

Proseminar Simulation und virtuelle Realität in der Medizin

The State of the Art in automatic, fixed class, single-image Segmentation

Proseminararbeit
von

Marvin Teichmann und Martin Thoma

an der Fakultät für Informatik
Institut für Anthropomatik
Humanoids and Intelligence Systems Lab

Betreuer: Dipl.-Inform. Sebastian Bodenstedt

Wintersemester 2015/16

Zusammenfassung

works

Inhaltsverzeichnis

1	Introduction	3
2	Evaluation and Datasets	3
3	Traditional Approaches	3
4	Neural Networks for Segmentation	3
5	Typical Problems for Segmentation algorithms	3
6	Speed-ups for Segmentation	3

1 Introduction

asdf [1]

2 Evaluation and Datasets

3 Traditional Approaches

4 Neural Networks for Segmentation

5 Typical Problems for Segmentation algorithms

6 Speed-ups for Segmentation

Literatur

- [1] R. Dillmann and T. Asfour, “Collaborative research center on humanoid robots (sfb 588),” *KI - Zeitschrift Künstliche Intelligenz*, vol. 4, pp. 26–28, 2008.