FCS — Flexionization Control System

One-Pager (Investor Version)

🚀 What is FCS

FCS (Flexionization Control System) is a next-generation control architecture for drones, robotics, and embedded systems.
It replaces classical PID controllers using the nonlinear **FXI–Δ–E** model designed for noisy, unstable, and highly dynamic environments.

FCS enables smoother, more stable, and more adaptive control compared to traditional methods.

🧠 How it Works

The control loop processes deviation through a chain of monotonic transformations:

Δ → F → E → F^{-1} → G → Control Output

- **F** — transforms deviation into FXI-space
- **E** — stabilizes and smooths the error
- **F^{-1}** — maps corrected value back
- **G** — generates the final control signal

This architecture produces predictable and stable behavior even under nonlinearities, noise, and load spikes.

💡 Key Advantages Over PID

- Robust against noise and sudden disturbances
- Minimal tuning required (few parameters)
- Smooth control response in nonlinear systems
- Modular: F, E, F^{-1}, G operators are fully replaceable
- Runs on any microcontroller: STM32, PX4, ROS2, Arduino, ESP32

📦 What's Already Done

- **Fully working C++ SDK**

    - Default F / E / F^{-1} / G operators
    - Ready-to-use control loop
    - Nonlinear test loop (simple_loop_nonlinear.cpp)

- **Whitepaper structure is ready**

    - Mathematical foundation
    - FXI–Δ–E architecture
    - Operator definitions

- **Presentation materials**

    - PITCH.pdf
    - FCS.pdf
    - INVESTOR-SLIDES.pdf

◎ Use Cases

- UAV flight controllers
- Robotic actuators and servo systems
- Manipulators and mobile robots
- Adaptive stabilization loops
- Precision positioning systems

♀ Project Status

- SDK: **Complete**
- Whitepaper: **Core structure ready**
- Pitch Deck: **In progress**
- Investor readiness: **Yes**

☎ Contact

For technical questions, commercial licensing, or collaboration requests, please contact:

Email: m7823445@gmail.com
GitHub: https://github.com/MaryanBog

Full Mathematical Theory (Flexionization V1.5)
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