view frames Result

Recorded at time: 1625097988.6005683

odom

Broadcaster: /rf2o laser odometry

Average rate: 6.138

Buffer length: 4.887 Most recent transform: 1625097988.192 Oldest transform: 1625097983.305

robot footprint

Broadcaster: /mpu6050 serial to imu node

Average rate: 66.867

Buffer length: 4.98

Most recent transform: 1625097988.566

Oldest transform: 1625097983.586

Broadcaster: /base to laser broadcaster

Average rate: 25.075

Buffer length: 4.945

Most recent transform: 1625097988.573

Oldest transform: 1625097983.628

 $imu_link$ 

laser