Modeling: Some Concrete Cases

By MiMaCh System – Course of Intelligent Systems – a.a. 2021/2022

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Introduction

What is Modeling?

- Generally, the process of representing a real-world object or phenomenon.
- The representation, often mathematical, of a process, concept, or operation of a system, often implemented by a computer program.

Why is it important?

- It is important to model a problem or the input of a problem in order to find an easy way to understand and solve it.
- Model the whole universe to understand it.
- Basic of ontological foundations of cognitive and communicative processes, knowledge engineering, conceptual modeling and software engineering.

The world of two coins

Description:

- Two coin with two sides
 - $C1 = \{T\} \{H\}$
 - $C2 = \{T\} \{H\}$
- Toss both the coins one or more time
- Win 10\$ each turn if the following purposes occur.

Purposes:

- Never two tails
- At least one tail
- Consider both the purposes (in conjunction)

Formal definition:

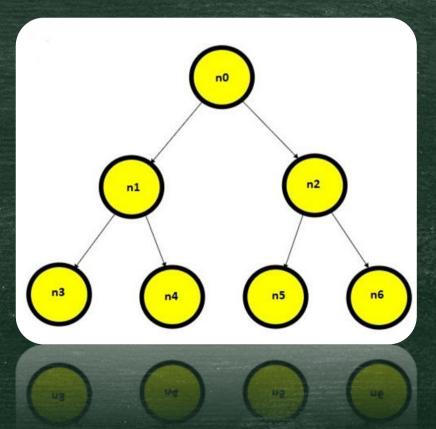
- The set of all the possible outcomes without {T, T}
- The set of all the possible outcomes with at least a T
- Conjunction of the first two

The world of two coins

Structure and Modelization:

- The binary tree explores every possible outcomes:
 - n0 = no coins tossed
 - n1 = head for the first coin
 - n2 = tail for the first coin
 - n3 = head after head
 - n4 = tail after head
 - n5 = head after tail
 - n6 = tail after tail

Model the outcomes as a Tree

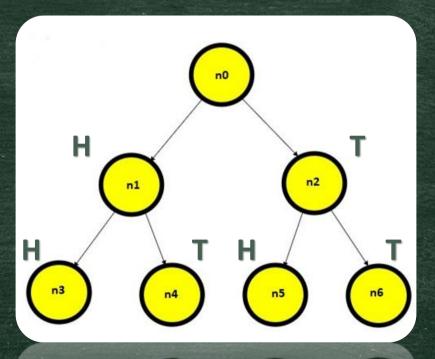


The world of two coins

Structure and Modelization:

- Focus on the first purpose:
 - Never two tail
 - n3={H,H}; n4={H,T}; n5={T,H};
- Focus on the second purpose:
 - At least one tail
 - n4={H,T}; n5={T,H}; n6={T,T};
- Focus on the third purpose:
 - First purpose AND second purpose
 - n4={H,T}; n5={T,H};

Model the outcomes as a Tree



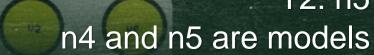
Φ: n4 ∧ n5

T1: n4

T2: n5







The world of a robot

Description:

- There is a robot in a room
- The robot wants to exit avoiding obstacles

Purpose:

Reach the exit

Formal definition:

• Find a **«safe»** path from the initial position of the robot to the position of the exit.

The world of a robot

- The map is a 2-D array of size NxM. In this case there are 4 rows and 5 columns.
- Each object is in a cell with position (i, j).
- Three kind of objects:
 - The Robot (Dynamic)
 - k Bombs (Static)
 - 1 single Exit (Static)
- Given the objects and an ID that identifies them in the matrix, knowing their position, it will be easy to construct a path using an algorithm that allows the robot to reach the exit cell without die by reaching the cell with bombs.

0,0	0,1	0,2	0,3	0,4
1,0	1,1	1,2	1,3	1,4
2,0	2,1	2,2	2,3	2,4
3,0	3,1	3,2	3,3	3,4

The world of «Mean-Max» Game

Description:



The map:

- Model the "mean-max" game as a circular map in a Cartesian plane, with the center equal to C(0,0) and radius r=6000.
- Water Town is the core of the game and it is in the center of the map and has a radius of 3000.

The Entities:

- Map each object in the map as an Entity.
- There are different types of players and autonomous objects:

Reapers
Destroyers
Doofs
Tankers
Wrecks

Every Entity has some attributes and properties

The world of «Mean-Max» Game

The Moves:

As **players** we can:

- Move to a position (X, Y) with a THROTTLE >=0 and <= 300
- Use a SKILL in position (X, Y)
 - Reaper's Skill = Tar Pool
 - Destroyer's Skill = Nitro
 Grenade
 - Doof's Skill = Oil Pool

WAIT

Purpose:

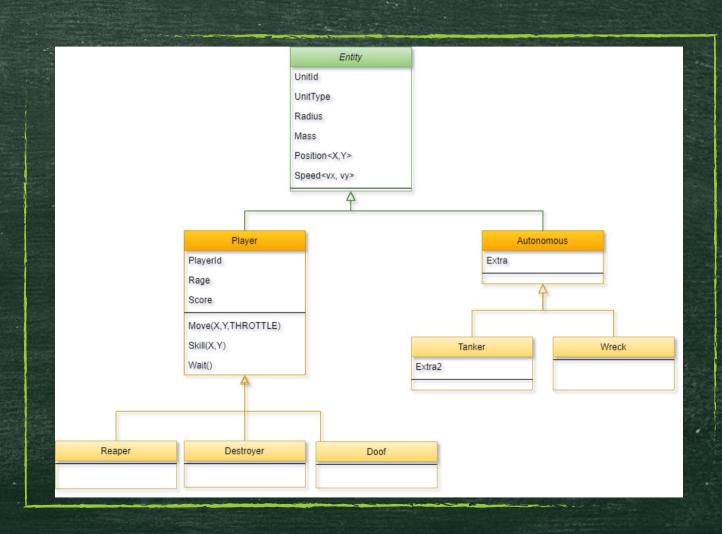
 Win the play by gathering more water than the other players.

Formal definition:

 Have an higher «score» then the other reapers.

The world of «Mean-Max» Game – Class Diagram





Resources

- Text Book (Mainly Chapter 10):
 Intelligenza Artificiale. Un Approccio Moderno. Stuart J Russell, Peter Norvig. Pearson, 2021.
- Modeling definitions: dictionary.com
- Mean-Max Game: codingame.com
- Class Diagram UML:
 visual-paradigm.com

THANKS FOR YOUR ATTENTION

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