

Model Selection

CE/CZ4042 – Tutorial 6

1. A three-layer perceptron network is used to approximate the following function mapping:

$$y = \sin(\pi x_1) \cos(2\pi x_2)$$

where $-1.0 \leq x_1, x_2 \leq +1.0$.

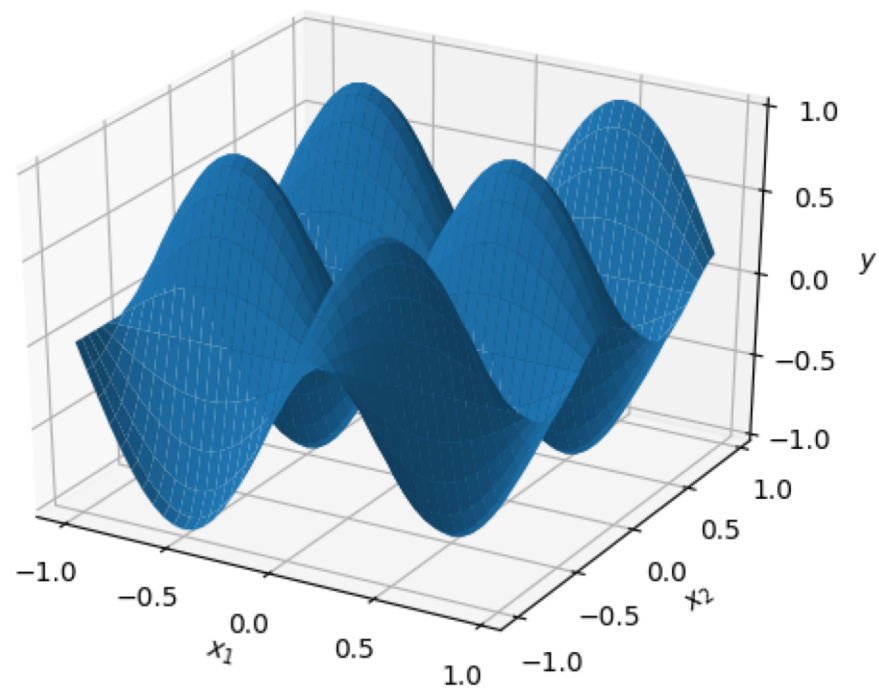
By using 100 data points in an equally spaced 10x10 grid of the input space, find the optimal number of hidden neurons for the approximation by using the following procedures:

- a. Random subsampling
- b. Five-fold cross validation
- c. Three-way data split

Use a learning factor $\alpha = 0.05$ and learning up to 20,000 epochs.

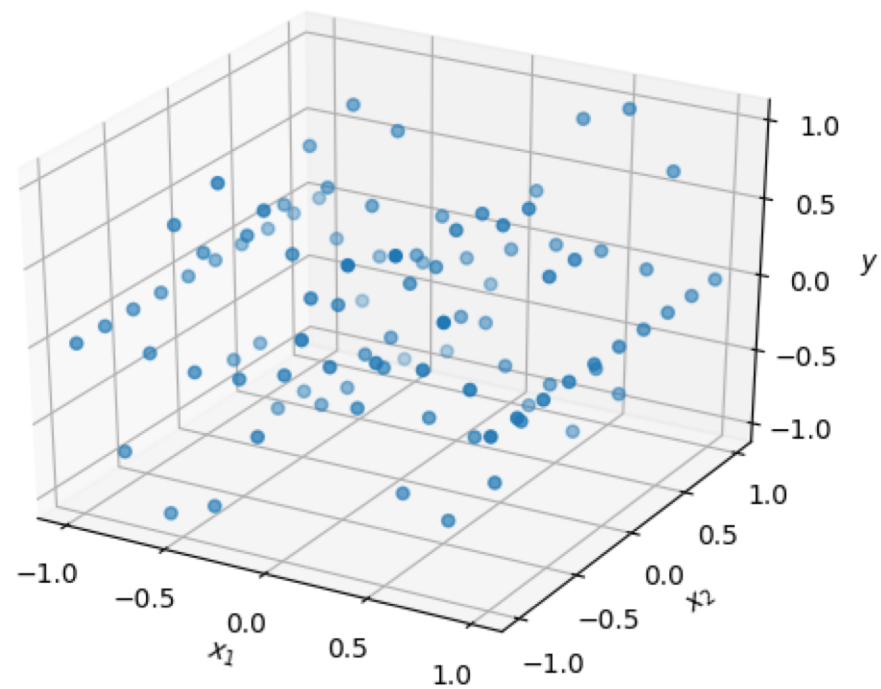
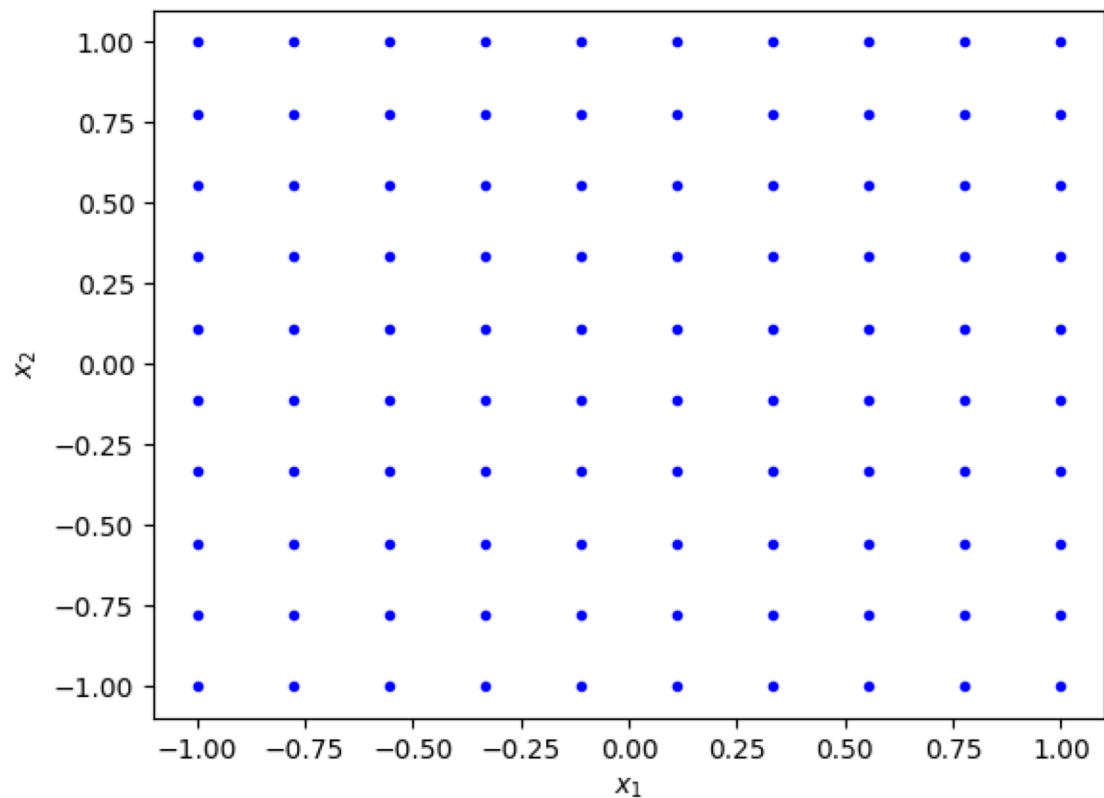
Show learning curves and predicted data points with the optimal number of hidden neurons.

$$y = \sin(\pi x_1) \cos(2\pi x_2) \quad \text{where } -1.0 \leq x_1, x_2 \leq +1.0.$$

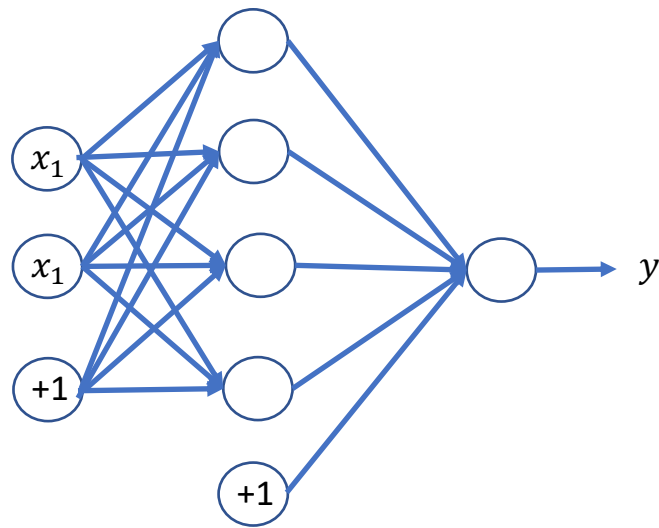


$$y = \sin(\pi x_1) \cos(2\pi x_2) \quad \text{where } -1.0 \leq x_1, x_2 \leq +1.0.$$

Data is in a grid of 10x10



$$y = \sin(\pi x_1) \cos(2\pi x_2) \quad \text{where } -1.0 \leq x_1, x_2 \leq +1.0.$$



For hidden neurons, let $f(u) = \frac{1}{1+e^{-u}}$

Output neuron is a linear neuron

K Data Splits: Random Subsampling



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K Data Splits: Random Subsampling

For each experiment k :

For each model m :

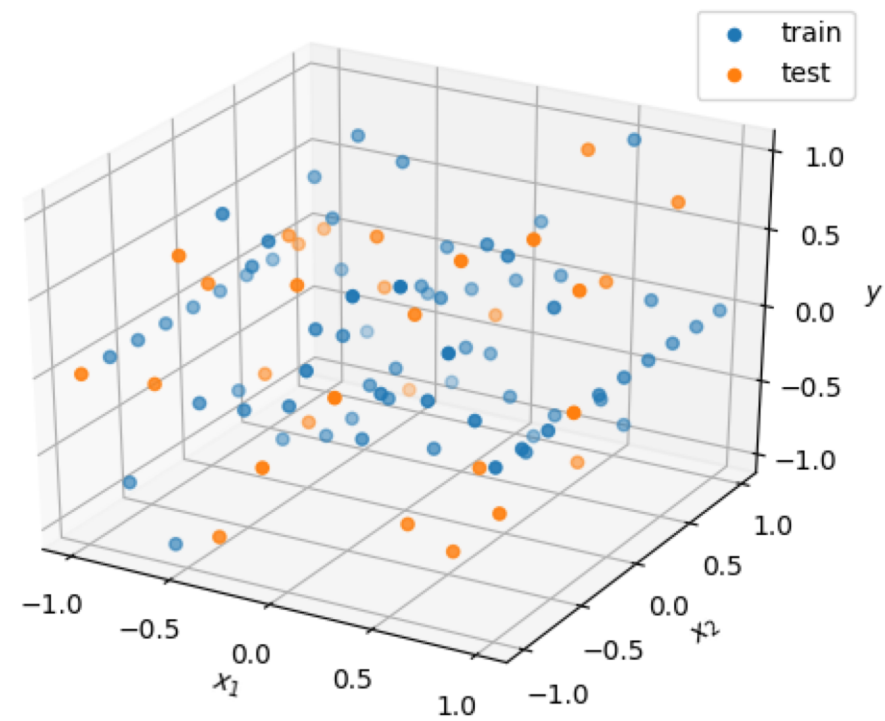
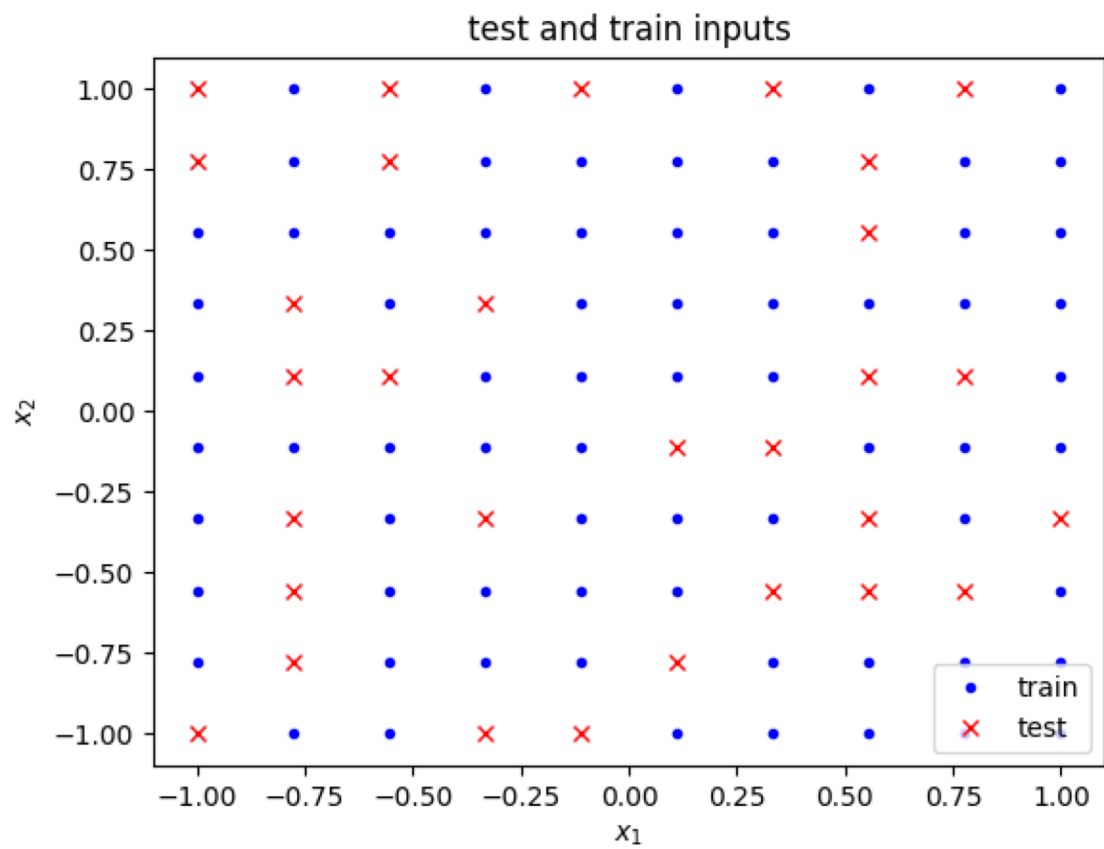
Compute error $e_{k,m}$

Compute mean error $e_m = \frac{1}{K} \sum_{k=1}^K e_{k,m}$

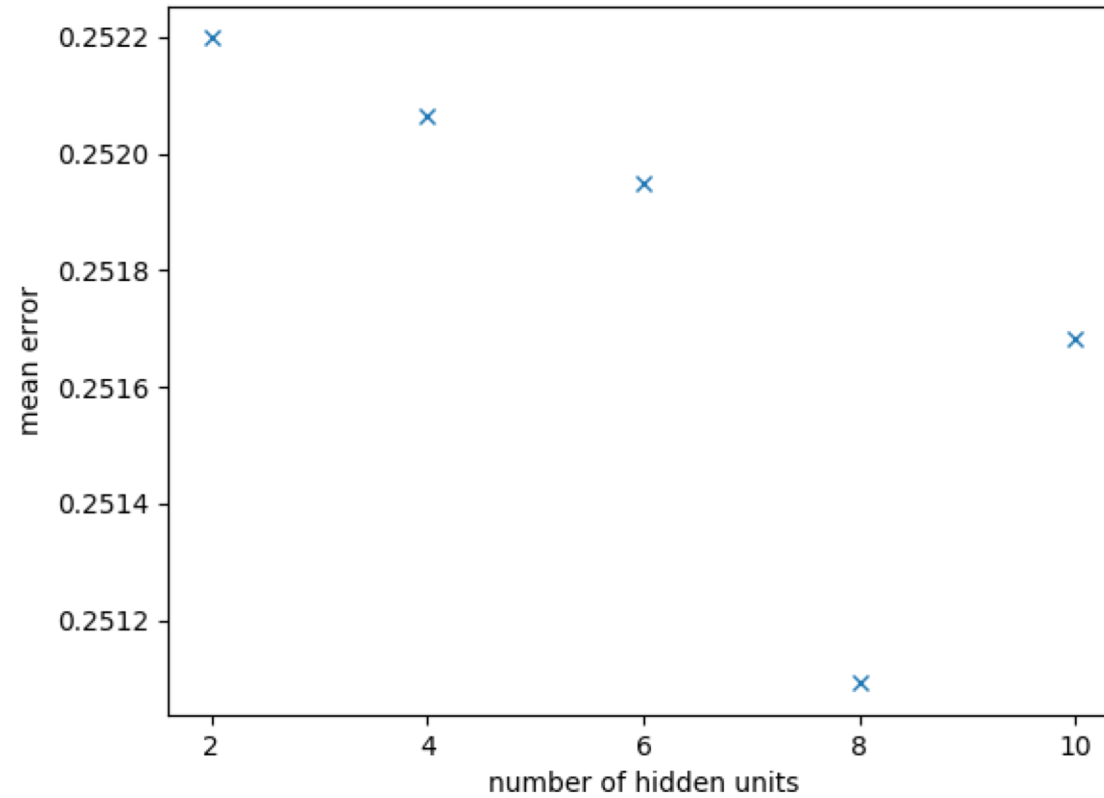
Optimal model with minimum error, $m^* = \operatorname{argmin} e_m$

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Train and test data for one experiment: [30: 70] split



Mean error of 10 experiments



Optimum number of hidden neurons = 8

K-fold Cross Validation



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For every fold f :

For every model m

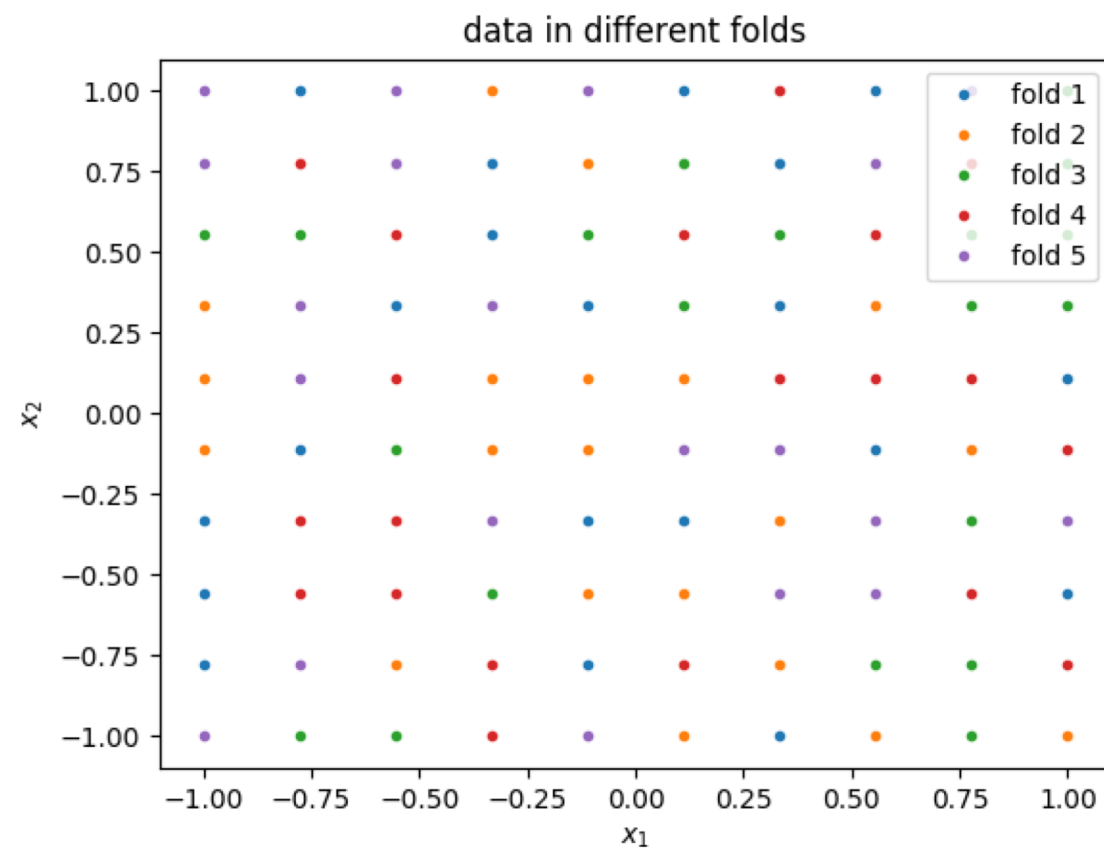
Train the model, using data not in fold f

Error $e_{m,f}$ = error on data in fold f

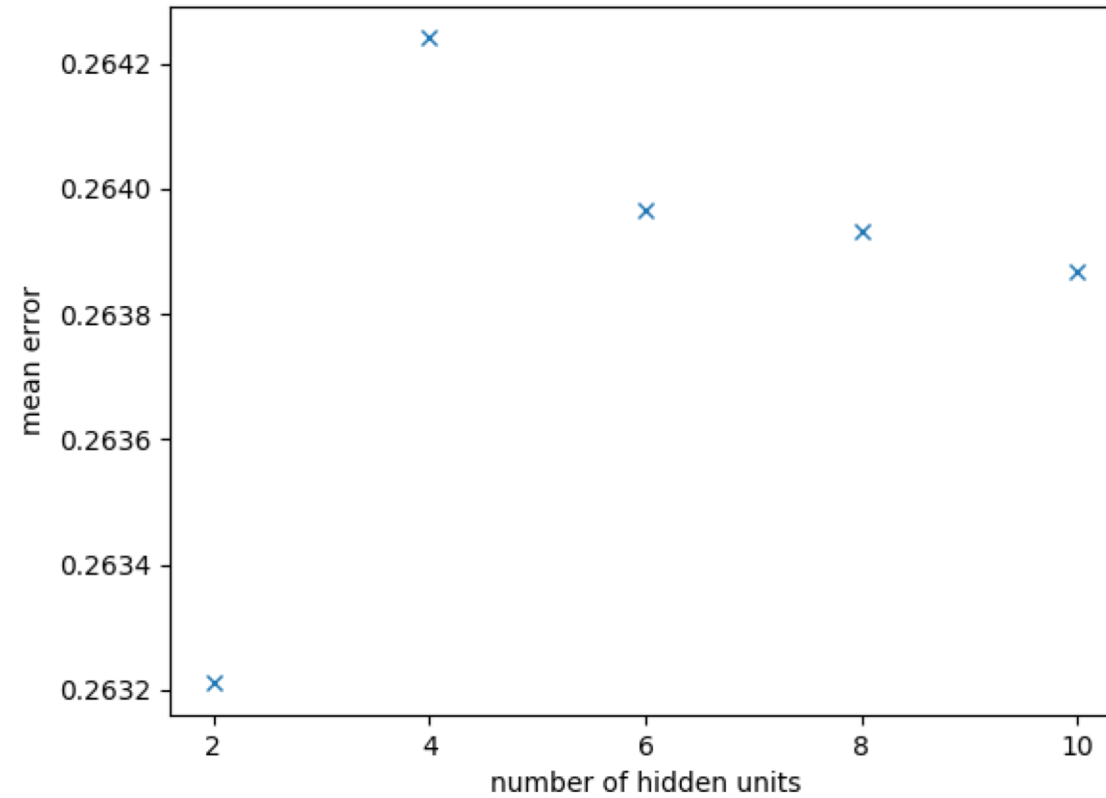
For every model m

$$\text{CV error } e_m = \frac{1}{F} \sum_f e_{m,f}$$

Select the model with minimum CV error, $m^* = \operatorname{argmin} e_m$



Mean cross-validation error of 10 experiments



Optimum number of hidden neurons = 2

Three-Way Data Splits Method

- **Training set:** examples for *learning* to fit the parameters of several possible classifiers. In the case of DNN, we would use the training set to find the “optimal” weights with the gradient descent rule.

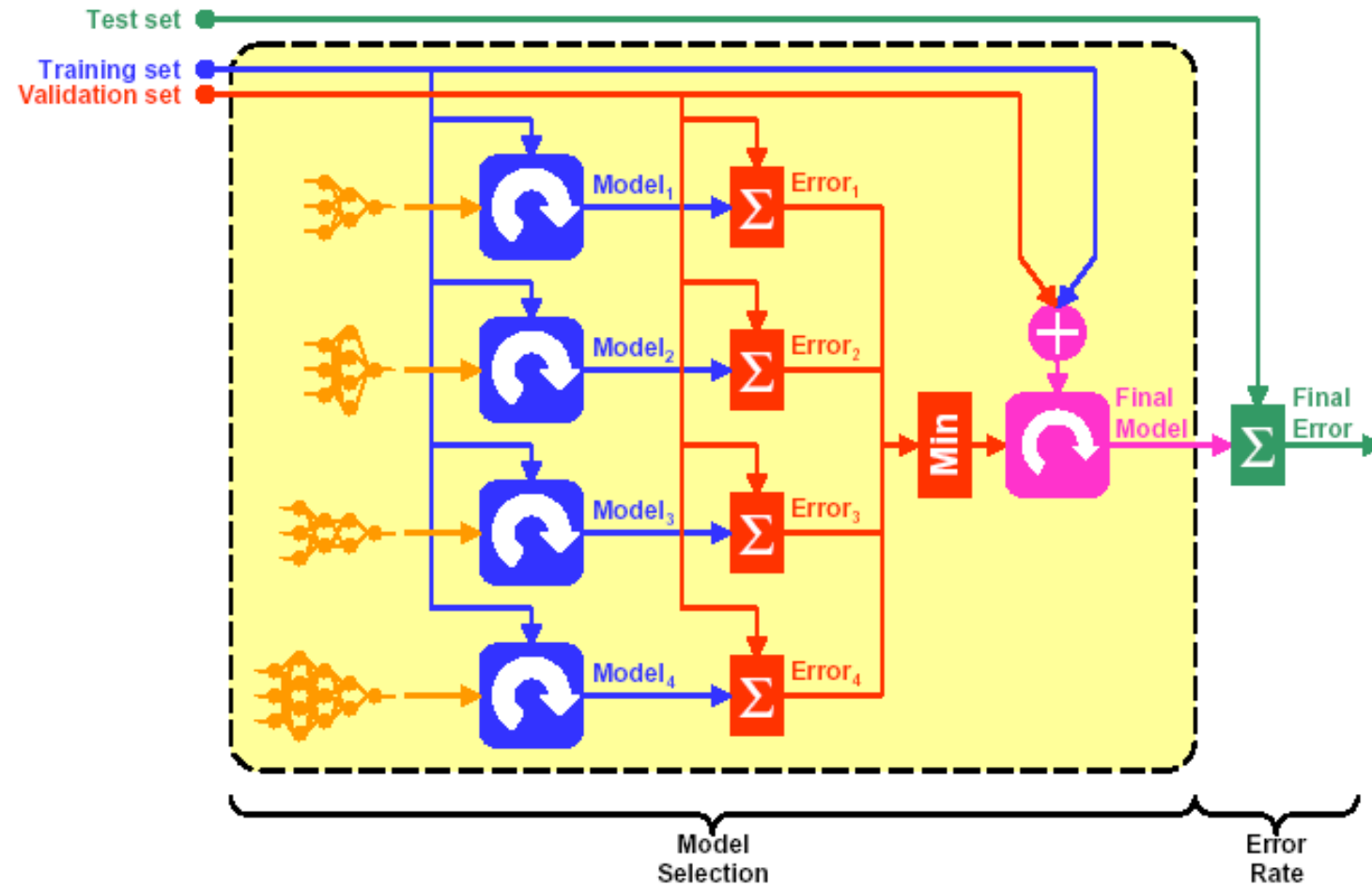
$$\mathbf{W}^*, \mathbf{b}^* = \underset{\mathbf{W}, \mathbf{b}}{\operatorname{argmin}} J(\mathbf{W}, \mathbf{b})$$

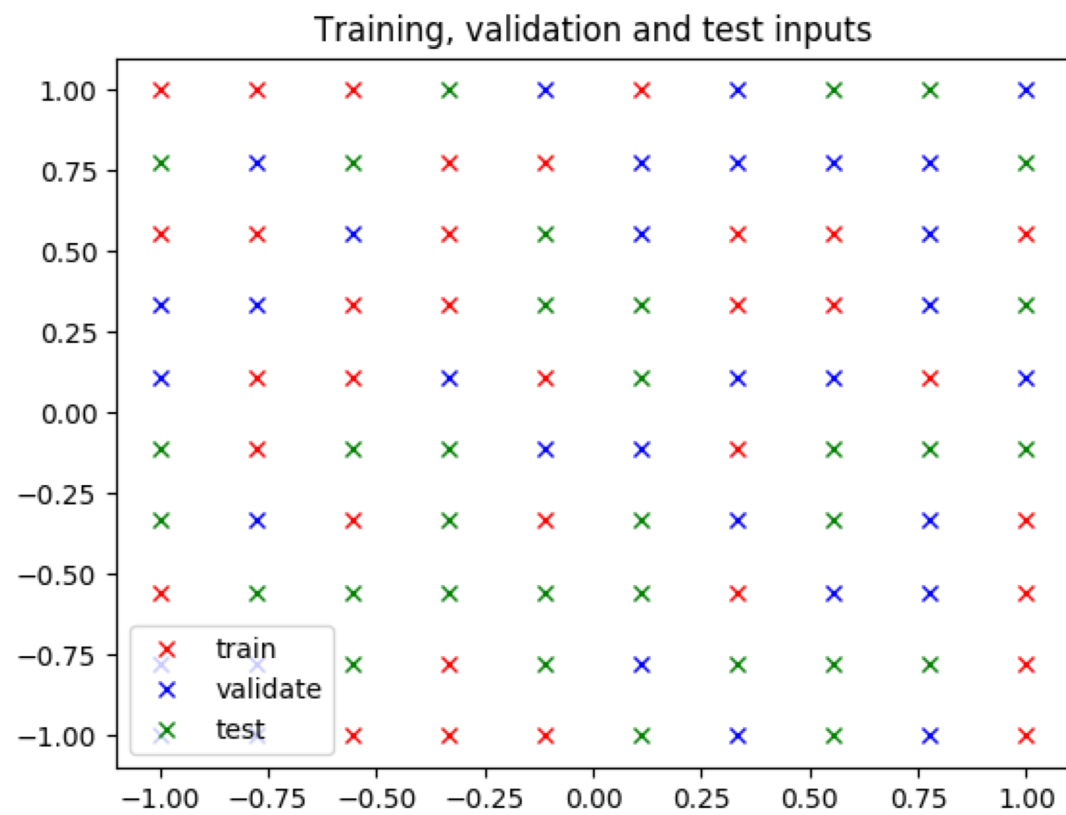
- **Validation set:** examples to *determine* the error J_m of different models m , using the validation set. The optimal model m^* is given by

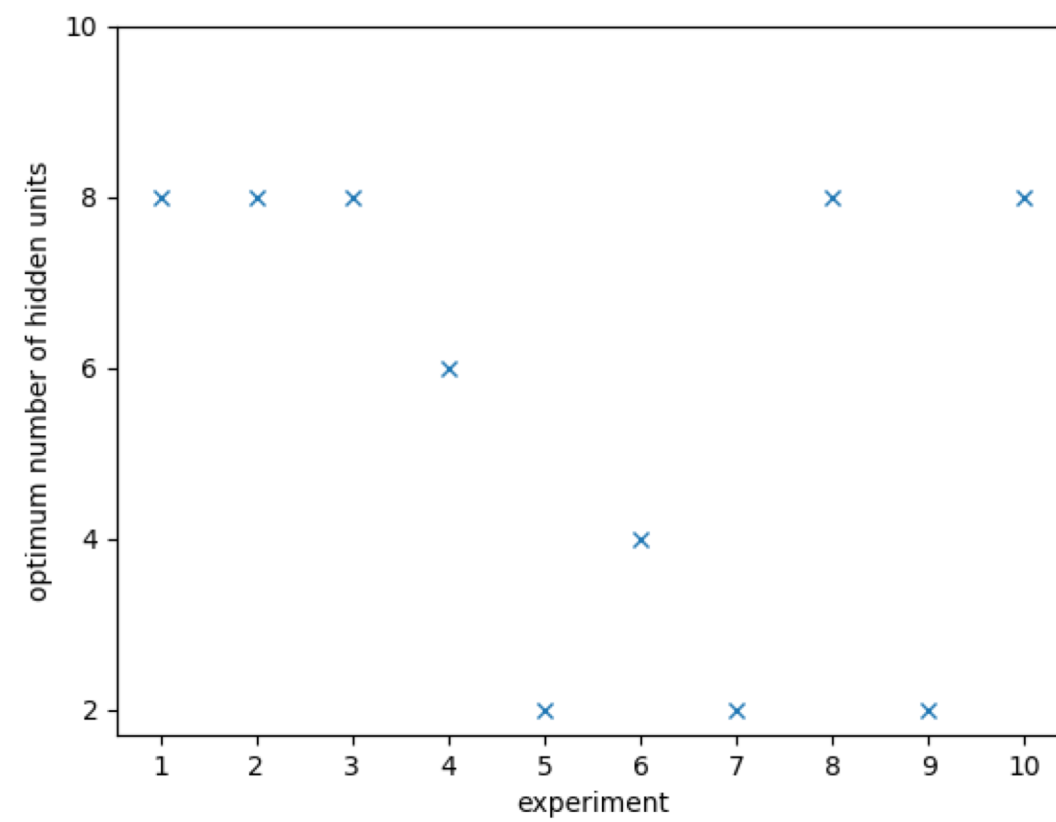
$$m^* = \underset{m}{\operatorname{argmin}} J_m$$

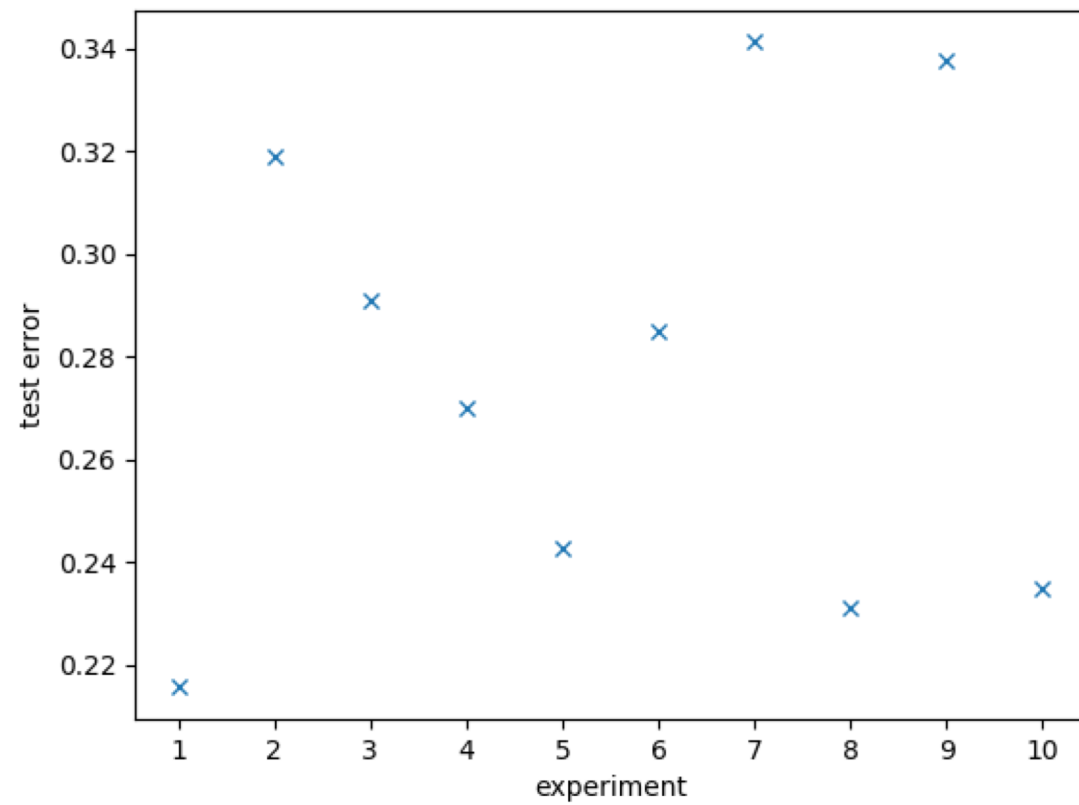
- **Training + Validation set:** combine examples used to re-train/redesign $model_{m^*}$, and find new “optimal” weights.
- **Test set:** examples used only to *assess* the performance of a *trained model* m^* . We will use the test data to estimate the error rate after we have trained the final model with train + validation data.

Three-Way Data Splits Method









Optimal number of hidden neurons is 8