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Exercise 1

1. False

if $V \in R_{3k}$, $\alpha = (1.1)$, b = (0.0), c = c(1.2):

then: $c\alpha \cdot c = 3 > c\alpha \cdot b + cb \cdot c > 0$

i. if α , $c \neq 0$ and $c\alpha$, e > >0 and $b \neq 0$ then $c\alpha$, $c > > <\alpha$, b > + < b, $c > <\alpha$

2. False

if VER2+2. a. c. #0. b=0

then sorietized coubs=0 and cbics=0, but <a.c> #0 as long as <a,c> #0

3. True

span(s) = k, v, +k, v, + .. + knvn (ki could be any value)

i x is orthogonal to all of bi

~ < x , vi > =0

<i set y e spon(s), y = kivithyor +...+ knun

<xiy>= <x. kivithyor+ -+ knun>

いくx、バフン

? < x14> =0

Front :

4. True

For spen(4), S is a orthonormal basis of Span(5), which means any y & Span(5) can be represented by S linearly:

y= kivit kivit. + knvn (ki could be ony value)

if x to and x G Span (3)

then x = kivitevent + knun

" <x.v.>=0

· <xxx> = <x, kivitkyvit..+ knun>=0 => X=0

Howeven x + 0

2. Disproof

5. True

if RESpones), then: X: kivithout + ++ + kava (k: could be any value)

2 <x, vi >=0

< < x, x > = 0 =) X=0

However x \$0

: Dispurg

6. True

if not unique. then

X= CIVIT .. + CHVA

where cound di one not all the same.

7= divit - + dn un

Let's say difci. (15:5 N). other c=d.

then X-X = civit. + Cavy - divit. + duly

- Cci-di)vi + + + cci-di)vi + ccn-du)vn = (Ci-di) vi

" x-x =0

.: Cci-di) vi >0

= ci +d: . vi +> 2 contlict

:- Prive that confliction.

7. False

For example set $V \in \mathbb{R}_{1\times 1}$. $S = \{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 2 \end{pmatrix} \}$ $X = \begin{pmatrix} 4 \\ 4 \end{pmatrix}$

then $x = 2 V_1 + V_2$

=4v1

= 1V2

E X= CIVI+CLUST ... + CNUN

-: C1, C2 cas be (2,1), (4.0), (0,2), not onique

- Disprot

8. talse

V: U2 U3

for exemple set VFR3x3. S={(\(\bar{0} \), (\(\bar{0} \), (\(\bar{0} \))}

For vi in S:

V1 V3 one linearly independent V1 V3 one linearly independent V1 V3 ove linearly independent

For a linearly independent set S.

Any vector in the set S counse be linearly represented by other vectors

However:

V1 = V2+V3

- :. 5 is not linearly independent
- Disprost

Exercise 2.

if 11.11 is a norm, 11.11 should satisfy 3 properties.

1. ||x||7,0, if ||x|| =0, then x=0

Obvinusly, 11x11= J(x,x) >,0

To proof:

: Proof

To proof :

7. proof .

(According to CS inequality <xry> < 11x111y11)

Exercise 3

then
$$L(0,c) = \frac{11y-y' \cdot 11A^2 + 110' \cdot 12^2 + 11c \cdot 1^2 A}{20}$$
 $PoL(0,c) = \frac{2L(0,c)}{20} = \frac{211y-y' \cdot 11A}{20} + \frac{2110' \cdot 12}{20}$ (according to sum rule)

D Using Chain me:

$$\frac{\partial \|y-y'\|_{A}^{2}}{\partial \theta} = \frac{\partial \|y-y'\|_{A}^{2}}{\partial y'} \cdot \frac{\partial y'}{\partial \theta} = \frac{\partial (y-y')^{2} \cdot A \cdot (y-y')}{\partial y} \cdot x$$

$$= -(y-y')^{2} \cdot (A+A^{2}) \times$$

$$= -2(y-y')^{2} \cdot A \cdot x$$

$$= -2(y-y')^{2} \cdot A \cdot x$$

$$= -2(y^{2} - b^{2}x^{2} - c^{2}) \cdot A \cdot x$$

$$= -2(y^{2} - b^{2}x^{2} - c^{2}) \cdot A \cdot x$$

2. Let
$$-2(y^{T}-0^{T}x^{T}-c^{T})AX + 20^{T}B=0$$

then

To proof (B+XTAX) is invertible.

- : Bis positive symmetric define motivix
- cionly need to prof XTAX is positive symmetric define metrix.

 Then (Bf XTAX) is positive symmetric define matrix

Dette YTXTAXY. Were XY can be written by a (Y can be any vector)

" D is possue, symmetric define mornix

- .. Any vector wTAW >0
- C. CTA L'SO, Where C=XY.
- · Proof (B+XTAX) is symmetric positive define motorix = invertible
- " 0=[(B+ xTAX)"]" . (yTAX-CTAX)"

3. Define y= x0+0

$$\nabla_{\mathcal{C}} \mathcal{L}(\theta, c) = \frac{\partial \mathcal{L}(\theta, c)}{\partial c} = \frac{\partial \|y - y'\|_{A}^{2}}{\partial c} + \frac{\partial \|c\|_{A}^{2}}{\partial c}$$

$$\frac{\partial \|y \cdot y' \|_{A^{\frac{1}{2}}}}{\partial c} = \frac{\partial \|y \cdot y' \|_{A^{\frac{1}{2}}}}{\partial y'} \cdot \frac{\partial y'}{\partial c} = -2(y - y')^{T} A$$

$$= -2(y^{T} - \theta^{T} X^{T} - c^{T}) A$$

4. let Ped(0.0) =0

- : A is positive. symmetric definite matric,
- : Ais invertible

$$C^{\mathsf{T}} = \frac{1}{2} \left(\mathbf{y}^{\mathsf{T}} \mathbf{A} - \mathbf{0}^{\mathsf{T}} \mathbf{x}^{\mathsf{T}} \mathbf{A} \right) \cdot \mathbf{A}^{\mathsf{T}}$$

$$C = \frac{1}{2} \left(\mathbf{A}^{\mathsf{T}} \right)^{\mathsf{T}} \cdot \left(\mathbf{y}^{\mathsf{T}} \mathbf{A} - \mathbf{0}^{\mathsf{T}} \mathbf{x}^{\mathsf{T}} \mathbf{A} \right)^{\mathsf{T}}$$

5. For my answer in 3.2:

$$0 = \left[(y^T A \times - c^T A \times) \cdot (B + x^T A \times)^T \right]^T$$

$$= \left[(B + x^T A \times)^T \right]^T \cdot (y^T A \times - c^T A \times)^T$$

When A=I. C= 0. B=NI.

: correct. the same as 3.5