Sensors

**External Communication**
Xbox controller?
Voicebox?

**Navigation**
Nav Management
A* Pathfinding
Random Goal Navigation
Nav 2

**SLAM**
Slam Management
Map Change Detector
Maps
SLAM Toolbox
Follow Colorspot Algorithm

**Random Explorer**
Random Explorer

**Obstacle Avoidance**
Abstandsmessung mit full stop

**Hardware**
Hardware Control

**Services**
Robot Control

**Actions**
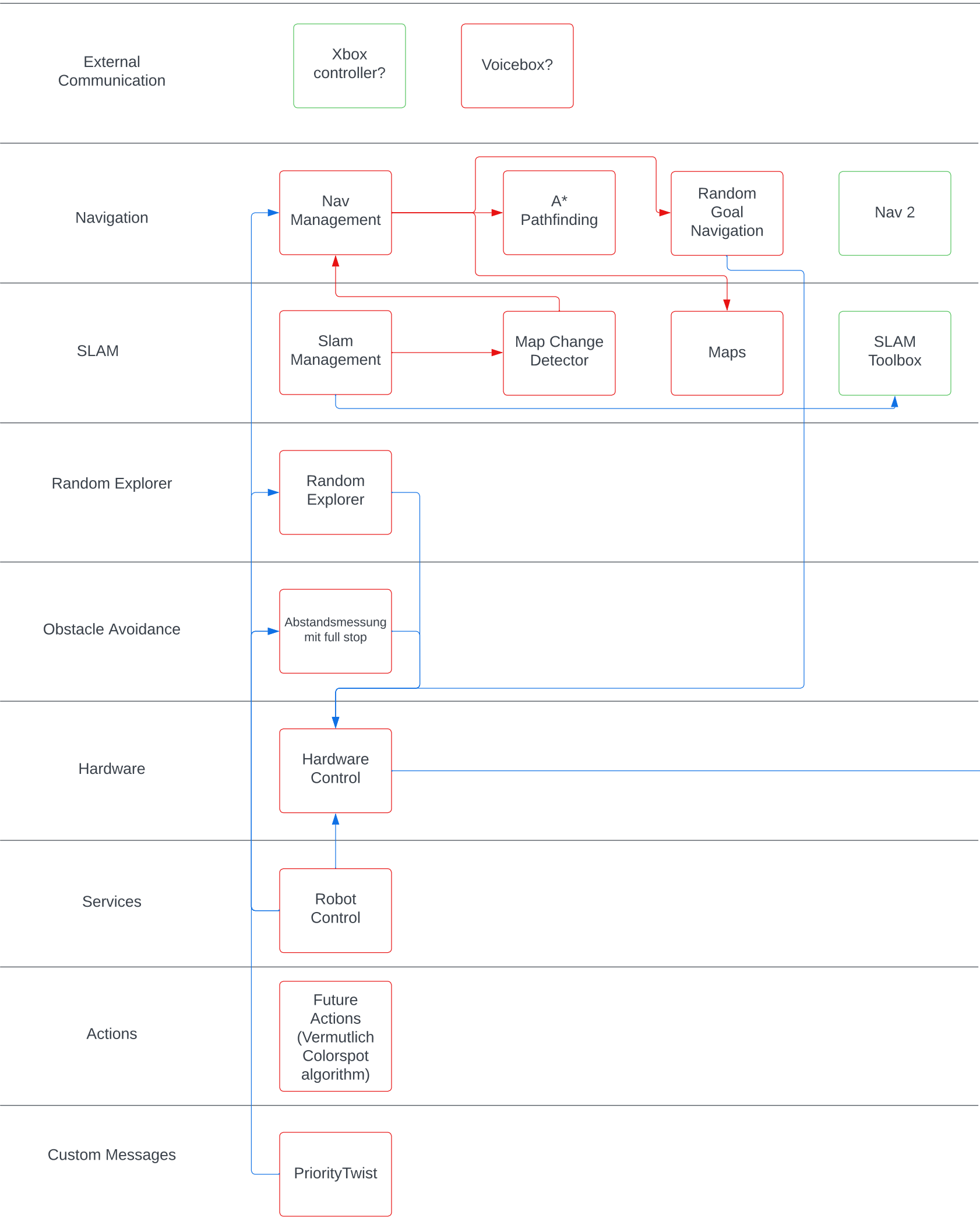Future Actions (Vermutlich Colorspot algorithm)

**Custom Messages**
PriorityTwist

ROS packages

Self

Actuators