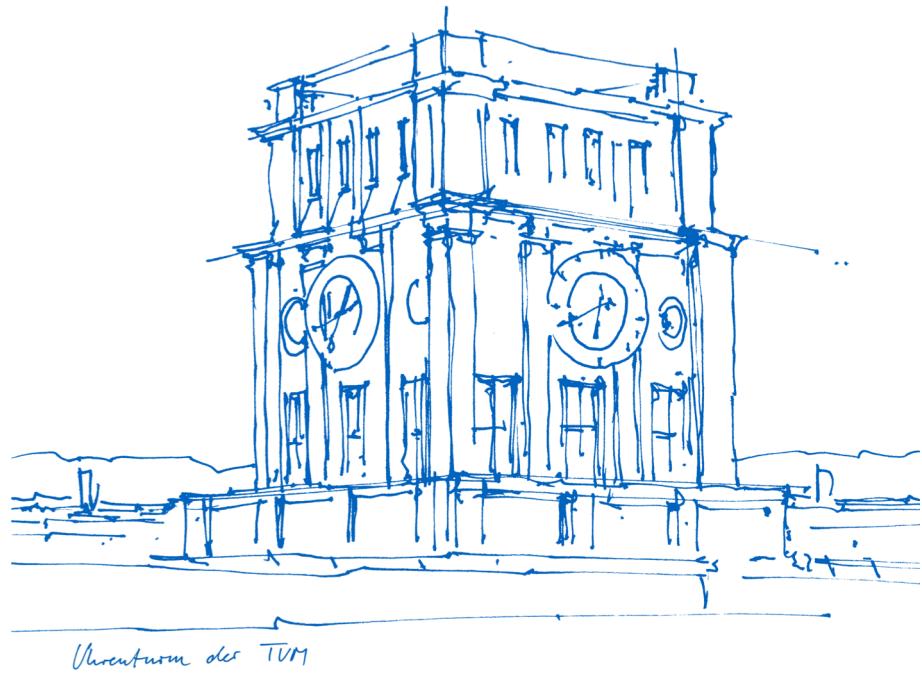


Exercises for Social Gaming and Social Computing (IN2241 + IN0040)

**Introduction to
Exercise Sheet 1 -
Introduction to
Python and Network
Visualization**



Repetition: Python and IPython Books

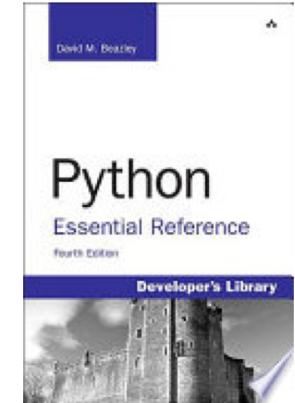
- **Learning Python:**

Python Essential Reference (2012)

by David M. Beazley, Safari Books

(especially **chapter 1: A Tutorial Introduction (25 pages)**)

free eAccess: <https://eaccess.ub.tum.de/login>



- **Learning IPython / Reference for IPython:**

Learning IPython for Interactive Computing and Data

Visualization (SECOND EDITION) by Cyrille Rossant, 175

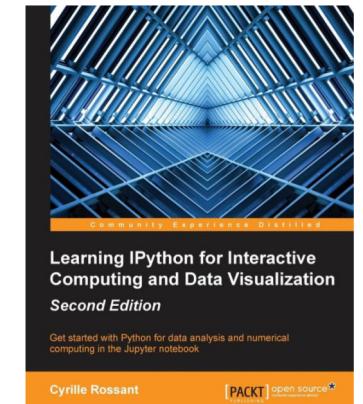
pages, Packt Publishing, October 25 2015

(Especially (free) [chapter 1.4. A crash course on Python](#))

free access:

<http://nbviewer.ipython.org/github/ipython-books/minibook-2nd-code/blob/master/chapter1/14-python.ipynb>

(do not try to open this ipynb with Jupyter directly. Instead, download all the ipynb's from the book from Github: <https://github.com/ipython-books/minibook-2nd-code>)



Installation

- get the installer from here: <https://www.anaconda.com/download>
- follow the installation instructions
- open Anaconda Prompt and type in:

```
conda update - -all
```

- type into Anaconda Prompt:

```
jupyter notebook
```

- **goal:** get used to working with Jupyter Notebook and Python
- **warm-up ex.:** use loops to create a simple **#-Pyramid:**



- in the **main** ex. you will learn how to:
 - work with **large datasets**
 - choose the right **format** for your variables
 - choose the right **format** for your variables
 - use powerful tools to **create**, **manipulate** and **display graphs**

The Data: The Marvel Characters

- *MarvelAppearances.csv*:

edges between character and comic issue appearance



Task

Task 1.1: Python Rhombus

a) Create a function which takes a number of levels (N) and prints a rhombus that looks like this for N = 4:

```
#  
###  
###  
#
```

for N = 5:

```
#  
###  
#####  
###  
#
```

Hints:

- Do not forget the spaces left of the rhombus, except on the widest floor. In the example above 2 spaces to the left and at the peak.
- In order to execute a code cell, press Shift + Enter.

```
def printRhombus(N):  
    #TODO: Create a Rhombus  
printRhombus(5)
```

b) Extend the program by implementing user input. The user is asked to enter a number for the levels of the rhombus. Afterwards the pyramid is printed.

```
# TODO: Implement user input  
num_levels =  
printRhombus(num_levels)
```

Task

- a) To get to see which characters appear together merge the Dataframe together with itself. This is not unlike the join operation in SQL.

```
# TODO: Merge characters  
# Hint: Use a left join  
  
df_merged
```

- b) Next we will group together the same characters on both sides to get the amount of times these characters appeared together. This will be used as the weights later.

```
df_merged2 = df_merged  
# TODO: Group the Characters together  
  
df_merged2
```

- c) Now we are only interested in characters who have appeared at least 100 times together. Select those. Additionally delete rows of characters with references to themselves.

```
# TODO: Select the rows of characters with less than 100 appearances  
  
# Delete these row indices from the dataframe  
df_merged2.drop(indexNames, inplace=True)  
  
# TODO: Select self-referential characters  
  
# Delete these rows  
df_merged2.drop(indexNames2, inplace=True)  
df_merged2
```

Task

d) Now you have to include your alter ego into the network. Create a pandas Series with your name, and weights. Connect yourself to THANOS with weight 345.

```
# TODO:  
# Create a series for your character who is connected to THANOS 345 times and add it to the dataframe  
  
# TODO:  
# Append the newly created series to the pandas data frame  
  
# Create the graph from the dataframe  
graph = nx.from_pandas_edgelist(df_merged3, source="Character_x", target="Character_y", edge_attr=True)  
df_merged3
```

Task

e) Draw the resulting graph with the given options. Choose 2 [layout](#) [6] options that seem the most suitable for the data. Briefly discuss why you chose these over the others.

```
# Set the edge color according to the weight
edges,weights = zip(*nx.get_edge_attributes(graph,'size').items())

# Style the graph
options = {
    "font_size" : 14,
    "font_color" : '#552222',
    "node_color" : '#22FF22',
    "width" : 5.0,
    "edgelist" : edges,
    "edge_color" : weights,
    "edge_cmap" : plt.cm.Blues
}

plt.figure(1,figsize=(40,40))

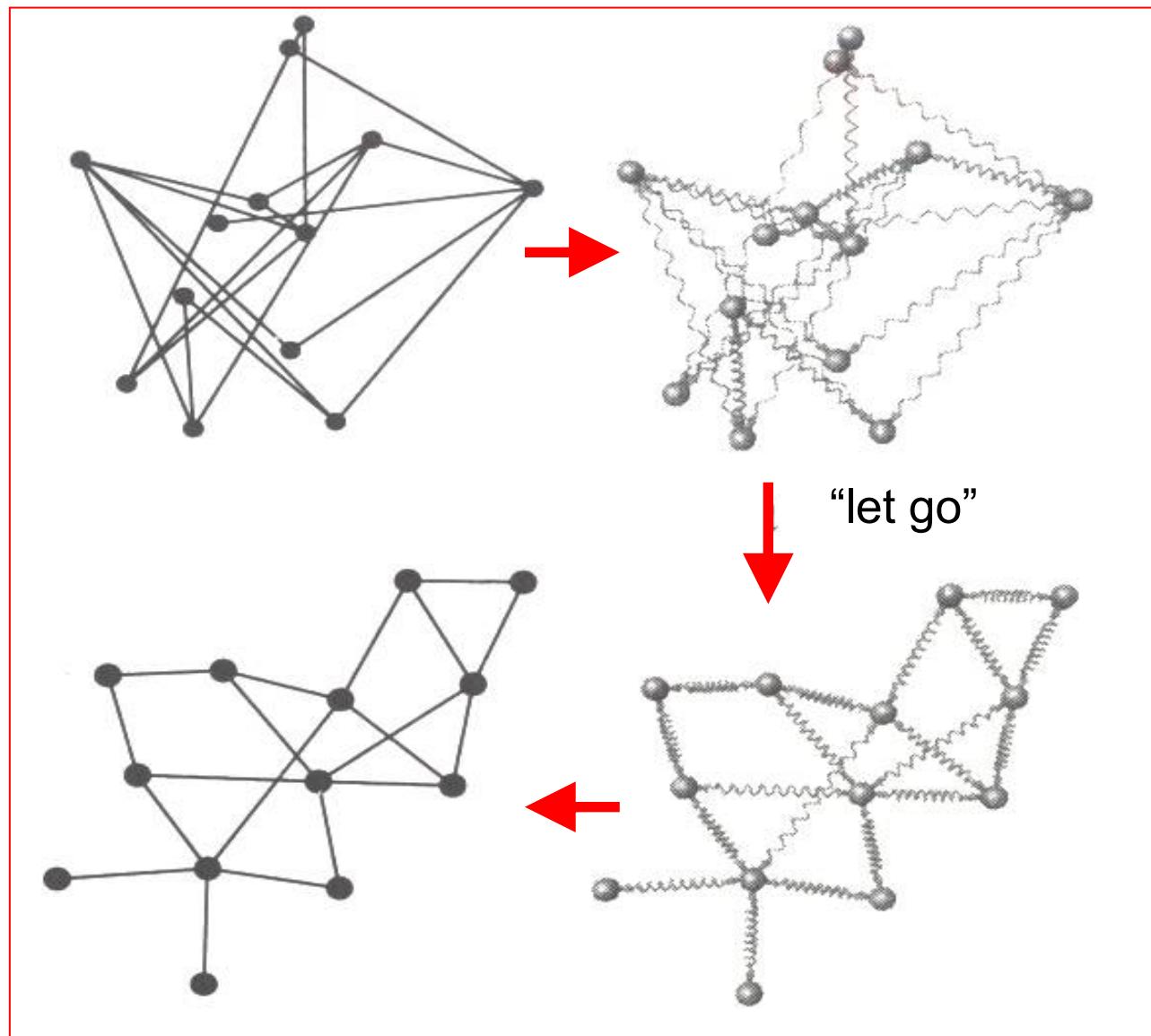
# TODO: plot the graph

plt.show()
```

TODO: Write your observations here:

- Quality criteria used here:
 - nodes should **spread well** on the canvas
 - adjacent vertices should **be close** to each other
- Realized by:
 - Repelling **forces** between nodes: Charged nodes
 - Attractive + Repelling **forces** between nodes: Springs between nodes
 - → small deviations from uniform length edges

Drawing by Using Physical Analogies [5]



- → Edges will have different length in equilibrium. (Deciding whether a graph has an embedding in \mathbb{R}^n with equal length edges (regardless of n) is NP-hard.)[5]
- Intuition: System will “move” into a state of minimal energy → Either minimize energy function or incrementally “move” nodes until “stable state” is reached.

- Original approach by Eades (see [5]): Change repelling and spring forces a bit:

$$\mathbf{F}_{repell}(\mathbf{v}_i, \mathbf{v}_j) = -\frac{c_\rho}{\|\mathbf{v}_i - \mathbf{v}_j\|^2} \frac{(\mathbf{v}_i - \mathbf{v}_j)}{\|\mathbf{v}_i - \mathbf{v}_j\|}$$

applied only to
nodes not connected
by edge of graph

$$\mathbf{F}_{spring}(\mathbf{v}_i, \mathbf{v}_j) = c_\sigma \log \frac{\|\mathbf{v}_i - \mathbf{v}_j\|}{l} \frac{(\mathbf{v}_i - \mathbf{v}_j)}{\|\mathbf{v}_i - \mathbf{v}_j\|}$$

applied only to
nodes connected by
edge of graph

log a/b instead of a-b exerts less force
on far apart nodes

Drawing by Using Physical Analogies [5]

small constant



- Move node under total force \mathbf{F} as: $\mathbf{v}_i \leftarrow \mathbf{v}_i + \delta \cdot F_{v_i}(t)$

whole spring embedder algorithm (see [5])

Input: Graph $G = (V, E)$; initial placements $\{\mathbf{v}_i\}$ of nodes
Output: "Relaxed" new positions $\{\mathbf{v}_i\}$

```
for (t = 0; t < numberOfIterations; t++) {  
    forall (vi ∈ V) {  
         $F_{v_i}(t) \leftarrow \sum_{\{u | (u, v_i) \notin E\}} F_{repell}(u, v_i) + \sum_{\{u | (u, v_i) \in E\}} F_{spring}(u, v_i)$   
         $\mathbf{v}_i \leftarrow \mathbf{v}_i + \delta \cdot F_{v_i}(t)$   
    }  
}
```

- Modified approach by Fruchterman & Reingold (see [5]):

- 1) Change repelling and spring forces a bit:

$$\mathbf{F}_{repell}(\mathbf{v}_i, \mathbf{v}_j) = -\frac{l^2}{\|\mathbf{v}_i - \mathbf{v}_j\|^2} \frac{(\mathbf{v}_i - \mathbf{v}_j)}{\|\mathbf{v}_i - \mathbf{v}_j\|}$$
$$\mathbf{F}_{spring}(\mathbf{v}_i, \mathbf{v}_j) = \frac{\|\mathbf{v}_i - \mathbf{v}_j\|^2}{l} \frac{(\mathbf{v}_i - \mathbf{v}_j)}{\|\mathbf{v}_i - \mathbf{v}_j\|}$$

if $\|\mathbf{v}_i - \mathbf{v}_j\| = l$

- Modified approach by Fruchterman & Reingold (see [5]):
 - 2) **Speed up computation** by restricting contributions to repulsive force on node v_i to “nearby” nodes. Use grid to determine which nodes are “nearby”. Among these use only those repelling force contributions above a threshold
 - 3) **Clip net displacement** $\delta(t)$ on node at iteration t to prevent excessive displacements in late stages → better convergence
 - 4) **Clip coordinates** at canvas boundaries

- Further Modified approach by Frick et al. (see [5]):

1) change forces a bit further in order to

- slow down nodes with high degree
- speed up computation further by dropping square-root computation

$$\mathbf{F}_{repell}(\mathbf{v}_i, \mathbf{v}_j) = -\frac{l^2}{\|\mathbf{v}_i - \mathbf{v}_j\|^2} (\mathbf{v}_i - \mathbf{v}_j)$$

$$\mathbf{F}_{spring}(\mathbf{v}_i, \mathbf{v}_j) = \frac{\|\mathbf{v}_i - \mathbf{v}_j\|^2}{l \Phi(v_j)} (\mathbf{v}_i - \mathbf{v}_j)$$

$$\Phi(v_j) = 1 + \frac{\deg(v_j)}{2}$$

- Further Modified approach by Frick et al. (see [5]):
 - 2) introduce additional “gravitational” force towards the “barycenter” to prevent disconnected components of graph to drift too far to the boundary of the canvas

$$\mathbf{F}_{grav}(\mathbf{v}_i, \mathbf{v}_j) = \gamma \Phi(v_j) \left(\frac{\zeta}{|V|} - \mathbf{v}_j \right)$$

Barycenter:

$$\zeta = \sum_{v_i \in V} \mathbf{v}_i$$

- Even simpler possibility: Drop Barycenter and direct gravitation towards canvas center ☺

$$\Phi(v_j) = 1 + \frac{\deg(v_j)}{2}$$

- Further Modified approach by Frick et al. (see [5]):
 - 3) Detect and suppress rotational and oscillatory moves by nodes (“ineffective” movements) (see [5] for details)

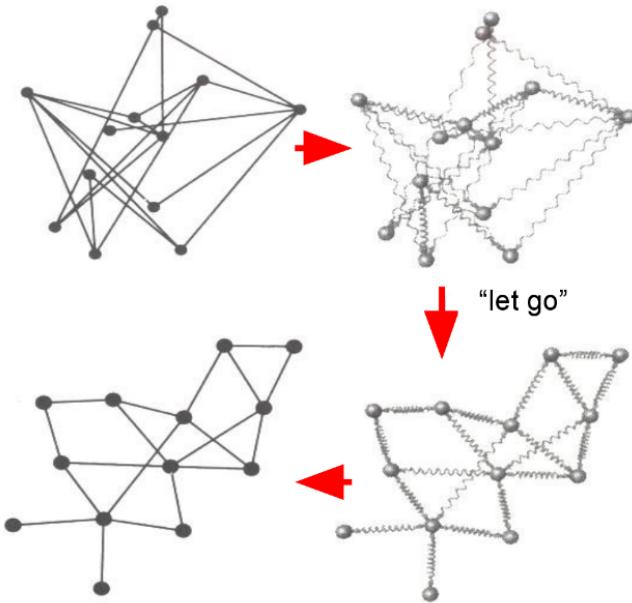
What we see: Spring embedder type of graph drawing algorithms are

- Robust towards adaptations
- Allow for an intuitive interpretation of change options

Problem 1.3: Graph Visualization and Analysis with IGraph Library



Fruchtermann & Reingold approach uses an analogy to classical mechanics for the graph modelling



- By introducing **forces between the nodes**, we receive edges with equal length and few crossings
- Mechanical analogon: springs between the nodes

$$\left. \begin{aligned} \mathbf{F}_{repell}(\mathbf{v}_i, \mathbf{v}_j) &= -\frac{l^2}{\|\mathbf{v}_i - \mathbf{v}_j\|^2} \frac{(\mathbf{v}_i - \mathbf{v}_j)}{\|\mathbf{v}_i - \mathbf{v}_j\|} \\ \mathbf{F}_{spring}(\mathbf{v}_i, \mathbf{v}_j) &= \frac{\|\mathbf{v}_i - \mathbf{v}_j\|^2}{l} \frac{(\mathbf{v}_i - \mathbf{v}_j)}{\|\mathbf{v}_i - \mathbf{v}_j\|} \end{aligned} \right\} \begin{array}{l} \mathbf{F}_{repell} - \mathbf{F}_{spring} = 0 \\ \text{if} \\ \|\mathbf{v}_i - \mathbf{v}_j\| = l \end{array}$$

Further reading:

- http://igraph.org/r/doc/layout_with_fr.html
- Graph visualization slides on Moodle (just FYI, relevant for exam: just these exercise intro slides)

Tips and Tricks

- for most TODOs it is sufficient to look at the [pandas Manual](#) and use [library functions](#)

Submitting your solution

- work by **expanding** the .ipynb iPython notebook for the exercise that you **downloaded** from Moodle
- **save** your expanded .ipynb iPython notebook in **your working** directory
- **submit** your .ipynb iPython notebook **via Moodle** (nothing else)
- remember: working in groups is not permitted. Each student must submit **their own** .ipynb notebook!
- we check for **plagiarism**. Each detected case will be graded with 5.0 for the whole exercise
- **deadline**: check Moodle

Citations

-
- (1) [Beazley 2013] David Beazley: Python Essential Reference, Safari Books 2013, E-Book available via www.ub.tum.de
 - (2) [Rossant 2015] Learning IPython for Interactive Computing and Data Visualization (SECOND EDITION) by Cyrille Rossant, 175 pages Packt Publishing, October 2015