

## 1-.Theoretical/Kernel density function on a histogram

(Example 1.1-Exercises\_Bank)

### Histogram:

```
hist( data, breaks = whatever, xlab = "", ylab = "", main = "",
      prob = TRUE)
```

### How to plot theoretical density function on a histogram:

```
data = r... (...)
sequence = seq( min(data), max(data), length = length(data))
y.values = d...(sequence,...)
lines(sequence, y.values, lwd = , col = )
```

**d** - Density  
**r** - Realizations  
**p** - probability  
**q** - quantile

**Ex)**

```
data = rexp(1000, rate = 1/2)
sequence = seq( min(data), max(data), length = length(data))
y.values = dexp(sequence, rate = 1/2)
# Note: seq can have the parameter by= ...
```

### How to plot the Kernel Density Function on a histogram:

```
lines( density(data, bw = value),
      lwd = 2, col = "red")
```

→ Different ways for bw:

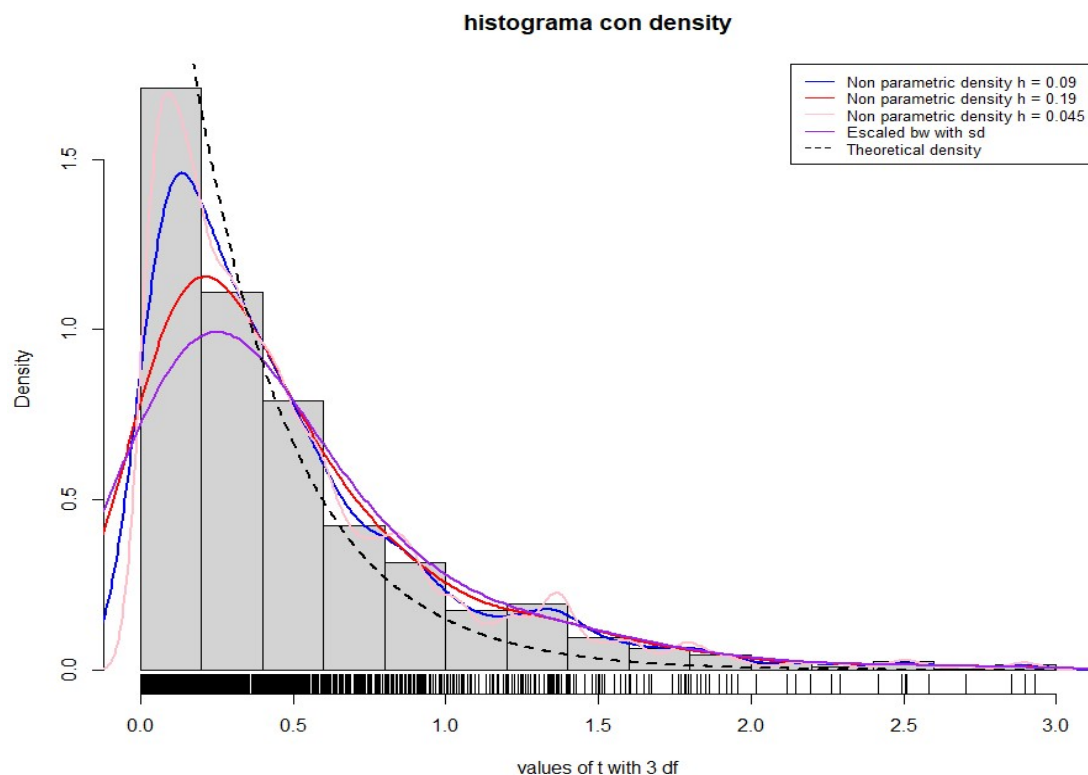
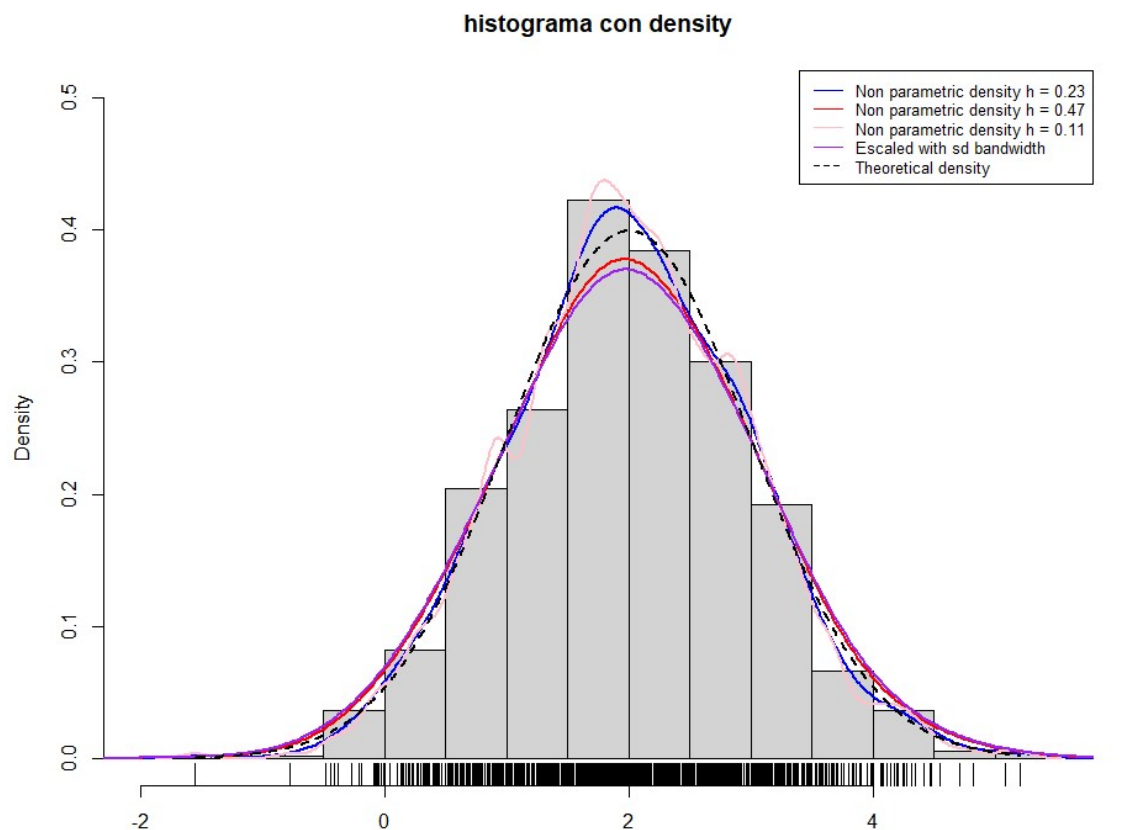
```
fx = density(data)
1-. density(data, bw = fx$bw*2)
2-. density(data, bw = fx$bw*0.5)
3-. density(data, bw = sd(data)/2)
```

**Note:** more bw smoother, less bw squigglier..  
(Check Exercise 3 Chapter 1)

### How to add a legend

```
legend( "position_legend",
      legend = c(names_in_legend),
      col = c(color_of_lines),
      lty = c(lines_types),
      cex = size_legend)
```

**Note:** Remember KDE is worse for distrubution like the Exponential(picture 2). That's why the exponential converges to infinity when it tends to 0. Conversely, it works very good for function such as normal (picture 1).



## 1-. Montecarlo:

### Montecarlo Integral:

$$\int_a^b f(x)dx$$

```
1-. realizations = runif(M, a , b)
2-. We evaluate these realizations
for (i in 1:M){
    sum = 0
    sum = sum + f(realizations[i])
}
```

**Montecarlo:** we know ahead of calculating anything the underlying distribution of the data.

Basic Montecarlo Example:

```
M = 1000
storage = numeric(M) # Storing results for each montecarlo iteration
for (i in 1:M) {
    # We need to generate different noise in each iteration
    noise = rnorm(1000, mean = 10, sd = 2)
    # We add that noise to whatever, for example
    Y = true_theta*x + noise
    # And now we calculate what we are interested in...
    ...
}
```

**Note:** remember Montecarlo is based on CLT (Central Limit Theorem). So that, the more M or the more N we have the better our estimation will be. (Check exercise 3 b) 2019)

Moreover, if we are trying to estimate the sd of a distribution  
 $Sd(storage) = sd(distribution) / \sqrt{N}$  **(CLT)** (check 02\_Rscrip\_L14)  
(We should know ahead of calculating anything sd of the distribution)

### How to make a good boxplot

```
boxplot( data_1, data_2,... ,  
         names = c("name_data_1", "name_data_2", ...),  
         col = c("col_data_1","col:data_2",...),  
         ylab = "",  
         xlab = "",  
         main = "")
```

### Statistics of interest for Montecarlo

- 1-. **Bias:** estimated value - real value
- 2-. **Percentage of bias:** (estimated value - real value) / real value
- 3-. **Variance/sd:** var(storage) or sd(storage)
- 4-. **MSE:** Bias<sup>2</sup> + Variance or mean( (estimated - real)<sup>2</sup> )

### Using abline

```
abline(h = horizontal_line, v = vertical_line, lwd = 2, col = "red")
```

### Storages variables

- 1-. storage = numeric(K)
- 2-. Storage = matrix(NA, nrow = nrow, ncol = ncol)

## Non-parametric confidence interval

Ex) for a 95%

```
quantile(data, prob = c(0.025, 0.975))
```

**2-. Bootstrap:** We learn from the data without assuming an underlying distribution.

Bootstrap **relies on** the assumption that the sample appropriately represents the underlying distribution.

Bootstrap **takes an average of 63.4%** of the data in each iteration.

Example of an easy bootstrap:

```
B = 100
storage = numeric(B) or matrix(NA, nrow = nrow, ncol = ncol)
n = nrow(data)
for (b in 1:B){
  # We are generating a sample WITH REPLACEMENT
  temporal.index = sample(1:n, n, replace = TRUE)
  # We use the indices now..
  temporal.data = data[temporal.index,]
  # We calculate whatever we wanted now...
  ...
}
```

**Caution:** We generate the indices just ONCE in each iteration

**Useful command if they are asking for lm (inside the loop)**

```
temp.lm = lm(y ~ x , data = dat, subset = temp.index)
```

**Function apply**

```
apply(whatever, 2(columns) or 1(rows), mean/sd/median...)
```

## Statistics of interest for Bootstrap

- 1-. **Bias:** `estimated value - value (taking all data)`
- 2-. **Percentage of bias:** `(estimated value - value_all_data) / value_all_data`
- 3-. **Variance/sd:** `var(storage) or sd(storage)`
- 4-. **MSE:** `Bias^2 + Variance or mean( (estimated - real)^2 )`

## Bootstrap confidence intervals

### ♦ Naïve or Non-Parametric interval:

$$(q_L, q_M) = \text{quantile}(\text{storage}, c(0.025, 0.975)) - 95\%$$

### ♦ Studentized CI

$$\text{Bootstrap\_estimate} \pm t_{N-1, 1-\alpha/2} * se(\text{bootstrap\_estimate})$$

### ♦ Bootstrap CI

$$(2 * \text{value}_{all\_data} - q_M, \quad 2 * \text{value}_{all\_data} - q_L)$$

(check exercise 3 part c) Assignment 1)

### 3-. Cross Validation:

1-. **LOO:** using as many folds as your data's rows has

- ◆ We use only one point for testing in each iteration and n-1 points for training.
- ◆ We are OVERFITTING
- ◆ Each point is tested just once.

2-. **K-FOLD CV: (most important)**

- ◆ We have k-folds of the same lengths
- ◆ Each point is just tested once
- ◆ The smaller sample, the smaller k-fold
- ◆ We'd like to have 70% training 30% testing

An easy K-fold Cross Validation

```
n = nrow(data)
```

**Shuffle the data**

```
data = data[sample(1:n, n, replace = F),]
```

**Number of folds**

```
K = 10
```

```
folds = cut(1:n, K, labels = F)
```

```
storage = numeric/matrix...
```

```
# Loop all over folds
```

```
for (k in 1:K){
```

```
  train.set = which(folds != k)
```

```
  test.set = which(folds == k)
```

```
  # And now we make whatever...
```

```
  # But usually we fit a model with the training data and we check  
  errors with the test set (predictions...)
```

### 3-. Repeated K-fold CV:

An example is as follows:

```
n = nrow(data)
R = 10 # repetitions
K = 10 # Number of folds
folds = cut(1:n, K, labels = F) # folds
storages =...

# First loop
for (r in 1:R){
  # Shuffle the data en each repetition
  Data = data[sample(1:n, n, replace = F),]
  for (k in 1:K){
    train.set = which(folds != k)
    test.set = which(folds == k)

    # And now we make whatever...

    # But usually we fit a model with the training data and we
    check errors with the test set (predictions...)

    # To store something changes
    storage[k + (r-1)*K] = whatever...

    (Check exercise 3.7 Exercises Bank)
```

### 4-.Out-of-Bag Bootstrap:

Since in bootstrap we are generally taking 63.4% of the data. We will use 63.4 training set and the remaining for test.

(Example 03\_Out\_of\_Bag\_Boots\_Kfold - Chapter 03)



## **1-. Polynomial Regression**

We are constructing here a polynomial with ideally (N-1) degrees

**R code:**

```
polynomial = lm(y ~ x + I(x^2) + ... + I(x^r))
```

**Plotting it**

```
lines(x, fitted(polynomial), ...) # it has fitted values
```

**Predicting with the polynomial**

We use the coefficients

```
cc = coef(polynomial)
```

```
new = seq(min, max , length = 1)
```

```
y.pred = cc[1] + cc[2]*new + cc[3]*new^2 + ... + cc[r+1]*new^r
```

## **2-. NLS**

**R code:**

```
model.nls = nls(y ~ formula,
```

```
      start = list(a = a1, b = b1, ...)) # Parameters involved in the  
formula
```

Formula ex:

```
y ~ a + b*exp(c*x)
```

```
y ~ log(a*b)/c
```

**How to plot it**

```
1-. lines(x, fitted(nls.model),...)
2-. curve(coefficients*x, ...)
```

### **Predict with it**

We use the coefficients

```
cc = coef(nls.model)
new = seq(min, max , length = 1)
y.pred = coefficients*x
```

### **3-. OPTIM**

(Example in 02\_Optim.R - Chapters)

It should have three functions associated:

1. **Model:** it will have the expression of your model.

Ex: (for a model  $y \sim \exp(\theta x)$ )

```
model <- function(x, theta){
  # Here if we had more than one parameter we could use
  # a = theta[1]
  # b = theta[2]
  return(theta*x)
}
```

2. **Criterion:** it will have the criterion to minimize such as MSE, RMSE or whatever...

**Important:** this function **must have theta as 1st parameter and return a single value**

Ex:

```
crit <- function(theta,x,y){
  # RSS in this case...
  return( sum( (y-model(x,theta))^2 )
}
```

3. **Optim:** we use optim function

Ex:

```
(optim.out <- optim(par=c(3), fn=crit, x=x, y=y,
                    method="L-BFGS-B",
                    lower=c(0.01), upper=c(3.05)))
```

**Note:** par could have been **par = c(theta\_1, theta\_2, ...)**, as many parameters as we have.

(See an example with more than one parameter in *Exercise-11 Shiny Apps*)

**Result:** we can obtain the estimations for the parameters using

**optim.out\$par**

**Plot it**

Since we have the coefficients we can use curve

```
curve(expression using par coefficients, lwd = ..., col = "")
```

## **4-. Grid Search**

(Example 03\_02\_Grid\_Search - Chapter 03)

In this scenario we are going to build a grid and then we are gonna evaluate or criterion to see which point in the grid **has the minimum value associated**.

**R Code:**

**2-D grid search:** when we have to optimize two parameters (i.e a and b)

```
L = length
```

```
a.grid = seq(min_value, max_value, length=L)
```

```
b.grid = seq(min_value, max_value, length=L)
```

```

# Storage
crt = matrix( NA , nrow = L, ncol = L)

# Loop all over the grid
for(i in 1:L){
  for(j in 1:L){
    crit[i,j] = crit(c(a.grid[i],a.grid[j], x, y)
  }
}

# We find the minimum
ij.best = which.min(crit.values)
ij.best = arrayInd(ij.best, .dim=dim(crt))

# grid search solutions:
a.best = a.grid[ij.best[1]]
b.best = b.grid[ij.best[2]]

# 3-D Plot grid search
persp(a.grid, b.grid, crt, col = "..", theta = angle)
contour(a.grid, b.grid, crt)

```

**Note:** this grid search is not only useful with optim it **can be used for splines** as well...

(Example 02\_2018\_2019 - Winter 2018)

**5-. Regularization:** they are techniques to reduce the overfitting of glm/lm. (i.e. they will increase a little the train\_error but will reduce test\_error)

(Exercise 07\_Exercise.R Exercises Bank Chapter 3)

We are going to stand out **three regularization techniques.**

**R Code FOR ALL OF THEM:**

They **DO NOT HAVE FITTED VALUES**

```
library(glmnet)
```

**CAUTION:** all of these three model requires **x (predictors) TO BE A MATIRX**

```
xm = as.matrix(x)
```

**We can tune the parameter lamda by grid search or using CV:**

```
cv.l = cv.glmnet(xm[i.train,],y[i.train],grouped=FALSE)
```

**Plot them**

They have coefficients so go ahead with them with curve

**Calculate training errors (since they do no have fitted values)**

```
yh.r = predict(lasso/ridge/elastic ,newx=xm[train.set,])
```

**Predict with them**

```
yh.p = predict( lasso/ridge/elastic , newx = xm[-train.set,])
```

**1-. Ridge**

$$J_1(\theta) = \sum_{i=1}^n (Y_i - \theta_0 - \theta_1 X_{1,i} - \dots - \theta_p X_{p,i})^2 + \lambda \sum_{j=1}^p \theta_j^2$$

This technique **does not drop from the model any variables.**

**R Code:**

```
ridge = glmnet(xm[train.set], y[train.set] ,
               lambda=lam$lambda.min,
               alpha = 0)
```

## 2-. LASSO

$$J_2(\theta) = \sum_{i=1}^n (Y_i - \theta_0 - \theta_1 X_{1,i} - \dots - \theta_p X_{p,i})^2 + \lambda \sum_{j=1}^p |\theta_j|$$

This technique is **ABLE TO RULE OUT VARIABLES FROM THE MODEL.**

**R Code:**

```
lasso = glmnet(xm[train.set], y[train.set] ,
               lambda=lam$lambda.min,
               alpha = 1 # it is the default value)
```

## 3-. Elastic Net

$$J_3(\theta) = \sum_{i=1}^n (Y_i - \theta_0 - \theta_1 X_{1,i} - \dots - \theta_p X_{p,i})^2 + \lambda_1 \sum_{j=1}^p \theta_j^2 + \lambda_2 \sum_{j=1}^p |\theta_j|$$

This technique **is capable to drop variables from the model.**

**Is less strict than LASSO**

**R Code:**

```
elastic = glmnet(xm[train.set], y[train.set] ,
                 lambda=lam$lambda.min,
                 alpha = values between 0 and 1)
```

In this chapter we are trying to estimate the underlying distribution. So all the techniques are **NON-PARAMETRIC**.

These models **WON'T HAVE COEFFICIENTS** since we are estimating the underlying distribution...

## 1-. Local Polynomial Regression

Although both of them has the capability of predict, **their predictions will be PLAIN** and so we would consider Splines instead. (i.e. their prediction **are far away from reality**)

*(03\_B-Splines\_P-Splines (and predicting from polynomial regression).R)*

### Lowess (1 vs 1)

**CAUTION:** lowess sorts the x values

It has fitted values `lw$y`

**R code:**

```
lw = lowess(x, y)
```

**Plot it**

```
# Remember that lowess sorts the x values...
```

```
lines(sort(x), lw$y # fitted values, col='red', lwd=3)
```

**Predict with lowess**

```
# We need to use approx since lowess is not capable to predict values outside its range
```

**Interpolation**

```
pred.lw = approx(lw$x, lw$y, xout=newx, rule=2)$y
```

(don't care about warnings)

## Loess (1 vs many)

**CAUTION:** check output values are in the same order as input values

```
lo$x - x ; lo$y - y ; # It should give u all 0s
```

It has fitted values `lo$fitted`

R code:

```
lo = loess(y ~ x1 + x2 + ... + x_n, span = value, degree = degree)
```

### Span

By 0 to jittery

0.5 suitable

1 to smooth

Plot it

```
# Remember that lowess sorts the x values...
```

```
points(x, lo$fitted, col='navy', pch=15)
```

**Predict with loess (Important)**

**Interpolation**

```
pred.low = approx(lo$x, lo$fitted, xout=newx, rule=2)$y
```

(don't care about warnings)

**Note:** we could have used `for loess predict`

```
pred.lo = predict(lo, newdata=data.frame(x=newx))
```



## 2-. Splines

They are **very common** when it comes to predict values outside our **predictors' range** such as temporal series... . Since their **predictions are more realistic** than the local polynomial.

(Check that difference in: *03\_B-Splines\_P-Splines (and predicting from polynomial regression).R* )

There are mainly 2 types of splines: **B and P Splines**

### B-Splines

Here is a cubic B-Spline with 3+J knots.

$$S(x) = \beta_0 + \beta_1 x + \beta_2 x^2 + \beta_3 x^3 + \sum_{j=1}^J \alpha_j (x - x_j)^3 +$$

**Total knots = degree of the spline + internal knots**

**R Code**

```
library(splines)
```

**Process:**

**1-. Set the B Spline (basis)**

```
BM = bs(x, knots = c(knot_1, knot_2,...), df = degree_Bspline # default 3)
```

With the **knots** we **can control the tailance**.

**Note:** usually the **knots are the quantiles of x**

```
Ex) knots = quantile(x, prob = c(0.25,0.5,0.75))
```

**Plot** the basis

```
matplot(x,BM,xlab="x",ylab="Spline basis",main="total_knots-basis", t
= 'b')
```

## 2-Fit a linear model $y \sim BM$

```
lm.out = lm(mM~BM) # of course it has fitted values
coef(lm.out) # Will have as many coefficients as knots has
```

### Plot it

```
points(x,fitted(lm.out),t='l',col="red", lwd = 3)
```

### Predict with it

```
pred = predict(lm.out, newdata = data_frame)
```

## P-splines

They give us even a better tailance than B-Splines.

### R Code

#### They have fitted values

```
# Smooth spline with spar set with CV
```

```
p1 = smooth.spline(age, mF, cv = TRUE, df = degrees_freedom)
```

```
par = p1$spar
```

```
p2 = smooth.spline(age, mF, spar = par/2) # different spar
```

**CAUTION:** We need to check that they have the same order than x.

```
p1$x - x # should give u all 0s
```

**If not** we just need to **sort x**

**Plot it**

```
points(x, fitted(P.spline), pch=15, col='navy')
```

**Predicting**

```
pred.pspline = predict(P.spline, x=newx)
```

## **Other models**

**lm / glm**

The unique difference between both is that **lm uses least squares** and **glm uses maximum likelihood**.

**Predict**

```
pred = predict(lm/glm.model , newdata = should_be_dataframe)
```