Results

March 19, 2020

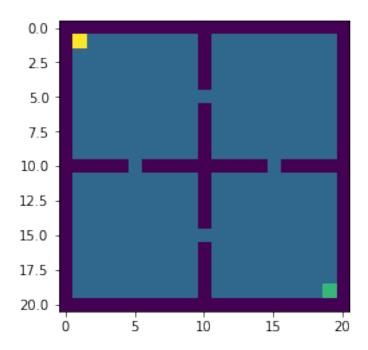
1 Visualize results of experiments

1.0.1 Final figures will be saved in the 'figures' folder

Creating an environment with 9 cells in each room. Each cell is representing a random number from mnist dataset

1.1 State Representation

1.1.1 Figure 2. (left)



1.2 Find true SR with dynamic programming

```
In [52]: # Use this to ensure same order every time
    idx_to_state = {i:state for i,state in enumerate(env.state_dict.keys())}
    state_to_idx = {v:k for k,v in idx_to_state.items()}
```

Build a transition matrix

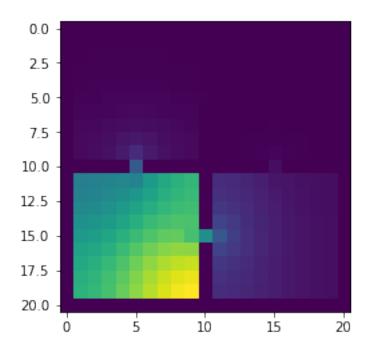
Visualize the transition matrix

```
T_image[x,y] = 0
else:
    idx = state_to_idx[(x,y)]
    T_image[x,y] = T[s_idx,idx]
return T_image
```

Build true SR matrix

1.3 Visualize the true SR representation

1.3.1 Figure 2. (right)



1.4 Loading saved data and visualize results

The running time for our project is ~1 day. Therefore for the sake of visualization we have uploaded the saved weights and data

VAE * Input: mnist image with size 28 X 28 * Output: embedding representation with size 32 X 1 * Upload the trained VAE

```
In [59]: in_channels = 1
        embedding_size = 32
        in_height = 28
        in_width = 28
        vae = VAE(in_channels,embedding_size,in_height,in_width)
        vae.load_state_dict(torch.load('../weights/VAE/VAE_rooms_mnist.pt'))
Out[59]: <All keys matched successfully>
```

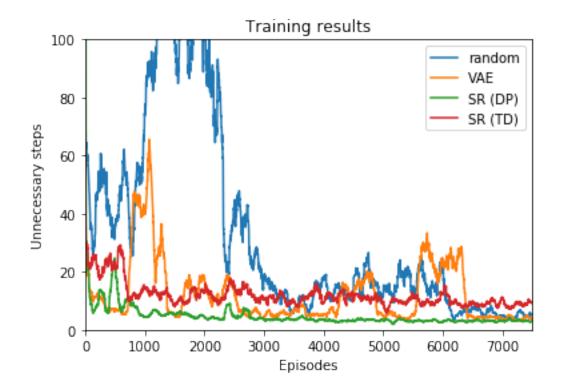
Calulate the state embedding representation using the trained VAE encoder

```
In [60]: n_states = env.n_states
         VAE_reps = np.zeros([n_states,embedding_size])
         VAE_labels = []
         for i,(state,obs) in enumerate(env.state_dict.items()):
             obs = torch.tensor(obs).permute(2,0,1) \#(H, W, C) \rightarrow (C, H, W)
             obs = obs.unsqueeze(0)
             with torch.no_grad():
                 mu, logvar = vae.encoder(obs)
                  state_embedding = torch.cat([mu, logvar],1)
                  state_embedding = state_embedding.squeeze()
                  state_embedding = state_embedding.cpu().numpy()
             VAE_reps[i,:] = state_embedding
             # different label for each room
             if state[0] < room_size + 1 and state[1] < room_size + 1:</pre>
                  label = 0
             elif state[0] > room_size + 1 and state[1] < room_size + 1:</pre>
                 label = 1
             elif state[0] < room_size + 1 and state[1] > room_size + 1:
             elif state[0] > room_size + 1 and state[1] > room_size + 1:
                  label = 3
             else:
                  label = 4
             VAE_labels.append(label)
```

1.5 Forced KNN, 3 neighbors

1.5.1 Figure 3

```
In [61]: rand_3knn = np.load('../results/MFEC/MFEC_rand_rooms_mnist_3knn.npy')
         VAE_3knn = np.load('.../results/MFEC/MFEC_VAE_rooms_mnist_3knn.npy')
         SR_DP_3knn = np.load('../results/MFEC_SR/MFEC_SR_rand_DP_rooms_mnist_3knn.npy')
         SR_TD_3knn = np.load('../results/MFEC_SR/MFEC_SR_rand_TD_rooms_mnist_200epochs_3knn.npy
In [62]: window = 100
         smoothed_rand_3knn = np.convolve(rand_3knn[:,2], np.ones((window,))/window, mode='valid'
         smoothed_VAE_3knn = np.convolve(VAE_3knn[:,2], np.ones((window,))/window, mode='valid')
         smoothed_SR_DP_3knn = np.convolve(SR_DP_3knn[:,2], np.ones((window,))/window, mode='val
         smoothed_SR_TD_3knn = np.convolve(SR_TD_3knn[:,2], np.ones((window,))/window, mode='val
In [63]: plt.plot(smoothed_rand_3knn)
         plt.plot(smoothed_VAE_3knn)
         plt.plot(smoothed_SR_DP_3knn)
         plt.plot(smoothed_SR_TD_3knn)
         plt.title("Training results")
         plt.xlabel("Episodes")
         plt.ylabel("Unnecessary steps")
        plt.xlim([0,7500])
         plt.ylim([0,100])
         plt.legend(["random","VAE","SR (DP)", "SR (TD)"])
         plt.savefig("figures/train_curves.png",bbox_inches = 'tight',pad_inches = 0,dpi=100)
         plt.show()
```



Average number of extra steps throughout training:

```
In [64]: print("Random:", np.mean(rand_3knn[:7500,2]))
         print("VAE:", np.mean(VAE_3knn[:7500,2]))
         print("SR (DP):", np.mean(SR_DP_3knn[:7500,2]))
         print("SR (TD):", np.mean(SR_TD_3knn[:7500,2]))
Random: 35.21786666666666
VAE: 12.92
SR (DP): 8.1637333333333333
SR (TD): 12.6072
   Average number of extra steps in the last 100 episodes
In [65]: print("Random:", np.mean(rand_3knn[7400:7500,2]))
         print("VAE:", np.mean(VAE_3knn[7400:7500,2]))
         print("SR (DP):", np.mean(SR_DP_3knn[7400:7500,2]))
         print("SR (TD):", np.mean(SR_TD_3knn[7400:7500,2]))
Random: 4.3
VAE: 4.46
SR (DP): 3.24
SR (TD): 9.21
```

1.6 Multidimensional scaling plots to visualize representations of each type of embedding

```
In [66]: colors = ['green','blue','red','purple','orange']
```

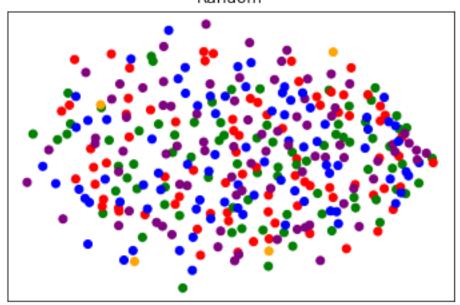
Loading the saved representational results and their corresponding labels

1.7 Visualize Random Representations

1.7.1 Figure 4. (top-left)

```
which='both',
bottom=False,
top=False,
left=False,
labelbottom=False,
labelleft=False)
plt.ticklabel_format(style='plain',useOffset=False)
plt.savefig("figures/mds_rand.png",bbox_inches = 'tight',pad_inches = 0.1,dpi=100)
plt.show()
```

Random

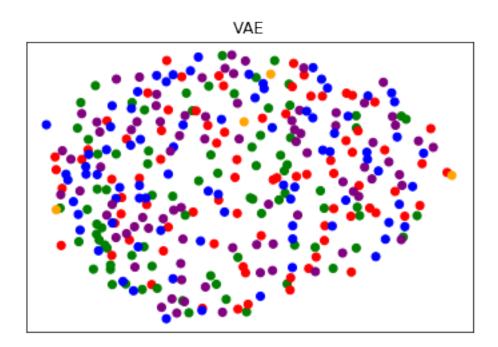


1.8 Visualize VAE Representation

1.8.1 Figure 4. (top-right)

We have represented multidimensional scaling of VAE, random and SR representation

```
left=False,
    labelbottom=False,
    labelleft=False)
plt.ticklabel_format(style='plain',useOffset=False)
plt.savefig("figures/mds_VAE.png",bbox_inches = 'tight',pad_inches = 0.1,dpi=100)
plt.show()
```

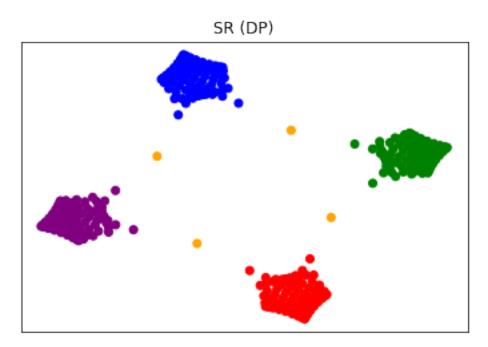


1.9 Visualize SR Representation

1.9.1 Figure 4. (bottom-left)

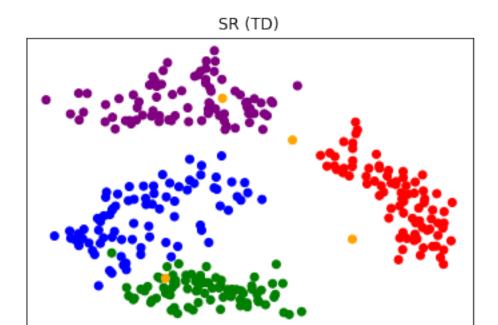
/Users/Maryam/anaconda3/lib/python3.6/site-packages/sklearn/manifold/mds.py:421: UserWarning: The warnings.warn("The MDS API has changed. ``fit`` now constructs an"

```
labelbottom=False,
    labelleft=False)
plt.ticklabel_format(style='plain',useOffset=False)
plt.savefig("figures/mds_SR_DP.png",bbox_inches = 'tight',pad_inches = 0.1,dpi=100)
plt.show()
```



1.10 Visualize SR Representation

1.10.1 Figure 4. (bottom-right)



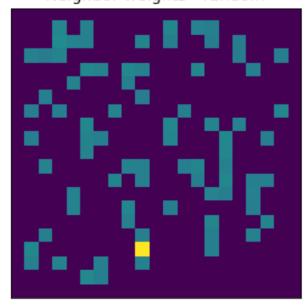
1.11 Visualization of the weights assigned to each of the k-nearest neighbors by an episodic control agent

1.11.1 Figure 5

```
In [128]: # Get true SR of embeddings by matrix-multiplying SR by embedding matrix
          true_SR_reps = np.matmul(true_SR,emb_reps)
In [129]: true_SR_reps = true_SR_reps/np.linalg.norm(true_SR_reps,axis=1,keepdims=True)
          emb_reps = emb_reps/np.linalg.norm(emb_reps,axis=1,keepdims=True)
In [130]: sr_kdtree = KDTree(true_SR_reps)
          emb_kdtree = KDTree(emb_reps)
In [131]: state = (17,9)
         k = 80
In [132]: def weights(distances):
              delta = 0.01
              distances = distances/(np.sum(distances)+1e-8)
              similarities = 1 / (distances+delta)
              return similarities/np.sum(similarities)
In [133]: state_idx = state_to_idx[state]
          state_sr = true_SR_reps[state_idx,:]
          sr_distances,sr_indices = sr_kdtree.query([state_sr],k=k,return_distance=True)
          sr_weights = weights(sr_distances)
```

```
sr_w_matrix = np.zeros([env.n_states,env.n_states])
          for sr_weight,idx in zip(sr_weights,sr_indices):
              sr_w_matrix[state_idx,idx] = sr_weight
          state_emb = emb_reps[state_idx,:]
          emb_distances,emb_indices = emb_kdtree.query([state_emb],k=k,return_distance=True)
          emb_weights = weights(emb_distances)
          emb_w_matrix = np.zeros([env.n_states,env.n_states])
          for emb_weight,idx in zip(emb_weights,emb_indices):
              emb_w_matrix[state_idx,idx] = emb_weight
In [136]: emb_sim_im = visualize_fourrooms_matrix(env,emb_w_matrix,state)
         plt.imshow(emb_sim_im)
          plt.title("Neighbor weights - random")
         plt.tick_params(
              axis='both',
              which='both',
              bottom=False,
              top=False,
              left=False,
              labelbottom=False,
              labelleft=False)
          plt.ticklabel_format(style='plain',useOffset=False)
          plt.savefig("figures/random_neighbors.png",bbox_inches = 'tight',pad_inches = 0.1,dpi=
          plt.show()
```

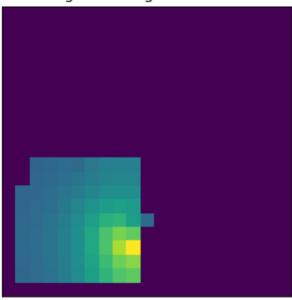
Neighbor weights - random



```
In [137]: sr_sim_im = visualize_fourrooms_matrix(env,sr_w_matrix,state)
    plt.imshow(sr_sim_im)
    plt.title("Neighbor weights - SR (DP)")

plt.tick_params(
        axis='both',
        which='both',
        bottom=False,
        top=False,
        left=False,
        labelbottom=False,
        labelleft=False)
    plt.ticklabel_format(style='plain',useOffset=False)
    plt.savefig("figures/SR_DP_neighbors.png",bbox_inches = 'tight',pad_inches = 0.1,dpi=1
    plt.show()
```

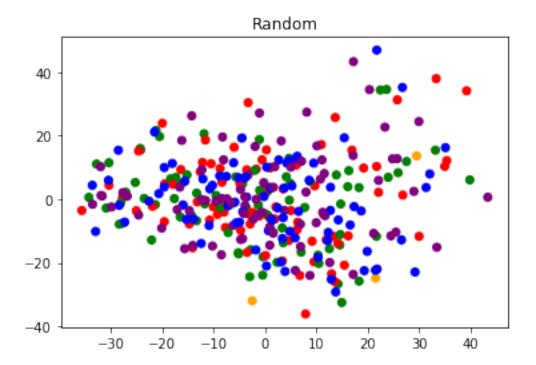
Neighbor weights - SR (DP)

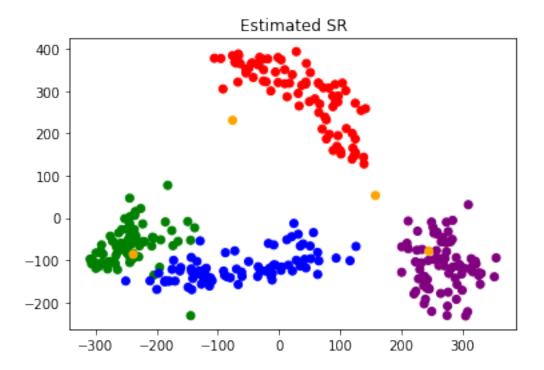


1.12 Principal Component Analysis (PCA)

1.12.1 Not included in the paper

In addition to MDS, we also used PCA to represent our embedding representation





Both MDS and PCA showed how SR has more meaningful temporal abstract information compare to random and VAE embedding representations

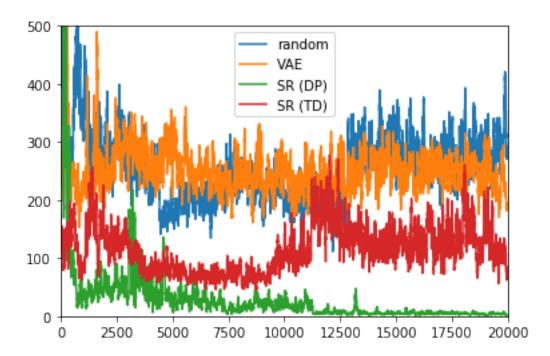
1.13 Train results

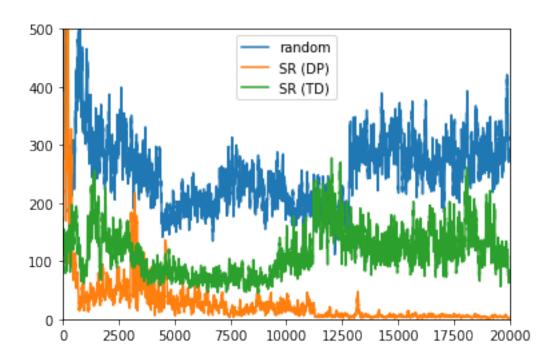
We uploaded the saved data for random, VAE and SR representation

1.13.1 Forced KNN

Not included in the paper

```
plt.xlim([0,20000])
plt.ylim([0,500])
plt.legend(["random","VAE", "SR (DP)", "SR (TD)"])
plt.show()
```





1.14 Running the code for state embedding representations

(not using the saved data)

```
In [44]: #MFEC_SR_rand_TD_rooms_mnist_200epochs_3knn
```

```
!python train.py \
--seed 1 \
--environment_type fourrooms \
--room_size 9 \
--fourrooms_state_type mnist \
--frames_to_stack 1 \
--n_episodes 20000 \
--initial_epsilon 1.0 \
--final_epsilon 0.1 \
--epsilon_decay 0.9 \
--gamma 0.99 \
--Q_train_algo MC \
--use_Q_max \
--force_knn \
--weight_neighbors \
--delta 0.01 \
--SR_gamma 0.99 \
--SR_batch_size 64 \
--SR\_train\_frames 1000000 \setminus
--SR_epochs 200 \
```

```
--SR_train_algo TD \
         --agent MFEC \
         --num_neighbors 3 \
         --embedding_type SR \
         --SR_embedding_type random \
         --embedding_size 32 \
         --in_height 28 \
         --in_width 28 \
         --max_memory 328 \
         --n_hidden 100 \
         --lr 0.0001 \
         --optimizer 'RMSprop' \
         --SR_filename ../results/MFEC_SR/random_TD_mnist_200epochs_3knn \
         --print_every 20 \
         --out_data_file ../results/MFEC_SR_MFEC_SR_rand_TD_rooms_mnist_200epochs_3knn.npy
Traceback (most recent call last):
  File "train.py", line 10, in <module>
    from models.MFEC import *
 File "/Users/Maryam/Courses_UCDavis/Winter2020/EEC289A_RL/project/finalVersion_RL_project/Pred
    from utils.utils import get_optimizer
 File "/Users/Maryam/anaconda3/lib/python3.6/site-packages/utils.py", line 632
    print 'Warning: Unknown file extension. Using fileformat value.'
SyntaxError: Missing parentheses in call to 'print'. Did you mean print('Warning: Unknown file e
In [0]: #MFEC_SR_rand_TD_rooms_mnist_200epochs_3knn
        !python train.py \
        --seed 1 \
        --environment_type fourrooms \
        --room_size 9 \
        --fourrooms_state_type mnist \
        --frames_to_stack 1 \
        --n_{episodes} 20000 \
        --initial_epsilon 1.0 \
        --final_epsilon 0.1 \
        --epsilon_decay 0.9 \
        --gamma 0.99 \
        --Q_train_algo MC \
        --use_Q_max \
        --force_knn \
        --weight_neighbors \
        --delta 0.01 \
```

 $--SR_gamma 0.99 \setminus --SR_batch_size 64 \setminus$

--SR_train_frames 1000000 \

```
--SR_epochs 200 \
--SR_train_algo TD \
--agent MFEC \
--num_neighbors 3 \
--embedding_type SR \
--SR_embedding_type random \
--embedding_size 32 \
--in_height 28 \
--in_width 28 \
--max_memory 328 \
--n_hidden 100 \
--lr 0.0001 \
--optimizer 'RMSprop' \
--SR_filename ../results/MFEC_SR/random_TD_mnist_200epochs_3knn \
--print_every 20 \
--out_data_file ../results/MFEC_SR_MFEC_SR_rand_TD_rooms_mnist_200epochs_3knn.npy
```

1.15 Running the code for train results

(not using the saved data)

```
In [0]: # MFEC_rand_rooms_mnist_3knn
        !python train.py \
        --seed 1 \
        --environment_type fourrooms \
        --room_size 9 \
        --fourrooms_state_type mnist \
        --frames_to_stack 1 \
        --n_episodes 20000 \
        --initial_epsilon 1.0 \
        --final_epsilon 0.1 \
        --epsilon_decay 0.9 \
        --gamma 0.99 \
        --Q_train_algo MC \
        --use_Q_max \
        --force_knn \
        --weight_neighbors \
        --delta 0.01 \
        --agent MFEC \
        --num_neighbors 3 \
        --embedding_type random \
        --embedding_size 32 \
        --in_height 28 \
        --in_width 28 \
        --max_memory 328 \
        --print_every 20 \
        --out_data_file ../results/MFEC/MFEC_rand_rooms_mnist_3knn.npy
```

```
In [0]: # MFEC_VAE_rooms_mnist_3knn
        python train.py \
        --seed 1 \
        --environment_type fourrooms \
        --room_size 9 \
        --fourrooms_state_type mnist \
        --frames_to_stack 1 \
        --n_episodes 20000 \
        --initial_epsilon 1.0 \
        --final_epsilon 0.1 \
        --epsilon_decay 0.9 \
        --gamma 0.99 \
        --Q_train_algo MC \
        --use_Q_max \
        --force_knn \
        --weight_neighbors \
        --delta 0.01 \
        --agent MFEC \
        --num_neighbors 3 \
        --embedding_type VAE \
        --vae_batch_size 4 \
        --vae_train_frames 100000 \
        --vae_epochs 10 \
        --embedding_size 32 \
        --in_height 28 \
        --in_width 28 \
        --max_memory 328 \
        --optimizer 'RMSprop' \
        --lr 1e-5 \
        --print_every 20 \
        --vae_print_every 100 \
        --load_vae_from weights/VAE/VAE_rooms_mnist.pt \
        --out_data_file ../results/MFEC/MFEC_VAE_rooms_mnist_3knn.npy
In [0]: # MFEC_SR_rand_DP_rooms_mnist_3knn
        !python train.py \
        --seed 1 \
        --environment_type fourrooms \
        --room_size 9 \
        --fourrooms_state_type mnist \
        --frames_to_stack 1 \
        --n_episodes 20000 \
        --initial_epsilon 1.0 \
        --final_epsilon 0.1 \
        --epsilon_decay 0.9 \
        --gamma 0.99 \
```

```
--Q_train_algo MC \
        --use_Q_max \
        --force_knn \
        --weight_neighbors \
        --delta 0.01 \
        --SR_gamma 0.99 \
        --SR_batch_size 32 \
        --SR_train_frames 1000000 \
        --SR_epochs 10 \
        --SR_train_algo DP \
        --agent MFEC \
        --num_neighbors 3 \
        --embedding_type SR \
        --SR_embedding_type random \
        --embedding_size 32 \
        --in_height 28 \
        --in_width 28 \
        --max_memory 328 \
        --n_hidden 100 \
        --lr 0.000006 \
        --optimizer 'RMSprop' \
        --SR_filename ../results/MFEC_SR/random_DP_mnist_3knn \
        --print_every 20 \
        --out_data_file ../results/MFEC_SR/MFEC_SR_rand_DP_rooms_mnist_3knn.npy
In [0]: # MFEC_SR_rand_TD_rooms_mnist_200epochs_3knn
        !python train.py \
        --seed 1 \
        --environment_type fourrooms \
        --room_size 9 \
        --fourrooms_state_type mnist \
        --frames_to_stack 1 \
        --n_episodes 20000 \
        --initial_epsilon 1.0 \
        --final_epsilon 0.1 \
        --epsilon_decay 0.9 \
        --gamma 0.99 \
        --Q_train_algo MC \
        --use_Q_max \
        --force_knn \
        --weight_neighbors \
        --delta 0.01 \
        --SR_gamma 0.99 \
        --SR_batch_size 64 \
        --SR_train_frames 1000000 \
        --SR_epochs 200 \
        --SR_train_algo TD \
```

```
--agent MFEC \
--num_neighbors 3 \
--embedding_type SR \
--SR_embedding_type random \
--embedding_size 32 \
--in_height 28 \
--in_width 28 \
--max_memory 328 \
--n_hidden 100 \
--lr 0.0001 \
--optimizer 'RMSprop' \
--SR_filename results/MFEC_SR/random_TD_mnist_200epochs_3knn \
--print_every 20 \
--out_data_file ../results/MFEC_SR/MFEC_SR_rand_TD_rooms_mnist_200epochs_3knn.npy
```