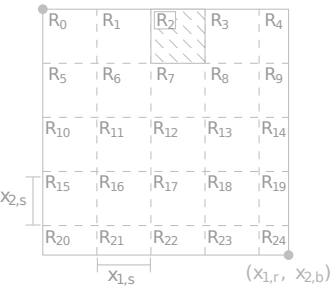
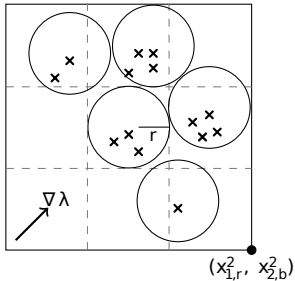


$(x_{1,l}, x_{2,t})$  $R$  $R_2$