



HRW ROS Assignment 3 Week 4 Part 1

To complete the last assignment of the week, you need to follow this steps.

1. Complete the script `week4_assignment3.py` located on the scripts folder of the `hrwros_week4` package.
You only need to change wherever you are instructed with `<write your code here>`.
2. After you have completed the script, start the factory simulation in a new CCS with:

```
$ roslaunch hrwros_week4 hrwros_week4_environment.launch
```
3. Then, make sure to adjust the perspective of the Gazebo Simulation to have a clear view of Robot2.
4. In another CCS, first navigate to the `hrwros_week4/scripts` folder with `roscd`. Make the `week4_assignment3.py` script executable.
5. Finally, run the command: `roslaunch hrwros_week4 week4_assignment3.launch`. You should see the robot2 execute simple pick and place motions.

You should see the robot moving in Gazebo!

This concludes HRW ROS Assignment 3 Week 4