

Security Verification and Bug-finding

José Santos Ana Matos

Bug-finding

- Testing and code reviews is widely used to find bugs in code
 - But, each test only explores one possible execution → some bugs are still missed (complex features, rare circumstances...)
- Static analysis can analyze all possible runs of a program in a tractable way
 - But, abstraction introduces conservatism → expertise is required to manage errors

Syntact Analysis

- EmPoWeb* found often than 100 leaks in JS browser extensions
- It uses a simple syntactic analysis that explicitly looks for expressions:
 - chrome.cookies.getAll
 - chrome.cookies.remove
- But there are multiple other ways to access these values that would not be caught by this analysis

Obfuscated JS leak

- Implicit flows can be very subtil

```
function getBit(x) {
    var a = [ "a", "b", "c" ];
    if ((x % 2) === 0) {
        Object.defineProperty(a, "1", {value: "d", configurable: false})
    }
    a.length = 1;
    return (a.length === 1) ? 1 : 0;
}
```

Changes first element of a to “d”, and makes it non-configurable.

- Bit by bit we can leak all the bits

```
function getBits(x) {
    var bits = [];
    while (x > 0) {
        bits.push(getBit(x));
        x = x >> 1;
    }
    return (bits.length === 0) ? 0 : bits.reverse();
}
```

Obfuscated JS leak

- Malicious code can exploit corner case behaviors of the JavaScript semantics to encode sophisticated information flow
- And now we can access `chrome.cookies.remove`

```
var x = chrome;
var y1 = "cook";
var y2 = "ies";
var z1 = "rem";
var z2 = "ove";
var w = getBits(x[y1+y2][z1+z2])
```

- Sometimes we need stronger guarantees than simple syntactic analysis!

Symbolic Execution

- Middle ground: Symbolic execution generalizes testing by computing over unknown symbolic variables
- If execution path depends on unknown, conceptually fork symbolic executor
- Each symbolic execution path stands for runs whose concrete values satisfy the path condition

Class Outline

- Program Properties and Noninterference
 - Trace-properties vs. Hyper-properties
 - Verification and Bug-finding for Noninterference
 - Self-composition + Symbolic Execution

Class Outline

- Program Properties and Noninterference
 - Trace properties vs. Hyper properties
- Verification and Bug-finding for Noninterference
- Self-composition + Symbolic Execution

Verification vs. Bug-finding

- Verification: verifying a program S with respect to a property \mathcal{P} means proving that all the behaviors $\llbracket S \rrbracket$ of S are contained in \mathcal{P} :
$$\llbracket S \rrbracket \subseteq \mathcal{P}$$

- Bug Finding: debugging a program S with respect to a property \mathcal{P} means finding a behavior of S that is not in \mathcal{P} :
$$\llbracket S \rrbracket \cap \neg \mathcal{P} \neq \emptyset$$

Verification vs. Bug-finding

- Verification
 - $\llbracket S \rrbracket \subseteq \mathcal{P}$
 - Harder: “for all”
- Bug Finding
 - $\llbracket S \rrbracket \cap \neg \mathcal{P} \neq \emptyset$
 - Easier: “exists”

Program properties

- Program property \mathcal{P} = set of “behaviors”
- How do we define behavior?
- Depending on how we define the set of allowed behaviors, we get different classes of properties.

Trace

- Complete trace - a sequence of configurations (cfg) that represents a complete execution according to the small-step semantics
- Finite: $[\text{cfg}_0, \dots, \text{cfg}_n]$ such that $\text{cfg}_0 = \langle S_0, \rho_0 \rangle$ and cfg_n “final” and for all $0 \leq i < n$ $\text{cfg}_i \Rightarrow \text{cfg}_{i+1}$
- Infinite: $[\text{cfg}_0, \dots]$ such that $\text{cfg}_0 = \langle S_0, \rho_0 \rangle$ and for all $0 \leq i < n$ $\text{cfg}_i \Rightarrow \text{cfg}_{i+1}$

Traces Properties

$\llbracket S_0 \rrbracket$ (set of “behaviors” of S_0)

= set of complete traces (both finite and infinite)

= $\{[cfg_0, \dots, cfg_n]\} \cup \{[cfg_0, \dots]\}$

remember:

$\{[cfg_0, \dots, cfg_n]\}$ abbreviates the set of all such that
 $cfg_0 = \langle S_0, \rho_0 \rangle$ and $cfg_n = \rho_n$ and for all $0 \leq i < n$ $cfg_i \Rightarrow cfg_{i+1}$

and $[cfg_0, \dots]$ abbreviates the set of all infinite traces

Safety and Liveness

- Safety Properties: Something bad never happens. Examples:
 - Type Safety
 - Memory Safety (no null pointer exceptions)
- Liveness Properties: Something good will eventually happen. Examples:
 - Termination
 - Absence of memory leaks

WHILE + Errors

Assignment:

$$\frac{\mathcal{A}[a]_\rho = c}{\langle x:=a, \rho \rangle \Rightarrow \rho[x \mapsto c]}$$

$$\frac{\mathcal{A}[a]_\rho = \downarrow}{\langle x:=a, \rho \rangle \Rightarrow \downarrow}$$

Skip: $\langle \text{skip}, \rho \rangle \Rightarrow \rho$

Sequential composition:

$$\frac{}{\langle S_1, \rho \rangle \Rightarrow \rho'}$$

$$\frac{\langle S_1, \rho \rangle \Rightarrow \langle S_1', \rho' \rangle}{\langle S_1; S_2, \rho \rangle \Rightarrow \langle S_2, \rho' \rangle}$$

$$\langle S_1; S_2, \rho \rangle \Rightarrow \langle S_2, \rho' \rangle$$

$$\langle S_1; S_2, \rho \rangle \Rightarrow \langle S_1'; S_2, \rho' \rangle$$

Conditional test:

$$\frac{\mathcal{B}[t]_\rho = \downarrow}{\langle \text{if } t \text{ then } S_1 \text{ else } S_2, \rho \rangle \rightarrow \downarrow}$$

$$\mathcal{B}[t]_\rho = \text{true}$$

$$\frac{}{\langle \text{if } t \text{ then } S_1 \text{ else } S_2, \rho \rangle \Rightarrow \langle S_1, \rho \rangle}$$

$$\mathcal{B}[t]_\rho = \text{false}$$

$$\frac{}{\langle \text{if } t \text{ then } S_1 \text{ else } S_2, \rho \rangle \Rightarrow \langle S_2, \rho \rangle}$$

While loop:

$$\frac{\mathcal{B}[t]_\rho = \downarrow}{\langle \text{while } t \text{ do } S, \rho \rangle \Rightarrow \downarrow}$$

$$\mathcal{B}[t]_\rho = \text{true}$$

$$\frac{}{\langle \text{while } t \text{ do } S, \rho \rangle \Rightarrow \langle S; \text{while } t \text{ do } S, \rho \rangle}$$

$$\mathcal{B}[t]_\rho = \text{false}$$

$$\frac{}{\langle \text{while } t \text{ do } S, \rho \rangle \Rightarrow \rho}$$

Safety property - NoDivZero

“No program execution performs a division by zero”

$$\text{NoDivZero} = \{[\text{cfg}_0, \dots, \text{cfg}_n] \mid \text{cfg}_n \neq \downarrow\} \cup \{[\text{cfg}_0, \dots]\}$$

Verification of that S satisfies the property:

$$[S] \subseteq \text{NoDivZero}$$

Verification of that S satisfies *the property*:

$$[S] \subseteq \text{NoDivZero}$$

Liveness property - Termination

“All program executions eventually terminate correctly”

$$\text{Termination} = \{[\text{cfg}_0, \dots, \text{cfg}_n] \mid \text{cfg}_n = \rho\}$$

Verification of that S satisfies the property:

$$[S] \subseteq \text{Termination}$$

Trace Properties

Trace Properties

Safety Properties

- *NoDivZero*

Liveness Properties

- *Termination*

Is Noninterference a Trace Property?

- **Deterministic Input-Output Noninterference -**

A program S is secure if for every security level L and for all pairs of memories ρ_1 and ρ_2 such that $\rho_1 \sim_L \rho_2$, we have that

$\langle S, \rho_1 \rangle \rightarrow \rho_1'$ and $\langle S, \rho_2 \rangle \rightarrow \rho_2'$ implies $\rho_1' \sim_L \rho_2'$.

2-Traces Property

$\llbracket S_0 \rrbracket$ (set of “behaviors of S_0) = set of pairs of traces

$$= \{([cfg_0, \dots, cfg_n], [cfg'_0, \dots, cfg'_m])\}$$

$$\cup \{([cfg_0, \dots, cfg_n], [cfg'_0, \dots])\}$$

$$\cup \{([cfg_0, \dots], [cfg'_0, \dots, cfg'_m])\}$$

$$\cup \{([cfg_0, \dots], [cfg'_0, \dots])\}$$

Includes all pairs of traces,
finite or infinite.

Noninterference: a 2-Trace Property

“No pair of program executions reveals an information leak”

Noninterference =

$$\{([cfg_0, \dots, cfg_n], [cfg'_0, \dots, cfg'_m]) \mid \rho_0 \not\sim_L \rho'_0 \text{ or } \rho_n \sim_L \rho'_m\}$$

$$\cup \{([cfg_0, \dots, cfg_n], [cfg'_0, \dots])\}$$

$$\cup \{([cfg_0, \dots], [cfg'_0, \dots, cfg'_m])\}$$

$$\cup \{([cfg_0, \dots], [cfg'_0, \dots])\}$$

Include all pairs of finite
traces which preserve low
memory indistinguishability...

... and all pairs of traces
that are not both finite.

Noninterference

Verification vs. Bug-finding

“No pair of program executions reveals an information leak”

- Verification
 $\llbracket S \rrbracket \subseteq \text{Noninterference}$
All pairs of traces satisfy the property
- Bug-finding
 $\llbracket S \rrbracket \cap \neg \text{Noninterference} \neq \emptyset$
A pair of traces that does not satisfy the property

A program with an information flow bug

- Deterministic Input-Output Noninterference -
A program S is secure if for every security level L and **for all pairs** of memories ρ_1 and ρ_2 such that $\rho_1 \sim_L \rho_2$, we have that
 $\langle S, \rho_1 \rangle \rightarrow \rho_1'$ and $\langle S, \rho_2 \rangle \rightarrow \rho_2'$ implies $\rho_1' \sim_L \rho_2'$.
- S does not satisfy *Noninterference*
= S has a *Noninterference bug* if
there exist ρ_1 and ρ_2 such that $\rho_1 \sim_L \rho_2$,
 $\langle S, \rho_1 \rangle \rightarrow \rho_1'$ and $\langle S, \rho_2 \rangle \rightarrow \rho_2'$ **but** $\rho_1' \not\sim_L \rho_2'$.

Trace Properties

Hyper Properties

- *Noninterference*

Trace Properties

Safety Properties

- *NoDivZero*

Liveness Properties

- *Termination*

Class Outline

- Program Properties and Noninterference
 - Trace-properties vs. Hyper-properties
- Verification and Bug-finding for Noninterference
 - Self-composition + Symbolic Execution

Verification tools

- How to verify Noninterference?
- Existing verification tools are mainly for trace properties
- Scalable program analysis are hard to design and implement, especially when targeting real world languages
- If we can reduce Noninterference to a trace property, we can use an existing analysis to check it instead of building a new one from scratch!

Verifying Noninterference by Self-composition

$[S] \subseteq \text{Noninterference}$ (2-trace property)

iff

$[C(S)] \subseteq \text{SafetyNoninterference } ???$ (trace property)

Idea: Self-Composition

- How to perform two runs of S in only one go?
 - Create a “copy” \underline{S} of program S using fresh variables from $\underline{\text{Var}}$. Then execute $S;\underline{S}$.
 - How to assume and assert same “low” variables in the encoded “two runs”?
 - Use a memory $\rho+\underline{\rho}$ where ρ and $\underline{\rho}$ don’t overlap but between which we can map variables
- ✓ To automatize: Define a source-to-source compiler
 $C(S) = \underline{S}$

A program with an information flow bug

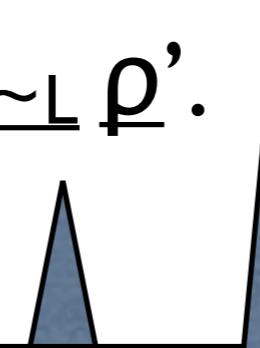
- Deterministic Input-Output Noninterference -
A program S is secure if for every security level L and **for all pairs** of memories ρ_1 and ρ_2 such that $\rho_1 \sim_L \rho_2$, we have that
 $\langle S, \rho_1 \rangle \rightarrow \rho_1'$ and $\langle S, \rho_2 \rangle \rightarrow \rho_2'$ implies $\rho_1' \sim_L \rho_2'$.
- S does not satisfy *SafetyNoninterference*
= S has a *SafetyNoninterference bug* if
there exist ρ_1 and ρ_2 such that $\rho_1 \sim_L \rho_2$,
 $\langle S, \rho_1 \rangle \rightarrow \rho_1'$ and $\langle S, \rho_2 \rangle \rightarrow \rho_2'$ **but** $\rho_1' \not\sim_L \rho_2'$.

Safety Noninterference

Deterministic Input-Output Safety Noninterference -

A program S is secure if, *for $S;S$ obtained by self composition of S ,* and for every observation level L and for all memories $\rho+\underline{\rho}$ such that $\rho \simeq_L \underline{\rho}$, we have that

$\langle S;S, \rho+\underline{\rho} \rangle \rightarrow \rho'+\underline{\rho}'$ implies $\rho' \simeq_L \underline{\rho}'$.



$\rho \simeq_L \underline{\rho}$ iff

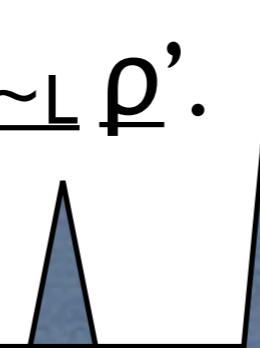
For all x such that $\Gamma(x) \leq L$,
then $\rho(x) = \underline{\rho}(x)$

Safety Noninterference

Deterministic Input-Output Safety Noninterference -

A program S is secure if, *for $S;S$ obtained by self composition of S ,* and for every observation level L and for all memories $\rho+\underline{\rho}$ such that $\rho \simeq_L \underline{\rho}$, we have that

$\langle S;S, \rho+\underline{\rho} \rangle \rightarrow \rho'+\underline{\rho}'$ implies $\rho' \simeq_L \underline{\rho}'$.



$\rho \simeq_L \underline{\rho}$ iff

For all x such that $\Gamma(x) \leq L$,
then $\rho(x) = \underline{\rho}(x)$

Noninterference as a Safety Property

“No self-composed execution reveals an information leak”

SafetyNoninterference =

$$\{([cfg_0, \dots, cfg_n]) \mid \rho_0 \not\preceq_L \underline{\rho_0} \text{ or } \rho_n \not\preceq_L \underline{\rho_n}\} \cup \{[cfg_0, \dots]\}$$

Include all finite traces which
preserve low memory
indistinguishability...

... and infinite traces.

Symbolic Execution for Noninterference

To prepare a program S for verification/bug finding for Noninterference by symbolic execution:

1. Produce a program $S;\underline{S}$ by self-composition
2. For each low variable x that appears in S :
 - add assumptions and assertions $x=\underline{x}$, at the beginning and end of the program, respectively.

Self-composition for Symbolic Execution

- $x_L := y_H$

```
assume(x = x);
x := y;
x := y;
assert(x = x)
```

- if (y_H) then $x_L := 1$ else skip

```
assume(x = x);
if (y) then x:=1 else skip;
if (y) then x:=1 else skip;
assert(x = x)
```

Self-composition for Symbolic Execution

```
zL := l;  
if (hH) then xL := lL else skip;  
if (!hH) then xL := zL else skip;  
lL := xL + yL
```

```
assume(l=lL ∧ x=xL ∧ y=yL ∧ z=zL)  
z:=1;  
if(h) then x:=1 else skip;  
if(!h) then x:=z else skip;  
l:=x+y;  
z:=1;  
if (h) then x:=1 else skip;  
if (!h) then x:=z else skip;  
l:=x+y;  
assert(l=lL ∧ x=xL ∧ y=yL ∧ z=zL)
```

Does the assertion hold?

Symbolic Execution: Example I

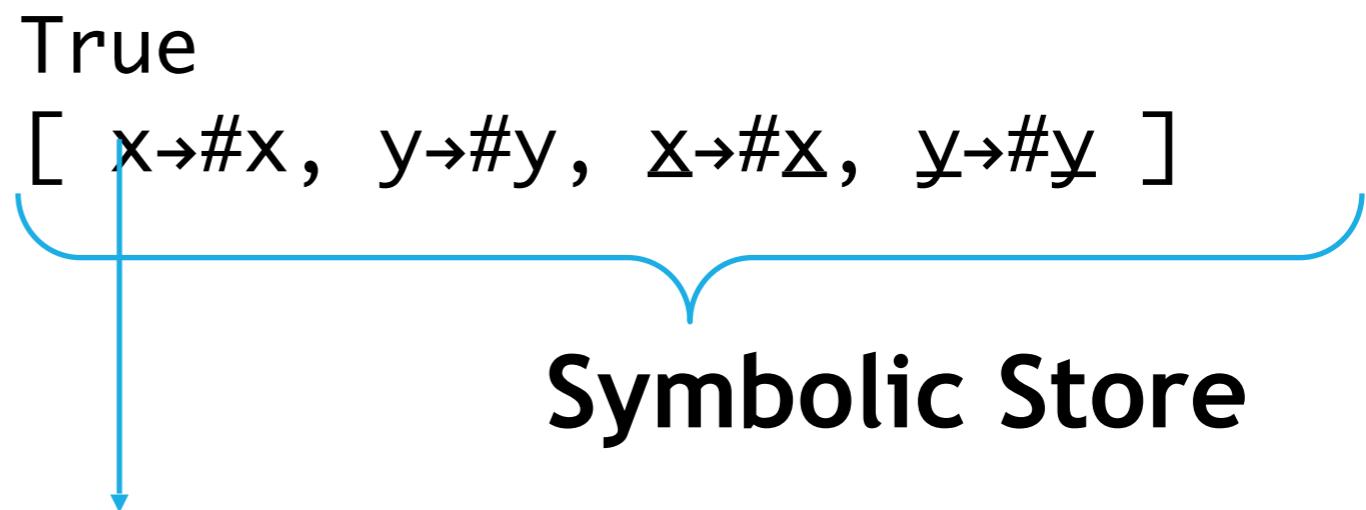
```
assume(x = x);  
x := y;  
x := y;  
assert(x = x)
```

We will execute the generated program symbolically

Instead of using concrete values, we'll use **symbolic variables** #x, #y, ...

Self-Composition: Example I

```
assume(x = x);  
x := y;  
x := y;  
assert(x = x)
```



Path Condition: conjunction of all the expressions on which the execution has branched before reaching the current execution point

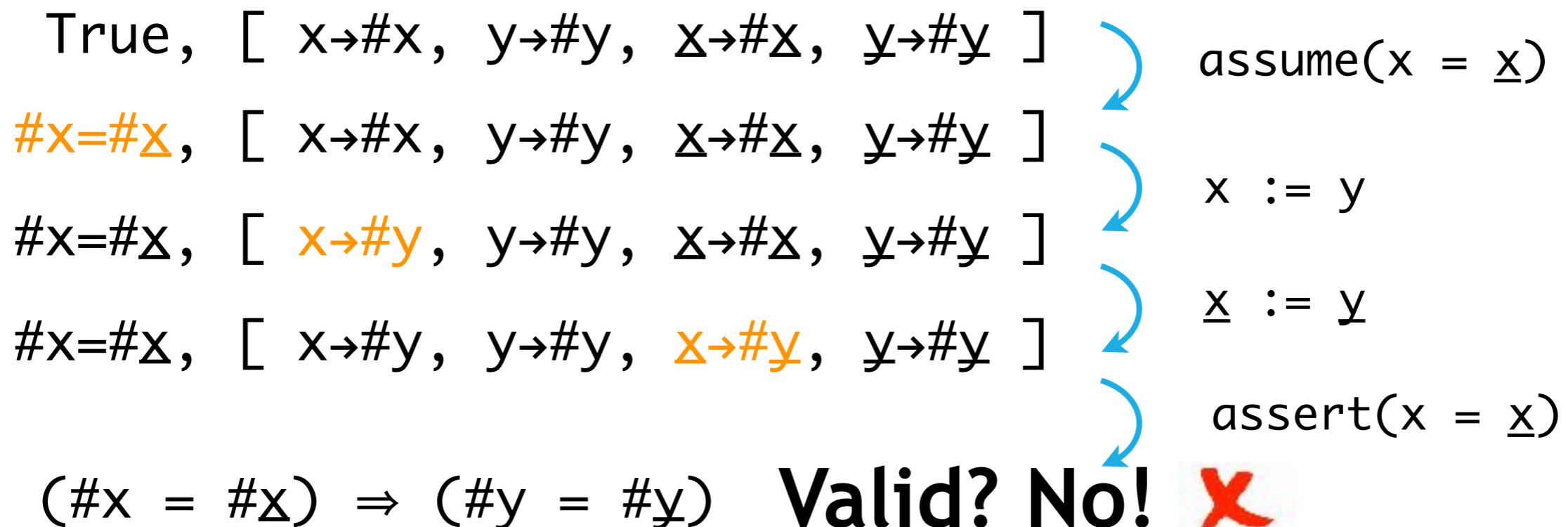
Bug-finding for Noninterference

To search for a Noninterference bug in S:

1. Prepare S for verification/bug finding for Noninterference by symbolic execution
2. Perform a symbolic execution of the new program
 - collect all assumptions over the symbolic variables in the path condition
3. See if path condition implies assertions for all possible symbolic values
 - (equivalently) see if negation of the implication is satisfiable for any symbolic values

Example I (bug)

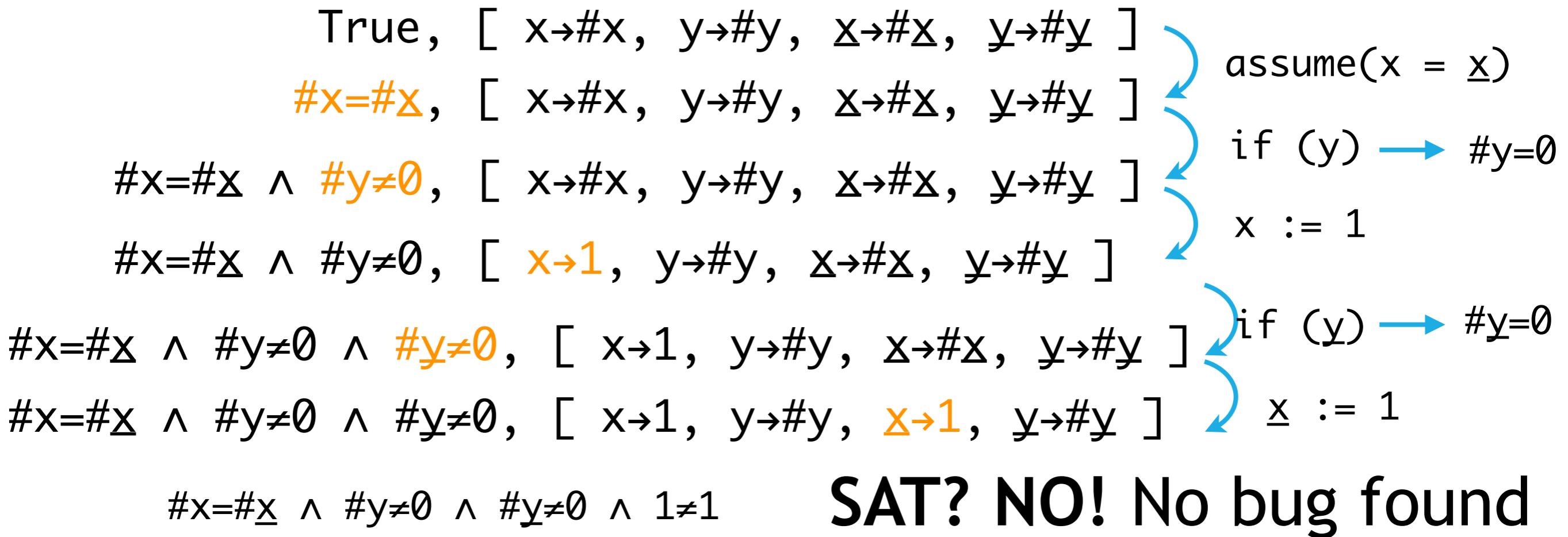
```
assume(x = x);  
x := y;  
x := y;  
assert(x = x)
```



$(\#x = \#\underline{x}) \wedge (\#y \neq \#\underline{y})$ Is its negation SAT? Yes!

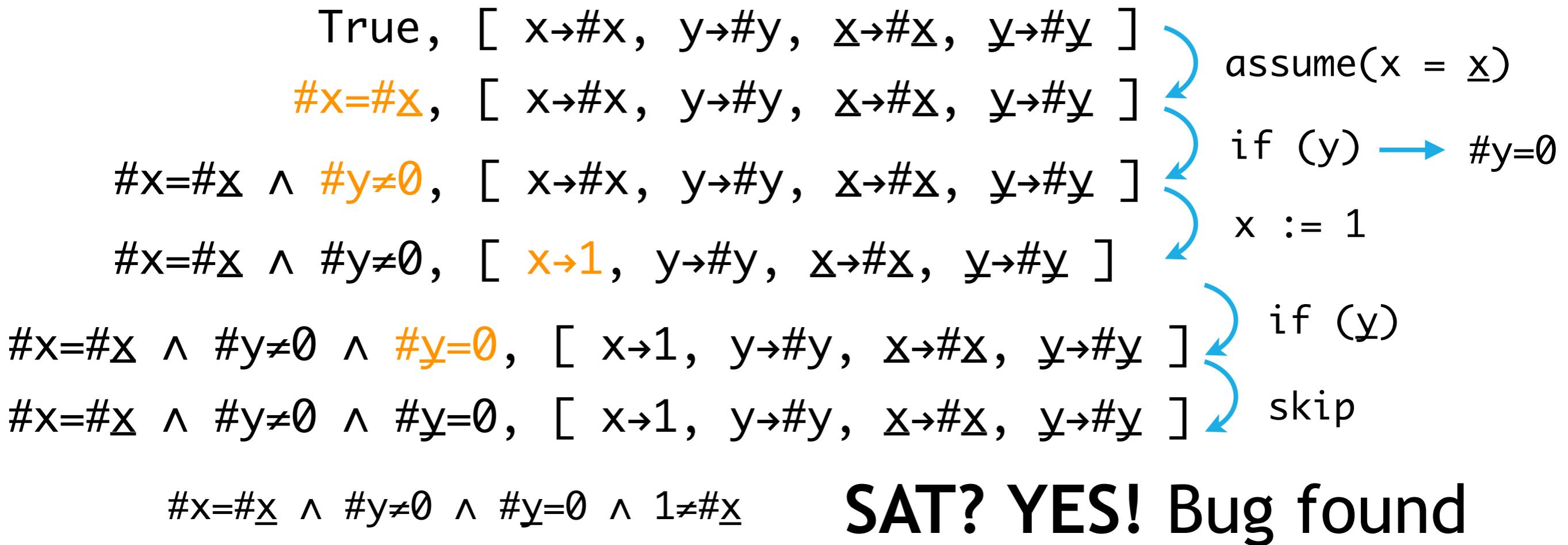
Example 2 (no bug)

```
assume(x = x);
if (y) then x := 1 else skip;
if (y) then x := 1 else skip;
assert(x = x)
```



Example 2 (finds bug)

```
assume(x = x);
if (y) then x := 1 else skip;
if (y) then x := 1 else skip;
assert(x = x)
```



Example 2 (all paths)

```
assume(x = x);
if (y) then x := 1 else skip;
if (y) then x := 1 else skip;
assert(x = x)
```

True, [$x \rightarrow \#x$, $y \rightarrow \#y$, $x \rightarrow \#x$, $y \rightarrow \#y$]

$\#x = \#x \wedge \#y = 0$

$\#x = \#x \wedge \#y = 0$,
[$x \rightarrow 1$, $y \rightarrow \#y$, $x \rightarrow \#x$, $y \rightarrow \#y$]

$\#y = 0$

$\#y \neq 0$

$\#x = \#x \wedge \#y = 0 \wedge$
 $\#y = 0$,
[$x \rightarrow \#x$, $y \rightarrow \#y$,
 $x \rightarrow \#x$, $y \rightarrow \#y$]



$\#x = \#x \wedge \#y = 0 \wedge$
 $\#y \neq 0$,
[$x \rightarrow \#x$, $y \rightarrow \#y$,
 $x \rightarrow 1$, $y \rightarrow \#y$]



$\#x = \#x \wedge \#y \neq 0$,
[$x \rightarrow \#x$, $y \rightarrow \#y$, $x \rightarrow \#x$, $y \rightarrow \#y$]

$\#y = 0$

$\#y \neq 0$

$\#x = \#x \wedge \#y \neq 0 \wedge$
 $\#y = 0$,
[$x \rightarrow 1$, $y \rightarrow \#y$,
 $x \rightarrow \#x$, $y \rightarrow \#y$]



$\#x = \#x \wedge \#y \neq 0 \wedge$
 $\#y \neq 0$,
[$x \rightarrow 1$, $y \rightarrow \#y$,
 $x \rightarrow 1$, $y \rightarrow \#y$]



Verification for Noninterference

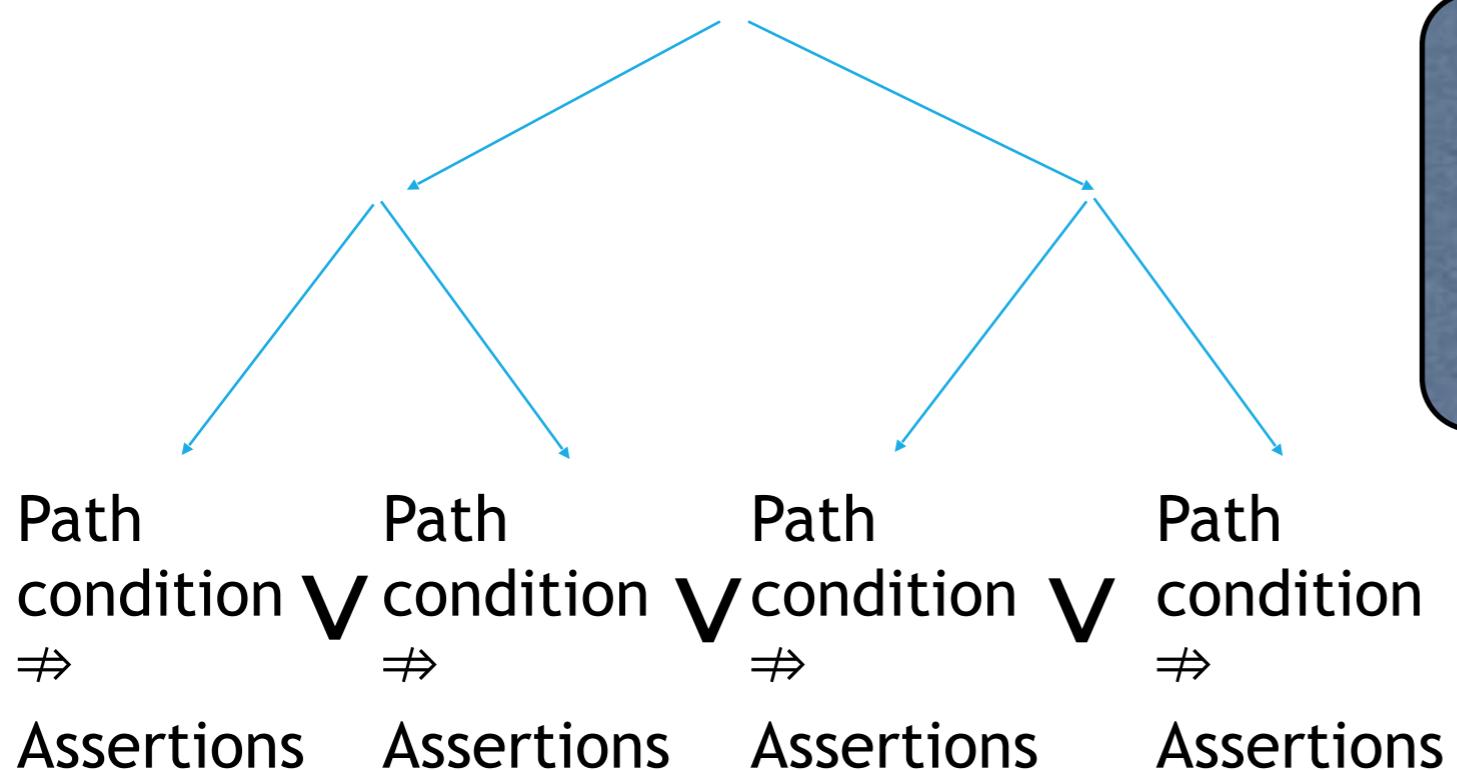
To verify absence of Noninterference bugs in S:

- I. Prepare S for verification/bug finding for Noninterference by symbolic execution
2. For each low variable x that appears in S:
 - add assumptions and assertions $x = \underline{x}$, at the beginning end end of the program, respectively.
3. For each symbolic execution path of the new program
 - search for a Noninterference bug
4. S satisfies Noninterference iff no bug is found

Example: Self-Composition

If we find a bug, we know that the program is **not** secure

The program is secure if we covered **all the possible execution paths without finding a bug.**

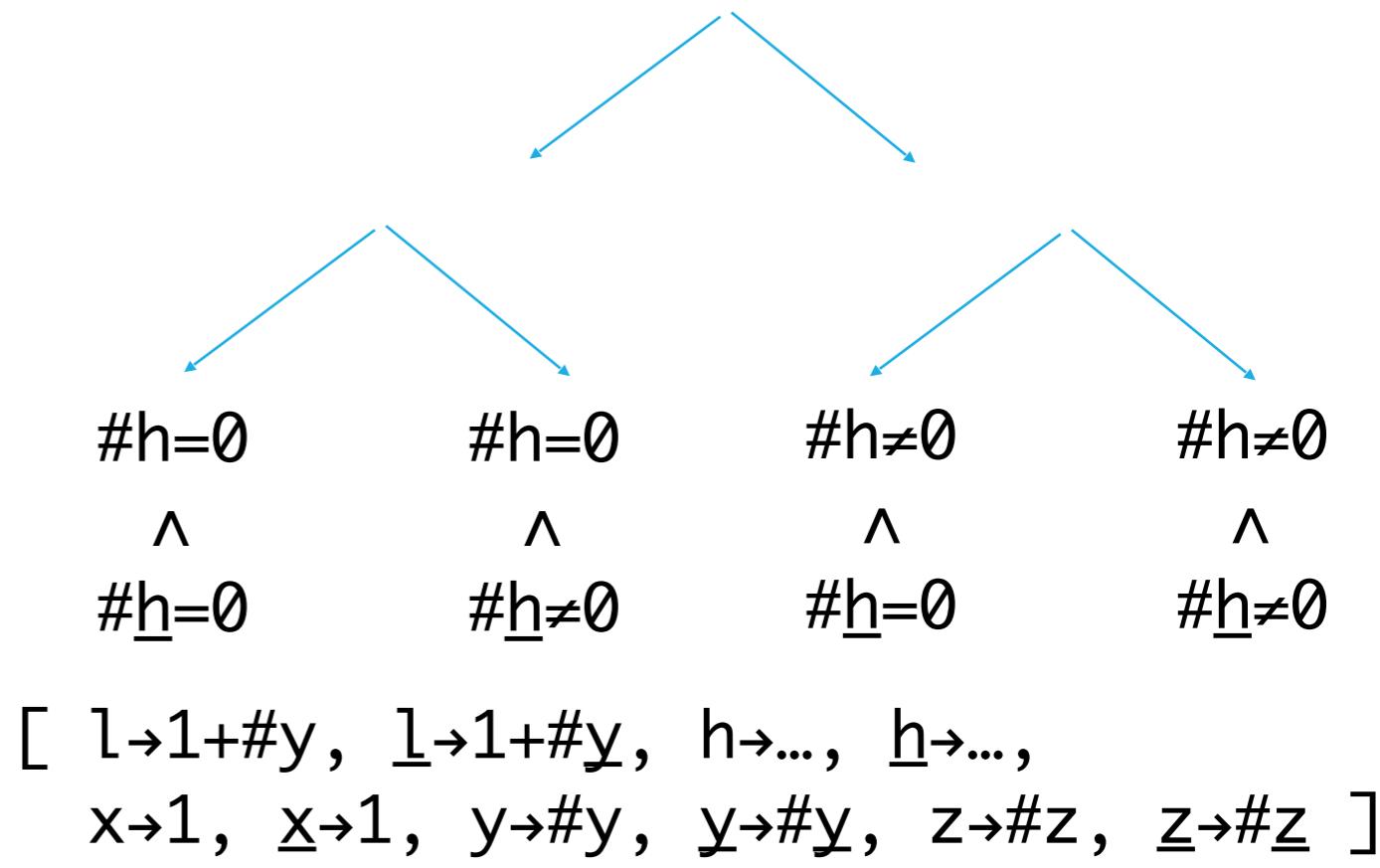


Bug found! Program does
NOT satisfy
Noninterference!

= True

Example 3

```
assume(l=l ∧ x=x ∧ y=y ∧ z=z)
z:=1;
if(h) then x:=1 else skip;
if(!h) then x:=z else skip;
l:=x+y;
z:=1;
if (h) then x:=1 else skip;
if (!h) then x:=z else skip;
l:=x+y;
assert(l=l ∧ x=x ∧ y=y ∧ z=z)
```



The final symbolic store
is always the same!

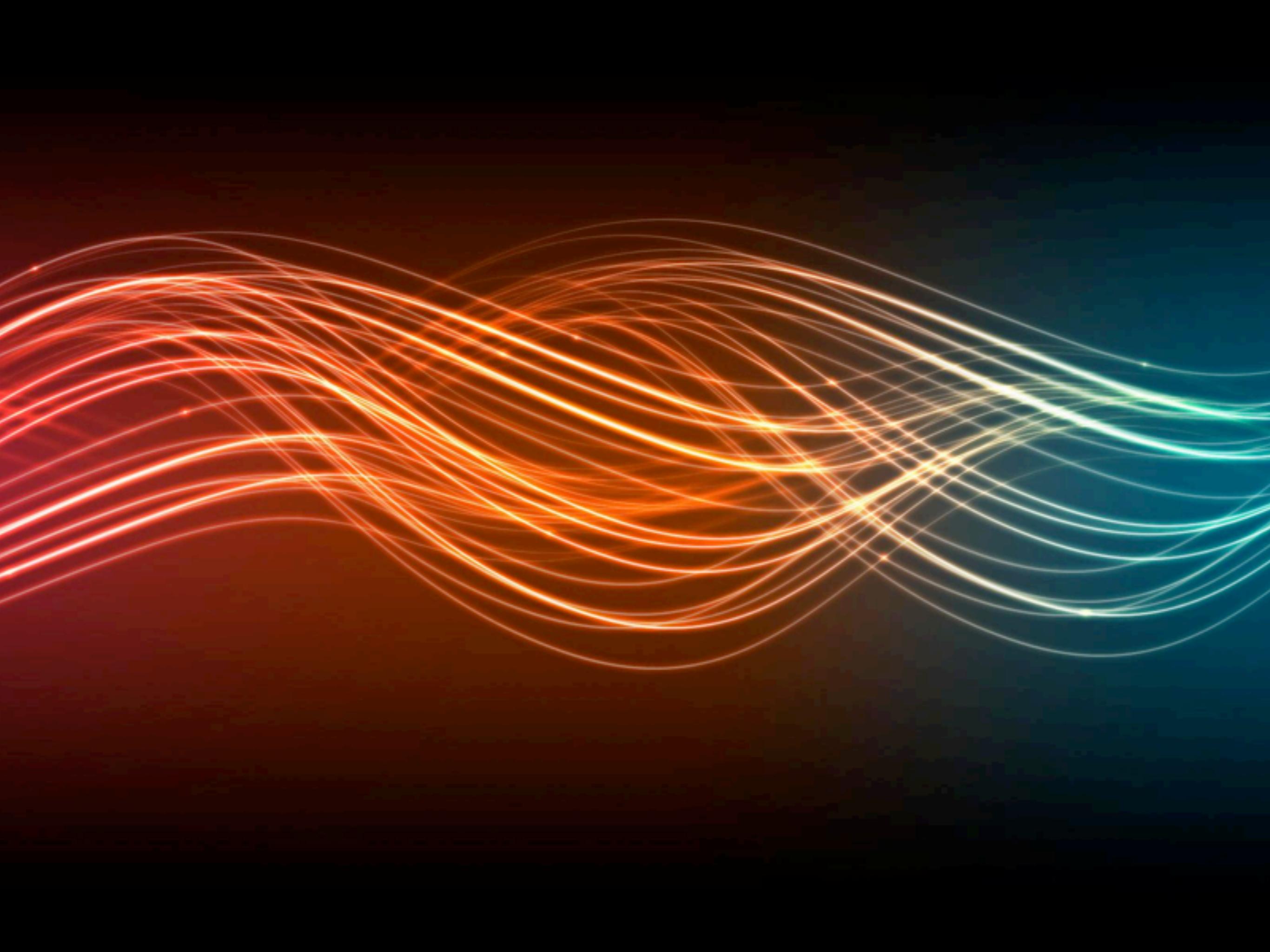
What is the SAT query?

Conclusions (this class)

- Important **security properties** cannot be expressed over individual execution traces of a system but rather as properties of a system as a whole.
 - information flow (confidentiality, integrity)
 - another example: stipulating a bound on mean response time (availability)
- It can still be possible to use trace-based tools such as for symbolic execution to find **security** bugs in programs

Conclusions (part II of course)

- We have studied how to use different language-based techniques for designing mechanisms that enforce a security property over different kinds of programming languages.
- We used as a running example the fundamental security problem of controlling information flows.
- We have seen how different techniques enable to attain and reason about the guarantees offered by a given enforcement mechanism.



CONCOLIC SYMBOLIC EXECUTION – THE MAIN IDEA

Idea: Execute the program concretely and symbolically at the same time



P. Godefroid

Why?

- Symbolic execution is often too expensive...
- Back-end constraint solvers sometimes (often!) cannot find the answer :

UNKNOWN

CONCOLIC SYMBOLIC EXECUTION – THE MAIN IDEA

Concolic Testing: Main Algorithm

```
Input0 = Pick random  
Coverage = False  
i = 0  
While (Inputi ≠ NULL) {  
    (RESi, PCi) = Run Program with  
    Inputi  
    Coverage = Coverage ∨ PCi  
    Inputi+1 ∈ Models(¬  
        Coverage)  
    i = i+1
```

CONCOLIC SYMBOLIC EXECUTION – THE MAIN IDEA

```
z := 2*y;  
if (z = x) {  
    if (x > y+10)  
    {  
  
assert(false)  
    } else { skip  
};  
} else { skip }
```

Step 1:

$\text{Inputs}_0 = [x \rightarrow 22, y \rightarrow 7]$
 $(\text{RES}_1, \text{PC}_1) = (\text{OK}, (x \neq 2*y))$
 $\text{Coverage} = (x \neq 2*y)$
 $\text{Inputs}_1 = [x \rightarrow 2, y \rightarrow 1]$

CONCOLIC SYMBOLIC EXECUTION – THE MAIN IDEA

```
z := 2*y;  
if (z = x) {  
    if (x > y+10)  
    {  
        assert(false)  
    } else { skip y+10))  
};  
} else { skip }
```

Step 2:

Inputs₁ = [x→2, y→1]
(RES₂, PC₂) = (OK, (x =
2*y) ∧ (x ≤ y+10))
Coverage = (x ≠ 2*y) ∨
((x = 2*y) ∧ (x ≤

Inputs₂ = [x→30, y→15]

CONCOLIC SYMBOLIC EXECUTION – THE MAIN IDEA

```
z := 2*y;  
if (z = x) {  
    if (x > y+10)  
    {  
        assert(false)  
    } else { skip  
};  
} else { skip } 2*y) ∧ (x > y+10))  
Step 3:  
Inputs2 = [x→30, y→15 ]  
(RES3, PC3) = (FAIL, (x =  
2*y) ∧ (x > y+10))  
Coverage = (x ≠ 2*y) ∨  
          ((x =  
2*y) ∧ (x > y+10))  
Inputs3 = NULL
```

CONCOLIC SYMBOLIC EXECUTION – THE MAIN IDEA

```
z := 2*y;  
if (z = x) {  
    if (x > y+10)  
    {  
        assert(false)  
    } else { skip  
};  
} else { skip } 2*y) ∧ (x > y+10))  
Step 3:  
Inputs2 = [x→30, y→15 ]  
(RES3, PC3) = (FAIL, (x =  
2*y) ∧ (x > y+10))  
Coverage = (x ≠ 2*y) ∨  
          ((x =  
2*y) ∧ (x > y+10))  
TInputs3 = NULL
```

A LOT MORE TO COVER...

- 1. Symbolic execution with data structures**
 - Lazy-Initialization
- 2. Declassification unfolding**
- 3. Other Security Properties:
Confinement**
- 4. Invariants and verification**