

**Homework 6***Instructor: Fei He*

YOUR NAME (YOUR TSINGHUA ID)

*TA: Jianhui Chen, Fengmin Zhu*

*Read the instructions below carefully before you start working on the assignment:*

- Please typeset your answers in the attached L<sup>A</sup>T<sub>E</sub>X source file, compile it to a PDF, and finally hand the PDF to Tsinghua Web Learning *before the due date*.
- Make sure you fill in your *name* and *Tsinghua ID*, and replace all “TODO”s with your solutions.
- Any kind of dishonesty is *strictly prohibited* in the full semester. If you refer to any material that is not provided by us, you *must cite* it.

**Problem 1: Multiple Choice**

For each of questions below, four choices marked (A), (B), (C) and (D) are provided. ONLY ONE of them is correct. Read the questions carefully and choose the correct answers.

**1-1** Which of the following is *not* a loop invariant for the following IMP loop?

```
while  $Y > 0$  do  $Y := Y - 1; X := X + 1$  end
```

- (A)  $X > 10$ .
- (B)  $Y > 10$ .
- (C)  $X + Y = Z$ .
- (D)  $Z + Y < X$ .

**Solution** B ■

**1-2** Which of the following is *false* about the IMP program shown below?

```
 $X := 1;$   
while  $X > 0$  do  
  if  $N \leq 100$  then  
     $N := N + 11;$   
     $X := X + 1$   
  else  
     $N := N - 10;$   
     $X := X - 1$   
  fi  
end
```

- (A)  $X = 0$  is a post condition.
- (B)  $X \geq 0$  is a loop invariant (for the while-loop).
- (C)  $N \leq 111$  is a loop invariant (for the while-loop).
- (D) The program may not terminate.

**Solution D ■**

**1-3** Let  $[X = 0]$  **while**  $b$  **do**  $c$  **end**  $[X = 1]$  be a Hoare triple. Which of the following is *true*?

- (A) If  $c$  is  $X := 1$ , then the Hoare triple is valid for some  $b$ .
- (B) If  $b$  is **true**, then the Hoare triple is valid for some  $c$ .
- (C) If  $b$  is  $X \neq 1$ , then the Hoare triple is valid no matter what  $c$  is.
- (D) The Hoare triple is always invalid no matter what  $b$  and  $c$  are.

**Solution A ■**

**1-4** Recall that two IMP programs (with havoc)  $c_1$  and  $c_2$  are *behaviorally equivalent*, if for every states  $\sigma$  and  $\sigma'$ , their big-step operational semantic evaluation relations satisfy  $\langle \sigma, c_1 \rangle \Downarrow \sigma' \iff \langle \sigma, c_2 \rangle \Downarrow \sigma'$ . In which of the following are  $c_1$  and  $c_2$  behaviorally equivalent?

- (A)  $c_1 : X := Y; Y := X$       $c_2 : Y := X; X := Y$
- (B)  $c_1 : \text{skip}$       $c_2 : \text{if } X > 10 \text{ then } X := 0 \text{ else skip fi}$
- (C)  $c_1 : \text{havoc } X; X := 10$       $c_2 : X := 10$
- (D)  $c_1 : \text{havoc } X; \text{havoc } Y$       $c_2 : \text{havoc } Y$

**Solution C ■**

**1-5** Let  $F$  be a CNF with four variables  $x_1, x_2, x_3, x_4$ . We apply the DPLL algorithm (without backjump) on  $F$  and the following operations are done: decide  $x_1$ , propagate  $x_2$ , propagate  $x_3$ . Which of the following operations will be possibly done in the next step?

- (A) Decide  $\neg x_3$ .
- (B) Backtrack and decide  $\neg x_1$ .
- (C) Backtrack and decide  $\neg x_2$ .
- (D) Backtrack and decide  $\neg x_3$ .

**Solution B ■**

## Problem 2: Assumptions & Assertions

We consider two kinds of commands which indicate a certain statement should hold any time this part of the program is reached – the assumption statement “**assume**  $b$ ”, and the assertion statement “**assert**  $b$ ”:

- If an assertion statement fails, it causes the program to go into an *error state* and exit (or abort).
- If an assumption statement fails, the program fails to evaluate at all. In other words, the program gets *stuck* and has no final state.

To formally express the program may go into an error state, we have to change the evaluation relation (of big-step operational semantics) from “ $\langle \sigma, c \rangle \Downarrow \sigma'$ ” into “ $\langle \sigma, c \rangle \Downarrow r$ ”, where the evaluation *result*

$$r ::= \text{norm}(\sigma) \mid \text{err}$$

can state two possible cases:  $\text{norm}(\sigma)$  for normally execution with ending state  $\sigma$ , or  $\text{err}$  for reaching the error state. The inference rules for the original IMP commands need be modified and we should handle errors carefully (read and think about the differences):

$$\begin{array}{c}
\text{(Skip)} \frac{}{\langle \sigma, \text{skip} \rangle \Downarrow \text{norm}(\sigma)} \\
\text{(Seq)} \frac{\langle \sigma, c_1 \rangle \Downarrow \text{norm}(\sigma') \quad \langle \sigma', c_2 \rangle \Downarrow r}{\langle \sigma, c_1; c_2 \rangle \Downarrow r} \\
\text{(IfTrue)} \frac{\mathcal{B}[b]_\sigma = \top \quad \langle \sigma, c_1 \rangle \Downarrow r}{\langle \sigma, \text{if } b \text{ then } c_1 \text{ else } c_2 \text{ fi} \rangle \Downarrow r} \\
\text{(WhileFalse)} \frac{\mathcal{B}[b]_\sigma = \perp}{\langle \sigma, \text{while } b \text{ do } c \text{ end} \rangle \Downarrow \text{norm}(\sigma)} \\
\text{(WhileTrueErr)} \frac{\mathcal{B}[b]_\sigma = \top \quad \langle \sigma, c \rangle \Downarrow \text{err}}{\langle \sigma, \text{while } b \text{ do } c \text{ end} \rangle \Downarrow \text{err}}
\end{array}
\qquad
\begin{array}{c}
\text{(Ass)} \frac{\mathcal{A}[a]_\sigma = n}{\langle \sigma, x := a \rangle \Downarrow \text{norm}(\sigma[x \mapsto n])} \\
\text{(SeqErr)} \frac{\langle \sigma, c_1 \rangle \Downarrow \text{err}}{\langle \sigma, c_1; c_2 \rangle \Downarrow \text{err}} \\
\text{(IfFalse)} \frac{\mathcal{B}[b]_\sigma = \perp \quad \langle \sigma, c_2 \rangle \Downarrow r}{\langle \sigma, \text{if } b \text{ then } c_1 \text{ else } c_2 \text{ fi} \rangle \Downarrow r} \\
\text{(WhileTrue)} \frac{\mathcal{B}[b]_\sigma = \top \quad \langle \sigma', \text{while } b \text{ do } c \text{ end} \rangle \Downarrow r}{\langle \sigma, \text{while } b \text{ do } c \text{ end} \rangle \Downarrow r}
\end{array}$$

We redefine Hoare triples “ $\{P\} c \{Q\}$ ” to mean that, whenever  $c$  is started in a state satisfying  $P$ , and terminates with result  $r$ , then  $r = \text{norm}(\sigma)$  (and hence  $r \neq \text{err}$ ) where the state  $\sigma$  satisfies  $Q$ .

**2-1** Give the evaluation rules for assumption and assertion statements.

**Solution**

$$\begin{array}{c}
\text{(AssertTrue)} \frac{\mathcal{B}[b]_\sigma = \top}{\langle \sigma, \text{assert } b \rangle \Downarrow \text{norm}(\sigma)} \\
\text{(AssumeTrue)} \frac{\mathcal{B}[b]_\sigma = \top}{\langle \sigma, \text{assume } b \rangle \Downarrow \text{norm}(\sigma)}
\end{array}
\qquad
\begin{array}{c}
\text{(AssertFalse)} \frac{\mathcal{B}[b]_\sigma = \perp}{\langle \sigma, \text{assert } b \rangle \Downarrow \text{err}}
\end{array}$$

■

**2-2** Design Hoare rules for assumption and assertion statements.

**Solution**

$$\begin{array}{c}
\text{(AssertTrue)} \frac{P \Rightarrow b}{\{P\} \text{assert } b \{P\}} \\
\text{(AssumeTrue)} \frac{P \Rightarrow b}{\{P\} \text{assume } b \{P\}}
\end{array}
\qquad
\begin{array}{c}
\text{(AssertFalse)} \frac{P \Rightarrow \neg b}{\{P\} \text{assume } b \{\top\}} \\
\text{(AssumeFalse)} \frac{P \Rightarrow \neg b}{\{P\} \text{assume } b \{\perp\}}
\end{array}$$

■

**2-3** Compute  $\text{wlp}(X := X + 1; \text{assume } X > 0; Y := Y + X, X + Y + Y \geq 3)$ .

**Solution**

$$\begin{aligned}
 & \text{wlp}(X := X + 1; \text{assume } X > 0; Y := Y + X, X + Y + Y \geq 3) \\
 &= \text{wlp}(X := X + 1; \text{assume } X > 0, \text{wlp}(Y := Y + X, X + Y + Y \geq 3)) \\
 &= \text{wlp}(X := X + 1; \text{assume } X > 0, X + Y + X + Y + X \geq 3) \\
 &= \text{wlp}(X := X + 1, \text{wlp}(\text{assume } X > 0, X + Y + X + Y + X \geq 3)) \\
 &= \text{wlp}(X := X + 1, (X > 0) \rightarrow (X + Y + X + Y + X \geq 3)) \\
 &= (X + 1 > 0) \rightarrow (X + 1 + Y + X + 1 + Y + X + 1 \geq 3) \\
 &= Y \geq 0
 \end{aligned}$$

■