view\_frames Result Recorded at time: 79.065 world Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (79.065 sec old) Buffer length: 0.000 sec base\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (79.065 sec old) Most recent transform: 0.000 (79.065 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec base\_laser cpu\_link Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (79.065 sec old) Buffer length: 0.000 sec upper\_base\_link Broadcaster: /robot\_state\_publisher Average rate: 50.202 Hz Most recent transform: 79.049 (0.016 sec old) Buffer length: 4.960 sec torso\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (79.065 sec old) Most recent transform: 0.000 (79.065 sec old) Most recent transform: 0.000 (79.065 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec head\_pan\_link left\_shoulder\_link right\_shoulder\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 50.202 Hz Average rate: 50.202 Hz Average rate: 50.202 Hz Most recent transform: 79.049 ( 0.016 sec old) Most recent transform: 79.049 (0.016 sec old) Most recent transform: 79.049 (0.016 sec old) Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.960 sec head\_tilt\_link left\_shoulder\_forward\_link right\_shoulder\_forward\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 50.202 Hz Average rate: 50.202 Hz Average rate: 50.202 Hz Most recent transform: 79.049 (0.016 sec old) Most recent transform: 79.049 ( 0.016 sec old) Most recent transform: 79.049 (0.016 sec old) Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.960 sec left shoulder up link neck\_link right\_shoulder\_up\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (79.065 sec old) Most recent transform: 0.000 (79.065 sec old) Most recent transform: 0.000 (79.065 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec left\_upper\_arm\_link head\_link right\_upper\_arm\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 50.202 Hz Average rate: 50.202 Hz Most recent transform: 0.000 (79.065 sec old) Most recent transform: 79.049 (0.016 sec old) Most recent transform: 79.049 (0.016 sec old) Buffer length: 0.000 sec Buffer length: 4.960 sec Buffer length: 4.960 sec antenna\_link left\_elbow\_link right\_elbow\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (79.065 sec old) Most recent transform: 0.000 (79.065 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec left\_lower\_arm\_link right\_lower\_arm\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 50.202 Hz Average rate: 50.202 Hz Most recent transform: 79.049 (0.016 sec old) Most recent transform: 79.049 (0.016 sec old) Buffer length: 4.960 sec Buffer length: 4.960 sec left\_wrist\_link right\_wrist\_link Broadcaster: /robot state publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (79.065 sec old) Most recent transform: 0.000 (79.065 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec left\_hand\_link right\_hand\_link