Heuristic Opt. Techniques - Assignment 2 Report

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1 Implementation

To build a framework that can use different neighbourhood structures and different step functions on these, we first tried to think of three separate neighbourhoods.

1.0.1 Neighbourhood structures

• One Edge Swap

This neighbourhood provides all solutions that differ to our solution in only one edge swap - i.e one edge is moved to a different page.

• One Node Swap

This neighbourhood provides all solutions that differ to our solution in one swapped node in the spine order - i.e one node swaps place with one other node in the spine order.

• Node Neighbour Swap

This neighbourhood provides all solutions where the order of the nodes differs in one swap of two neighbouring nodes, i.e nodes that are next to each other in the spine order. This is essentially a smaller neighbourhood of the One Node Swap neighbourhood which is thus faster, but has less potential to escape local optima.

None of these neighbours (on its own) is complete, in the sense that all possible instances in the solution space are covered. We created neighbourhoods that either only focus on the edges or on the node order. So clearly only a combination of neighbourhoods would reach any valid solution in the search space.

1.0.2 Step Functions

• Best Improvement

This step function is quite trivial. Every neighbour is evaluated and only the best improvement (if any!) is accepted.

• First Improvement

This step function accepts the first neighbour with a lower crossing count than the original solution (where we created our neighbours from).

• Best Improvement

This step function accepts a random neighbour. To implement this, we actually instruct the neighbourhood itself to generate a random, but valid, neighbour for the given initial solution.

Furthermore, to increase the performance of our crossing counting, we implemented a new mechanism altogether, and extended the existing mechanism from our last assignment.

The new mechanism, which we called IntegerColission, is used when the spine order is changed, and it consists of an integer array that counts at which nodes which edge is "active", i.e., passing over it. This required that the edges are first sorted by their highest (w.r.t the ordering) end point.

The old mechanism, which we called ActiveEdge, almost the same, except it also inserted the edges itself in a search tree, sorted by their "span" (the distance between the current node at which it is passing, and its highest end point). We added the possibility to also remove edges from it, which allows an incremental evaluation of solutions, which only differ in their edge partition.

Therefore, the incremental evaluation is only used for the Edge Swap neighbourhood. Since we could not make our ActiveEdge mechanism incremental for changes in the spine order, we reduced the needed memory usage by replacing it with a simple integer array.

2 Evaluation

For the testing, we used the eowyn cluster (eowyn.ac.tuwien.ac.at) under the given login credentials. For our testing, we let each of the ten instances (automatic-1 to automatic-10) run for each of three construction heuristics. The first two are the Deterministic and Randomized construction heuristics from assignment 1. We furthermore added a completely Random construction "heuristic", it simply generates a totally random solution. Its purpose is simply to observe how the local search improves it compared to the other two. (The Randomized was run for 30 seconds and the best one taken as the initial solutions).

Then we used one the three neighbourhoods defined above and one of the three step functions from above. Altogether this gives us 27 possible test scenarios. Each specific instance was limited to 15 minutes, with a hard timeout. At the timeout, the last found solution was output.

For the larger instances (6 to 10), we only used the first improvement step functions, since the other two almost always stopped without finding anything within 15 minutes. Ideally, this could be solved in the case of Best Improvement by drastically increasing the performance of creating and evaluating new solutions.

The results can be seen in the table below. Each entry is the best (lowest) result that was achieved using that combination of heuristic for initial solution, step function and search in the neighbourhood.

3 Observations

We observerd, that using random solutions did not yield a gain, in any of the instances. Our construction heuristics preform much better than just random initial solutions. Since the construction heuristics are relatively cheap, they should be used over just random initial solutions.

• How many iterations does it take to reach local optima? What does this say about your neighbourhood(s)?

Measure this!

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automatic-10	2163516	2163516	2163516					ı	1	2163516	2163516	2163516			1				2163516	2163516	2163516		ı	1	1	ı	
automatic-9	66568	89299	66568						1	66568	66568	66568							66568	66568	66568		,	,			
automatic-8	561563	561563	561563		1			1	1	561563	561563	561563			1			1	561563	561563	561563	1		1	1	1	
automatic-7	12156016	12156016	12156016	1	1	1	1	1	1	12156016	12156016	12156016	1	1	1	1	1	1	12156016	12156016	12156016	-	1	1	1	1	
automatic-6	156651	156651	156651	1	-	1	1	-	1	156651	156651	156651	1	-	1	1	1	-	156651	156651	156651	-	1	1		1	-
automatic-5	56610	56610	56610	1	1	1	1	1	1	56610	56610	56610	1	1	1	1	1	1	56610	56610	56610	1	1	1		1	
automatic-5	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560	1560
automatic-4	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453	1453
automatic-3	513	513	513	513	513	513	513	513	513	513	513	513	513	513	513	513	513	513	513	513	513	513	513	513	513	513	513
automatic-2	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156
automatic-1	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156	156
Scenario	DFE	DFN	DFNE	DBE	DBN	DBNE	DRE	DRN	DRNE	RIFE	RIFN	RIFNE	RIBE	R1BN	R1BNE	RIRE	RIRN	RIRNE	R2FE	R2FN	R2FNE	R2BE	R2BN	R2BNE	R2RE	R2RN	R2RNE

Table 1: Code for scenario name: [Construction name] + [Step function name] + [Neighbourhood name] [Construction name] = [D := Deterministic, R1 := Randomized, R2 := Random] [Step function name] = [B := Best Improvement, F := First Improvement, R := Random] [Neighbourhood name] = [E := Edge Swap, N := Node Swap, NE := Node Neighbour]