Recorded at time: 1758729556.459023 world Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 table top Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: 10000.0 Average rate: 10000.0 Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 back_left_leg back right leg base link camera link front left leg front right leg Broadcaster: default authority | Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: 20.204 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.9 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 78.99 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 74.09 Oldest transform: 0.0 Link 1 camera depth frame camera color frame daadbot/joint 1/tcp fts sensor joint 1 Broadcaster: default authority | Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Average rate: 10000.0 Average rate: 20.204 Average rate: 10000.0 Average rate: 10000.0 Buffer length: 0.0 Buffer length: 4.9 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 78.99 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 74.09 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 daadbot/joint 2/tcp fts sensor joint 2 Link 2 camera depth optical frame camera color optical frame Broadcaster: default authority Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $2\overline{0.204}$ Buffer length: 0.0 Buffer length: 4.9 Most recent transform: 0.0 Most recent transform: 78.99 Oldest transform: 0.0 Oldest transform: 74.09 Link_3 daadbot/joint_3/tcp_fts_sensor_joint_3 Broadcaster: default authority Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $2\overline{0.204}$ Buffer length: 4.9 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 78.99 Oldest transform: 74.09 Oldest transform: 0.0 daadbot/joint 4/tcp fts sensor joint 4 Link 4 Broadcaster: default authority Broadcaster: default authority Average rate: 20.204 Average rate: $10\overline{0}00.0$ Buffer length: 4.9 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 78.99 Oldest transform: 0.0 Oldest transform: 74.09 Link 5 daadbot/joint 5/tcp fts sensor joint 5 Broadcaster: default authority Broadcaster: default authority Average rate: 20.204 Average rate: 10000.0 Buffer length: 4.9 Buffer length: 0.0 Most recent transform: 78.99 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 74.09 Link 6 daadbot/joint 6/tcp fts sensor joint 6 Broadcaster: default authority Broadcaster: default authority Average rate: $2\overline{0}.204$ Average rate: $10\overline{0}00.0$ Buffer length: 4.9 Buffer length: 0.0 Most recent transform: 78.99 Most recent transform: 0.0 Oldest transform: 74.09 Oldest transform: 0.0 daadbot/joint_7/tcp_fts_sensor_joint_7 Link 7 Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Average rate: $2\overline{0.204}$ Average rate: $10\overline{0}00.0$ Average rate: $2\overline{0.204}$ Buffer length: 0.0 Buffer length: 4.9 Buffer length: 4.9 Most recent transform: 0.0 Most recent transform: 78.99 Most recent transform: 78.99 Oldest transform: 0.0 Oldest transform: 74.09 Oldest transform: 74.09 base claw link1 base claw link2 endeffector Broadcaster: default authority Broadcaster: default authority Average rate: 20.204 Average rate: 20.204 Buffer length: 4.9 Buffer length: 4.9 Most recent transform: 78.99 Most recent transform: 78.99 Oldest transform: 74.09 Oldest transform: 74.09 gear2 link gear1 Broadcaster: default authority Broadcaster: default authority Average rate: 20.204 Average rate: 20.204 Buffer length: 4.9 Buffer length: 4.9 Most recent transform: 78.99 Most recent transform: 78.99 Oldest transform: 74.09 Oldest transform: 74.09 gear1_claw gear2 claw

view frames Result