

FAI LAB 6

Constraint satisfaction problems

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Constraint Satisfaction Problems

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- **Factored** state representation

- variables X_1, \dots, X_n
- with domains $\text{dom}(X_i) = \{v_1^{(i)}, \dots, v_{k_i}^{(i)}\}$
- and constraints C_1, \dots, C_m

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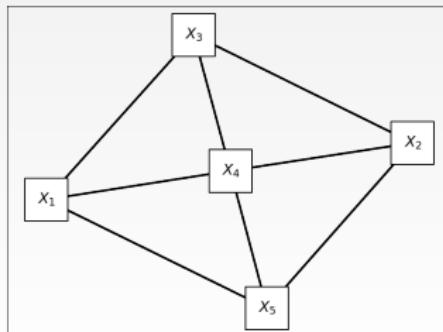
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- **State:** an assignment to some $(X_i = v)$ s.t. $v \in \text{dom}(X_i)$
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- **Solution:** a total **and** consistent assignment
- **CSPs as graphs:** nodes are vars, edges are (binary) constraints



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- **Search**: assigning X_i values from their domain

- Propagation and search are usually interleaved

Constraint propagation

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- **Arc consistency** (2-consistency): forward checking or AC3

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- There is more: path consistency (3-consistency), k-consistency

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- FC: only propagates to neighbors of the last assigned X_i
- AC3: full propagation
each time an arc is made consistent, (re)check its neighbors

function AC-3(csp) **returns** false if an inconsistency is found and true otherwise

inputs: csp , a binary CSP with components (X , D , C)

local variables: $queue$, a queue of arcs, initially all the arcs in csp

```
while  $queue$  is not empty do
     $(X_i, X_j) \leftarrow REMOVE-FIRST(queue)$ 
    if REVISE( $csp, X_i, X_j$ ) then
        if size of  $D_i = 0$  then return false
        for each  $X_k$  in  $X_i.NEIGHBORS - \{X_j\}$  do
            add  $(X_k, X_i)$  to  $queue$ 
    return true
```

function REVISE(csp, X_i, X_j) **returns** true iff we revise the domain of X_i

$revised \leftarrow false$

for each x **in** D_i **do**

if no value y **in** D_j allows (x,y) to satisfy the constraint between X_i and X_j **then**

 delete x from D_i

$revised \leftarrow true$

return $revised$

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```
function BACKTRACKING-SEARCH(csp) returns a solution, or failure
    return BACKTRACK({ }, csp)

function BACKTRACK(assignment, csp) returns a solution, or failure
    if assignment is complete then return assignment
    var  $\leftarrow$  SELECT-UNASSIGNED-VARIABLE(csp)
    for each value in ORDER-DOMAIN-VALUES(var, assignment, csp) do
        if value is consistent with assignment then
            add {var = value} to assignment
            inferences  $\leftarrow$  INFERENCE(csp, var, value)
            if inferences  $\neq$  failure then
                add inferences to assignment
                result  $\leftarrow$  BACKTRACK(assignment, csp)
                if result  $\neq$  failure then
                    return result
                remove {var = value} and inferences from assignment
            return failure
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SELECT-UNASSIGNED-VARIABLE

Two heuristics (*in this order*):

- **Minimum Remaining Values (MRV)** $\operatorname{argmin}_X |\operatorname{dom}(X)|$
- **Degree** $\operatorname{argmax}_X |\{(X, n) \mid \forall n \in \operatorname{Unneigh}(X)\}|$

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ORDER-DOMAIN-VALUES

Least constraining value (LCS) heuristic

Pick $v \in \operatorname{dom}(X)$ that has minimum impact on $\sum_{n \in \operatorname{Unneigh}(X)} |\operatorname{dom}(n)|$

Backtracking Search

INFERENCE

Two options:

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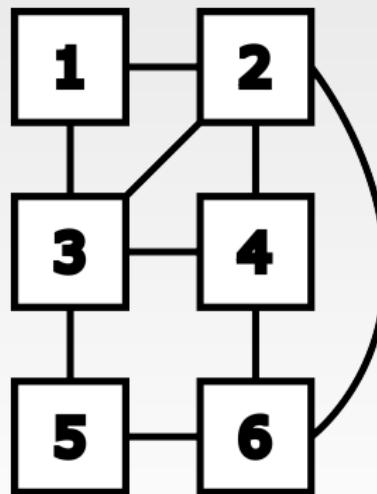
BACKTRACK

Standard Chronological Backtracking

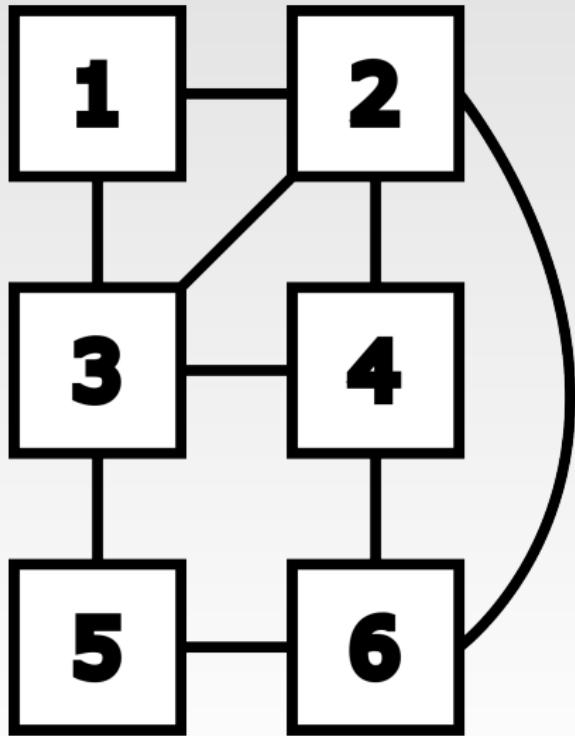
backtracks to the previous assignment

Graph coloring

- $\text{dom}(X_i) = \{\textcolor{red}{R}, \textcolor{green}{G}, \textcolor{blue}{B}\}$ (in this order)
- Edges represent $X_i \neq X_j$
- Multiple edge types are possible (e.g. $X_i = X_j$)

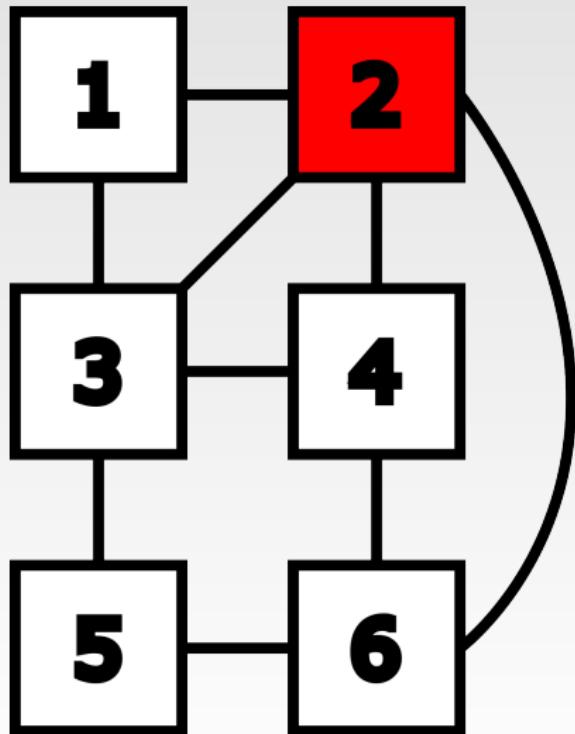


GC with backtracking search



GC with backtracking search

(2 = R)



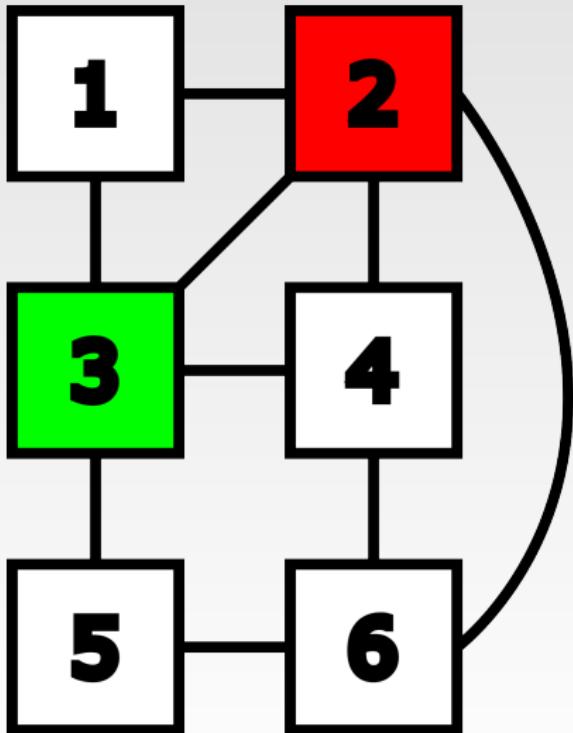
$\text{dom}(1) = [\text{G}, \text{B}]$

$\text{dom}(3) = [\text{G}, \text{B}]$

$\text{dom}(4) = [\text{G}, \text{B}]$

$\text{dom}(6) = [\text{G}, \text{B}]$

GC with backtracking search



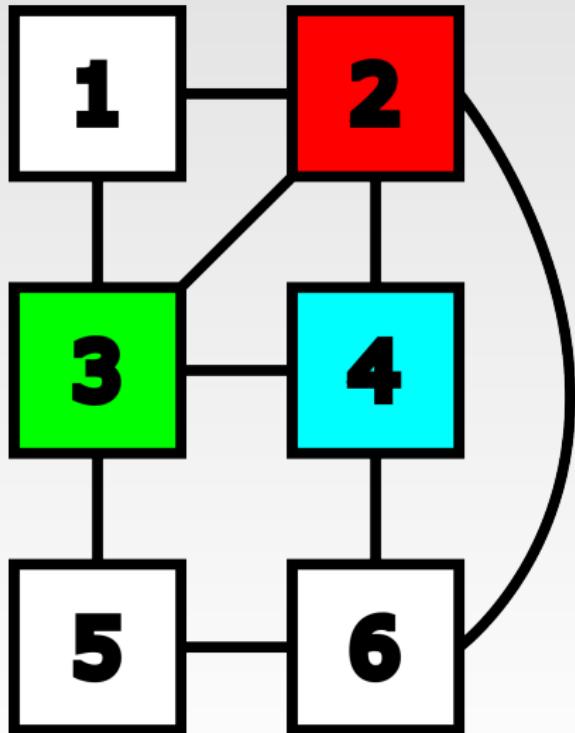
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(3 = G)

$\text{dom}(1) = [\text{B}]$
 $\text{dom}(4) = [\text{B}]$
 $\text{dom}(5) = [\text{R}, \text{B}]$

GC with backtracking search



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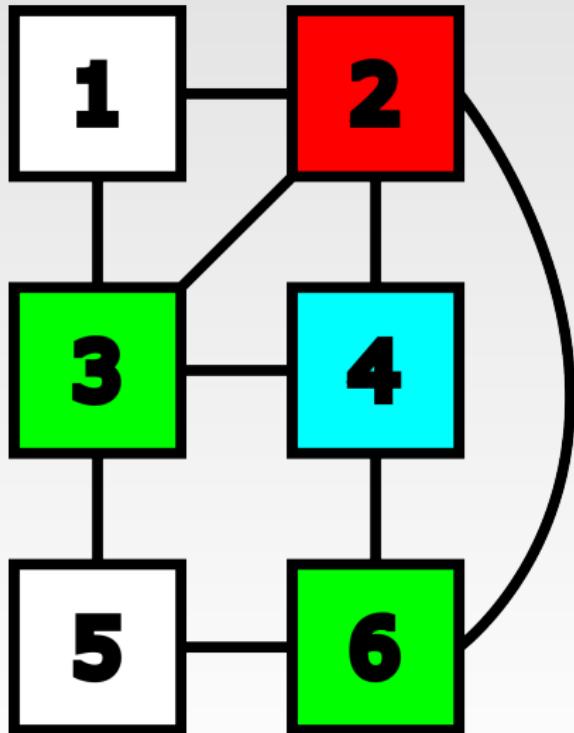
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(4 = B)

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GC with backtracking search



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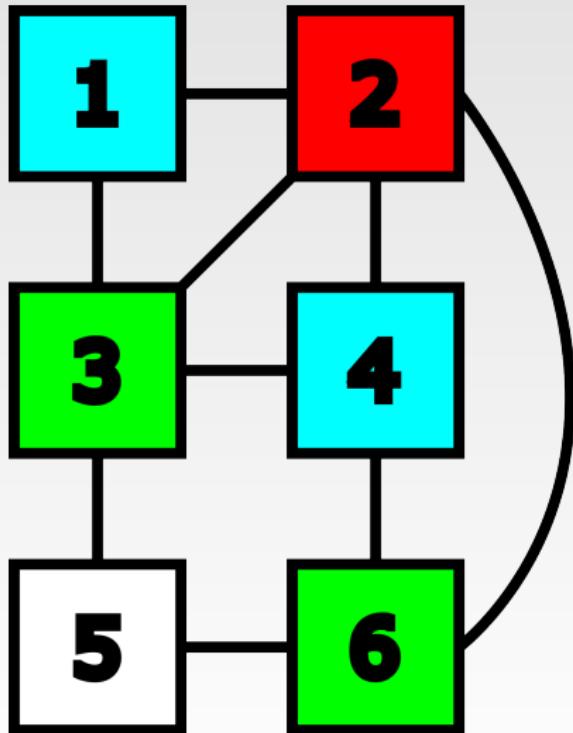
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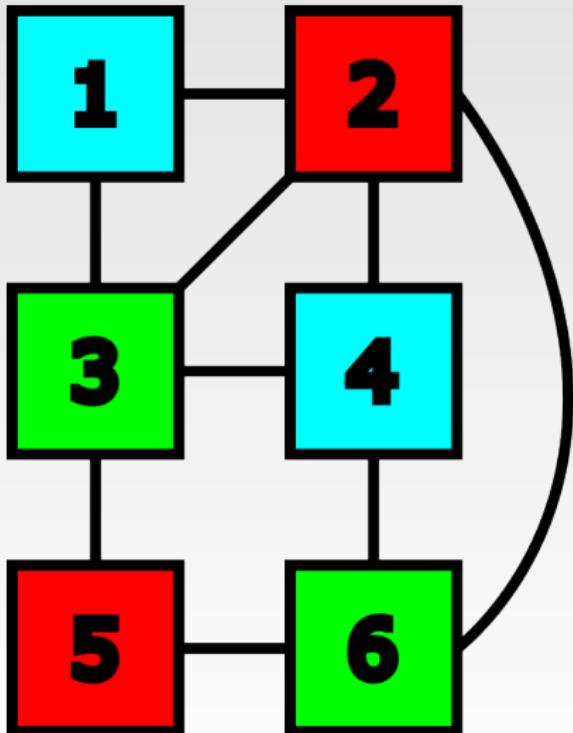
(4 = B)

$\text{dom}(6) = [\text{G}]$

(6 = G)

(1 = B)

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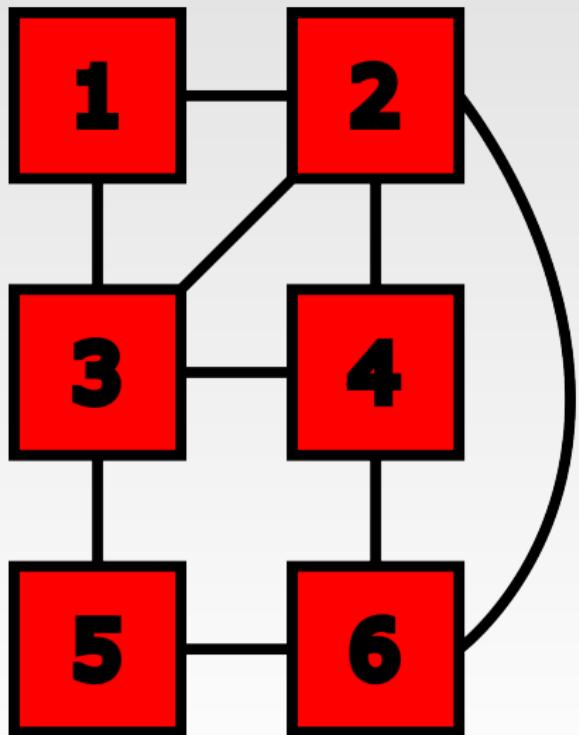
(5 = R)

Local Search with CSPs

Hill-climbing + MCH:

```
function MIN-CONFLICTS(csp, max_steps) returns a solution or failure
  inputs: csp, a constraint satisfaction problem
            max_steps, the number of steps allowed before giving up
  current  $\leftarrow$  an initial complete assignment for csp
  for i = 1 to max_steps do
    if current is a solution for csp then return current
    var  $\leftarrow$  a randomly chosen conflicted variable from csp.VARIABLES
    value  $\leftarrow$  the value v for var that minimizes CONFLICTS(var, v, current, csp)
    set var = value in current
  return failure
```

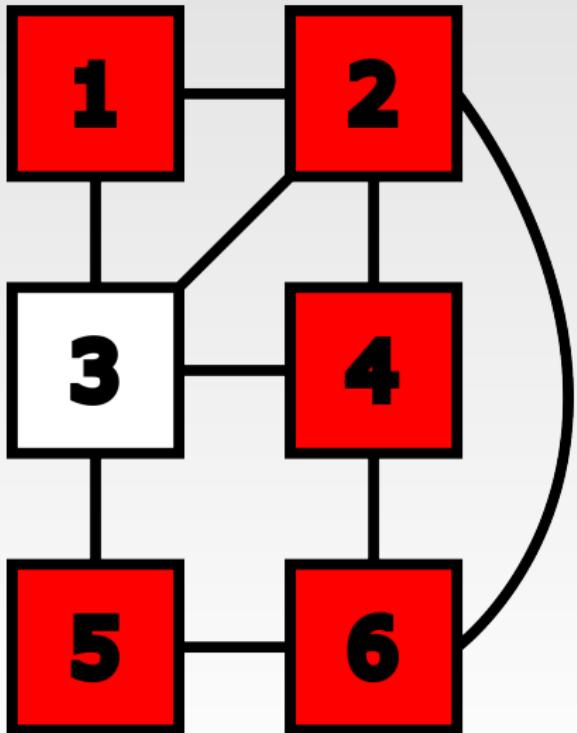
GC with HC + MCH search



conflicts = [1, 2, 3, 4, 5, 6]

choices = [0.44, 0.81, 0.76, 0.88]

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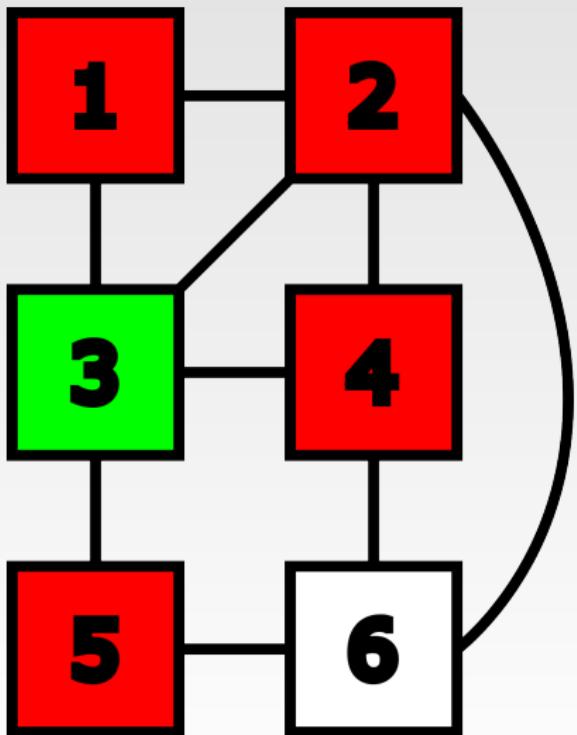
conflicts:

(R → 6)

(G → 5)

(B → 5)

GC with HC + MCH search



conflicts = [1, 2, 4, 5, **6**]

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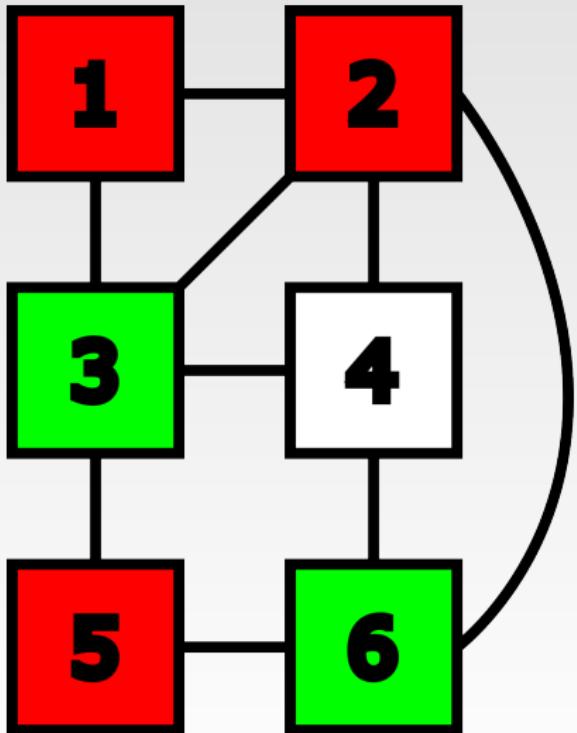
conflicts:

(R → 5)

(G → 3)

(B → 3)

GC with HC + MCH search



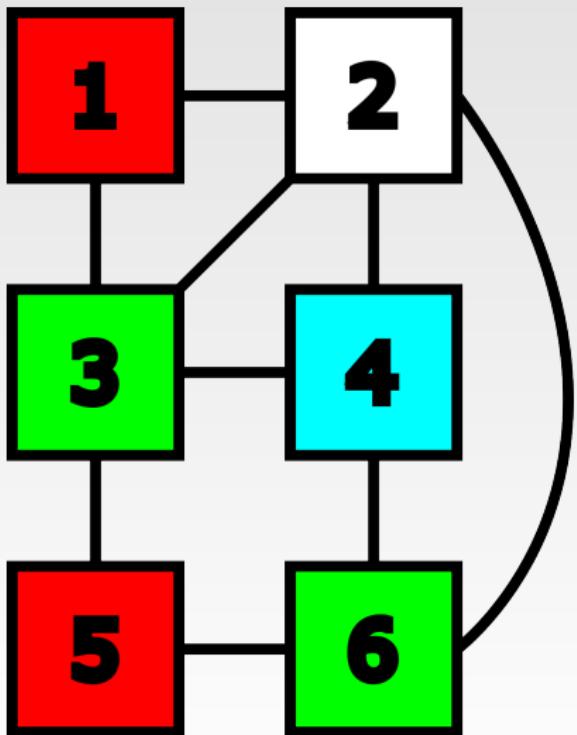
conflicts = [1, 2, **4**]

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conflicts:

(R → 3)
(G → 5)
(B → 2)

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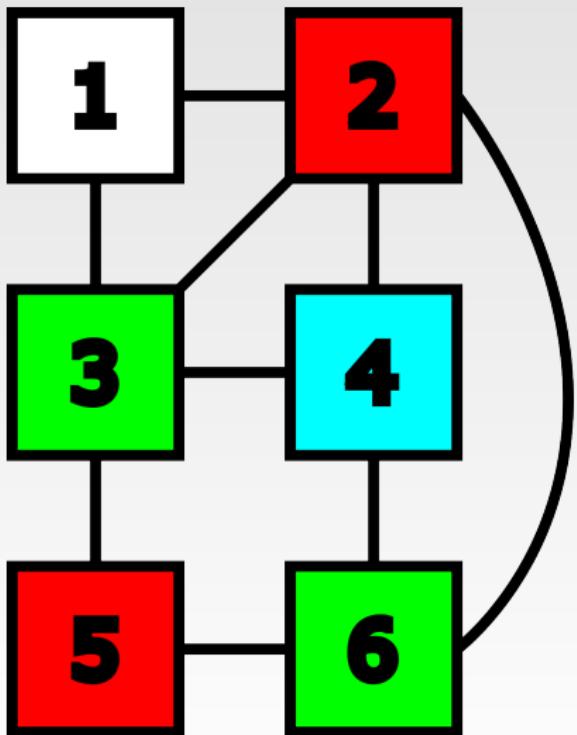
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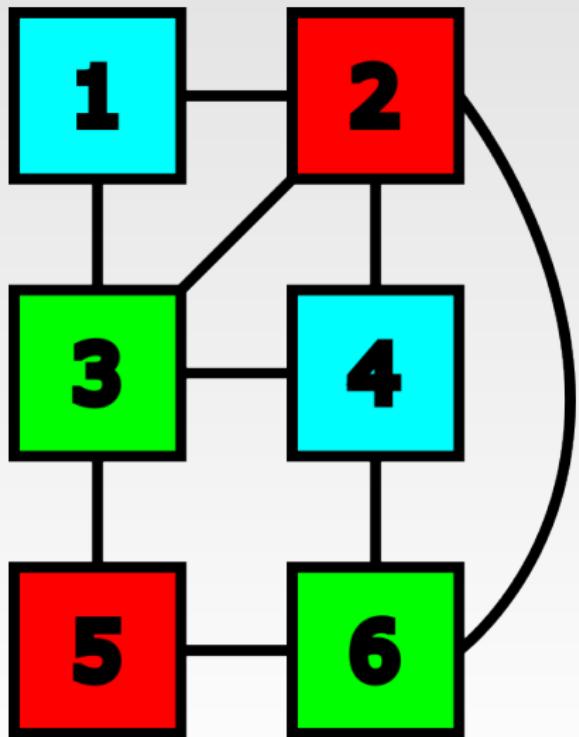
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conflicts:

(R → 2)
(G → 2)
(B → 0)

GC with HC + MCH search



conflicts = []

choices = [0.44, 0.81, 0.76 0.88]