9×9 =(1)

Interactive Theorem Proving Assignment 3
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12 May 2019

## **Question 1**

```
Mis is just list. Sold I not max
 import tactic.interactive
 import init.meta.interaction_monad
 import data.real.basic
 open tactic
-- Find the maximum element of a list/of \mathbb N. Used to work out at what point
 -- we don't need to traverse the targets list any further.
 \mathsf{def} \ \mathsf{find}_{\mathsf{max}} : \ \mathsf{list} \ \mathbb{N} \ \to \ \mathbb{N} \ \to \ \mathbb{N}
 | [] so_far := so_far
 | (h :: tl) so_far := if h > so_far then find_max tl h else find_max tl so far
-- Given a list of N (the 'targets'), return the goals corresponding the Said O-Normal Control of the second of t
meta def find_wanted_goals : list \mathbb{N} \to \mathbb
| tgts crnt max gls | if crnt > max then return []
                             else match gls with

[] := fail "No such goals!"

(may don't county in | (g::gs) := if crnt ∈ tgts then do out ← find_wanted.

(crnt+1) max gs, he color
                                                                                                                                                                                                                                                                                         do out ← find_wanted_goals
 tgts (crnt+1) max gs,
                                                                                                                                                                                                                                                                                                          else do out of the rate for return out
 find_wanted_goals tgts (crnt+1) max gs,
                                          can tell you're doing gongalhing lane here because this is a bad recusion
  -- A wrapper for find_wanted_goals. Only needs to be given the targets.
meta def find_goals : list \mathbb{N} \to \mathsf{tactic} unit
  | tgts := do let max := find_max tgts 0,
                                                                     gls ← get_goals,
                                                                      found_goals ← find_wanted_goals tgts 1 max gls,
                                                                                                                                                                                                                                                                                                                                                                     This is quite roundabout
                                                                      set_goals (found_goals)
meta def set_tactic_state (new_state : tactic_state) : tactic unit := \lambda s, (do
 skip new_state)
meta def get_tactic_state : tactic tactic_state := λ s,
 interaction_monad.result.success s s
```

Good to give all tactics a doc-string: /--..-/

```
-- focus goals as described in the assignment specifications
-- The tactic can be invoked using the syntax requested
-- After focus goals has been run, we restore the other goals. However,
-- Some of these might have been solved as a consequence of what was solved
-- the given goal block. For example, proving commutativity of addition will
also
-- tell Lean the definition of addition we are using. This is unavoidable.
 but what hoppers? test?

e ← to_expr pe,
tgts ← eval_expr (list N) e,
ever reporting of parsing ages wrong.

s'' get_goals,
let b''':= list.diff s' s

a but away hat you
get_goals,
t,
gls ← get_goals,
if gls ≠ [] then do set_tactic_state s, fail "Failed to discharge the

als!" else
set_goals s'''

So many mines?
meta def tactic.interactive.focus_goals (pe : interactive.pars@
lean.parser.pexpr) (t : tactic.interactive.itactic) : tactic unit :=
do s ← get_tactic_state,
goals!" else
section focus_goals_examples
-- Example of failing when there are no such goals.
example : ring R :=
begin
  constructor,
  success_if_fail {focus_goals [1,2,16] {simp}}, -- Error message "No such
goals!"
  exact neg_add_self,
  exact add_comm,
  exact one_mul,
  exact mul_one,
  exact left_distrib,
  exact right_distrib,
end
```

```
-- Example of succeeding and restoring other goals.
example (p q : Prop) : \neg (p \land q) \leftrightarrow \neg p \lor \neg q :=
begin
 constructor,
 focus_goals [1] {exact classical.not_and_distrib.mp},
 exact not and of not or not,
end
-- Example of discharging some goals but not others and therefore failing.
example : true \land (true \lor false) :=
begin
 split,
 success_if_fail {focus_goals [1,2] {repeat {trivial}}}, -- Failed with error
message "Failed to discharge the goals!"
 trivial,
 constructor,
 trivial,
end
                              n the assign-
-- Example of focus_goals succeeding
example : true ∧ true :=
begin
 split,
 focus_goals [1,2] {repeat {trivial}},
end
end focus goals examples
-- work_on_goals as described in the assignment specifications
meta def tactic.interactive.work_on_goals (pe : interactive.parse
lean.parser.pexpr) (t : tactic.interactive.itactic) : tactic unit :=
                                       lots of repetition here an your further it out?
do s ← get_tactic_state,
 s' ← get_goals,
 e ← to_expr pe,
 tgts ← eval_expr (list N) e,
 find_goals tgts,
 s'' ← get_goals,
 let s''' := list.diff s' s'',
 gls ← get_goals,
 do set_goals (gls ++ s''')
```

## **Question 3**

```
import tactic.interactive tactic.basic
          import tactic.basic
          import tactic.ring
          import data.real.basic
        meta def get_tactic_state : tactic tactic_state := \lambda s, \lambda s, \lambda \lamb
          complex" than the previous best
         meta def run_each (c : tactic \mathbb{N}) (best : \mathbb{N}) (s<sub>o</sub> : tactic_state) (t : tactic
         unit) : tactic ℕ
          | s := match t s₀ with -- Get the cuprent tactic state and try running the
          tactic on the original tactic state
                 | result.success _s<sub>1</sub> := do match c s<sub>1</sub> with | result.success c<sub>1</sub> _ := -- If
          it succeeds, try running our complexity function
                                                                                                                                    if (c₁ < best) then
          result.success c<sub>1</sub> s<sub>1</sub> -- If the result is less complex, store the new complexity
          -- and the new tactic state (before the complexity function was run)
                                                                                                                                                                        else
result.success best s -- If it is more complex, change nothing
                                                                                                                             | _ := result.success best s --
                                                                                                                                                                  such long lines --
         If it fails, change nothing
                 _ := result.success best s -- If it fails, change nothing
                 end
          -- Recursor function to deal with a list of tactics. Terminates if the list is
          done.
          -- Otherwise, use run_each to check if the head of the list is the best and
         then repeat.
         meta def run_list (c : tactic nat) (s₀ : tactic_state): N → list (tactic unit)
          → tactic unit
          [] := do skip -- We have no more tactics left to try
          | best (t :: ts) := do best' ← run_each c best so t, -- Run the first tactic
          and store its complexity
                                                                  out ← run_list best' ts, -- Repeat on tail of list
                                                                  return out
```

you doint ever need to run the other ugar-Suring fuctics should all have how to use the factic. -1.

- -- Note that the best tactic state is carried along by being set as current tactic state
- -- Can be invoked using the syntax "run\_best c [`[simp], `[ref1], `[trivial,
- -- Tried to remove the backtick syntax and use an interactive block, but Keeley
- -- explained that these are not foundational in Lean and are instead "tacked
- -- so a new parser would have had to be written. This would have been difficult,
- -- hard to maintain and likely quite inefficient.

meta def run\_best (c : tactic nat) (L : list (tactic unit)) : tactic unit := do s₀ ← get\_tactic\_state,

run\_list c s₀ 1000000000 L -- A large starting best value is used, because the natural numbers have no upper bound

-- and it needs to be larger than the output of the complexity function after the first iteration [ame] : 50 H | use numgoals \* 10<sup>20</sup>

example : true ∨ (false ∧ true) := begin

your tache fails? run\_best (num\_goals) [`[trivial, refl], `[constructor], `[ring]], --Constructor is only tactic that makes progress, so constructor runs

run\_best (num\_goals) [`[intros], `[trivial]], -- Trivial finishes the proof end

Good, but even more testing would be botter.