# **Predictive Episodic Control**

A predictive version of the neural episodic control models

Exploring the use of temporal abstraction in the context of episodic control.

## **Environment Setup**

Install numpy, pytorch, matplotlib, networkx, scikit-learn

Install jupyter-notebook (We have added a jupyter notebook and its corresponding Colab link).

### Usage

#### Random projection:

python train.py \ --embedding\_type random \ --out\_data\_file ../results/MFEC/MFEC\_rand\_rooms\_mnist\_3knn.npy

#### VAE:

python train.py  $\ --$ embedding\_type VAE  $\ --$ vae\_batch\_size 4  $\ --$ vae\_train\_frames 100000  $\ --$ vae\_epochs 10  $\ --$  Ir 1e-5  $\ --$ vae\_print\_every 100  $\ --$ load\_vae\_from ../weights/VAE/VAE\_rooms\_mnist.pt  $\ --$ out\_data\_f

## SR (DP):

#### SR (TD):

python train.py \ --SR\_gamma 0.99 \ --SR\_batch\_size 64 \ --SR\_train\_frames 1000000 \ --SR\_epochs 200 \ -- SR\_train\_algo TD \ --embedding\_type SR \ --SR\_embedding\_type random \ --n\_hidden 100 \ --lr 0.0001 \ -- SR\_filename ../results/MFEC\_SR/random\_TD\_mnist\_200epochs\_3knn \ --out\_data\_file ../results/MFEC\_SR/MFEC\_SR\_rand\_TD\_rooms\_mnist\_200epochs\_3knn.npy