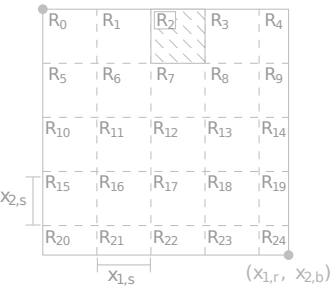
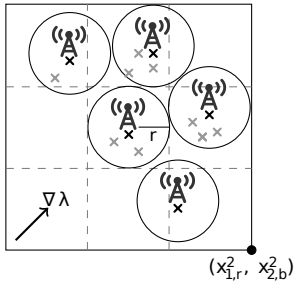


$(x_{1,l}, x_{2,t})$  R  R_2