

# TMA4110 - Øving 4 - Martin Skatvedt

mandag 24. oktober 2022

11:14

1)

$$\begin{bmatrix} 1 \\ 4 \\ 2 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 4 \\ -5 \\ 8 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 4 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} = 1 \cdot (-2) + 4 \cdot 0 + 2 \cdot 1 = \underline{0}$$

$$\begin{bmatrix} 1 \\ 4 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 4 \\ -5 \\ 8 \end{bmatrix} = 1 \cdot 4 + 4 \cdot (-5) + 2 \cdot 8 = \underline{0}$$

$$\begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 4 \\ -5 \\ 8 \end{bmatrix} = -2 \cdot 4 + 0 \cdot (-5) + 1 \cdot 8 = \underline{0}$$

skalarprodukt = 0 mellom hver vektor,  
så de står ortogonalt på hverandre

$$\left[ \begin{array}{ccc|c} 1 & -2 & 4 & 0 \\ 4 & 0 & -5 & 0 \\ 2 & 1 & 8 & 0 \end{array} \right]$$

$$\left[ \begin{array}{ccc|c} 1 & -2 & 4 & 0 \\ 0 & 8 & -21 & 0 \\ 0 & 5 & 0 & 0 \end{array} \right] \begin{array}{l} +I \cdot -4 \\ +II \cdot -2 \end{array}$$

$$\left[ \begin{array}{ccc|c} 1 & -2 & 4 & 0 \\ 0 & 5 & 0 & 0 \\ 0 & 8 & -21 & 0 \end{array} \right] \begin{array}{l} \leftarrow \\ \leftarrow \end{array}$$

$$\left[ \begin{array}{ccc|c} 1 & -2 & 4 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 8 & -21 & 0 \end{array} \right] III \cdot \frac{1}{5}$$

$$\left[ \begin{array}{ccc|c} 1 & 0 & 4 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -21 & 0 \end{array} \right] \begin{array}{l} +I \cdot 2 \\ +III \cdot -8 \end{array}$$

$$\left[ \begin{array}{ccc|c} 1 & 0 & 4 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right] III \cdot -\frac{1}{21}$$

$$\left[ \begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right] +III \cdot -4$$

x = y = z = 0, de er lineært uavhengige

$$2) \quad v = \begin{bmatrix} 3 \\ 4 \\ 2 \end{bmatrix} \quad \text{sp} \{e_1, e_2\}$$

$$p_{e_i}(v) = v_i e_i$$

$$p_{e_1}(v) = 3e_1$$

$$p_{e_2}(v) = 4e_2$$

Dermed får vi  $3e_1$  og  $4e_2$

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$$3) \quad u = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} \quad v = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$$

$$a) \quad p_v(u) = \frac{v \cdot u}{v \cdot v} v = \frac{2 \cdot 1 + 0 \cdot (-1) + 1 \cdot 0}{1 \cdot 1 + (-1) \cdot (-1) + 0 \cdot 0} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$$

$$= \frac{2}{2} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} = \underline{\underline{\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}}}$$

$$b) \quad u - p_v(u) = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} - \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\|u - p_v(u)\| = \sqrt{1^2 + 1^2 + 1^2} = \underline{\underline{\sqrt{3}}}$$

$$c) \quad \dim(\text{sp}\{v\})^\perp = \dim \mathbb{R}^3 - \dim(\text{sp}\{v\})$$

$$= 3 - 1 = \underline{\underline{2}}$$

$$4) \quad A = \begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 3 & 1 & 0 \\ 2 & 0 & 0 & 1 \end{bmatrix} \quad A^T = \begin{bmatrix} 1 & 0 & 2 \\ 2 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

null  $A^T$  ortogonal på  $\text{col } A$

$$\text{col } A^T = \text{row } A$$

oVS

$$(\text{null } A)^\perp = \text{row } A$$

$$\left[ \begin{array}{cccc|c} 1 & 2 & 0 & 0 & 0 \\ 0 & 3 & 1 & 0 & 0 \\ 2 & 0 & 0 & 1 & 0 \end{array} \right]$$

$$\left[ \begin{array}{cccc|c} 1 & 2 & 0 & 0 & 0 \\ 0 & 3 & 1 & 0 & 0 \\ 0 & -4 & 0 & 1 & 0 \end{array} \right] + \text{I} \cdot -2$$

$$\left[ \begin{array}{cccc|c} 1 & 2 & 0 & 0 & 0 \\ 0 & 3 & 1 & 0 & 0 \\ 0 & 1 & 0 & -\frac{1}{4} & 0 \end{array} \right] \text{II} \cdot -\frac{1}{4}$$

$$\left[ \begin{array}{cccc|c} 1 & 0 & 0 & -\frac{1}{2} & 0 \\ 0 & 0 & 1 & -\frac{3}{4} & 0 \\ 0 & 1 & 0 & -\frac{1}{4} & 0 \end{array} \right] + \text{III} \cdot -2 \\ + \text{III} \cdot -3$$

$$5) \quad v_1 \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix} \text{ og } v_2 \begin{bmatrix} 1 \\ 0 \\ 1 \\ 2 \end{bmatrix}$$

$$a) \quad v_1 = v_1$$

$$v_2 = v_2 - P_{v_1}(v_2) = v_2 - \frac{\langle v_1, v_2 \rangle}{\langle v_1, v_1 \rangle} v_1$$

$$= \begin{bmatrix} 1 \\ 0 \\ 1 \\ 2 \end{bmatrix} - \frac{0 \cdot 1 + (-1) \cdot 0 + 0 \cdot 0 + 1 \cdot 2}{0 \cdot 0 + (-1) \cdot (-1) + 0 \cdot 0 + 1 \cdot 1} \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 2 \end{bmatrix} - \frac{2}{2} \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \\ 0 \\ 1 \\ 2 \end{bmatrix} - \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

vi får da  $v_1$  og  $[1, 1, 1, 1]^T$  som ortogonale basiser

$$b) \quad P_U(e_1) = P_{v_1}(e_1) + P_{v_2}(e_2)$$

$$P_{v_1}(e_1) = \frac{v_1 \cdot e_1}{v_1 \cdot v_1} v_1 = \frac{0 \cdot 1 + (-1) \cdot 0 + 0 \cdot 0 + 1 \cdot 0}{0 \cdot 0 + (-1) \cdot (-1) + 0 \cdot 0 + 1 \cdot 1} \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix}$$

$$= \frac{0}{2} \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$P_{v_2}(e_1) = \frac{1 \cdot 1 + 0 \cdot 1 + 0 \cdot 1 + 0 \cdot 1}{1 \cdot 1 + 1 \cdot 1 + 1 \cdot 1 + 1 \cdot 1} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \frac{1}{4} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

$$P_U(e_1) = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + \frac{1}{4} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{4} \\ \frac{1}{4} \\ \frac{1}{4} \\ \frac{1}{4} \end{bmatrix}$$

$$\begin{aligned}
 P_U(e_2) &= \frac{\begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}}{\begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} + \frac{\begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}}{\begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} \cdot \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix}} \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} \\
 &= \frac{-1}{2} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix} + \frac{1}{4} \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} = \begin{bmatrix} 0 \\ -\frac{1}{2} \\ 0 \\ \frac{1}{2} \end{bmatrix} + \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} = \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix}
 \end{aligned}$$

$$\begin{aligned}
 P_U(e_3) &= \frac{\begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}{\begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix} + \frac{\begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}}{\begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} \cdot \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix}} \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} \\
 &= \frac{0}{2} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix} + \frac{-1}{4} \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} = \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix}
 \end{aligned}$$

$$\begin{aligned}
 P_U(e_4) &= \frac{\begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}}{\begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix} + \frac{\begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}}{\begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} \cdot \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix}} \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} \\
 &= \frac{1}{2} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix} + \frac{-1}{4} \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} = \begin{bmatrix} 0 \\ \frac{1}{2} \\ 0 \\ \frac{1}{2} \end{bmatrix} + \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} = \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix}
 \end{aligned}$$

$$[P_U] = \begin{bmatrix} \frac{1}{4} & \frac{1}{4} & \frac{1}{4} & \frac{1}{4} \\ \frac{1}{4} & \frac{3}{4} & \frac{1}{4} & \frac{1}{4} \\ \frac{1}{4} & \frac{1}{4} & \frac{1}{4} & \frac{1}{4} \\ \frac{1}{4} & -\frac{1}{4} & \frac{1}{4} & \frac{3}{4} \end{bmatrix} = \frac{1}{4} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 3 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & 3 \end{bmatrix}$$

c)  $V = \mathbb{R}^4$

$$U = \text{sp} \left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \\ 2 \end{bmatrix} \right\}$$

$$\dim U^\perp = \dim \mathbb{R}^4 - \dim U$$

$$\dim U^\perp = 4 - 2 = \underline{\underline{2}}$$

d)

$$\begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \\ 1 \end{bmatrix} = 0$$

$$\begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix} = 0$$

e)

$$\left[ \begin{array}{cccc|c} 1 & 1 & 1 & 1 & 0 \\ 1 & 3 & 1 & -1 & 0 \\ 1 & 1 & 1 & 1 & 0 \\ 1 & -1 & 1 & 3 & 0 \end{array} \right]$$

$$\left[ \begin{array}{cccc|c} 1 & 1 & 1 & 1 & 0 \\ 0 & 2 & 0 & -2 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & -2 & 0 & 2 & 0 \end{array} \right]$$

$$\left[ \begin{array}{cccc|c} 1 & 1 & 1 & 1 & 0 \\ 0 & 2 & 0 & -2 & 0 \\ 0 & -2 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \begin{array}{l} \nwarrow \\ \nearrow \end{array}$$

$$\left[ \begin{array}{cccc|c} 1 & 1 & 1 & 1 & 0 \\ 0 & 1 & 0 & -1 & 0 \\ 0 & -2 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \text{II} \cdot \frac{1}{2}$$

$$\left[ \begin{array}{cccc|c} 1 & 0 & 1 & 2 & 0 \\ 0 & 1 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \begin{array}{l} + \text{II} \cdot -1 \\ + \text{II} \cdot 2 \end{array}$$

$$\text{null } A = \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} t + \begin{bmatrix} -2 \\ 1 \\ 0 \\ 1 \end{bmatrix} s$$

$$\ker([P_U]) : \text{Alle vektorer p\u00e5 formen } \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} t + \begin{bmatrix} -2 \\ 1 \\ 0 \\ 1 \end{bmatrix} s$$

$$\text{col } A = \text{sp} \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \\ 3 \end{bmatrix} \right\}$$

$$b) \langle f, g \rangle = \int_0^1 f(x) g(x) dx$$

$$a) \langle x, \frac{1}{x^2+1} \rangle = \int_0^1 x \cdot \frac{1}{x^2+1} dx$$

$$= \int_0^1 \frac{x}{x^2+1} dx$$

$$u = x^2 + 1$$

$$\frac{du}{dx} = 2x$$

$$dx = \frac{du}{2x}$$

$$= \int_0^1 \frac{1}{2u} du = \frac{1}{2} \int_0^1 \frac{1}{u} du$$

$$= \frac{1}{2} [\ln u]_0^1 = \frac{1}{2} [\ln(x^2+1)]_0^1$$

$$= \frac{1}{2} (\ln 2 - \ln 1) = \underline{\underline{\frac{1}{2} \ln 2}}$$

Ikke ortogonale

$$b) u_1 = 1$$

$$u_2 = v_2 - \frac{\langle u_1, v_2 \rangle}{\langle u_1, u_1 \rangle} u_1 = x^2 - \frac{\langle 1, x \rangle}{\langle 1, 1 \rangle} 1$$

$$\langle 1, x \rangle = \int_0^1 1 \cdot x dx = \left[ \frac{1}{2} x^2 \right]_0^1 = \frac{1}{2} \cdot 1^2 - \frac{1}{2} \cdot 0^2 = \underline{\underline{\frac{1}{2}}}$$

$$\langle 1, 1 \rangle = \int_0^1 1 \cdot 1 dx = [x]_0^1 = 1 - 0 = 1$$

$$u_2 = x^2 - \frac{\frac{1}{2}}{1} \cdot 1 = \underline{\underline{x^2 - \frac{1}{2}}}$$



$$v_3 = v_3 - \frac{\langle v_1, v_3 \rangle}{\langle v_1, v_1 \rangle} v_1 - \frac{\langle v_2, v_3 \rangle}{\langle v_2, v_2 \rangle} v_2$$

$$= x^4 - \frac{\langle 1, x^4 \rangle}{\langle 1, 1 \rangle} \cdot 1 - \frac{\langle x^2 - \frac{1}{2}, x^4 \rangle}{\langle x^2 - \frac{1}{2}, x^2 - \frac{1}{2} \rangle} \cdot x^2 - \frac{1}{2}$$

$$\langle 1, x^4 \rangle = \int_0^1 x^4 dx = \left[ \frac{1}{5} x^5 \right]_0^1 = \frac{1}{5} \cdot 1 - \frac{1}{5} \cdot 0 = \frac{1}{5}$$

$$\langle 1, 1 \rangle = 1$$

$$\langle x^2 - \frac{1}{2}, x^4 \rangle = \int_0^1 \left( x^2 - \frac{1}{2} \right) (x^4) dx = \int_0^1 x^6 - \frac{1}{2} x^4 dx$$

$$= \int_0^1 x^6 dx - \frac{1}{2} \int_0^1 x^4 dx = \left[ \frac{1}{7} x^7 \right]_0^1 - \frac{1}{2} \left[ \frac{1}{5} x^5 \right]_0^1$$

$$= \left( \frac{1}{7} \cdot 1 - \frac{1}{7} \cdot 0 \right) - \frac{1}{2} \left( \frac{1}{5} \cdot 1 - \frac{1}{5} \cdot 0 \right) = \frac{1}{7} - \frac{1}{10} = \frac{10}{70} - \frac{7}{70}$$

$$= \frac{3}{70}$$

$$\langle x^2 - \frac{1}{2}, x^2 - \frac{1}{2} \rangle = \int_0^1 \left( x^2 - \frac{1}{2} \right) \left( x^2 - \frac{1}{2} \right) dx = \int_0^1 x^4 - x^2 + \frac{1}{4} dx$$

$$= \int_0^1 x^4 dx - \int_0^1 x^2 dx + \frac{1}{4} \int_0^1 1 dx = \left[ \frac{1}{5} x^5 \right]_0^1 - \left[ \frac{1}{3} x^3 \right]_0^1 + \frac{1}{4} [x]_0^1$$

$$= \frac{1}{5} - \frac{1}{3} + \frac{1}{4} = \frac{12}{60} - \frac{20}{60} + \frac{15}{60} = \frac{7}{60}$$

$$v_3 = x^4 - \frac{\frac{1}{5}}{1} - \frac{\frac{3}{70}}{\frac{7}{60}} \cdot \left( x^2 - \frac{1}{2} \right) = x^4 - \frac{1}{5} - \frac{18}{49} \left( x^2 - \frac{1}{2} \right)$$

$$U_3 = x^2 - \frac{1}{5} - \frac{18}{49}x^2 + \frac{18}{98} = \frac{31}{49}x^2 - \frac{8}{490}$$

vi får  $1, 2x^2 - 1$  og  $310x^2 - 8$

$$c) \left\| \frac{1}{\sqrt{x^2+1}} \right\| \quad \|v\| = \sqrt{\langle v, v \rangle}$$

$$\left\langle \frac{1}{\sqrt{x^2+1}}, \frac{1}{\sqrt{x^2+1}} \right\rangle = \int_0^1 \frac{1}{\sqrt{x^2+1}} \cdot \frac{1}{\sqrt{x^2+1}} dx$$

$$= \int_0^1 \frac{1}{x^2+1} dx = \left[ \arctan x \right]_0^1 = \arctan 1 - \arctan 0$$

$$= \frac{\pi}{4} - 0 = \underline{\underline{\frac{\pi}{4}}}$$

$$\left\| \frac{1}{\sqrt{x^2+1}} \right\| = \sqrt{\frac{\pi}{4}} = \underline{\underline{\frac{\sqrt{\pi}}{2}}}$$

$$2) \quad U = \text{sp} \{ \sin x \} \quad \text{av} \quad ([0, 2\pi])$$

$$\langle f, g \rangle = \frac{1}{2\pi} \int_0^{2\pi} f(x)g(x) dx$$

$$a) \quad p_U(\cos^2 x) = \frac{\langle \sin x, \cos^2 x \rangle}{\langle \sin x, \sin x \rangle} \sin x$$

$$\langle \sin x, \cos^2 x \rangle = \frac{1}{2\pi} \int_0^{2\pi} \sin x \cos^2 x dx$$

$$U = \cos x$$

$$\frac{dU}{dx} = -\sin x$$

$$= \frac{1}{2\pi} \int_0^{2\pi} \sin x \cdot U^2 \cdot -\frac{dU}{\sin x} = -\frac{1}{2\pi} \int_0^{2\pi} U^2 dU$$

$$dx = -\frac{dU}{\sin x}$$

$$= -\frac{1}{2\pi} \left[ \frac{1}{3} U^3 \right]_0^{2\pi} = -\frac{1}{2\pi} \left[ \frac{1}{3} \cos^3 x \right]_0^{2\pi} = \frac{1}{3} \cos^3(2\pi) - \frac{1}{3} \cos^3 0$$

$$= -\frac{1}{2\pi} \left( \frac{1}{3} - \frac{1}{3} \right) = \underline{0}$$

$$\text{ siden } \langle \sin x, \cos^2 x \rangle = 0 \quad \text{vil} \quad$$

$$\underline{\underline{p_U(\cos^2 x) = 0}}$$

$$b) \quad ||\sin x - \cos^2 x|| = \frac{1}{2\pi} \int_0^{2\pi} \sin x - \cos^2 x \, dx$$

$$= \frac{1}{2\pi} \int_0^{2\pi} \sin x \, dx - \frac{1}{2\pi} \int_0^{2\pi} \cos^2 x \, dx$$

$$\frac{1}{2\pi} \int_0^{2\pi} \sin x \, dx = \frac{1}{2\pi} [-\cos x]_0^{2\pi} = \frac{1}{2\pi} (-\cos 2\pi + \cos 0) = \underline{0}$$

$$-\frac{1}{2\pi} \int_0^{2\pi} \cos^2 x \, dx = \frac{\cos x \sin x}{2} + \frac{1}{2} \int 1 \, dx$$

$$= -\frac{1}{2\pi} \left[ \frac{\cos x \sin x}{2} + \frac{1}{2} x \right]_0^{2\pi} = \left[ -\frac{\cos x \sin x + x}{4\pi} \right]_0^{2\pi}$$

$$= -\frac{\cos 2\pi \cdot \sin 2\pi + 2\pi}{4\pi} + \frac{\cos 0 \sin 0 + 0}{4\pi}$$

$$= -\frac{1 \cdot 0 + 2\pi}{4\pi} + \frac{1 \cdot 0 + 0}{4\pi} = \underline{-\frac{1}{2}}$$

$$\underline{\underline{||\sin x - \cos^2 x|| = \frac{1}{\sqrt{2}}}}$$

8)

a)

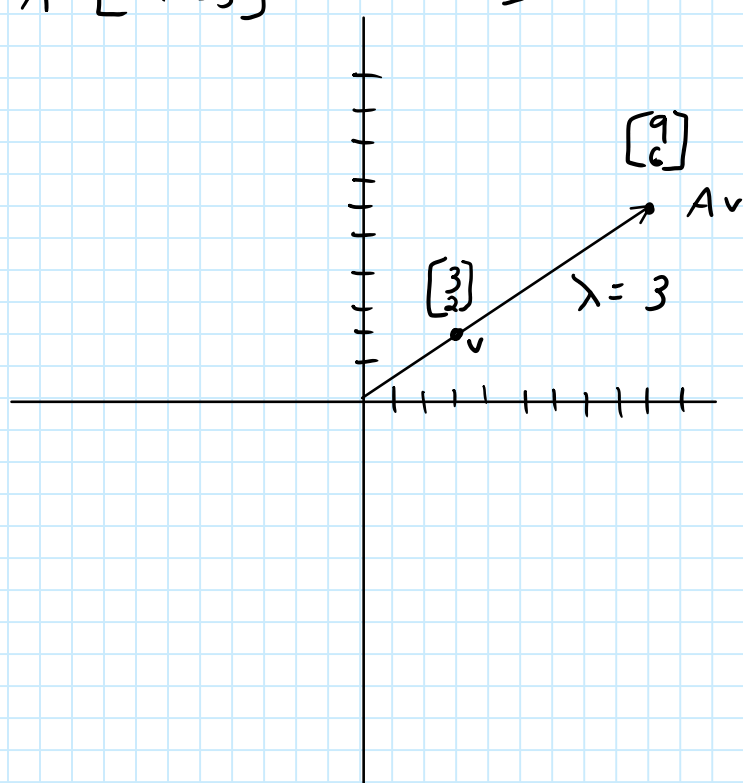
a)

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a) En vektor som er lik seg selv eller ganget med et tall etter en lineærtransformasjon

b) Tallet du må gange med en vektor  $v$ , får å få egenvektoren

$$A = \begin{bmatrix} 1 & 3 \\ 4 & -3 \end{bmatrix} \quad v = \begin{bmatrix} 3 \\ 2 \end{bmatrix} \quad Av = \begin{bmatrix} 9 \\ 6 \end{bmatrix}$$



$$10) A = \begin{bmatrix} 1 & 1 \\ -2 & -2 \end{bmatrix} \quad x = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

$$Ax = \begin{bmatrix} 1 & 1 \\ -2 & -2 \end{bmatrix} \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \cdot -1 + 1 \cdot 2 \\ -2 \cdot -1 + -2 \cdot 2 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

$$\text{Hvis } \lambda = -1 \quad \text{vil } \lambda x = \begin{bmatrix} -1 \\ -2 \end{bmatrix}$$

$x$  er en egenvektor for  $A$  med egenverd:  $\lambda = -1$

11) a) Sann, definisjon av egenvektor

b) sann,  $\lambda$  kan bli representert som  $\lambda I$

$$Ax = \lambda Ix \rightarrow Ax - \lambda Ix = 0 \rightarrow (A - \lambda I)x = 0$$

c) sann,  $\det(A - \lambda I) = 0$  for at

$$(A - \lambda I)x = \vec{0}, \text{ når } x \neq \vec{0}$$

d) Usann

e) sann,  $Ax = \lambda x$

f) Usann,  $Ax = \vec{0}$  hvis  $A$  ikke er inverterbar

g) Usann,  $\lambda = 0$  hvis  $A$  ikke er inverterbar

h) sann, for da vil alle  $R$  bli egenverdier

12)

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a) 1. Ja

2.  $Ax$  ligger på  $\text{sp}\{x\}$ 3.  $\lambda = 2$ 

b) 1. Ja

2.  $Ax$  ligger på  $\text{sp}\{x\}$ 3.  $\lambda = -1$ 

c) 1. Ja

2.  $Ax = x$ 3.  $\lambda = 1$ 

d) 1. Nei

2.  $Ax$  er rotert vekk

e) 1. Ja

2. Nullvektor ligger i  $\text{sp}\{x\}$ 3.  $\lambda = 0$ 

f) 1. Ja

2.  $Ax$  ligger på  $\text{sp}\{x\}$ 3.  $\lambda = \frac{1}{3}$