

The background is a dark, textured surface resembling a chalkboard. It is covered with faint, light-colored chalk drawings. On the left side, there is a detailed sketch of a microscope. Above it, a globe of the Earth is visible. In the bottom left corner, there are sketches of books and a cross-like geometric shape. The bottom right corner features a large percentage sign and other smaller, less distinct sketches. A large white rectangular area is positioned in the upper right, containing the title, and a green horizontal bar is located below it, containing the author information.

The Wumpus World

by **MiMaCh System** – *Course of Intelligent Systems a.a. 2021/2022*

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Wumpus World

- Description

- The **Wumpus world** is a simple world example to illustrate the importance of a **knowledge-based agent**.
- It was inspired by a video game **Hunt the Wumpus** by *Gregory Yob* in 1973.
- The Wumpus World is a **cave** composed by 16 **rooms** connected with passageways.
- The cave has a room with a **beast** called *Wumpus* who eats anyone in the room. (Note: the Wumpus is **static**)
- Other rooms can contain a **bottomless Pit**.



Wumpus World

- PEAS Description

Performance Measure:

- +1000 points if the agent takes the gold
- -1000 points if the agent dies (eaten by the *Wumpus* or falling into a pit)
- -1 for each action
- -10 for using its arrow

Environment:

- A matrix 4x4
- The agent starts from position [1,1]
- Location of *Wumpus* and gold are **chosen randomly** (they can be in the same position)
- Each room of the cave can be a **pit** with $p = 0.2$

Wumpus World

- PEAS Description

Actuators:

- Turn Left
- Turn Right
- Move
- Grab
- Release
- Shoot

Sensors:

- The agent will perceive:
 - **Stench**
 - **Breeze**
 - **Glitter**
 - **Bump**
- When the *Wumpus* is shot, its horrible **scream** can be perceived everywhere.

Goal:

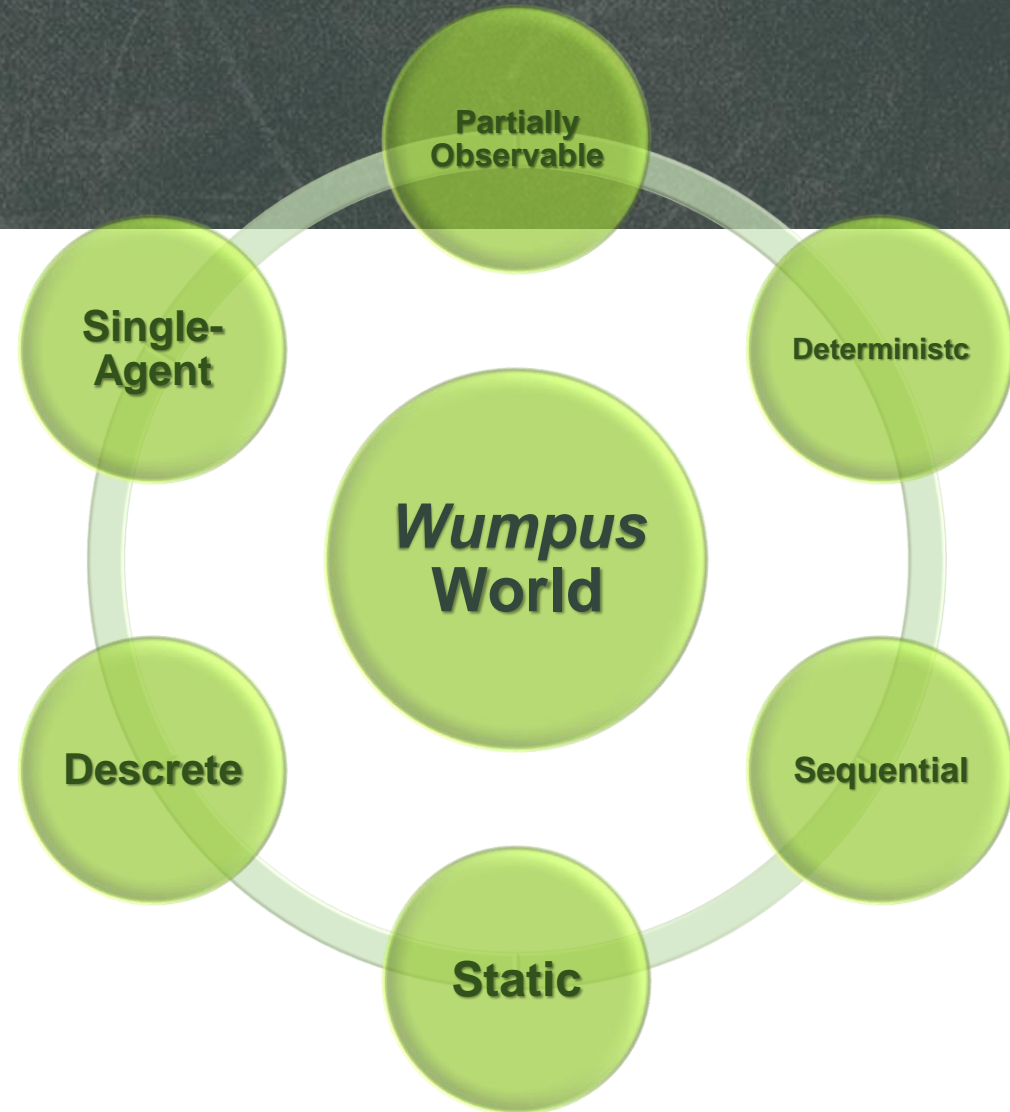
- The **game ends** if:
 - The agent dies
 - Came out of the cave with gold

Wumpus World

- Environment Properties

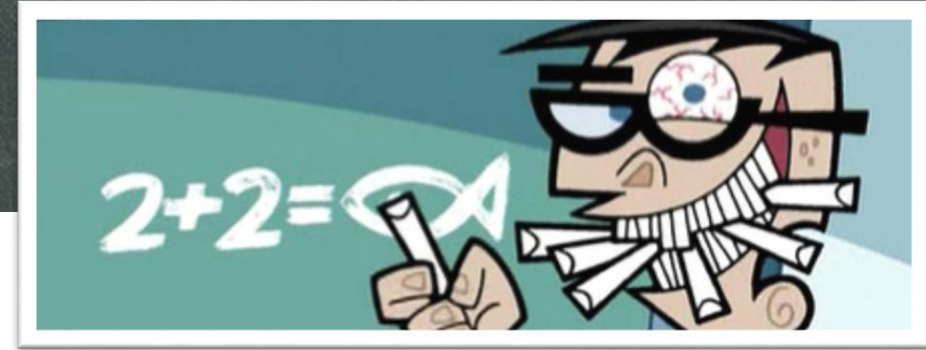
The *Wumpus* world properties:

- **Partially Observable:** the agent has a local perception.
- **Deterministic:** the result and outcome of the world are already known.
- **Sequential:** the order is important.
- **Static:** *Wumpus* and *Pits* are not moving.
- **Discrete:** the environment is discrete.
- **Single-Agent:** there is only one agent and *Wumpus* is not considered as an agent.

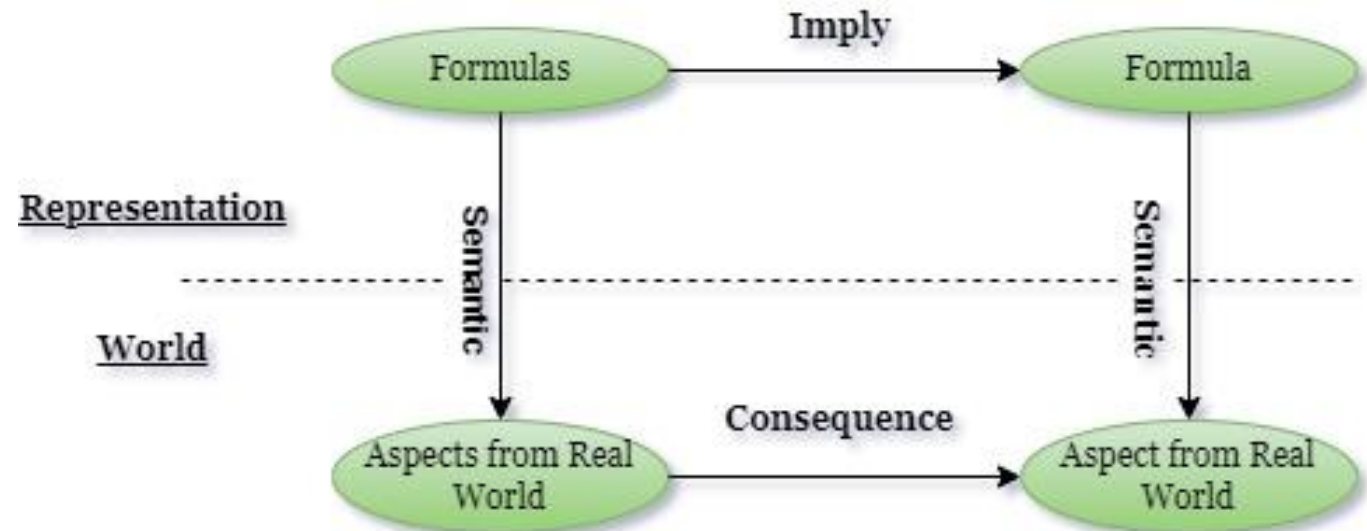


Logic and Knowledge

- Logical Agents



- **Knowledge-based agents** use their knowledge about the world to generate good decisions.
- Knowledge is represented as a **set of sentences** in a formal language. The language defines the truth value of a formula given a specific world.
- A Logical Agent is composed by a **knowledge base** and an **inferential procedures**.



Logic and Knowledge

- Fundamentals and Background

- In AI Inference is the process that **generates conclusions** from **evidence** and **facts**.
- **Inference rules** are the templates for generating **valid arguments**.
- The **implication** among all the connectives plays an important role.
$$A \rightarrow B$$
- There are different types of Inference rules.
- They are used in AI to derive **proofs** (a sequence of «*actions*» to reach the goal).
- **Propositional Logic** and **First-Order Logic** are the core of Logical Agents.
- Basis for **ASP** and **CSP**.

Logical Formalisms

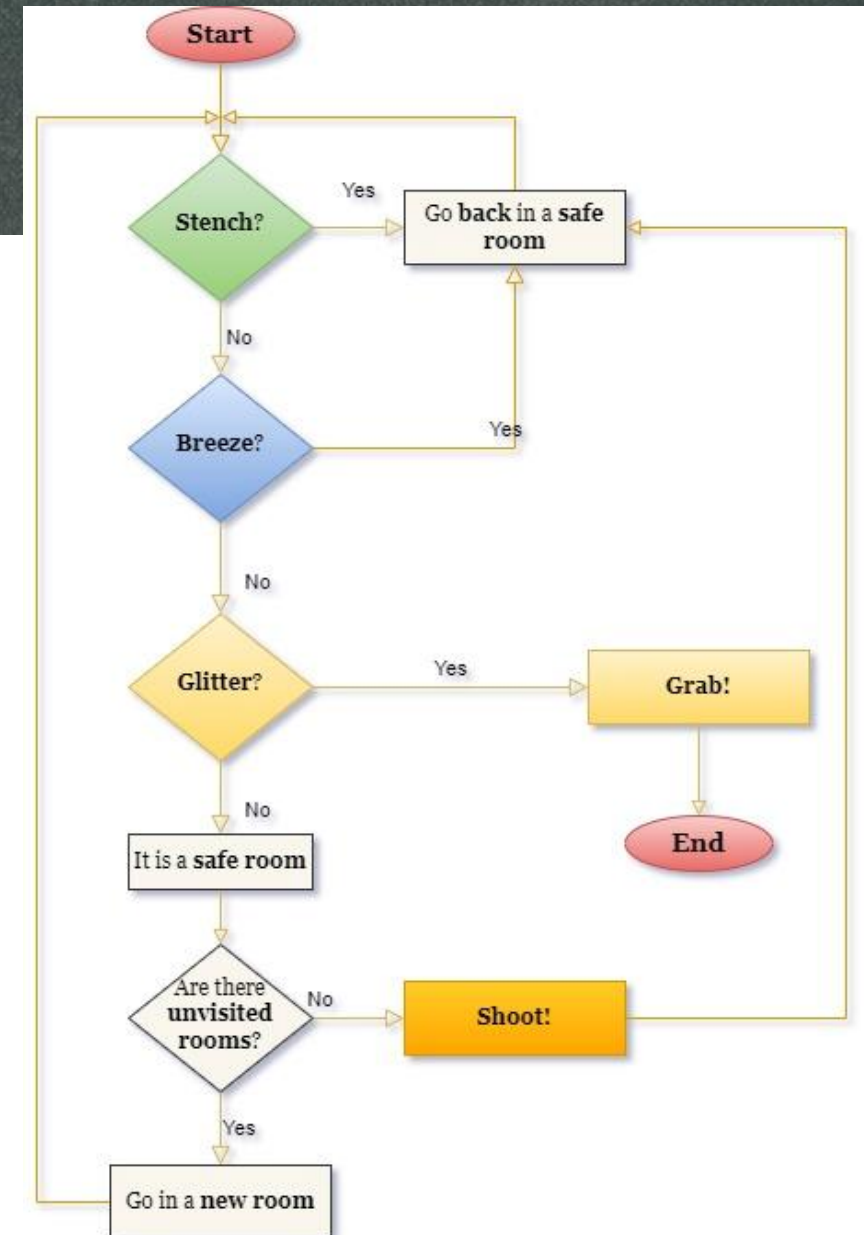
- Flow Chart
- ASP Program
- MiniZinc Program

Logical Formalism

- A Graphic Model

Flow Chart

- A flowchart is a **diagram** that describes a **process, system** or **algorithm**
- Simple and easy to understand
- There is a specific set of **flowchart symbols** ([see more here](#))



Logical Formalism

- ASP Program

Answer Set Programming

Logical Formalism

- ASP Program

ASP Implementation

Logical Formalism

- MiniZinc Program

Constraint Satisfaction Problems

- Many real-life problems of AI and OR can be formulated as a **Constraint Satisfaction Problem (CSP)**
- CSP is a powerful tool for **knowledge representation**
- **MiniZinc** is a free and open-source **constraint modeling language**.
- Use MiniZinc to **model constraint satisfaction and optimization problems**

Logical Formalism

- MiniZinc Program

MiniZinc Implementation

- **Data File**
- **Elements** = {Ok=0, Stench=2, Breeze=3, Glitter=4, Pit=5, Wumpus=6};
- We assume that the input instance is correct and there is only one Wumpus and only one room with the Gold

```
wumpus_world_instance.dzn ×  
1 size = 4;  
2 cave = [  
3     2, 0, 3, 5 |  
4     6, 4, 5, 3 |  
5     2, 0, 3, 0 |  
6     0, 3, 5, 3 | ];
```


Logical Formalism

- MiniZinc Program

MiniZinc Implementation

- Model File

```
%input matrix 4x4
int: size;
int: rows=size;
int: cols=size;
set of int: DIM = 1..size;
array[DIM, DIM] of int: cave;
output ["Cave: \n", show2d(cave)];
```

```
10 % as result we want a 0/1 matrix that encodes
11 % points on a path in the cave.
12 % 1 means the point is on the path and 0 means it's not.
13 array[DIM, DIM] of var 0..1: path;
14
15 %Archer starts from path[1,1]
16 %The Game ends when the Archer reaches the gold
17 var int: gold_row;
18 var int: gold_col;
19 constraint forall(i in 1..rows, j in 1..cols where cave[i, j] = 4)
20 (
21   gold_row=i /\ gold_col=j
22 );
23 %So we fix start room and end room
24 constraint path[4,1]=1 /\ path[gold_row, gold_col]=1;
```

Logical Formalism

- MiniZinc Program

▪ Model File

Cave:

```
[| 2, 0, 3, 5
 | 6, 4, 5, 3
 | 2, 0, 3, 0
 | 0, 3, 5, 3
 |]
```

Path:

```
[| 1, 1, 1, 0
 | 0, 1, 0, 1
 | 1, 1, 1, 1
 | 1, 1, 0, 1
 |]
```

Performance Measure: 988.

=====

```
25 %Pits can not be in the path
26 constraint forall(i in DIM, j in DIM where cave[i, j] = 5)(
27   path[i, j] = 0
28 );
29 %Also the room with the Wumpus can not be in the path
30 constraint forall(i in DIM, j in DIM where cave[i, j] = 6)(
31   path[i, j] = 0
32 );
33
34 %check the room that can be reached
35 constraint forall(i in DIM, j in DIM where cave[i, j] = 0 \/ cave[i, j] = 2 \/ cave[i, j] = 3)(
36   path[i, j] = 1
37 );
38
39 output ["\n Path: \n", show2d(path)];
40
41 var int: pathCost = sum(i in DIM, j in DIM where path[i, j] = 1)(1);
42 output ["\n Performance Measure: \n(1000-pathCost)."];
43 solve minimize pathCost;
```

Resources

- Text Book:
[Intelligenza Artificiale. Un Approccio Moderno. Stuart J Russell, Peter Norvig. Pearson, 2021.](#)
- Online Sources:
[javatpoint.com](#)
[logical agents for wumpus world](#)
[diagrams.net](#)
[what is a flowchart](#)
- ASP Programming:
- CSP Programming and MiniZinc:
[Constraint Satisfaction Problems](#)
[minizinc.org](#)



Thanks for your attention

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