view_frames Result

Recorded at time: 1765394032.5632453

map

Broadcaster: default_authority
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 6710.4
Oldest transform: 6705.5

mi_robot/odom

Broadcaster: default_authority
Average rate: 50.204
Buffer length: 4.9
Most recent transform: 6709.992
Oldest transform: 6705.092

mi_robot/robot_root

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_root

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

base_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

lidar_link

Broadcaster: default_authority
Average rate: 10.208
Buffer length: 4.8
Most recent transform: 6709.913
Oldest transform: 6705.113

wheel_fl_link

Broadcaster: default_authority
Average rate: 10.208
Buffer length: 4.8
Most recent transform: 6709.913
Oldest transform: 6705.113

wheel_fr_link

Broadcaster: default_authority
Average rate: 10.208
Buffer length: 4.8
Most recent transform: 6709.913
Oldest transform: 6705.113

wheel_rl_link

Broadcaster: default_authority
Average rate: 10.208
Buffer length: 4.8
Most recent transform: 6709.913
Oldest transform: 6705.113

wheel_rr_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

imu_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

sensor_back_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

sensor_front_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

lidar_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

mi_robot/robot_root/lidar_sensor