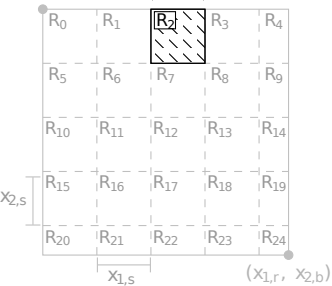
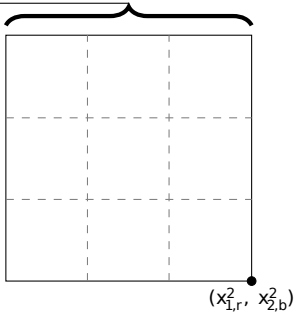


$(x_{1,l}, x_{2,t})$



$R$



$R_2$