation Schemes
- 3 Fixed-Parameter Tractability of FVS-BCL
- 4 Certified Algorithms
- 5 Conclusion

Problems Studied (Emphasis on Focus Areas)

- Dominating Set - BWCA is studied
- Feedback Vertex Set (FVS) - Approximation is studied
- Feedback Vertex Set with Four Cycle Length (FVS-4CL)
- Feedback Vertex Set with Bounded Cycle Length (FVS-BCL)
- r -Dominating Set (r -DS)

FVS-4CL is the primary focus of this work.

We aim to generalize results to **FVS-BCL**.

(Our hope in the beginning was generalizing our results to **FVS**).

Approximation Algorithms for Feedback Vertex Set (FVS)

- $\min\{2\Delta^2, 4 \log n\}$ where Δ is the max. degree in G .
(Bar-Yehuda et al., 1994)
Primal-dual algorithm on undirected graphs with general vertex weights.
- **2-Approximation (Bafna et al., 1995)**
Local ratio technique with improved efficiency.
- **2-Approximation (Becker and Geiger, 1996)**
Greedy-like approximation algorithm.
- **2-Approximation (Chudak et al., 1998)**
A primal-dual algorithm.
- **Hardness: APX-Complete (Dinur and Safra, 2005)**
NP-hard to approximate within a factor better than 1.36 via reduction from Vertex Cover.

Approximation Algorithms for Feedback Vertex Set (FVS) in planar graphs

- **PTAS for FVS (Kleinberg and Kumar, 2001)**
- **PTAS for FVS (Le and Zheng, 2020)**
Using a local search heuristic
- **EPTAS for unweighted FVS (Demaine and Hajiaghayi)**
Using bidimensionality
- **PTAS for weighted FVS (Cohen-Addad et al., 2016)**
Reduction from weighted feedback vertex set to vertex-weighted connected dominating set
- **EPTAS for weighted FVS (Open question.)**

- **Inapproximability of Feedback Vertex Set for Bounded Length Cycles (Guruswami and Lee, 2014)**

For any integer constant $\rho \geq 3$ and $\epsilon > 0$, it is hard to find a $(\rho - 1 - \epsilon)$ -approximate solution to the problem of intersecting every cycle of length at most ρ .

We obtain:

- $(1 + 2\epsilon)$ -approximation algorithm for the FVS-4CL problem with a running time of $2^{\mathcal{O}(\text{tw}^2)} \cdot n^{\mathcal{O}(1)}$.
- $\left(1 + \frac{\lfloor \rho/2 \rfloor}{\epsilon}\right)$ -approximation for the FVS-BCL problem with a running time of $f(\text{tw}, \rho) \cdot n^{\mathcal{O}(1)}$ for some computable function f .

Baker's Technique for Unweighted FVS-4CL

Algorithm Baker's technique for the unweighted FVS-4CL

Require: Planar graph $G = (V, E)$, parameter $\ell \leftarrow \frac{1}{\epsilon}$

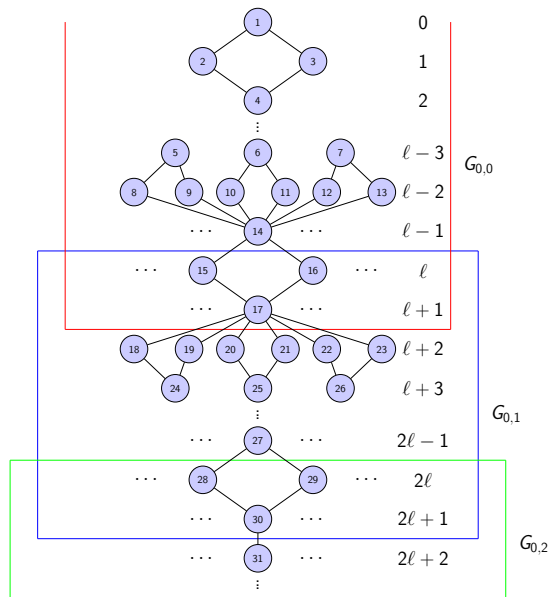
Ensure: $(1 + \epsilon)$ -approximation for FVS-4CL

- 1: Perform BFS from some arbitrary vertex r
- 2: $S \leftarrow \emptyset$
 i: shift; j: slice
- 3: **for** each $i = 0$ to $\ell - 1$ **do**
- 4: Let $G_{i,j}$ be the subgraph induced on vertices at levels $j \cdot \ell + i$ through $(j + 1) \cdot \ell + i + 1$ for all $j \geq 0$.
- 5: Let $S_{i,j}$ be the minimum unweighted FVS-4CL of $G_{i,j}$ using Algorithm 21 as a subroutine (weights are all ones).
- 6: Let $S_i = \bigcup_j S_{i,j}$
- 7: $S \leftarrow S \cup \{S_i\}$
- 8: **end for**
- 9: **return** S_{i^*} from S with minimum cardinality

BFS Layered Tree Structure

Idea: Break graph into layers via BFS.

- Nodes grouped by distance from root.
- Overlap grouped by distance from root mod ℓ
- Subgraphs $G_{0,0}, G_{0,1}, G_{0,2}, \dots$



Bounds on the Optimum Solution (Unweighted Case)

Lemma (Bound on the Optimum Solution in Subgraphs)

Let $S_{i,j}$ be the minimum unweighted feedback vertex set (FVS-4CL) for subgraph $G_{i,j}$, computed using Algorithm 1, and let $F \equiv \text{OPT}$ be the optimum solution for the full graph G .

Define $F_{i,j} := F \cap V(G_{i,j})$, i.e., the restriction of the global solution F to the subgraph $G_{i,j}$.

Then:

$$|S_{i,j}| \leq |F_{i,j}|$$

Result (Optimum solution bound for the whole graph)

Let S_i be the union of optimal solutions defined on Line 6 of Algorithm 1 for some shift i . Let $F \equiv \text{OPT}$ be the optimum solution in G and let $F_{i,j} = G_{i,j} \cap F$. For those sets it holds that:

$$|S_i| \leq \sum_j |S_{i,j}| \leq \sum_j |F_{i,j}|$$

Bounds on the Optimum Solution (Unweighted Case)

Lemma (Bound for the vertices on the boundaries (Unweighted Case))

Let $F_i = F \cap \{\text{vertices at levels } i \bmod \ell\}$. The sets F_i are disjoint and $\bigcup_i F_i = F$. We claim that:

$$\exists q \in \{0, 1, \dots, \ell - 1\} : |F_q| + |F_{q+1}| \leq \frac{2}{\ell} \cdot |F|.$$

Lemma (Bound for the cardinality of the intersection sets)

Let $F \equiv \text{OPT}$ be the optimal solution and $F_{i,j} = F \cap G_{i,j}$ be the intersection sets with the subgraphs. Then we have:

$$\sum_j |F_{i^*,j}| \leq |F| + \frac{2}{\ell} \cdot |F|$$

for some specific integer i^* .

$$|S_i^*| \leq \sum_j |S_{i^*,j}| \leq \sum_j |F_{i^*,j}| \leq \left(1 + \frac{2}{\ell}\right) \cdot |F| = (1 + 2\epsilon) \cdot |F|$$

Weighted Bounds for FVS-BCL Problems

Weighted FVS-4CL:

$$w(S_{i^*}) \leq \sum_j w(S_{i^*,j}) \leq \sum_j w(F_{i^*,j}) \leq \left(1 + \frac{2}{\ell}\right) \cdot w(F) = (1 + 2\epsilon) \cdot w(F)$$

Weighted FVS-BCL (break cycles of length ρ):

$$w(S_{i^*}) \leq \sum_j w(S_{i^*,j}) \leq \sum_j w(F_{i^*,j}) \leq \left(1 + \frac{\lfloor \rho/2 \rfloor}{\ell}\right) \cdot w(F)$$

Fixed-Parameter Tractability of FVS-BCL

Fixed-Parameter Tractability of FVS-BCL

- Monadic Second Order Logic for FVS-BCL
- Dynamic Programming Algorithm for FVS-4CL using Nice Tree Decompositions

- An extension of First-Order Logic
- Object variables: *vertices*: v_1, v_2, \dots and *edges*: e_1, e_2, \dots
- Set variables: sets of vertices V_1, V_2, \dots and sets of edges E_1, E_2, \dots
- Binary relation $\in: \{\text{object variable}\} \times \{\text{set variable}\} \rightarrow \{0, 1\}$.
Therefore $v \in V$ iff v is an element of the corresponding set V .
- The $Adj(e, v_i, v_j)$ relation. It detects whether edge e is an edge from vertex v_i to vertex v_j where $v_i \neq v_j$.
- Quantification over set variables: $\forall V_i, \forall E_i$ and $\exists V_i, \exists E_i$.

MSOL Formulation: Unweighted FVS-4CL

$$\min_{F \subseteq V} |F| :$$

$$\forall v : \forall u : \forall w : \forall z :$$

$$v \in (V \setminus F) \wedge u \in (V \setminus F) \wedge w \in (V \setminus F) \wedge z \in (V \setminus F) \quad (1)$$

$$\wedge v \neq w \wedge u \neq z$$

$$\wedge \neg((v, u) \in E \wedge (u, w) \in E \wedge (w, z) \in E \wedge (v, z) \in E)$$

MSOL Formulation: Weighted FVS-4CL

$$\min_{F \subseteq V} w(F) :$$

$$\forall v : \forall u : \forall w : \forall z :$$

$$v \in (V \setminus F) \wedge u \in (V \setminus F) \wedge w \in (V \setminus F) \wedge z \in (V \setminus F) \quad (2)$$

$$\wedge v \neq w \wedge u \neq z$$

$$\wedge \neg((v, u) \in E \wedge (u, w) \in E \wedge (w, z) \in E \wedge (v, z) \in E)$$

MSOL Formulation: Weighted FVS- ρ CL

$$\min_{F \subseteq V} w(F) :$$

$$\forall v_1 : \forall v_2 : \dots \forall v_\rho :$$

$$v_1 \in (V \setminus F) \wedge v_2 \in (V \setminus F) \cdots \wedge v_\rho \in (V \setminus F)$$

$$\wedge (v_1 \neq v_2 \wedge v_1 \neq v_3 \wedge \cdots \wedge v_1 \neq v_\rho)$$

$$\wedge (v_2 \neq v_1 \wedge v_2 \neq v_3 \wedge \cdots \wedge v_2 \neq v_\rho)$$

...

$$\wedge (v_\rho \neq v_1 \wedge v_\rho \neq v_2 \wedge \cdots \wedge v_\rho \neq v_{\rho-1})$$

$$\wedge \neg((v_1, v_2) \in E \wedge (v_2, v_3) \in E \wedge \cdots \wedge (v_{\rho-1}, v_\rho) \in E \wedge (v_\rho, v_1) \in E)$$

(3)

Courcelle's Theorem and MSOL Solvability of FVS- ρ CL

Theorem (Courcelle's theorem)

Assume that ϕ is a MSOL formula and G is an n -vertex graph, with an evaluation of all free variables of ϕ . Suppose a tree decomposition of G of width t is given. Then there exists an algorithm that verifies whether ϕ is satisfied in G in time:

$$f(\|\phi\|, t) \cdot n$$

for some computable function f .

Corollary (MSOL Solvability of FVS- ρ CL on Bounded-Treewidth Graphs)

Let $\rho \geq 3$ be a constant and $G = (V, E)$ be a graph of treewidth at most tw , with vertex-weight function $w : V \rightarrow \mathbb{N}$. Then the minimum-weight set breaking all ρ -cycles (FVS- ρ CL) can be computed in time:

$$f(\rho, \text{tw}) \cdot n$$

for some computable function f depending only on ρ and tw .

Dynamic Programming Algorithm for FVS-4CL over Nice Tree Decompositions

Algorithm Design for FVS-4CL

- ① **Solution:** For the FVS-4CL problem, a solution for graph G is a set F such that $G - F$ contains no 4-cycles.
- ② **Partial Solution:** For subgraph $G_i = (V_i, E_i)$, a partial solution F_i is a subset $F_i \subseteq V_i$, a restriction of a full solution.
- ③ **Extension of Partial Solution:** A solution F extends F_i if $F \cap V_i = F_i$.
- ④ **Characteristic of a Partial Solution:** For X_i , vertices are partitioned as:
 - $I \subseteq X_i$: vertices in the partial solution.
 - $\mathcal{F} = \{(v, u) \in X_i \times X_i : \exists w \in V_i \setminus X_i, (v, w), (u, w) \in E_i, w \notin F_i\}$
$$ch(G_i, F_i) = (I, \mathcal{F})$$

The valuation table $c[i, I, \mathcal{F}] \in \mathbb{N} \cup \{\infty\}$ gives the min. weight of F_i :

$$c[i, I, \mathcal{F}] = \min\{w(W) : W \text{ is a FVS-4CL of } G_i \wedge W \cap X_i = I\}$$

- ⑤ **Full Set of Characteristics:** For node X_i , valuations exist for all

$$I \in \{0, 1\}^{|X_i|} \quad \text{and} \quad \mathcal{F} \in \{0, 1\}^{|X_i \times X_i|}$$

There are at most $2^{(tw+1)} \cdot 2^{\binom{tw+1}{2}} = 2^{\mathcal{O}(tw^2)}$ entries.

DP Transitions over Tree Decomposition Nodes

Leaf Node: $X_i = \emptyset$

$$c[i, \emptyset, \emptyset] = 0$$

Introduce Node: Let $X_i = X_j \cup \{v\}$

$$c[i, I \cup \{v\}, \mathcal{F}] = w(v) + c[j, I, \mathcal{F}]$$

$$c[i, I, \mathcal{F}] = \begin{cases} \infty & \text{if } \exists u, w \notin I : (u, w) \in \mathcal{F}, (v, u), (v, w) \in E_i \\ c[j, I, \mathcal{F}] & \text{otherwise} \end{cases}$$

Forget Node: Let $X_i = X_j \setminus \{v\}$

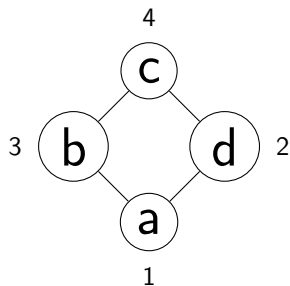
$$c[i, I, \mathcal{F}] = \min \left(c[j, I \cup \{v\}, \mathcal{F}], c[j, I, \mathcal{F} \cup \{(u, w) : (v, u), (v, w) \in E_i\}] \right)$$

Join Node: Let $X_i = X_{j_1} = X_{j_2}$

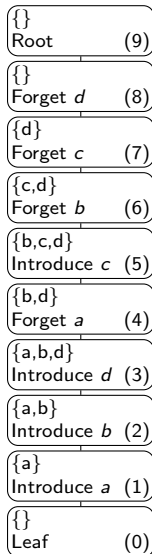
$$c[i, I, \mathcal{F}] = \min_{\mathcal{F}_1 \cup \mathcal{F}_2 = \mathcal{F}} (c[j_1, I, \mathcal{F}_1] + c[j_2, I, \mathcal{F}_2] - w(I))$$

Infeasible if $\exists u, w \notin I : (u, w) \in \mathcal{F}_1 \cap \mathcal{F}_2 \Rightarrow c[i, I, \mathcal{F}] = \infty$

Rhombus Graph and Tree Decomposition

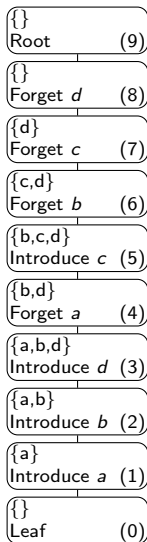


Rhombus Graph G



Nice Tree Decomposition
of the graph G with a width of 2.

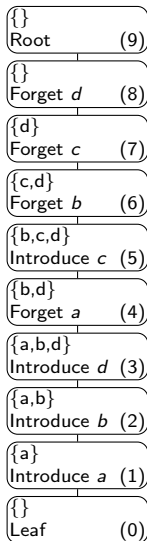
Rhombus Graph and Tree Decomposition



i	I	\mathcal{F}	Value
0	\emptyset	\emptyset	0
1	a	\emptyset	1
1	\emptyset	\emptyset	0
2	$\{a, b\}$	\emptyset	4
2	$\{a\}$	\emptyset	1
2	$\{b\}$	\emptyset	3
2	\emptyset	\emptyset	0
3	$\{a, b, d\}$	\emptyset	6
3	$\{a, b\}$	\emptyset	4
3	$\{a, d\}$	\emptyset	3
3	$\{b, d\}$	\emptyset	5
3	$\{a\}$	\emptyset	1
3	$\{b\}$	\emptyset	3
3	$\{d\}$	\emptyset	2
3	\emptyset	\emptyset	0
4	$\{b, d\}$	\emptyset	6
4	$\{b, d\}$	$\{(b, d)\}$	5
4	$\{b\}$	\emptyset	4
4	$\{b\}$	$\{(b, d)\}$	3

i	I	\mathcal{F}	Value
4	$\{d\}$	\emptyset	3
4	$\{d\}$	$\{(b, d)\}$	2
4	\emptyset	\emptyset	1
4	\emptyset	$\{(b, d)\}$	0
5	$\{b, c, d\}$	\emptyset	10
5	$\{b, c, d\}$	$\{(b, d)\}$	9
5	$\{b, d\}$	\emptyset	6
5	$\{b, d\}$	$\{(b, d)\}$	5
5	$\{b, c\}$	\emptyset	8
5	$\{b, c\}$	$\{(b, d)\}$	7
5	$\{b\}$	\emptyset	4
5	$\{b\}$	$\{(b, d)\}$	3
5	$\{c, d\}$	\emptyset	7
5	$\{c, d\}$	$\{(b, d)\}$	6
5	$\{d\}$	\emptyset	3
5	$\{d\}$	$\{(b, d)\}$	2
5	$\{c\}$	\emptyset	5
5	$\{c\}$	$\{(b, d)\}$	4
5	\emptyset	\emptyset	1
5	\emptyset	$\{(b, d)\}$	∞

Rhombus Graph and Tree Decomposition



i	I	\mathcal{F}	Value
6	$\{c, d\}$	\emptyset	10
6	$\{c, d\}$	\emptyset	9
6	$\{d\}$	\emptyset	6
6	$\{d\}$	\emptyset	5
6	$\{c\}$	\emptyset	8
6	$\{c\}$	\emptyset	7
6	\emptyset	\emptyset	4
6	\emptyset	\emptyset	3
6	$\{c, d\}$	\emptyset	7
6	$\{c, d\}$	\emptyset	6
6	$\{d\}$	\emptyset	3
6	$\{d\}$	\emptyset	2
6	$\{c\}$	\emptyset	5
6	$\{c\}$	\emptyset	4
6	\emptyset	\emptyset	1
6	\emptyset	\emptyset	∞

i	I	\mathcal{F}	Value
6	$\{c, d\}$	\emptyset	6
6	$\{d\}$	\emptyset	2
6	$\{c\}$	\emptyset	4
6	\emptyset	\emptyset	1
7	$\{d\}$	\emptyset	2
7	\emptyset	\emptyset	1
8	\emptyset	\emptyset	1
9	\emptyset	\emptyset	1

Beyond the Worst-Case Analysis

Beyond the Worst-Case Analysis

- Perturbation resilience
- m -Stitching and Π - m -Stitching
- Certified Algorithms

Definitions: γ -Perturbation and γ -Stability

Definition (γ -Perturbation for Vertex-Optimization Problems)

Let (G, w) be a weighted graph. For any $\gamma \in \mathbb{R}_{\geq 0}$, a γ -**perturbation** of the weight function $w : V \rightarrow \mathbb{N}$ is a function $w' : V \rightarrow \mathbb{R}$ such that:

$$w(v) \leq w'(v) \leq \gamma \cdot w(v) \quad \forall v \in V.$$

the number may be different for each parameter!

Definition (γ -Stability)

Let Π be a vertex-minimization problem. For any $\gamma \in \mathbb{R}_{\geq 0}$, a weighted graph (G, w) is called a γ -**stable instance** of Π if it admits a unique optimal solution S that remains optimal under all γ -perturbations of the weight function w .

Definition: Certified Algorithm

Definition (Certified Algorithm)

A γ -**certified solution** to an instance (G, w) of a weighted vertex-optimization problem Π is a pair (S, w') , where:

- w' is a γ -**perturbation** of the original weight function w , and
- S is an **optimal solution** for the instance (G, w') .

A γ -**certified algorithm** for Π maps each instance (G, w) to a γ -certified solution.

Perturbation-Resilient Instances

- An instance I is γ -**perturbation resilient** if:
 - I has a **unique optimal solution**, and
 - every γ -perturbation of I preserves that optimal solution.

Certified Algorithms

- A γ -**certified algorithm**:
 - **Exactly solves all γ -perturbation-resilient instances.**
 - Always returns a γ -**approximate solution**.
 - Gives a γ -**approximate solution** for the complement problem.

Definition: m -stitching

Definition (m -stitching)

Assume $m \geq 0$ is an integer, J is an induced subgraph of G , and $S_1, S_2 \subseteq V(G)$. Then we define the m -stitch of S_2 onto S_1 along J as the set:

$$S_3 := (S_1 \setminus J) \cup (S_2 \cap N_G^m[J]).$$

Illustration of 2-stitching

$$S_3 := (S_1 \setminus J) \cup (S_2 \cap N_G^2[J]).$$

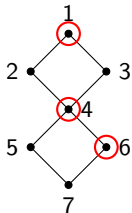


Figure: Vertex set S_1

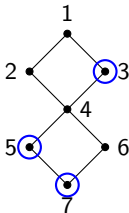


Figure: Vertex set S_2

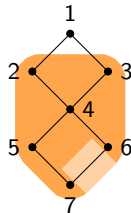


Figure: J and $N_G^2[J]$

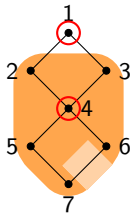


Figure: $S_1 \setminus J$

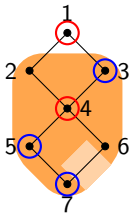


Figure: Add $S_2 \cap N_G^2[J]$

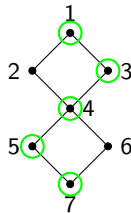


Figure: Final set S_3

Meta-Theorem for Minor-Closed Graph Classes

Theorem (Meta-Theorem for Minor-Closed Graph Classes)

Let \mathcal{G} be a minor-closed graph class whose local treewidth is bounded by $g(r) = \lambda \cdot r$, for fixed $\lambda \in \mathbb{R}$ and $r \in \mathbb{N}$.

Let Π be a vertex-minimization problem such that:

- 1 Π is guessable.
- 2 Π is m -stitchable.
- 3 There exists an algorithm A_Π that solves Π - m -stitching in time $f(t) \cdot |V(G)|^{\mathcal{O}(1)}$, where $t = \text{tw}(G[N_G^m(J)])$ and f is computable.

Then, for each $\epsilon > 0$, there exists a $(1 + \epsilon)$ -certified algorithm for Π running in time $f(\lambda \cdot m/\epsilon) \cdot |V(G)|^{\mathcal{O}(1)}$ on any input $(G, w : V(G) \rightarrow \mathbb{N})$, with $G \in \mathcal{G}$ and polynomially-bounded weights.

(Bumpus et al., 2024)

Definition (Guessable)

A problem Π is *guessable* if there is an algorithm that outputs a feasible solution with no requirement for optimality in polynomial time.

In the case of FVS-BCL:

This set is $F \leftarrow V$ for a graph $G = (V, E)$.

Lemma: FVS-BCL is 2-stitchable

Lemma (FVS-BCL is 2-stitchable)

Let (G, w) be any instance of the FVS-4CL problem, let $J \subseteq V(G)$ be a subset of the vertices in the graph, and let S_1 and S_2 be any two feasible solutions to the problem in G . Then the set

$$S_3 := (S_1 \setminus J) \cup (S_2 \cap N_G^2[J])$$

is a feasible solution to the problem.

Stitch-FVS-4CL Algorithm

Algorithm Stitch-FVS-4CL

Require: Vertex-weighted planar graph $(G, w : V(G) \rightarrow \mathbb{N})$, a feasible solution S_1 on G , and a vertex set $J \subseteq V(G)$

Ensure: Feasible solution S' on G , such that for all feasible solutions S^* ,

$$w(S') \leq w(S^* \oplus_{G,J}^2 S_1)$$

- 1: $H \leftarrow G[N_G^2[J] \setminus (S_1 \setminus J)]$
 - 2: Let S_2 be the output of algorithm A on input (H, w)
 - 3: **if** $w(S_2 \oplus_{G,J}^2 S_1) < w(S_1)$ **then**
 - 4: **return** $S_2 \oplus_{G,J}^2 S_1$
 - 5: **else**
 - 6: **return** S_1
 - 7: **end if**
-

Case-distinction proof

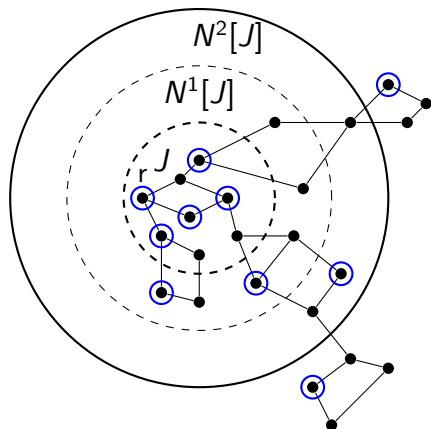


Figure: Sets $J \subseteq N_G^1[J] \subseteq N_G^2[J]$;
Solution S_1 in blue

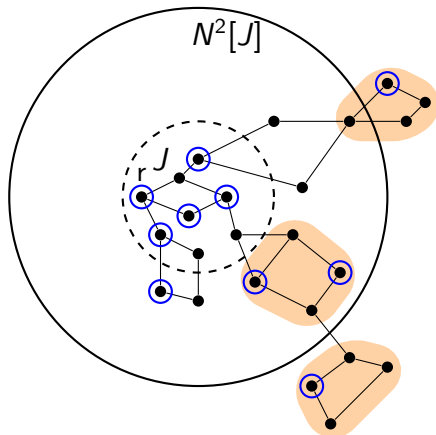


Figure: $\forall v \in \{v_1, v_2, v_3, v_4\}$, such that
 $v \in S_1$, it holds that $v \notin J$

Case-distinction proof

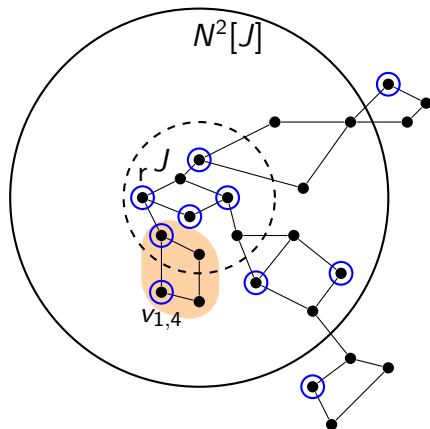


Figure: $\exists v \in \{v_1, v_2, v_3, v_4\}$, such that $v \in S_1: v \in J$

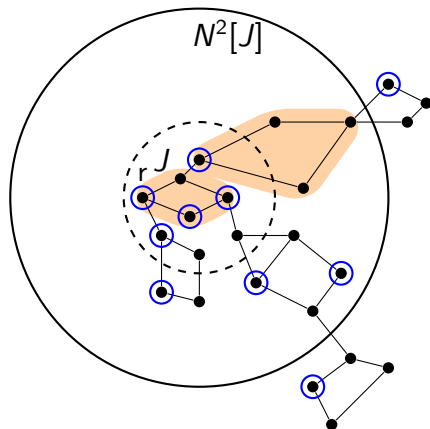


Figure: $\forall v \in \{v_1, v_2, v_3, v_4\}$, such that $v \in S_1: v \in J$

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$(1 + \epsilon)$ -Certified Algorithm for FVS-4CL

Algorithm $(1 + \epsilon)$ -Certified algorithm for FVS-4CL

Require: Vertex-weighted planar graph $(G, w : V(G) \rightarrow \mathbb{N})$, $\epsilon > 0$

Ensure: A vertex set $S^* \subseteq V(G)$ and a $(1 + \epsilon)$ -perturbation w' of w such that S^* is optimal for FVS-4CL on (G, w')

- 1: $\kappa \leftarrow \lceil \frac{2m}{\epsilon} \rceil + 2m$, where $m \leftarrow 2$
- 2: Let S^* be a feasible solution (FVS-4CL is guessable)
- 3: Perform BFS from an arbitrary vertex r
- 4: **while** there exists a subgraph $J_{\kappa-2m}$ of width $\kappa - 2m$ such that $w_A((G, w), S^*, J_{\kappa-2m}) < w(S^*)$ **do**
- 5: $S^* \leftarrow A((G, w), S^*, J_{\kappa-2m})$
- 6: **end while**
- 7: Define $w' : V(G) \rightarrow \mathbb{R}^+$ by:

$$w'(x) = \begin{cases} w(x) & \text{if } x \in S^* \\ (1 + \epsilon)w(x) & \text{otherwise} \end{cases}$$

Summary of Contributions

- Applied **Baker's technique** to establish an **EPTAS** for the **FVS-BCL** and **FVS-4CL** problems in planar graphs.
- Proved that the **FVS-4CL** problem is tractable via **dynamic programming over nice tree decompositions**, and that the **FVS-BCL** problem is tractable via a formulation in **monadic second-order logic (MSOL)**.
- Designed an algorithm for computing **$(1 + \varepsilon)$ -certified solutions** for both problems.

- Extend the DP algorithm over nice tree decompositions to FVS-BCL
- Improve the current algorithm that has a running time of $2^{\mathcal{O}(\text{tw}^2)} \cdot n^{\mathcal{O}(1)}$
 - Cut & Count technique, which obtained a $3^{\mathcal{O}(\text{tw})} \cdot n^{\mathcal{O}(1)}$ randomized algorithm (**Cygan et al., 2011**)
 - Deterministic $2^{\mathcal{O}(\text{tw})} \cdot n^{\mathcal{O}(1)}$ rank-based approach (**Bodlaender et al., 2015**)
- Improve the certified algorithm for FVS-BCL. In particular, it would be valuable to develop an approach that eliminates the current reliance on the polynomially-bounded weights constraint

Thank you!

Questions?