

# Final competition

By MiMaCh System - course of Intelligent Systems a.y. 21/22

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# Introduction

## Description of the game

### CodinGame Platform

Brief introduction to the platform

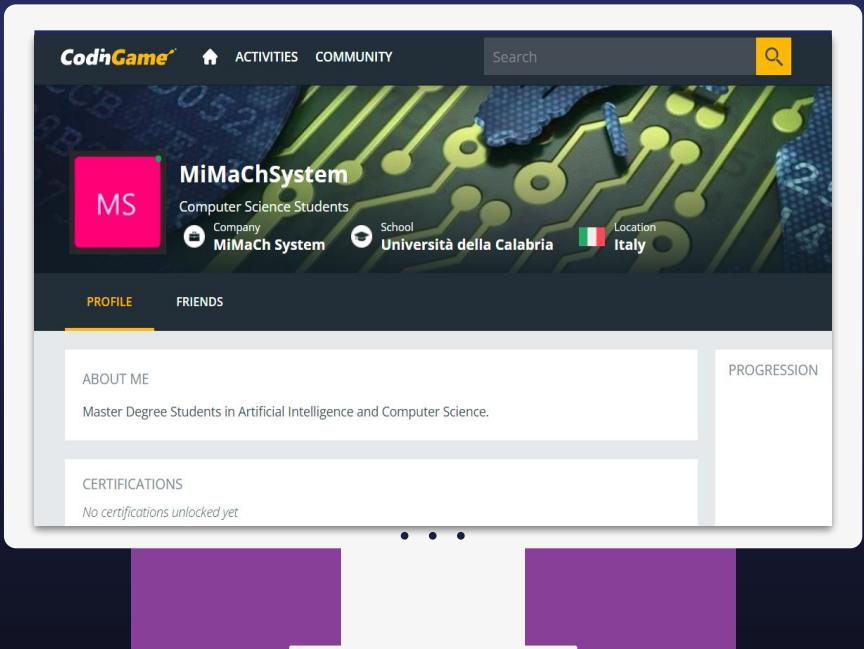
### Pacman with a twist

Brief description of the game



# The Platform CodinGame

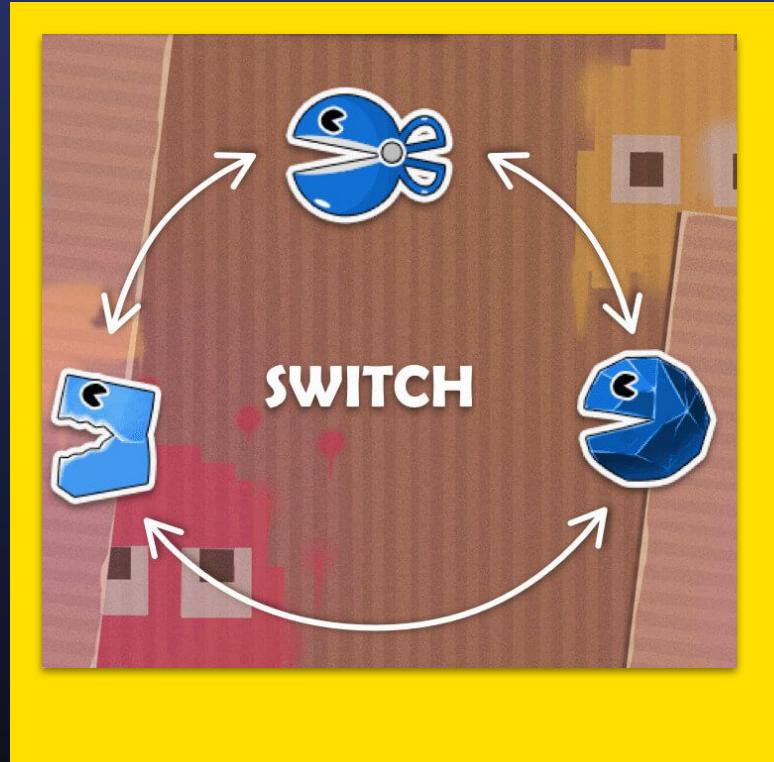
- On CodinGame, passionate developers learn, train, chat and have tons of fun!
- On the [home page](#) you can find a quick tutorial and introduction about the platform.
- The goal of this platform is to let programmers keep on improving their coding skills by solving the World's most challenging problems, learn new concepts, and get inspired





# Spring Challenge 2020

- This Challenge is a **Pacman** game but with a nice twist: pacmans can transform themselves and eat each other following the rules of the game **rock-paper-scissors**
- It is really interesting and attracting version of the classical arcade game!
- This puzzle can be solved using different topics, also studied during our lectures:
  - Pathfinding
  - Multiagent
  - Distances & 2D Array
- It is possible to find more information on the website [Practice AI, Pathfinding and Multi-agent with "Spring Challenge 2020"](#)



- The game is played on a grid, composed by walls and floors.
- Each player controls a team of pacs.
- The map is filled with pellets (**1 point**) and super-pellets (**10 points**).
- The game stops when there are no enough pellets to change the final result or after 200 turns.



## Target

- Eat more pellets than your opponent!
- Avoid getting killed!
- The winner is the player with the highest score, regardless of the amount of surviving pacs.





# Description of the Environment

## Partially Observable

Our pacmans have vision on pellets and enemies connected by a continuous straight line. Super-pellets can be seen from everywhere.

## Dynamic

Even if the grid does not change and the pallets do not move, our actions and opponents actions change the condition of the play and pellets count.

## Deterministic (Strategic)

Each decision made by our agents determines next steps.

## Discrete

It is available a finite number of possible decisions, perceptions and actions.

## Sequential

Each decision depends on the previous ones and has effect on the next ones. Each turn is not episodic.

## Multiagent

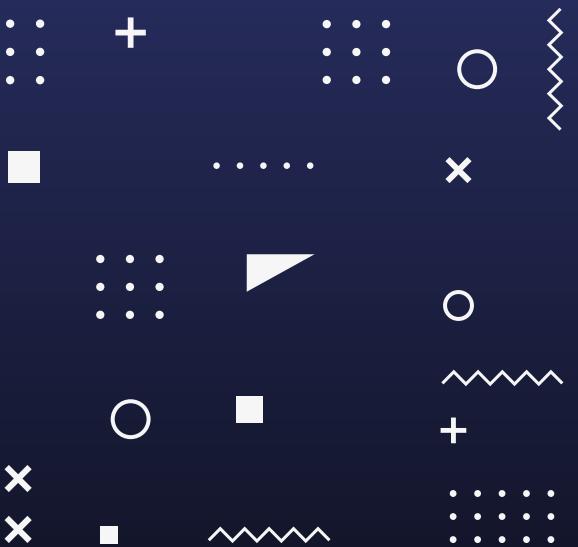
We control a number of pacs between 2 and 5 against the same number of opponents.



- At each turn, we have information regarding the visible pacs and pellets.
- For each pac, we have its identifier, whether it's ours or not and its coordinates.
- Each pac has access to two abilities (**SWITCH** and **SPEED**) with the same cooldown period of 10 turns.
- Or it can **MOVE** to the target position

## Description of the Agent





# The approach adopted

# 1º step: BRAINSTORMING

We started our approach by sharing ideas, main goals and possible strategies to apply.

- **Analyze the game**
- **Analyze the possible situations**
- **Be specific**

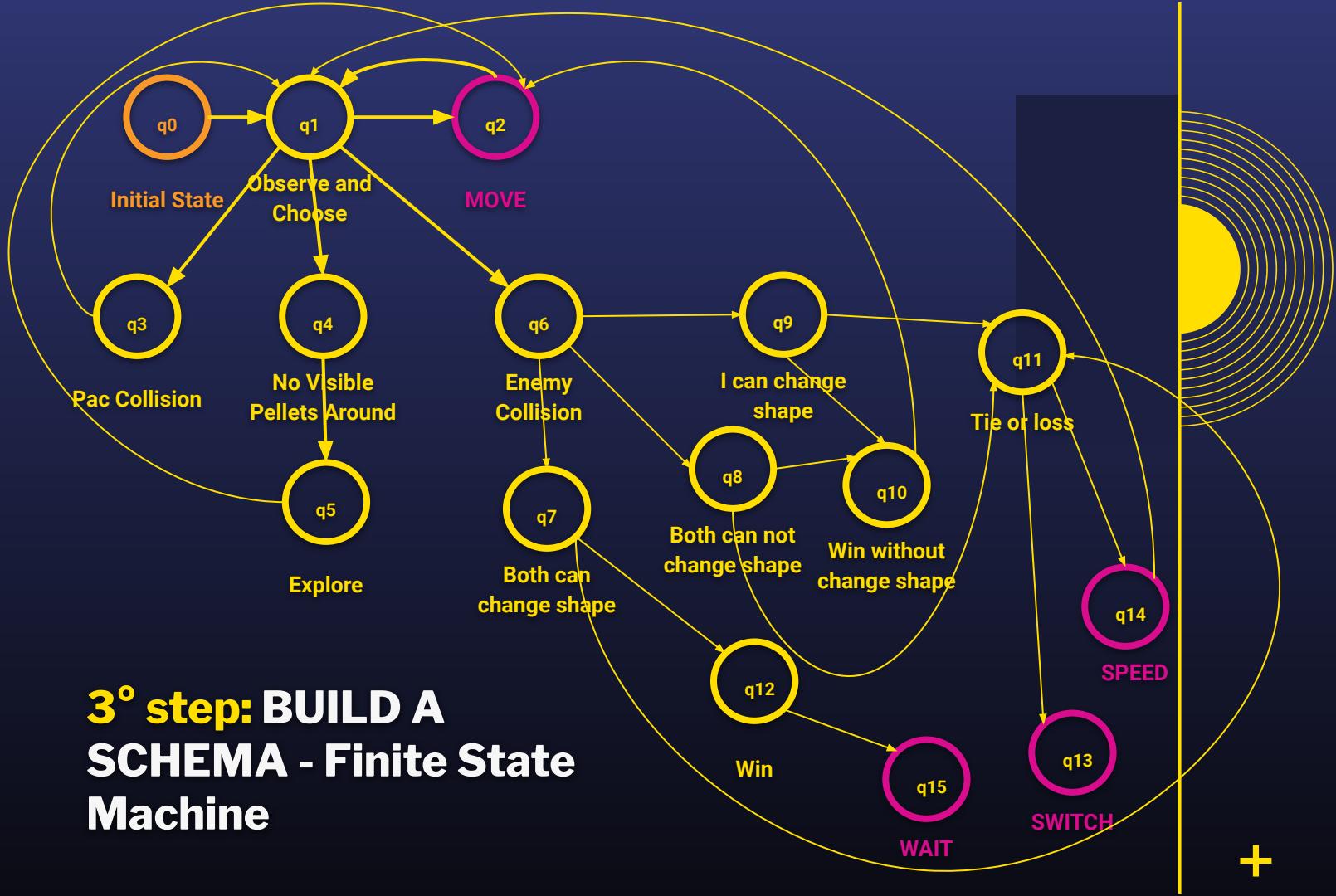
We wrote everything down on paper, writing in natural language.



# 2° step: MODELING

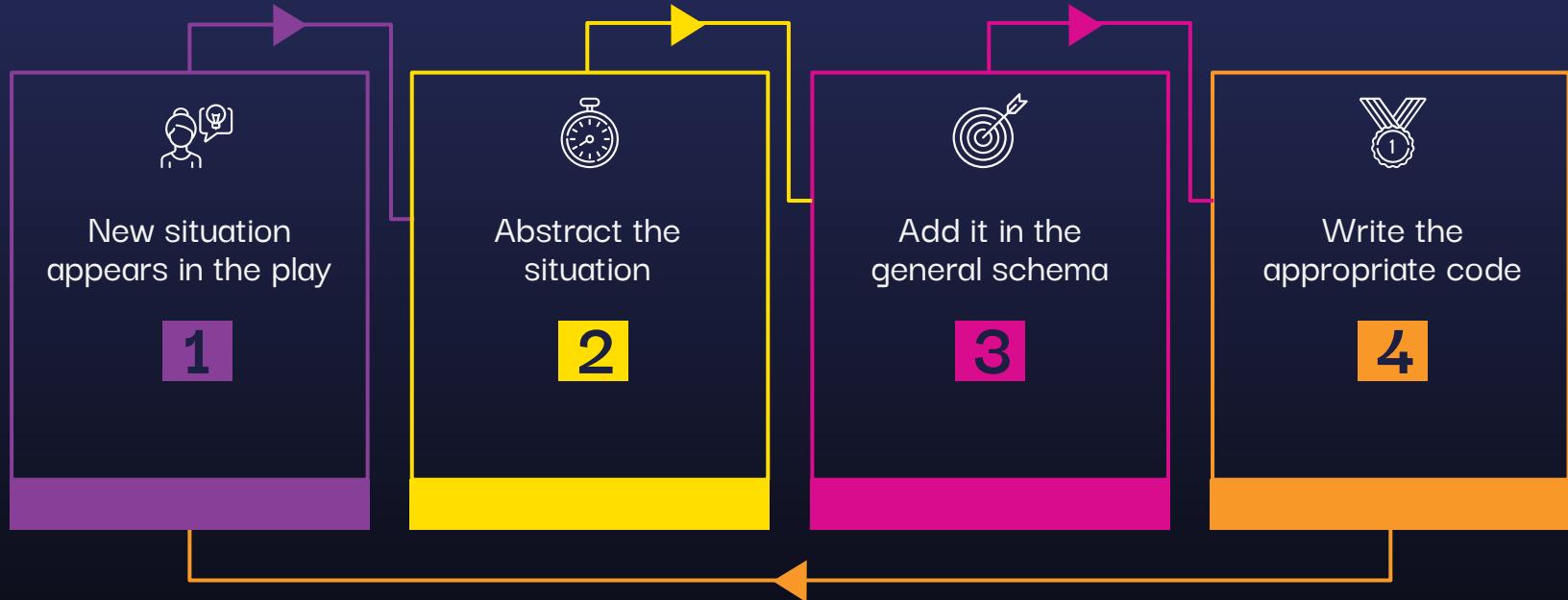
We modeled the World in a Diagram Class





### 3° step: BUILD A SCHEMA - Finite State Machine

# A CYCLIC APPROACH



# Implementation



# Game Manager

```
class GameManager{  
    Map board;  
    ArrayList<Pacman> myPacmans;  
    ArrayList<Pacman> opponents;  
  
    ArrayList<Pacman> myLastPosition;  
    ArrayList<Pacman> opponentsLastPosition;  
  
    ArrayList<Pellet> superPellets;  
  
    int myScore;  
    int opponentScore;  
    String output;  
  
    public GameManager(int w, int h){...}  
  
    void stampaMappa(){...}  
  
    void setBoard(String line, int row){...}  
  
    void addMyPacman(Pacman p){...}  
  
    void addOpponentPacman(Pacman p){...}  
  
    void setScores(int my, int oppo){...}  
  
    void setVisible(ArrayList<Pellet> visible){...}  
  
    void addVisible(Pellet p){...}  
  
    void clearAll(){...}  
  
    void clearPos(){...}  
  
    void updateMap(){...}
```

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```
boolean isSuperPellet(int x, int y){...}  
  
void chooseDirection(){...}  
  
void explore(Pacman p){...}  
  
int fightResult(Pacman my, Pacman oppo) {...}  
  
Pacman isOpponentNear(Pacman p) {...}  
  
void findPacman(Pellet p){...}  
  
void closestCell(ArrayList<Cell> cells, Pacman p){...}  
  
boolean presente(ArrayList<Cell> cell, Cell c){...}  
  
void goAway(Pacman p, Pacman near){...}  
  
void checkCollision(){...}  
  
void checkForNull(){...}  
  
void checkForFight() {...}  
  
void checkForSuperPellets(){...}  
  
void activeSpeed(){...}
```

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```
void genOutput(){...}  
  
void play(){...}
```



```
class Pacman{  
  
    int pacId;  
    int x;  
    int y;  
    String typeId;  
    int speedTurnsLeft;  
    int abilityCooldown;  
    ArrayList<Direction> possiblesMoves;  
    Direction choice;  
    Cell explore;  
    String action;  
    String switchTo;  
    boolean iChoose;  
    boolean locked;  
  
    public Pacman(int pacId, int x, int y, String typeId, int speedTurnsLeft, int abilityCooldown)  
  
    void setLocked(boolean b) ...  
  
    boolean isNear(Pacman p, int i){ ...  
  
    void bestDirection(){ ...  
  
    void tryToWin(Pacman oppo) { ...  
  
    void changeDirection(String notDir){ ...  
}
```

```
class Map{  
    char[][] mappa;  
    int width;  
    int height;  
    ArrayList<Pellet> visible;  
  
    public Map(int w, int h){ ...  
  
    void setVisible(ArrayList<Pellet> visiblePellet){ ...  
  
    void addVisible(Pellet p){ ...  
  
    void setRow(String row, int i){ ...  
  
    void stampa(){ ...  
  
    boolean checkPellet(int x, int y){ ...  
}
```

# Pacman & Map

# Cell, Direction & Pellet

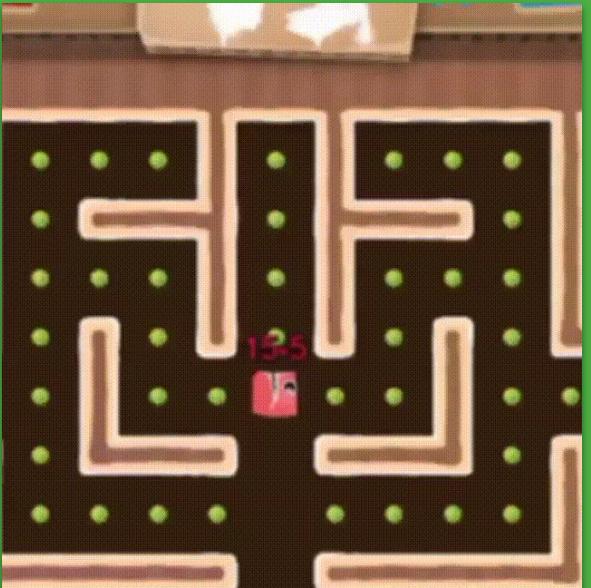
```
class Cell{  
    int x;  
    int y;  
  
    public Cell(){...}  
  
    public Cell(int x, int y){...}  
  
    public void setCoord(int x, int y){...}  
}  
  
class Pellet{  
  
    int x;  
    int y;  
    int value;  
  
    public Pellet(){...}  
  
    public Pellet(int x, int y, int value){...}  
}
```

```
class Direction{  
    String direction;  
    double pointsOnTime;  
  
    public Direction(String d, int points, int time){...}  
  
    void setDirection(String d){...}  
  
    void setPointsOnTime(int points, int time){...}  
  
    void setDirection(Pacman my, Pacman op){...}  
}
```



# Manage the movement

MOVE pacId x y



- For the **Wood** leagues, we fixed a **target** position to our player. The target was the closest **SuperPellet** or the closest **Pellet**.
  - The **distance (x, y)** method simply returns the distance between two points in a cartesian plane.
- 
- For the **Bronze** and **Silver** leagues, we fixed a **direction** to our players. It can **move** or **explore** according to this direction.
  - We chose a different approach because the player has a **different perception** of the environment. It can see only up and down its **y** and left and right its **x**.
  - The player chooses its **best direction** by observing the possible directions and then it calculates the best according to the **ratio** between points over time.
  - Otherwise, if there are no points around it, the player will **explore** an unvisited cell.





# Manage New Skills

## SWITCH

SWITCH pacId pacType

With pacType equal to:

- SCISSORS
  - ROCK
  - PAPER
- (- DEAD in the Silver level)

## SPEED

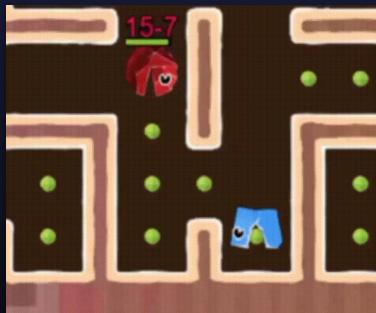
SPEED pacId

Allows a pac to move by 2 steps instead of 1 during the next 5 turns.





# How to activate the SWITCH



X

X

■

## I can switch

- If I win -> MOVE to the enemy
- If I lose -> SWITCH
- If it is a tie -> SWITCH

## Both can switch

- If I win -> WAIT
- If I lose -> goAway()
- If it is a tie -> goAway()

## Nobody can switch

- If I win -> MOVE to the enemy
- If I lose -> goAway()
- If it is a tie -> goAway()

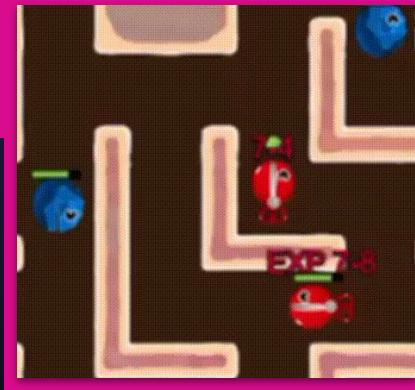
## Opponent can switch

- In any case -> goAway()

```
void checkForFight() {
    for(Pacman p: myPacmans) {
        Pacman near=isOpponentNear(p);
        if(near!=null) {
            if(p.abilityCooldown==0 && near.abilityCooldown!=0) {
                if(fightResult(p, near)==1){ //vittoria
                    p.action="MOVE";
                    if(p!=null && near!=null){
                        p.choice=null;
                        p.explore=new Cell(near.x, near.y);
                    }
                }
                else // sconfitta o pareggio
                    p.tryToWin(near);
            }
            else if(p.abilityCooldown==0 && near.abilityCooldown==0) {
                if(fightResult(p, near)==1){ //vittoria
                    p.action="WAIT";
                }
                else //sconfitta o pareggio
                    goAway(p, near);
            }
            else if(p.abilityCooldown!=0 && near.abilityCooldown!=0) {
                if(fightResult(p, near)==1){ //vittoria
                    p.action="MOVE";
                    p.choice=null;
                    p.explore=new Cell(near.x, near.y);
                }
                else //pareggio o sconfitta
                    goAway(p, near);
            }
            else if(p.abilityCooldown!=0 && near.abilityCooldown==0) {
                goAway(p, near);
            }
        }
    }
}
```

# How to activate the SPEED

```
void checkForNull(){
    for(Pacman p: myPacmans){
        if(p.iChoose==false && p.action.equals("")){
            if(p.abilityCooldown==0)
                p.action="SPEED";
            else{
                explore(p);
            }
        }
    }
}
```



EXPLORE

We decided to activate the SPEED ability when the pacman explores, in order to quickly get new points.

But, in the Silver League, we noticed that the Boss intelligence always activates the SPEED. So we adapted our strategy.

```
void activeSpeed(){
    for(Pacman p: myPacmans){
        if(p.abilityCooldown==0){
            p.action="SPEED";
        }
    }
}
```

Silver League

# How works the method explore (Pacman p)

```

void explore(Pacman p){
    ArrayList<Cell> cell = new ArrayList<Cell>();
    ArrayList<Cell> visited = new ArrayList<Cell>();
    cell.add(new Cell(p.x, p.y));
    boolean found=false;
    while(found==false){
        ArrayList<Cell> temp = new ArrayList<Cell>();

        for(Cell c: cell){
            if(board.mappa[Math.floorMod(c.y-1, board.height)][c.x]!='#')
                temp.add(new Cell(c.x, Math.floorMod(c.y-1, board.height)));
            if(board.mappa[Math.floorMod(c.y+1, board.height)][c.x]!='#')
                temp.add(new Cell(c.x, Math.floorMod(c.y+1, board.height)));
            if(board.mappa[c.y][Math.floorMod(c.x+1, board.width)]!='#')
                temp.add(new Cell(Math.floorMod(c.x+1, board.width), c.y));
            if(board.mappa[c.y][Math.floorMod(c.x-1, board.width)]!='#')
                temp.add(new Cell(Math.floorMod(c.x-1, board.width), c.y));
        }
        visited.addAll(cell);
        cell=new ArrayList<Cell>();

        for(Cell po: temp){
            if(board.mappa[po.y][po.x]=='o' || board.mappa[po.y][po.x]=='0' || board.mappa[po.y][po.x]==' '){
                boolean ok=true;
                for(Pacman pac:myPacmans){
                    if(pac.pacId!=p.pacId && pac.explore!= null && (pac.explore.x==po.x && pac.explore.y==po.y))
                        ok=false;
                }
                if(ok){
                    p.explore=new Cell(po.x, po.y);
                    found=true;
                }
            }
            else if(presente(visited, po)==false)
                cell.add(po);
        }
    }
}

```

Check adjacent cells

Check if the cell to explore is already visited

```

ArrayList<Cell> celle=new ArrayList<Cell>();
if(p.explore!=null){
    boolean up=true, down=true, right=true, left=true;
    int i=1;
    while(up || down || right || left){

        if(up){
            int y=Math.floorMod(p.explore.y - i, board.height);
            if(board.mappa[y][p.explore.x]=='#'){
                up=false;
            }
            else if(board.mappa[y][p.explore.x+1]!='#' || board.mappa[y][p.explore.x-1]!='#'){
                celle.add(new Cell(p.explore.x, y));
            }
        }
        if(down){
            int y=Math.floorMod(p.explore.y + i, board.height);
            if(board.mappa[y][p.explore.x]=='#'){
                down=false;
            }
            else if(board.mappa[y][p.explore.x+1]!='#' || board.mappa[y][p.explore.x-1]!='#'){
                celle.add(new Cell(p.explore.x, y));
            }
        }
        if(right){
            int x=Math.floorMod(p.explore.x + i, board.width);
            if(board.mappa[p.explore.y][x]=='#'){
                right=false;
            }
            else if(board.mappa[p.explore.y+1][x]!='#' || board.mappa[p.explore.y-1][x]!='#'){
                celle.add(new Cell(x, p.explore.y));
            }
        }
        if(left){
            int x=Math.floorMod(p.explore.x - i, board.width);
            if(board.mappa[p.explore.y][x]=='#'){
                left=false;
            }
            else if(board.mappa[p.explore.y+1][x]!='#' || board.mappa[p.explore.y-1][x]!='#'){
                celle.add(new Cell(x, p.explore.y));
            }
        }
        i++;
    }
    closestCell(celle, p);
    p.action="MOVE";
}

```

This second part check in an iterative way if there is a cell that allows us to see in advance the explorable cell

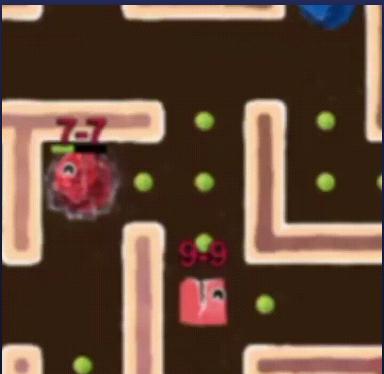
```
void play(int turn){  
    clearPos();  
    updateMap();  
    chooseDirection();  
    checkForNull();  
    checkCollision();  
    checkForFight();  
    activeSpeed();  
    genOutput(turn);  
}
```

## The strategy core

- The method `play()` is the main core of our strategy.
- It is the `implementation` of our finite state machine described previously.
- Thanks to this method it is possible to have a `clear vision` of our chosen strategy.

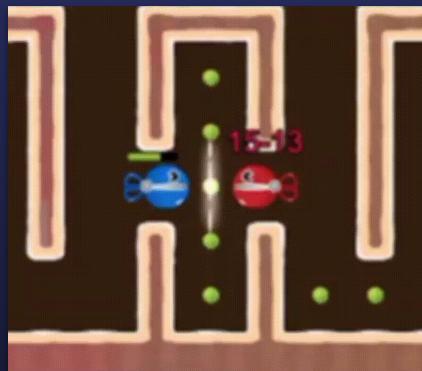


# Manage Collision



## With our Allies

Otherwise both  
pacs will be locked  
in a loop.



## With Enemies

With the same  
type.



## While Exploring

Otherwise pacs  
can explore the  
same cells.

X  
X

..



# Strengths and Weakness



Collision  
Management



Switch  
strategy



The good world  
modeling



The exploration is  
still not optimized

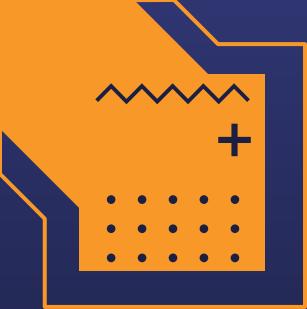


Grids without  
tunnels represent a  
difficulty for our  
strategy



Super Pellets are not  
our target and often for  
then we do not reach  
enough score





# Other Criticism

## To our code:

Not high level of generalization

## To the challenge environment:

By reaching the Silver League the Switch strategy is not more used because of the ability SPEED is broken



# CONCLUSION - OUR RESULTS



Result



League





# RESOURCES

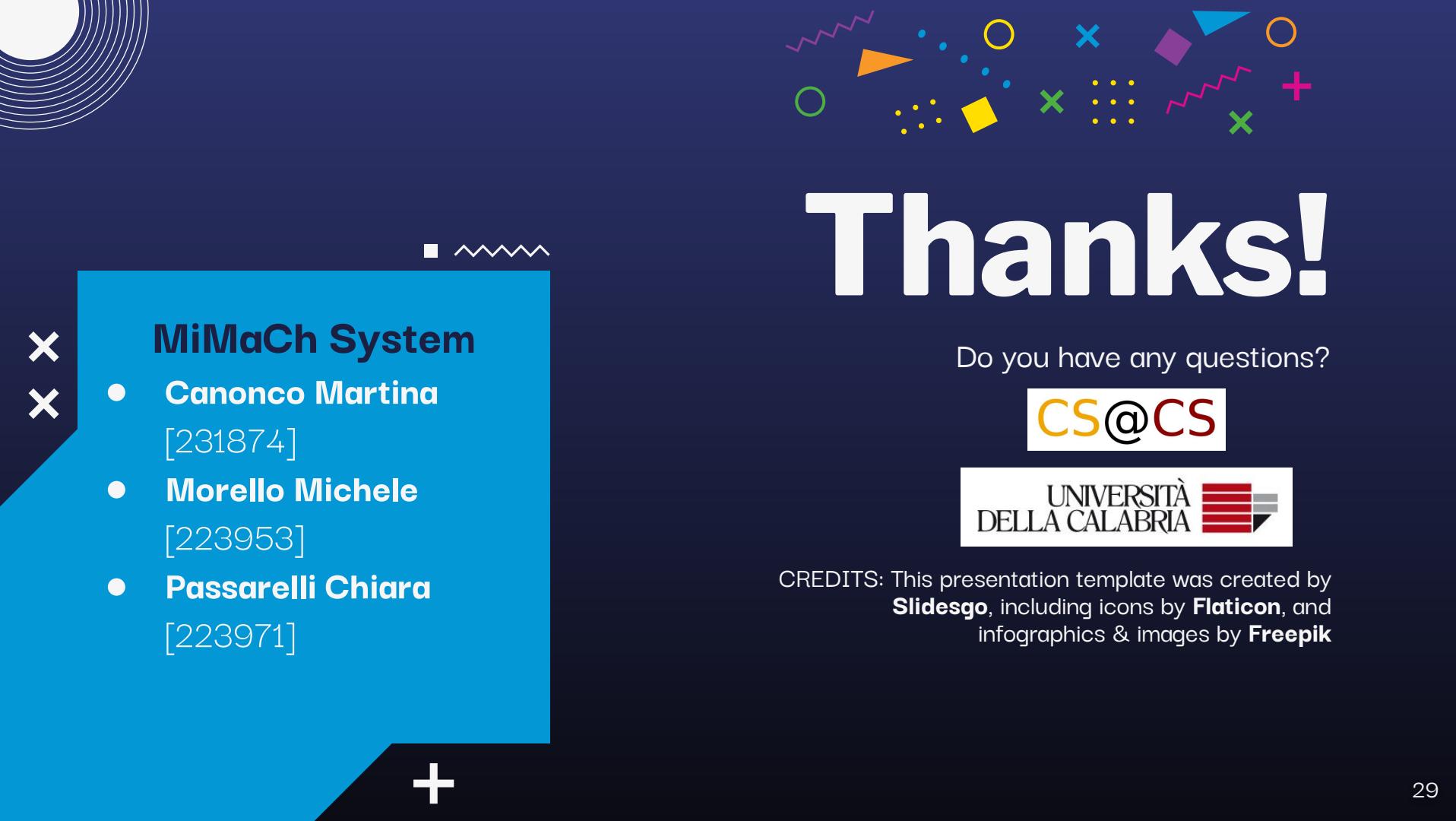


## Online

- [Practice AI, Pathfinding and Multi-agent with "Spring Challenge 2020"](#)
- [CodinGame](#)
- [CodinGame Profile - MiMaCh System](#)
- [github.com - MiMaCh-System-Proj - final competition](#)

## Text Book

- [Intelligenza artificiale. Un approccio moderno. Vol. 1 - Stuart J. Russell - Peter Norvig - - Libro - Pearson - | IBS](#)



## MiMaCh System

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# Thanks!

Do you have any questions?

**CS@CS**



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