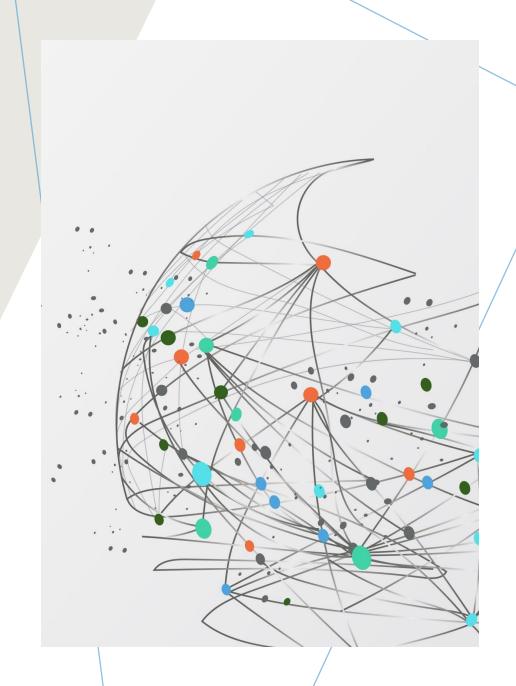
PWM DRAWER

• EMBEDDED SYSTEM PROJECT

BY: MARYAM EMAD



PWM DRAWER



Atmega32 Interfacing with GLCD



This presentation will provide a detailed overview of the *PWM Drawer* project.



This presentation will provide a detailed overview of the *PWM Drawer* project.



The goal is to display the quantity of PWM while allowing the user to draw and write on the LCD.



The project components and implementation details will be thoroughly discussed.



Overview of the Embedded System Used

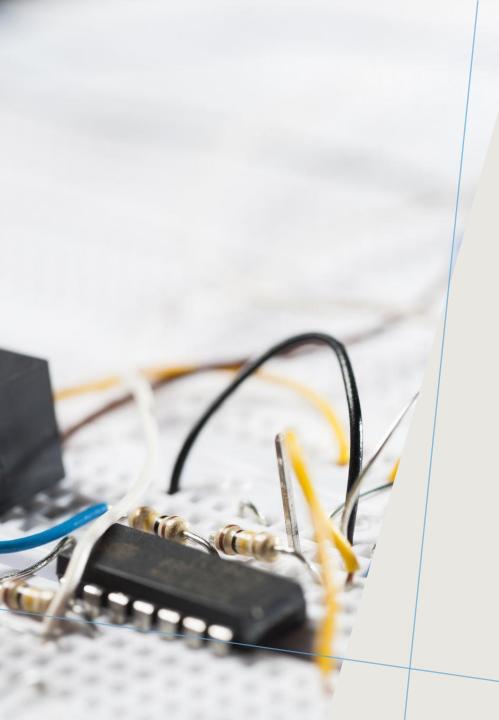
GLCD Interaction and Display

Implementation in Atmega32

Atmega32 and GLCD Interface

PWM Calculation & Control

Conclusion



Overview of the Embedded
 System Used



- 1) Graphical
 - GLM12641BS1R
- · 2)Microcontroller
- Atmega32
 3)Pulse Width Modulation (PWM)

 PRE_64
 -Fast_PWM
 -Polling

 - -Timer1



An intuitive user interface

makes it easy to operate the drawer

access its features seamlessly.

MICROCONTROLLER

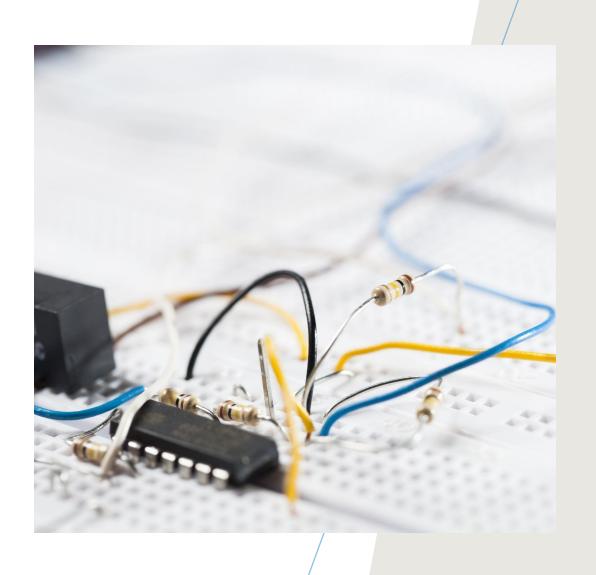
The system is powered by a high-performance



microcontroller designed for



Precision and reliability which is ATmega32



PULSE WIDTH MODULATION (PWM)

 The system integrates PWM technology to control the power output allowing for precise control of the drawer.



Initial Interfacing

PWM Integration

Main Functionality

INITIAL INTERFACING

 Started by interfacing with the GLCD without PWM and achieved successful functionality for writing and drawing on it.

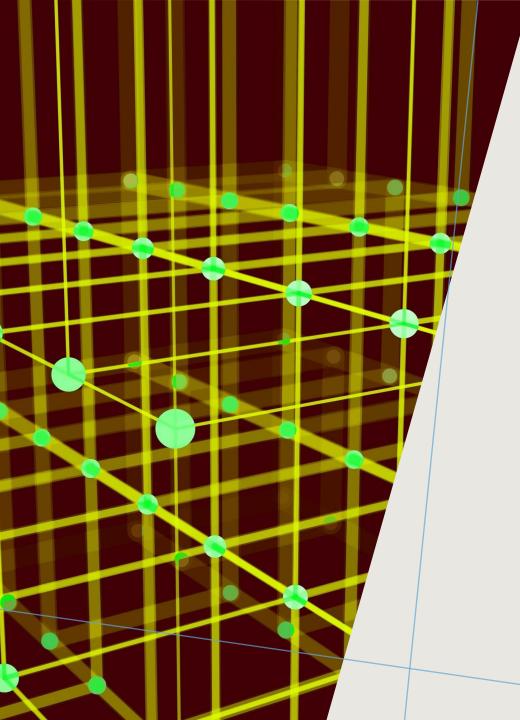
PWM INTEGRATION

• Subsequently, incorporated PWM and established successful interfacing, leading to the final *main.c* integration.

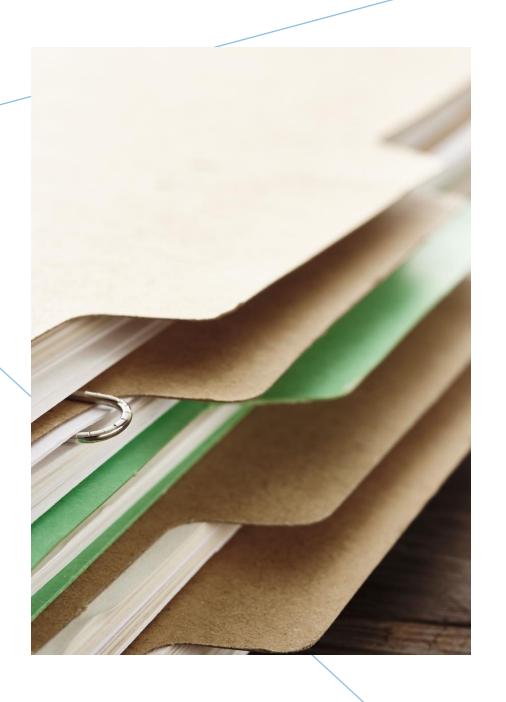


MAIN FUNCTIONALITY

• The *main.c* file depicted the comprehensive usage of PWM and GLCD for drawing PWM signals and numerical display.



Implementation in Atmega32



ECUAL





HEADER FILES

INCLUDE FILES



MAIN FUNCTIONALITY

HEADER FILES

 Introduced header files for GLCD interfacing consists of GLCD, GLCD_DATA (font and image) and PWM calculation, providing enhanced organization and modularity.

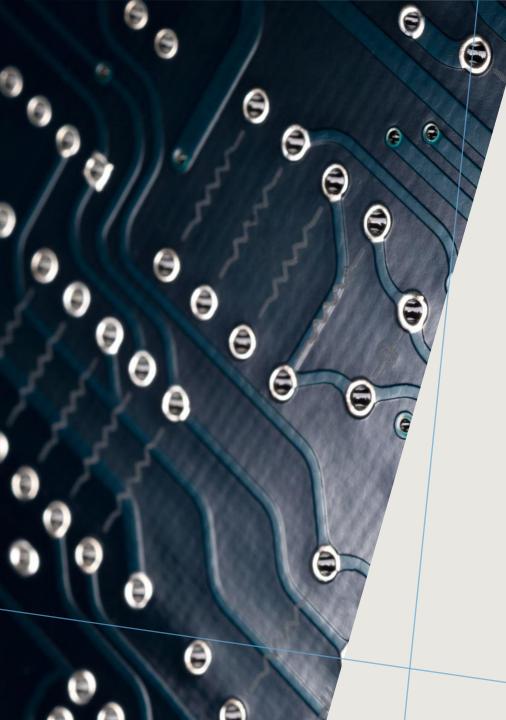




SAME HEADER FILES MADE WILL HAVE ITS TWIN INCLUDE FILE FOR IMPLEMENTING THE FUNCTIONS







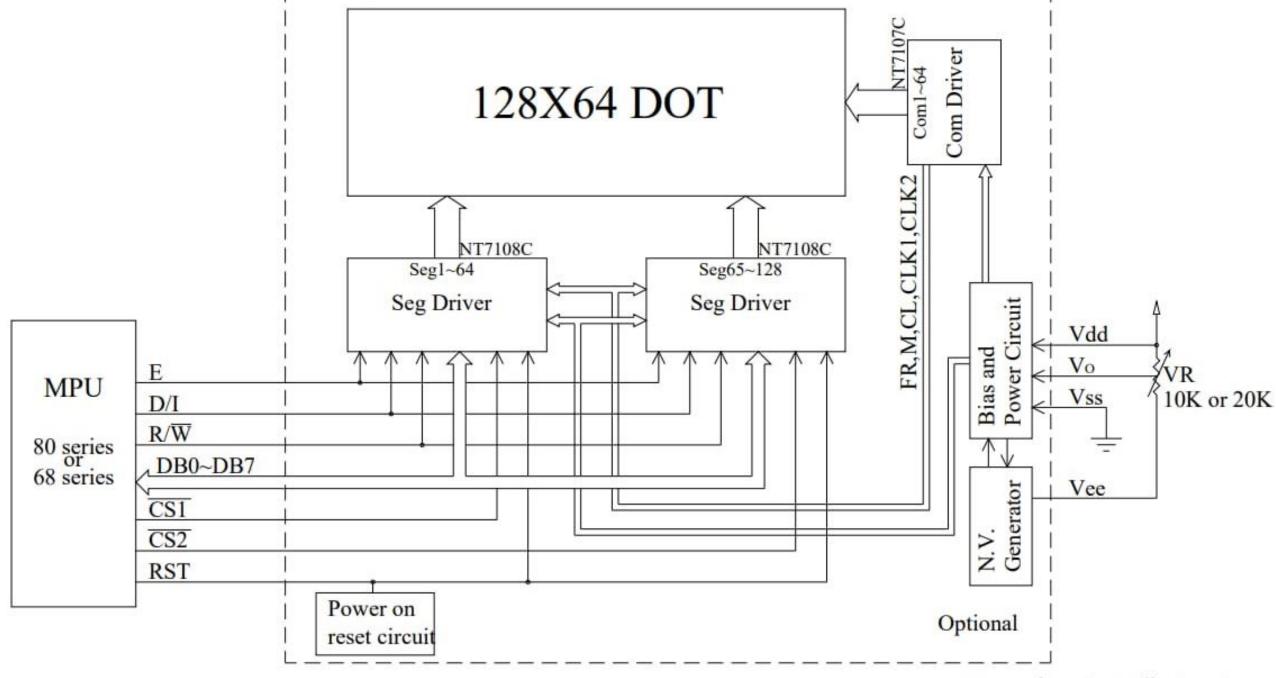


Atmega32 and GLCD Interface





- Drawing
- Writing



External contrast adjustment.

Instruction	RS	R/W	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0	Function
Display on/off	L	L	L	L	Н	н	Н	н	Н	L/H	Controls the display on or off. Internal status and display RAM data is not affected. L:OFF, H:ON
Set address (Y address)	L	L	L	Н	Y address (0-63)					Sets the Y address in the Y address counter.	
Set page (X address)	L	L	Н	L	Н	Н	Н	Page (D-7)			Sets the X address at the X address register.
Display Start line (Z address)	L	L	н	Н	Display start line (0-63)					Indicates the display data RAM displayed at the top of the screen.	
Status read	L	н	Busy	L	On/ Off	Reset	L	L	L	L	Read status. BUSY L: Ready H: In operation ON/OFF L: Display ON H: Display OFF RESET L: Normal H: Reset
Write display data	Н	L	Write data							Writes data (DB0: 7) into display data RAM. After writing instruction, Y address is increased by 1 automatically.	
Read display data	Н	Н	Read data							Reads data (DB0: 7) from display data RAM to the data bus.	

GLCD INTERFACE

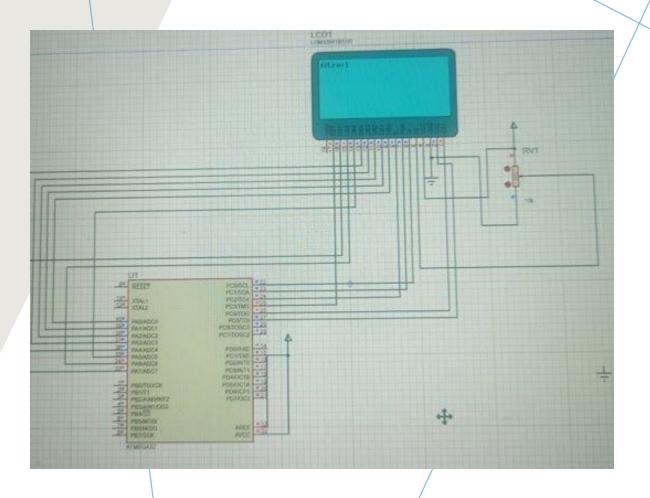
Define and connections TotalPage 8 RS =PC0 RW=PC1 EN=PC2 CS1=PC4 RST=PC3 CS2=PC5 **Functions** void GLCD_Command(char Command); void GLCD_Data(char Data); void GLCD_Init(); void GLCD_ClearAll(); void GLCD_String(char page_no, char *str); void GLCD_Str(const char* image);

```
int main(void)
{
GLCD_Init(); /* Initialize GLCD */
GLCD_ClearAll(); /* Clear all GLCD display */
GLCD_String(img); /* Print Image Array */
while (1); }
```

WRITING

- glcd-font.h
- char font[][5];
- glcd-font.c
- char font[][5] = {
- {0x00, 0x00, 0x00, 0x00, 0x00} // 20 (Space)
- ,{0x00, 0x00, 0x5f, 0x00, 0x00} // 21 !
- ,{0x00, 0x07, 0x00, 0x07, 0x00} // 22 "
- ,{0x14, 0x7f, 0x14, 0x7f, 0x14} // 23 #

```
INT MAIN(VOID)
GLCD_INIT(); /* INITIALIZE GLCD
GLCD_CLEARALL(); /* CLEAR
ALL GLCD DISPLAY */
GLCD_STRING(0,"ATMEL"); /*
PRINT STRING ON OTH PAGE OF
DISPLAY */
WHILE(1);
```



05

PWM Calculation & Control



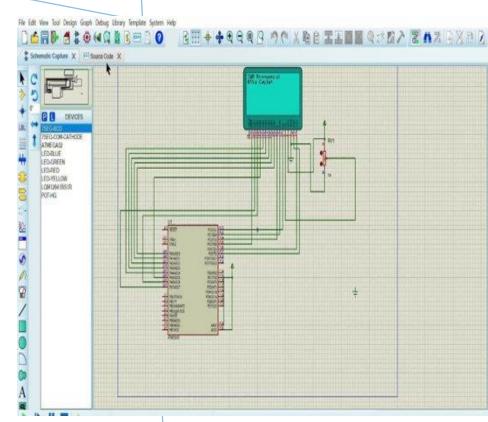
1) CONTROL

```
PWM.h
void PWM_init();
uint_16 PWM_getFrequency();
uint_8 PWM_getDutyCycle();
Void PWM_init() {
TIMER_cfgstruct pwmConfig;
pwmConfig.pre = PRE_64;
pwmConfig.mode = Fast_PWM;
pwmConfig.Op_mode = Polling;
pwmConfig.Timer = Timer1;
Timer_Setup(pwmConfig);
Timer1_start();
```

2) CALCULATIONS

- uint_16 PWM_getFrequency();
- The PWM frequency is calculated using the formula:
- Frequency = F_CPU / (2 * prescalerValue * (topValue + 1)) * (1 + compareValue / (topValue + 1))
 - F CPU: Clock frequency of the microcontroller.
 - prescalerValue: The value used to divide the clock frequency.
 - topValue: The top value for the PWM waveform.
- compare Value: The compare value for the PWM waveform.
- uint_8 PWM_getDutyCycle();
- Calculating Duty Cycle:
 - Based on the comlaMode:
 - For toggle mode or normal mode, duty cycle is assumed to be 0%.
 - For certain other modes, duty cycle is assumed to be 0%.
 - For clear on compare match or set on compare match mode, duty cycle is calculated as a percentage:
 - dutyCycle = (compareValue * 100) / (topValue + 1) **or**
 - (topValue compareValue) *100 / (topValue+1) respectively.

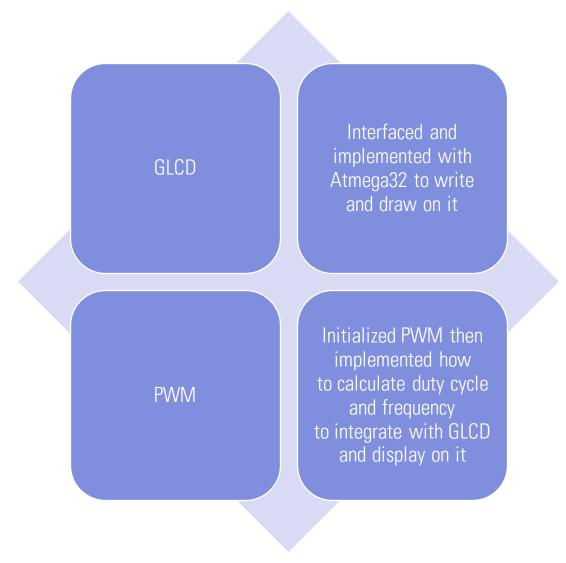
```
INT MAIN(VOID) {
PWM INIT(); // INITIALIZE PWM
GLCD_INIT(); // INITIALIZE GLCD
WHILE(1) {
// READ PWM FREQUENCY AND DUTY CYCLE
UINT16 T FREQUENCY = PWM_GETFREQUENCY();
UINT8 T DUTYCYCLE = PWM GETDUTYCYCLE();
// DRAW PWM SIGNAL ON GLCD
GLCD CLEARALL(); // CLEAR THE GLCD DISPLAY
GLCD_STRING(0, "PWM FREQUENCY: "); // DISPLAY PWM FREQUENCY
GLCD_STRING(1, "DUTY CYCLE: "); // DISPLAY PWM DUTY CYCLE
CHAR FREQUENCY STR[5];
CHAR DUTYCYCLE STR[4];
SPRINTF(FREQUENCY_STR, "%D", FREQUENCY); // CONVERT FREQUENCY TO STRING
SPRINTF(DUTYCYCLE_STR, "%D%%", DUTYCYCLE); // CONVERT DUTY CYCLE TO STRING
GLCD STRING(0, FREQUENCY STR); // DISPLAY PWM FREQUENCY VALUE
GLCD_STRING(1, DUTYCYCLE_STR); // DISPLAY PWM DUTY CYCLE VALUE
RETURN 0;
```





CONCLUSION

1) **SUMMARIZE**



2) APPLICATIONS

- Harnessing PWM for Versatile Applications
- **Dynamic Lighting Control**: Implementing PWM allows for precise control over LED brightness, enabling dynamic lighting effects in various applications such as ambient lighting, signage, and automotive lighting.
- **Motor Speed Regulation**: PWM can be employed to regulate motor speeds efficiently, enabling precise control over mechanisms in robotics, automation, and industrial systems.
- Analog Signal Generation: By modulating PWM signals, analoglike waveforms can be synthesized, facilitating applications like audio synthesis, waveform generation, and sensor signal simulation.
- **Artistic Expression**: Enable creative individuals to express their artistic talents digitally through drawing and writing.
- **Educational Tools**: Offer educational institutions an innovative tool to facilitate interactive learning and creative expression.
- Professional Design: Provide professionals with a versatile tool for creating professional designs with precision and efficiency.



THANK

YOU!

