FLEXIONIZATION CONTROL SYSTEM (FCS)

NONLINEAR CONTROL ARCHITECTURE
FOR UAVS & ROBOTICS

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PROBLEM

Modern robotics and UAV systems operate in unstable, nonlinear environments where classical PID-based control loops lose stability and accuracy.

• Nonlinear dynamics cannot be controlled reliably using classical methods.
• PID requires constant manual tuning and does not scale across systems.
• Turbulence, vibration and heterogeneous media create large error spikes.
• Manufacturers rely on dozens of ad-hoc filters and patches (“control duct tape”).
• The industry lacks a unified, mathematically robust control framework.

SOLUTION

Flexionization (FCS) introduces a new control architecture based on the FXI–Δ–E model — a mathematically structured loop for stable nonlinear control.

• Converts deviation into a controlled FXI-space where stability is preserved.
• Smooths errors through an equilibrium operator instead of PID reactive jumps.
• Works consistently in turbulence, vibration and heterogeneous media.
• Eliminates the need for dozens of ad-hoc filters and patches.
• Provides a universal control framework for drones, robotics and embedded systems.

PRODUCT

We provide a lightweight, embeddable C++ SDK that implements the full Flexionization (FCS) control loop for real-time systems.

- Minimal, modular C++ core (<300 lines) ready for STM32, PX4, ROS2.
- Plug-and-play operators: F, E, F^{-1}, and G with default and custom variants.
- Stable nonlinear control without PID tuning.
- Works as a drop-in module for drones, robots, actuators, motion controllers.
- Fully documented with API reference, examples, and integration patterns.

MARKET & TRACTION

Market:

• UAV market: $38B → $90B by 2030 (commercial + defense).
• Robotics market: $40B → $140B by 2030.
• Motion control & embedded systems: >$20B annually.

Why now:

• Demand for autonomous drones and robotics is rapidly accelerating.
• Nonlinear environments expose the limitations of PID-based control.

Traction:

• Working C++ SDK, documented and integration-ready.
• Architecture validated through the FXI-Δ-E mathematical model.
• Preparing for pilot integrations with UAV and robotics developers.

ASK & CONTACT

Ask:

• Seeking early-stage investment to assemble the core engineering team.
• Funding need: $250k-$400k for 12 months of development, pilots, and audit.
• Goals: finalize SDK v1.0, integrate with PX4/ROS2, run 3-5 pilot deployments.

Use of funds:

• Core engineering (control theory + embedded systems).
• Certification, security audit, and optimization.
• Pilot programs with drone/robotics manufacturers.

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Full Mathematical Theory (Flexionization V1.5)
Preprint: https://zenodo.org/records/17618948
DOI: 10.5281/zenodo.17618948