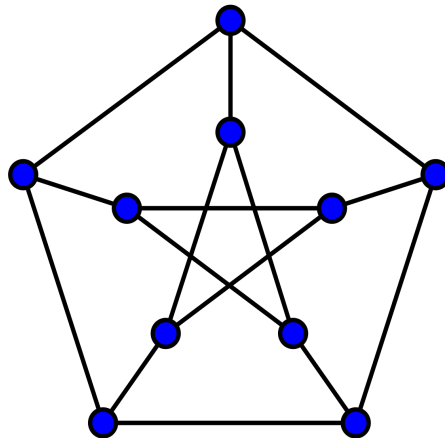


UNIVERSITY OF LJUBLJANA
FACULTY OF MATHEMATICS AND PHYSICS

Investigating Graph Metric Identities
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REPORT

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Introduction

This report presents the findings of our investigation into the *metric dimensions* of graphs, specifically focusing on the two relationships among the metric dimension, the edge metric dimension, and the mixed metric dimension of a graph. Our objective is the following:

Problem Statement: Let $G \in \mathcal{G}(V, E)$ be a connected graph with $\mathbf{dim}(G)$, $\mathbf{edim}(G)$, and $\mathbf{mdim}(G)$ representing the metric dimension, edge metric dimension, and mixed metric dimension of G , respectively. Objective is to find graphs $G \in \mathcal{G}$ such that one of the following relationships holds:

$$(1) \dim(G) = \text{edim}(G) + \text{mdim}(G)$$

$$(2) \text{mdim}(G) = \dim(G) + \text{edim}(G)$$

Before we delve deeper, we need to clarify some of the key concepts and ideas that will be foundational to our problem. Let's define some key terms.

Preliminary Definitions

Since we need to understand the concept of *resolving sets* for definition of metric dimension, we will first explain when vertex is resolved by a set of vertices. We say that a vertex s *resolves* a pair of vertices v_1 and v_2 if the shortest distance between v_1 and s is different from the shortest distance between v_2 and s , i.e. $d(v_1, s) \neq d(v_2, s)$. Let's examine one example:



In the left graph, vertex s resolves vertices v_1 and v_2 , because $d(v_1, s) = 1$ and $d(v_2, s) = 2$, while in the right graph, vertex s does not resolve v_1 and v_2 since $d(v_1, s) = d(v_2, s) = 1$.

Definition. (*Resolving Set*)

Set $S \subseteq V(G)$ is a resolving set of a graph G if for every pair of distinct vertices $u, v \in V(G)$, there exists a vertex $s \in S$ such that $d(u, s) \neq d(v, s)$.

For better understanding of resolving sets, it is essential to understand how vertices can be uniquely distinguished based on their distances to specific subsets of the graph.

Definition. (*Metric Representation*)

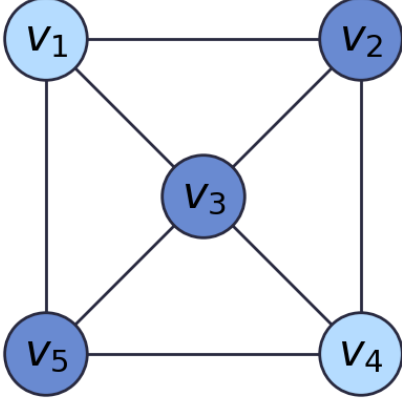
Let $G \in \mathcal{G}(V, E)$ and $W \subseteq V(G)$ be an ordered set. Metric representation of G is a function $r : V(G) \rightarrow \mathbb{R}^{|W|}$ defined as $r(v | W) = (d(v, w_1), d(v, w_2), \dots, d(v, w_{|W|}))$ for all $v \in V(G)$.

Set $W \subseteq V(G)$ is also called *set of representatives* of G and it has important connection to resolving sets. But first, let's look into metric representations for two graphs from above. If we chose $W = \{s\}$, then metric representation of the left graph would be $r(v_1 | W) = (1)$ and $r(v_2 | W) = (2)$, while for the right graph, $r(v_1 | W) = (1)$ and $r(v_2 | W) = (1)$. This leads us to the following proposition:

Proposition. (Resolving Set Criterion)

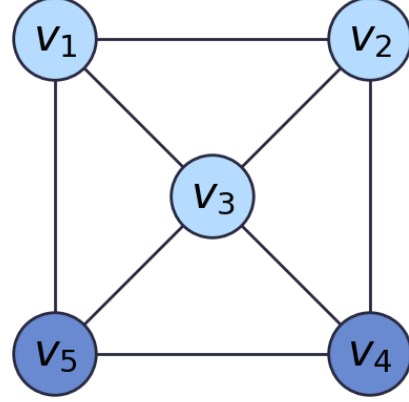
Set of representatives $W \subseteq V(G)$ is a resolving set of G if and only if the distinct vertices $u, v \in V(G)$ have distinct metric representation, i.e. $\forall u, v \in V, u \neq v : r(u | W) \neq r(v | W)$.

Let's look into another example for better understanding. Consider the following graphs:



In the left graph, set of representatives is $W_1 = \{v_2, v_3, v_5\}$ and the following metric representation are:

$$\begin{aligned} r(v_1 | W_1) &= (1, 1, 1) \\ r(v_2 | W_1) &= (0, 1, 2) \\ r(v_3 | W_1) &= (1, 0, 1) \\ r(v_4 | W_1) &= (1, 1, 1) \\ r(v_5 | W_1) &= (2, 1, 0) \end{aligned}$$



While on the right graph, $W_2 = \{v_4, v_5\}$ and this selection corresponds to the following metric representations:

$$\begin{aligned} r(v_1 | W_2) &= (2, 1) \\ r(v_2 | W_2) &= (1, 2) \\ r(v_3 | W_2) &= (1, 1) \\ r(v_4 | W_2) &= (0, 1) \\ r(v_5 | W_2) &= (1, 0) \end{aligned}$$

Set W_1 is not the resolving set, because $r(v_1 | W_1) = r(v_4 | W_1)$, while on the other hand W_2 is resolving set since every metric representation is distinct. Now, with better understanding of resolving sets, we are prepared to define *graph metric dimension*, notated with $\dim(G)$.

Definition. (Metric Basis)

Metric basis of connected graph G is a smallest resolving set of G .

Definition. (Metric Dimension)

Metric dimension of a connected graph G is the minimum cardinality of a resolving set of G .

In other words, the metric dimension seeks the smallest subset of vertices that can uniquely identify all other vertices in the graph based on their distances.

It is crucial to highlight that determining the metric dimension is an NP-hard problem, indicating that no polynomial-time solution is known for solving this problem in general cases. Consequently, finding an optimal resolving set requires the use of heuristic or approximation methods in practical applications.

Proposition. (Metric Dimension's Bounds)

Let $G(V, E)$ be a connected graph with $|V| = n$ vertices. The metric dimension of G , denoted by $\dim(G)$ is bounded by: $1 \leq \dim(G) \leq n - 1$.

As discussed above, determining metric dimension of a graph poses significant computational challenges, but for some graphs, analytical methods have been established [4]. Those are:

- Complete Graphs with n vertices : $\dim(K_n) = n - 1$
- Path Graphs with n vertices : $\dim(P_n) = 1$
- Star Graphs with n vertices : $\dim(S_n) = n - 2$
- Cycle Graphs with n vertices : $\dim(C_n) = 2$
- Bipartite Graphs between two sets of vertices t and s : $\dim(K_{s,t}) = s + t - 2, t \geq 1$

What about in general? How do we determine metric dimension? Let us explore computation of the K-metric dimension in greater detail [3].

Integer Linear Programme for K-metric dimension:

Let $G \in \mathcal{G}(V, E)$ be a connected graph with vertex set $V(G) = \{v_1, v_2, v_3, v_4, v_5\}$ and D_G a distance matrix defined as $D_G = [d_{ij}]_{i,j=1}^n$, where $d_{ij} = d_G(v_i, v_j)$. Note : $|V(G)| = n$.

$$\text{objective : } \min \left(\sum_{h=1}^n x_h \right)$$

subject to :

$$(1) \quad \forall i \forall j, 1 \leq i < j \leq n : \sum_{h=1}^n \delta(d_{ih}, d_{jh}) x_h \geq K$$

$$(2) \quad \forall h \in \{1, \dots, n\} : x_h \in \{0, 1\}$$

where :

$$(1) \quad \delta(d_{ij}, d_{i'j'}) = \begin{cases} 1 & ; d_{ij} \neq d_{i'j'} \\ 0 & ; d_{ij} = d_{i'j'} \end{cases}$$

$$(2) \quad x_h = \begin{cases} 1 & ; v_h \text{ is included in metric basis} \\ 0 & ; \text{otherwise} \end{cases}$$

If a given ILP is feasible for chosen threshold K and $(x_1^*, x_2^*, \dots, x_n^*)$ is optimal solution, then the set $W = \{v_i \mid x_i^* = 1\}$ forms a K -metric basis of G . So $|W| = \dim^{(K)}(G)$.

Let's give a short explanation. Since the primary goal is to identify the smallest possible subset of vertices that can uniquely distinguish all other vertices in the graph, we aim to minimize the number of selected vertices, represented by x_k . In conjunction with this, the δ -function serves as a binary comparison operator that determines whether a given vertex can resolve other vertices. Essentially, it checks whether a given vertex is part of the resolving set, which allows us to distinguish vertices based on their distances. Important to mention is the fact that, point (1) gives us $\binom{n}{2}$ constraints.

Since we need to generate distance matrix, examine every distance and identify the optimal subset of vertices, this task becomes computationally challenging. Although the resulting equations are relatively straightforward to formulate, the sheer volume of combinations makes the problem computationally intensive and time-consuming.

Remember the first example from above, ILP for metric dimension of P_3 graph is equal to :

Distance matrix for given graph is :

$$D_{P_3} = \begin{bmatrix} 0 & 1 & 2 \\ 1 & 0 & 1 \\ 2 & 1 & 0 \end{bmatrix}$$

$$K = 1.$$

$$\text{minimize } x_1 + x_2 + x_3$$

s.t.

$$x_1 + x_2 + x_3 \geq 1,$$

$$x_1 + x_3 \geq 1,$$

$$x_1 + x_2 + x_3 \geq 1,$$

$$x_1, x_2, x_3 \in \{0, 1\}$$

So the optimal solution \mathbf{x}^* is either $[1, 0, 0]^C$ or $[0, 0, 1]^C$.

Definition. (*Edge Metric*)

The edge metric of a graph G is a metric defined on the edge set $E(G)$, where the distance between two edges $e_1, e_2 \in E(G)$ is the number of common vertices between the two edges.

Definition. (*Mixed Graph Metric*)

The mixed graph metric of a graph G is a metric defined on the vertex-edge set $V(G) \cup E(G)$, where the distance between a vertex $v \in V(G)$ and an edge $e \in E(G)$ is the number of common vertices between the vertex v and the edge e .

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