# Assignment 0

#### Assignment objective

The objective of this assignment is to learn:

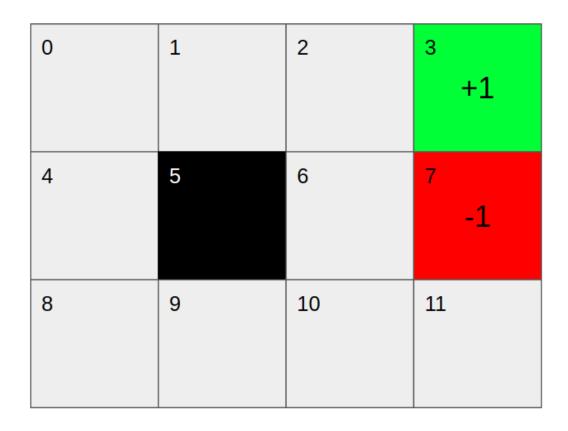
- o Understanding of a given RL problem parameters.
- o The implementation of the environment.
- o The implementation of Value iteration and q values.

### Assignment Rules

- Due date is 19/3.
- The assignment will be delivered in groups of 4 5 students.
- Your file name should be 1ID\_2ID\_3ID\_4ID.py
- Any cheats will got zero.

### • Assignment Description

Implement value iteration and q-values methods on the Grid World problem.



- 1. Build the Environment.
  - \* Number of states is 12 (each grid represent state)
  - \* Number of actions is 4 (Up, Down, Left, Right)
  - \* Reward of grid 3 is 1, for grid 7 is -1 and grid 5 is a wall
  - \* Discount factor (Gamma) = 0.9, noise = 0.2, Num of iterations = 100
- 2. For every iteration print the Grid Values

# Example of the output:

```
| -0.01 | -0.01 | 0.782 | +1 |
| -0.01 | WALL| -0.01 | -1 |
| -0.01 | -0.01 | -0.01 |
```

3. After the model converges or go through all iterations extract the policy and print it

## Example of the output:

Tip: for building the environment you could use  $3*4\ 2d$  array and each state is represented by the index of that array (state  $1 \Rightarrow [0][0]$ , state  $2 \Rightarrow [0][1]$  and so on), and for the actions you could write it as Actions =  $[(1, 0), (0, -1), (-1, 0), (0, 1)] \Rightarrow$  Down, Left, Up, Right then the next state when taking action a can be obtained by adding the current state indexes and the action values Ex. We are in state [0][1] and we go down which is (1,0) so the new state will be  $[0+1][1+0] \Rightarrow [1][1]$ . (You can use this implementation or do it your way)

Hint: Any trial will be appreciated so please try.