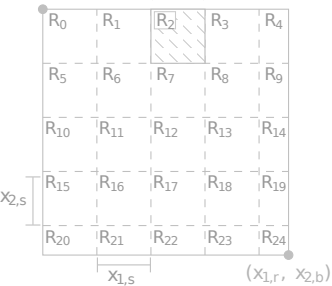
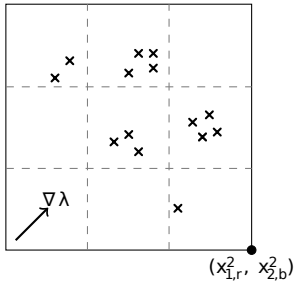


$(x_{1,l}, x_{2,t})$



R



R_2