

# Revisiting Joint Decoding based Multi-talker Speech Recognition with DNN Acoustic model

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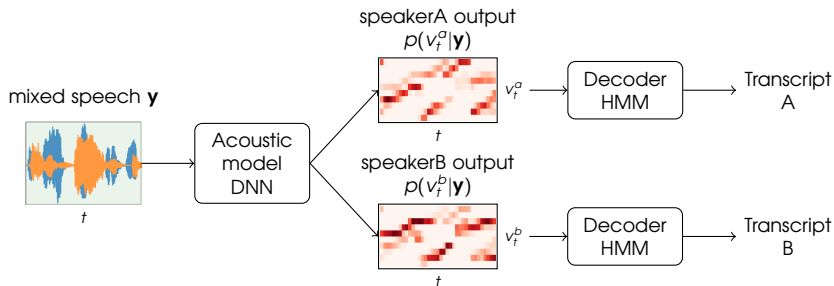
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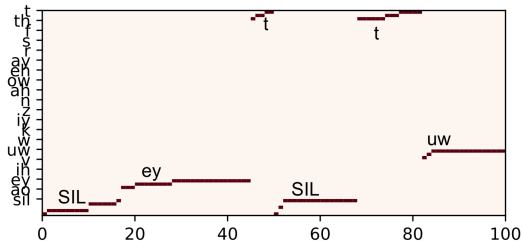
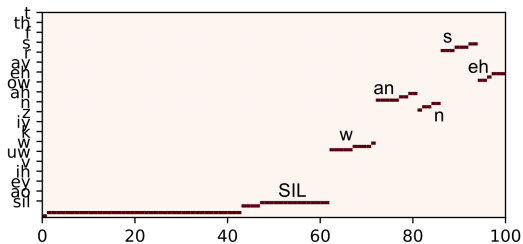
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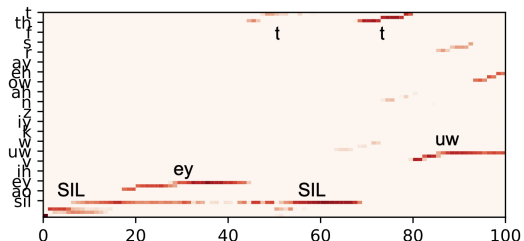
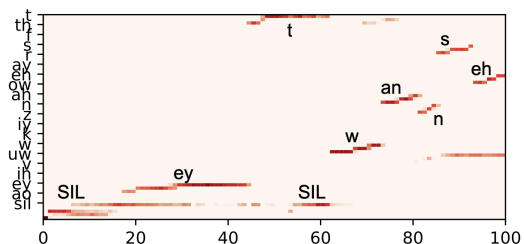
September 22, 2022



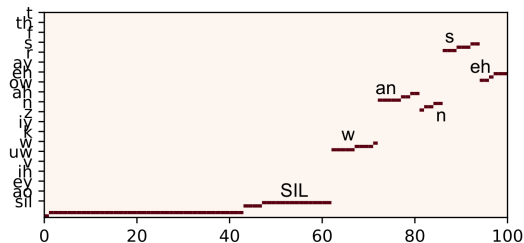
- The acoustic model is trained to produce pdf-posteriors for each speaker **separately**.
- The decoding is performed **independently**.
- **Not optimal** especially for mixtures with similarly sounding speakers (e.g. same-gender speakers).



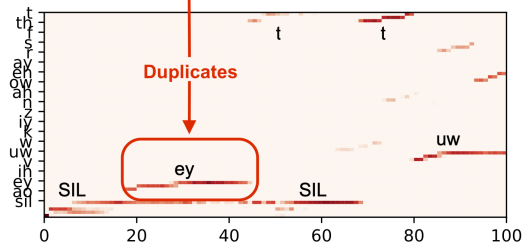
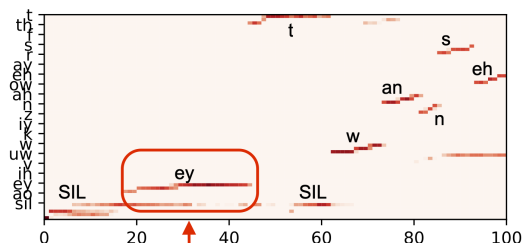
(a) Source phone alignments



(b) Separate phonetic posteriorgrams

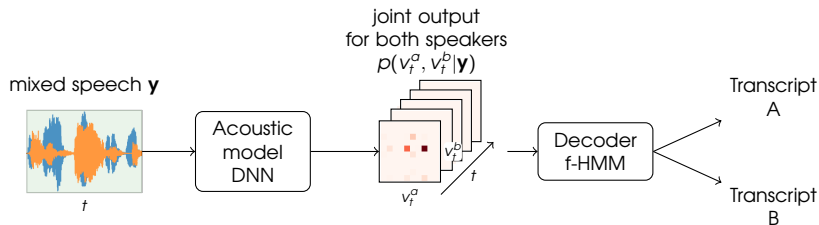


(a) Source phone alignments



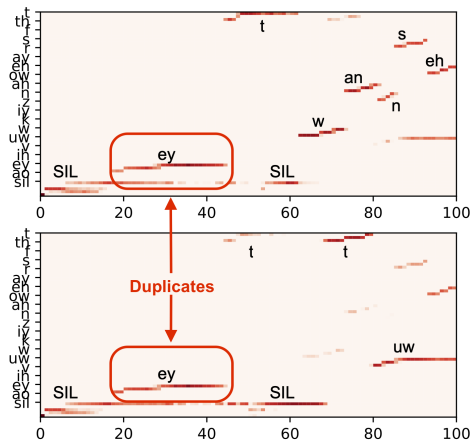
(b) Separate phonetic posteriorgrams

- Acoustic model assigns high probability of phone 'ey' to both speakers.

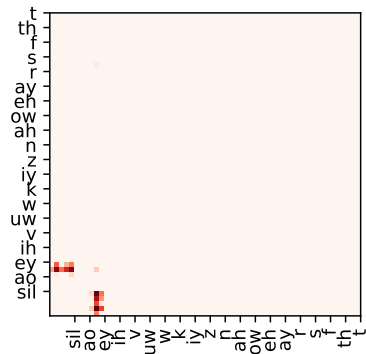


Main idea:

- Extend **factorial HMM** model to DNNs.
- The decoder also considers **the other speaker's speech states**.
- This can improve the performance especially in cases where acoustic model is unable to separate the speech.



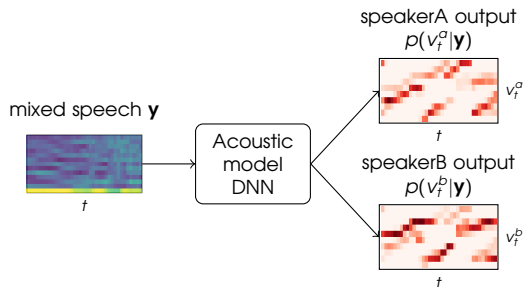
(a) Separate phonetic posteriograms



(b) Joint posteriors

- The proposed AM, which produces the joint posteriors, is able to distinguish that the phone **ey** comes from **either first or second speaker**, but not from both speakers



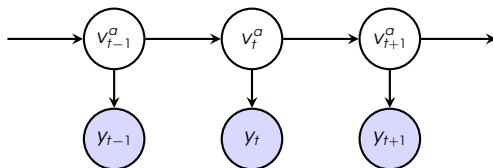


- The acoustic model predicts the posterior probabilities for each speaker  $k$  separately:

$$p(v_t^a | y_t), p(v_t^b | y_t) = f_{\text{NN}}(y_t) \quad (1)$$

- The acoustic model is forced to learn how to separate the mixed speech.
- The model is trained in **permutation-invariant** fashion.





- Recognising speech involves finding the most likely state sequence  $\hat{\mathbf{v}}^a$  given observed data  $\mathbf{y}$  (i.e. MAP state sequence).
- The MAP state sequence is obtained by Viterbi algorithm, where messages  $m(v_t)$  are defined as:

$$m(v_{t+1}^a) = \max_{v_t^a} p(v_{t+1}^a | v_t^a) m(v_t^a) \bar{p}(y_t | v_t^a) \quad (2)$$

$$\tilde{v}_t(v_{t+1}^a) = \arg \max_{v_t^a} p(v_{t+1}^a | v_t^a) m(v_t^a) \bar{p}(y_t | v_t^a). \quad (3)$$

- The MAP state sequence  $\hat{\mathbf{v}} = [\hat{v}_1, \dots, \hat{v}_T]$  is recovered by backtracking:

$$\hat{v}_t = \tilde{v}_t(\hat{v}_{t+1}) \quad (4)$$

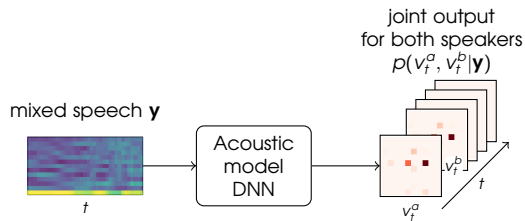
where  $\hat{v}_T = \arg \max_{v_T} m(v_T)$  initiates the recursion.

- Conventional ASR models assume conditional independence of the state sequences of the speakers given the observation, i.e.

$$p(\mathbf{v}^a, \mathbf{v}^b | \mathbf{y}) = p(\mathbf{v}^a | \mathbf{y}) p(\mathbf{v}^b | \mathbf{y}). \quad (5)$$

- We expect the acoustic model to fully solve the “separation” of the speakers, i.e., fully attribute parts of the mixed speech signal to the different outputs of the network.
- This may be challenging, especially when the speakers’ voices are very similar.
- There is no interaction between the decoders of the individual speakers.
- This can lead to duplicity where the same phoneme or word is attributed to both speakers.



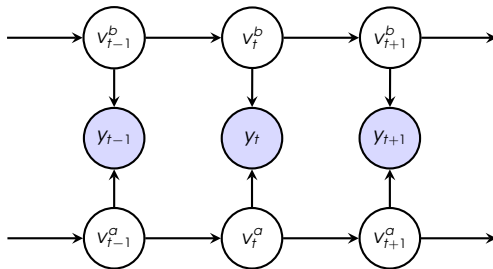


- To take account of the dependencies, we model the joint probability of mixed speech  $\mathbf{y}$  and hidden state sequences  $\mathbf{v}^a, \mathbf{v}^b$  in [Factorial HMM framework](#):

$$p(\mathbf{y}, \mathbf{v}^a, \mathbf{v}^b) = \prod_t p(y_t | v_t^a, v_t^b) p(v_t^a | v_{t-1}^a) p(v_t^b | v_{t-1}^b), \quad (6)$$

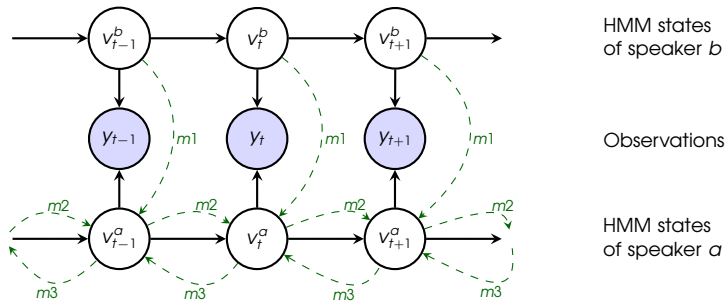
- where  $p(y_t | v_t^a, v_t^b)$  is derived from a neural network that predicts the posterior probabilities of a tuple of states  $(v_t^a, v_t^b)$  as

$$p(v_t^a, v_t^b | y_t) = g_{\text{NN}}(y_t), \quad (7)$$



- Standard Viterbi algorithm can be used to exactly infer the MAP hidden state sequences  $\hat{\mathbf{v}}^a, \hat{\mathbf{v}}^b$  in FHMM.
- We need to compute messages between all possible combinations of hidden states for all speakers, i.e. decoding network is a Cartesian product of HMM states from all speakers.
- Its time complexity is  $O(TKV^{K+1})$  for  $K$  speakers, HMM with  $V$  states and utterance time  $T$ .
- It scales exponentially w.r.t. to a number of speakers.

(Rennie S., Hershey J., and Olsen P., *Single-Channel Multitalker Speech Recognition*, IEEE Signal Processing Magazine)

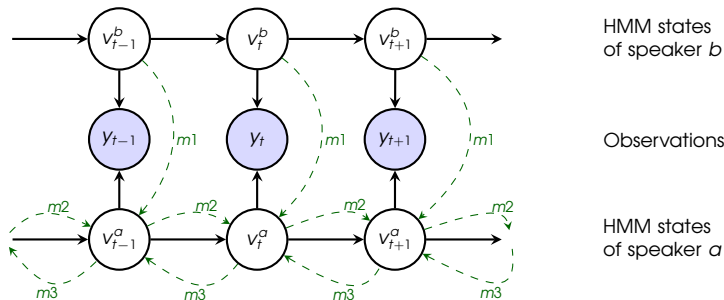


- The messages are passed between variables, which share the common factors according to a predefined schedule.
- Our message passing schedule has the following form for one speaker:

$$\tilde{p}(y_t | v_t^a) = \max_{v_t^b} \bar{p}(y_t | v_t^a, v_t^b) \tilde{p}_{fw}(v_t^b) \tilde{p}_{bw}(v_t^b) \quad (m1)$$

$$\tilde{p}_{fw}(v_t^a) = \max_{v_{t-1}^a} p(v_t^a | v_{t-1}^a) \tilde{p}_{fw}(v_{t-1}^a) \tilde{p}(y_{t-1} | v_{t-1}^a) \quad (m2)$$

$$\tilde{p}_{bw}(v_t^a) = \max_{v_{t+1}^a} p(v_{t+1}^a | v_t^a) \tilde{p}_{bw}(v_{t+1}^a) \tilde{p}(y_{t+1} | v_{t+1}^a) \quad (m3)$$



- When all messages for the first speaker are computed, the process is repeated for the next speaker, while messages of other speakers are fixed.
- The **maximizing arguments**  $\tilde{v}_t$  for all messages are also stored to recover the MAP state sequences in a manner analogous to the Viterbi algorithm.
- The whole process is repeated until it converges or some number of iterations is reached.
- The time complexity of the proposed LBP inference is  $O(TKV^2)$ , and thus it scales linearly w.r.t. to a number of speakers.





Comparing MT-ASR with separate and proposed joint decoding

- mixed TIDIGIT dataset, where each mixture consists of exactly 2 overlapping speakers
- Model architecture is same except the final layers:
  - AM for separate decoding contains 2 output layers of size 62 each
  - AM for joint decoding contains 1 output layer of size  $62 \times 62$
- hybrid ASR system, where decoding network is similar to the network used in Kaldi TIDIGIT recipe

|   | Arch     | Output (dim) | #params | Separate           | Joint        | Kaldi              |
|---|----------|--------------|---------|--------------------|--------------|--------------------|
| 1 | 5L-TDNN  | (62, 62)     | 1.9 M   | 26.09              | -            | 25.99              |
| 2 | 5L-TDNN  | (3844)       | 3.3 M   | 17.55 <sup>Σ</sup> | 15.79        | 17.83 <sup>Σ</sup> |
| 3 | 10L-TDNN | (62, 62)     | 4.1 M   | 18.68              | -            | 18.66              |
| 4 | 10L-TDNN | (3844)       | 5.5 M   | 16.36 <sup>Σ</sup> | <b>14.70</b> | 16.97 <sup>Σ</sup> |

- For a more fair comparison, we include a third *separate-marginal* method marked with Σ-symbol, which combines the AM predicting joint posteriors with separate decoding

$$p(v_t^a | y_t) = \sum_{v_t^b} p(v_t^a, v_t^b | y_t) \quad (8)$$

$$p(v_t^b | y_t) = \sum_{v_t^a} p(v_t^a, v_t^b | y_t) \quad (9)$$

- This allows us to separately evaluate the benefit of the joint posterior output (which also induces an increased number of parameters) and the benefit of the joint decoding itself

- Comparison of the systems on mixtures containing speakers of **same** or **different gender**.

| Genders  | Separate (%WER) |                    | Joint (%WER) |
|----------|-----------------|--------------------|--------------|
| F + F    | 30.54           | 28.57 <sup>Σ</sup> | 21.45        |
| M + M    | 32.61           | 27.87 <sup>Σ</sup> | 27.12        |
| same     | 31.56           | 28.23 <sup>Σ</sup> | 24.26        |
| opposite | 6.17            | 4.85 <sup>Σ</sup>  | 5.42         |



## Summary

- We proposed a new architecture for multi-talker speech recognition with [joint decoding](#).
- It has the potential to improve performance in challenging conditions where it may be difficult to achieve high separation by simply relying [only](#) on the acoustic information.
- Joint decoder was implemented in Julia using new [MarkovModels](#) toolkit (implemented by Lucas Ondel and Martin Kocour).

## Future plans

- Presented results are just a proof-of-concept experiments
- Extend the idea to larger task, e.g. WSJ0-2mix or even more realistic Chime6.
- Train the proposed AM with MMI/CTC loss, where joint pdf-posteriors would be approximated by LBP



- Performance measured on single-talker speech.

|   | Arch     | Output (dim) | #params | Separate           | Joint        |
|---|----------|--------------|---------|--------------------|--------------|
| 1 | 10L-TDNN | (62, 62)     | 4.1 M   | 22.17              | -            |
| 2 | 10L-TDNN | (3844)       | 5.5 M   | 21.35 <sup>Σ</sup> | <b>15.69</b> |

- 22.17 % WER ( 6338 / 28583, 3843 ins, 2407 del, 88 sub )
- 21.35<sup>Σ</sup> % WER ( 6103 / 28583, 3825 ins, 2119 del, 159 sub )
- 15.69** % WER ( 4485 / 28583, 2729 ins, 1552 del, 204 sub )

## Comparing MT-ASR with separate and proposed joint decoding

- Dataset: mixed TIDIGIT
  - overlapped speech of 2 speakers, where each is pronouncing some sequence of digits
  - train: 52.5 hours, valid: 5.3 hours of speech
- Acoustic model: CNN layers with batch normalization, and ReLu activation function
  - both PIT-ASR with separate decoding and the proposed ASR with joint decoding shares the same architecture
  - AM for separate decoding contains 2 output layers with size 62 each
  - AM for joint decoding contains 1 output layer with size  $62 \times 62 = 3844$
  - PIT-CE objective function (frame-level alignments from Kaldi)
- Decoding network: similar to Kaldi TIDIGT setup for monophone GMM-HMM ASR system
  - unigram LM, where each word (i.e., digit) is equally likely
  - silence is modeled by 5 HMM states
  - other 19 phones are modeled by 3-state HMM
  - states do not share emission probabilities, i.e., we have 62 PDFs in total