# **Chapter-05 Roots of Equations**



Bisection Method
Fixed Point Method
Newton-Raphson Method
Secant Method
Module Scipy.optimize

$$f(x) = 0$$

if equation is nonlinear, we cannot find analytical solution.

Question # 3 [Marks = 4+4]

- Apply appropriate theorem to test the existence of a root for each of the following functions.
  - (a)  $f_1(x) = \ln(x) + e^x$  in the interval [-6, 6]
  - (b)  $f_2(x) = e^x + \cos(x) x^3$  in the interval [-4, 4]

#### Solution:

We will apply the **Intermediate Value Theorem (IVT)**. Two conditions must be satisfied: 1. The function must be continuous on the given interval. 2. There must be a sign change between the function values at the endpoints of the interval.

(a) For  $f_1(x) = \ln(x) + e^x$  in the interval [-6, 6]:

**Continuity:**  $-\ln(x)$  is only defined for x > 0, so  $f_1(x)$  is not continuous in the interval [-6, 6] because it includes negative values where the logarithm is undefined.

**Conclusion:** - Since the function is not continuous in this interval, IVT cannot be applied, and we cannot test for a root in the interval [-6, 6].

(b) For  $f_2(x) = e^x + \cos(x) - x^3$  in the interval [-4, 4]:

**Continuity:** -  $f_2(x)$  is the sum of continuous functions  $(e^x, \cos(x), \text{ and } x^3)$ , so it is continuous over the entire interval [-4, 4].

Sign Change: - At x = -4:

$$f_2(-4) = e^{-4} + \cos(-4) - (-4)^3 \approx 0.0183 - 0.6536 + 64 = 63.3647 > 0$$

- At x = 4:

$$f_2(4) = e^4 + \cos(4) - 4^3 \approx 54.5981 - 0.6536 - 64 = -9.2045 < 0$$

**Conclusion:** - Since  $f_2(-4) > 0$  and  $f_2(4) < 0$ , there is a sign change. Therefore, by the IVT, there exists at least one root in the interval (-4,4).

CLO-3 Implement a numerical method in Python/Numpy/Scipy.

### **▼** Bisection Method

based on Bolzano's Intermediate Value Theorem

If a function f(x) satisfies the following conditions:

- f is continuous in [a,b]
- $f(a) \cdot f(b) < 0$

then there exists at least one solution  $x^*\in(a,b)$  of the equation f(x)=0 This means that the function changes sign in the interval

```
[a,b] and \mathrm{sign}(f(a)) 
eq \mathrm{sign}(f(b))
```

The **Bisection method** is used to find a very small interval [a,b] that contains the root of the equation f(x)=0 and the approximate solution is defined to be the midpoint of that interval (a+b)/2

```
def bisection(f, a, b, tol = 1.e-6):
   iteration = 0 #initialize counter iteration
   if (f(a) * f(b) < 0.0): # check if there is a root
        while ((b-a) > tol): # check if the end-points converge
            iteration = iteration + 1
            x = (a + b)/2
            if (f(a) * f(x) < 0.0):
                b = x
            elif (f(x) * f(b) < 0.0):
                a = x
            else:
                break
            print(iteration, x)
   else:
        print('failure')
    return x
# returns the midpoint of the final interval
```

 $\ln x + x = 0$  in the inteval [0.1, 1]

```
import numpy as np

def f(x):
    y = np.log(x) + x
    return y

a = 0.1
b = 1.0
tol = 1.e-4
x = bisection(f, a, b, tol)
print('The aproximate solution is: ', x)
print('And the error is: ', f(x))
```

**Output:** 

```
10.55
```

2 0.775

3 0.6625000000000001

4 0.6062500000000001

5 0.578125

6 0.5640625

7 0.57109375

8 0.567578125

9 0.5658203125000001

10 0.5666992187500001

11 0.567138671875

12 0.5673583984375

13 0.56724853515625

14 0.567193603515625

The approximate solution is: 0.567193603515625

And the error is: 0.0001390223881425623

Evaluating the value  $f(x^*)$  we observe that the approximate solution satisfies the equation f(x)=0 with 4 decimal digit is correct. This is because we chose tole 1.e-4. Try using smaller values of the variable tole.

We also observe that to achieve the requested accuracy the method required 14 iterations

#### **Experimental Convergence Rate**

In order to estimate the convergence rate, we compute the errors for three subsequent iterations, let's say  $e_1, e_2, e_3$ . Then we assume that

$$|e_2| = C|e_1|^r$$

$$|e_3| = C|e_2|^r$$

Dividing the previous equations we have

$$\frac{|e_2|}{|e_3|} = \left(\frac{|e_1|}{|e_2|}\right)^r$$

We then we solve for n to obtain the formula

$$r=rac{\lograc{|e_2|}{|e_3|}}{\lograc{|e_1|}{|e_2|}}$$

We modify the bisection function in order to compute the convergence rates numerically, and we try using the same problem as before.

```
def bisection_rates(f, a, b, tol = 1.e-6):
   iteration = 0
   if (f(a) * f(b) < 0.0):
      e1 = abs(b-a) #initialize e1 arbitrarily
      e2 = e1*2 #initialize e2 arbitrarily
      e3 = e1 #initialize e3 arbitrarily</pre>
```

```
while ((b-a)>tol):
              e1 = e2
              e2 = e3
              iteration = iteration + 1
              x = (a + b)/2
              if (f(a) * f(x) < 0.0):
                   b = x
              elif (f(x) * f(b) < 0.0):
                   a = x
              else:
                   break
              e3 = np.abs(b-a)
              rate = np.log(e2/e3)/np.log(e1/e2)
              print('iteration = ', iteration, 'rate =', rate)
      else:
           print('failure')
      return x
  def f(x):
     y = np.log(x) + x
      return y
 a = 0.1
  b = 1.0
  tol = 1.e-4
 x = bisection_rates(f, a, b, tol)
  print('The approximate solution x is: ', x)
 print('And the value f(x) is: ', f(x))
iteration = 1 rate = 1.0000000000000002
iteration = 3 \text{ rate} = 0.999999999999993
iteration = 4 rate = 1.0000000000000007
iteration = 5 rate = 1.00000000000000029
iteration = 6 rate = 0.999999999999911
iteration = 7 \text{ rate} = 1.0000000000000115}
iteration = 8 rate = 0.999999999999657
iteration = 9 rate = 1.000000000000082
iteration = 10 rate = 0.99999999999545
iteration = 11 rate = 0.999999999998177
iteration = 12 rate = 1.000000000001823
iteration = 13 rate = 1.0000000000007292
iteration = 14 rate = 0.999999999992709
The approximate solution x is: 0.567193603515625
And the value f(x) is: 0.0001390223881425623
```

Verify theoretically that for the previous example we need 14 iterations.

#### **Manual Method:**

	а	b	С	f(a)	f(b)	f(C)
1	0.1	1	0.55	-2.202585093	1	-0.047837001
2	0.55	1	0.775	-0.047837001	1	0.52010775
3	0.55	0.775	0.6625	-0.047837001	0.52010775	0.250765279
4	0.55	0.6625	0.60625	-0.047837001	0.250765279	0.105787163
5	0.55	0.60625	0.578125	-0.047837001	0.105787163	0.030159829
6	0.55	0.578125	0.5640625	-0.047837001	0.030159829	-0.008527718
7	0.5640625	0.578125	0.57109375	-0.008527718	0.030159829	0.010891853
8	0.5640625	0.57109375	0.567578125	-0.008527718	0.010891853	0.001201251
9	0.5640625	0.567578125	0.565820313	-0.008527718	0.001201251	-0.003658406
10	0.565820313	0.567578125	0.566699219	-0.003658406	0.001201251	-0.001227375
11	0.566699219	0.567578125	0.567138672	-0.001227375	0.001201251	-0.000012762
12	0.567138672	0.567578125	0.567358399	-0.000012762	0.001201251	0.000594321
13	0.567138672	0.567358399	0.567248536	-0.000012762	0.000594321	0.0002908
14	0.567138672	0.567248536	0.567193604	-0.000012762	0.0002908	0.000139024

So the approximate solution value is c and the error is f(c)



→ how to decide how many iterations? when f(c) < tolerance</p>

## **▼** Fixed Point Method

Given an interval, bisection is guaranteed to converge to a root However bisection uses almost no information about f(x) beyond its sign at a point

**Basic Idea**: Every equation of the form f(x)=0 can be written equivalently in the form x=g(x) in many different ways

	Date20_ MTWTFS
f(x)=cos(x) + x3-0.5	
$f(x) = (65(x) + x^3 - 0.5)$ = -5mx + 3x <sup>2</sup>	4
f(n)=0 (n) + n3 -0.5=0	
(05(n) + n, -0-2=0	
f(-5) = -125.216.	
f(5) = 124.78	
n3 = 0 -5 - Wh.	
	and the second second
f(x)= x3-x2-3x-3	[1,3] a h
f(x)=0 has 3 forms	
$x^3 = x^2 + 3x + 3$ $x^2 = x^3 - 3x - 3$	x= x3-x2-3
$x^{3} = x^{2} + 3x + 3$ $x^{2} = x^{3} - 3x - 3$ $x = 3 + 3x + 3$	3
Find deviatives -212	
$q(1/x) = \frac{1}{3} \frac{3(2x-3)(x^2x^3x+3)}{2}$	
$\frac{q^{1}(x)=\frac{1}{2}(3x^{2}-3)(x^{3}-3x-3)}{2}$	
	- 201
$\frac{q'(x)=1(3x^2-2x)}{3}$	
	1
9,'(1.5) = 2+36 0 / selecte	<u>o.                                    </u>
9,1(1.5) = 2-408 Math mux	
9 ((1.5) = 1.25	
	1987
TICK* INDUSTRIES PRIVATE LIMITED	Page #

```
def fixedpoint(g, x0, tol = 1.e-6, maxit = 100):
   \# g = the function g(x)
   # x0 = the initial guess of the fixed point x=g(x)
   # tol = tolerance for the absolute error
            of two subsequent approximations
   # maxit = maximum number of iterations allowed
   error = 1.0
   iteration = 0
   xk = x0
   while (error > tol and iteration < maxit):</pre>
       iteration = iteration + 1
       error = xk
       xk = g(xk)
        error = np.abs(error - xk)
        print ('iteration =', iteration, ', x =', xk)
   return xk
```

```
def f(x):
   y = x^*2-x-1.0
    return y
def g(x):
   y = np.sqrt(x+1.0)
    return v
tol = 1.e-4
maxit = 50
x0 = 0.0
x = fixedpoint(g, x0, tol, maxit)
print('The approximate solution x is: ', x)
print('And the value f(x) is: ', f(x))
#Output
iteration = 1 , x = 1.0
iteration = 2 , x = 1.4142135623730951
iteration = 3 , x = 1.5537739740300374
iteration = 4 , x = 1.5980531824786175
iteration = 5 , x = 1.6118477541252516
iteration = 6 , x = 1.616121206508117
iteration = 7 , x = 1.6174427985273905
iteration = 8 , x = 1.617851290609675
iteration = 9 , x = 1.6179775309347393
iteration = 10 , x = 1.6180165422314876
The approximate solution x is: 1.6180165422314876
And the value f(x) is: -3.9011296748103774e-05
```

## ▼ Newton-Raphson Method

Basic Idea: Given f(x) and f'(x) and and initial guess  $x_0$ , find the root of the tangent line to  $(x_0, f(x_0))$  to find  $x_1 \approx x^*$ . Continue using  $x_1$  to compute  $x_2$ , etc.

Given

 $x_{k_I}$  then the next approximation of the root  $x^*$  defined by Newton's method is:

$$x_{k+1} = x_k - rac{f(x_k)}{f'(x_k)}$$

```
Date_____20__
MTWTFS
     f(x)= enx +
      f((x) = 1
                  t(xx)
                          exx=to1+1=1xe-7+1=160001
                           e86 = 1
             - f(x0)
                ti(xo)
      f(x0)=f(1)= ln1+1=0+1=1
        1(x0)= f((1)= 5
                          ers = 1ers-xx1=11-11=0.5
          x - f(x1)
                           622= XK = 0.2
               Cix)iz
3
      f(x1)=f(112)= ln(0.5) + 112 = -0.19.31.47
      € 1(x1)=f,(115)=1
                      112
               (-0.19314) = 0.564382 err=0.5-0.564382
                                              =-0.064382
 3) X_3 = \chi_2 - f(\chi_2)
                             exx= x, = 0.564382
                f1(x2)
     f(x2) = f(0,664382) = th(0.664382)+ 0,664382
            = -7.641952 X10-3
     f'(x_2) = 1(0.664382 + 1 = 2.771849
     x = 0.564382 - 0.564382 (-7.6419(2x10-3)
                                      2.771849
        = 0.5671389871
                 est= 0.664382 - 0.5671389871 Page#
    OTICK°
                    =-2.7569871 x10-3
```

```
def newton(f, df, x0, tol = 1.e-6, maxit = 100):
   \# f = the function f(x)
   # df = the derivative of f(x)
   \# x0 = the initial guess of the solution
   # tol = tolerance for the absolute error
   # maxit = maximum number of iterations
   err = tol + 1.0
   iteration = 0
   xk = x0
   while (err > tol and iteration < maxit):
        iteration = iteration + 1
        err = xk # store previous approximation to err
        xk = xk - f(xk)/df(xk) # Newton's iteration
        err = np.abs(err - xk) # compute the new error
        print(iteration, xk)
    return xk
def f(x):
   y = np.log(x) + x
   return y
def df(x):
   y = 1.0 / x + 1.0
   return y
tol = 1.e-4
maxit = 50
x0 = 1.0
```

```
x = newton(f, df, x0, tol, maxit)
print('The aproximate solution is: ', x)
print('And the error is: ', f(x))
#Output
1 0.5
2 0.5643823935199818
3 0.5671389877150601
4 0.5671432903993691
The aproximate solution is: 0.5671432903993691
And the error is: -2.877842408821607e-11
```

### **▼** Secant Method

The secant method can be obtained from Newton's method with the approximation of the first derivative

$$f'(x_k)=rac{f(x_k)-f(x_{k-1})}{x_k-x_{k-1}}$$

The new iteration is the defined

Given  $x_k$  and  $x_{k-1}$ 

$$x_{k+1} = x_k - rac{x_k - x_{k-1}}{f(x_k) - f(x_{k-1})} f(x_k)$$

```
def secant(f, x1, x2, tol = 1.e-6, maxit = 100):
   # f = the function f(x)
   \# x1 = an initial guess of the solution
   \# x2 = another initial guess of the solution
   # tol = tolerance for the absolute error
   # maxit = maximum number of iterations
   err = 1.0
   iteration = 0
   while (err > tol and iteration < maxit):
       xk1 = x1
       xk = x2
        iteration = iteration + 1
        err = xk1
        xk1 = xk - (xk-xk1)/(f(xk)-f(xk1))*f(xk)
        err = np.abs(err - xk1)
        x1 = x2
        x2 = xk1
        print(iteration, xk1)
    return xk1
def f(x):
   y = np.log(x) + x
   return y
tol = 1.e-4
maxit = 50
x1 = 1.0
x2 = 2.0
```

```
x = secant(f, x1, x2, tol, maxit)
print('The approximate solution is: ', x)
print('And the error is: ', f(x))

#Output
1  0.40938389085035864
2  0.651575386390747
3  0.5751035382227284
4  0.5667851889083253
5  0.5671448866112347
6  0.5671432907314143
7  0.5671432904097836
The approximate solution is:  0.5671432904097836
And the error is: -6.661338147750939e-16
```

Chapter-05 Roots of Equations

```
MTWTFS
flx)= lnx + x
X1 = 1
X2=2
             (x2) - f(x1
               2.693147181
     0-409383891
          f(x3)-f(x2)
   104 < sasas 1,44n.
  = 0.5671432904097836
                                      Page #
 OTICK
```

## **▼** Module Scipy.optimize

The bisection method is implemented in the function [bisect] of the module [scipy.optimize]

```
import scipy.optimize as spo
def f(x):
    y = np.log(x)+x
    return y
a = 0.1
b = 1.0
tol = 1.e-4
x = spo.bisect(f, a, b, () , tol)
print('The approximate solution x is: ', x)
```

Chapter-05 Roots of Equations 12

```
print('And the value f(x) is: ', f(x))
#Output
The approximate solution x is: 0.567193603515625
And the value f(x) is: 0.0001390223881425623
```

The generic fixed-point method is also implemented in scipy.optimize in the function fixed\_point

```
import scipy.optimize as spo
def f(x):
   y = x^*2-x-1.0
   return y
def g(x):
   y = np.sqrt(x+1.0)
   return y
x0 = 1.0
tol = 1.e-4
maxit = 50
x = spo.fixed_point(g, x0, (), tol, maxit)
print('The approximate solution x is: ', x)
print('And the value f(x) is: ', f(x))
#Output
The approximate solution x is: 1.6180339887498991
And the value f(x) is: 9.547918011776346e-15
```

Both the Newton and Secant methods are implemented in the function newton of scipy.optimize.

```
import scipy.optimize as spo
def f(x):
    y = np.log(x)+x
    return y

def df(x):
    y = 1.0/x+1.0
    return y

x0 = 1.0

x = spo.newton(f, x0, df, tol=1.e-4, maxiter=50)
print('The approximate solution x is: ', x)
print('And the value f(x) is: ', f(x))

#output
The approximate solution x is: 0.5671432903993691
And the value f(x) is: -2.877842408821607e-11
```

In scipy.optimize one can find also a hybrid method that works in a more broader spectrum of problems compared to the previous implementation. This method is implemented in the function fsolve.

```
import scipy.optimize as spo
def f(x):
    y = np.log(x)+x
```

Chapter-05 Roots of Equations 13

```
return y
def df(x):
    y = 1.0/x+1.0
    return y
x0 = 1.0
x = spo.fsolve(f, x0, fprime=df, xtol=1.e-4)
print('The approximate solution x is: ', x)
print('And the value f(x) is: ', f(x))

#output
The approximate solution x is: [0.56714329]
And the value f(x) is: [3.4803842e-09]
```

### **Application in Astrophysics:**

If  $\psi$  is the mean anomaly of the orbit of a plant, then  $\theta$ , the eccentric anomaly, can be computed by solving the fixed point equation

```
\theta = \psi + e \sin \theta
```

where e is the eccentricity of the elliptical orbit.

This equation can be solved seamlessly using the function

fixed\_point Of scipy.optimize.

```
import numpy as np
import scipy.optimize as spo

def g(theta):
    e = 1.e-6
    psi = np.pi/6.0
    return psi+e*np.sin(theta)

theta0 = np.pi/6.0

theta = spo.fixed_point(g, theta0)
print('eccentric anomaly=', theta)

#Output
eccentric anomaly= 0.5235992755987319
```

Knowing the eccentric anomaly can lead to the estimation of the heliocentric distance

```
r=a(1-e\cos\theta) where {f a} is the semi-major axis.
```