

find(3.3)

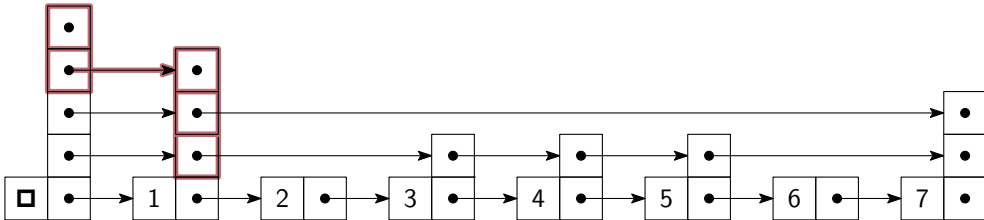
$L_4$

$L_3$

$L_2$

$L_1$

$L_0$



*sentinel*