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graph LR
    DS[DeepSoccer Simulation] --> S[2v2 Soccer]
    OD[Object Detection] --> OF[Object Following]
    BM[Basic Motion] --> OF
    OF --> S
  
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The diagram illustrates the DeepSoccer architecture. It consists of four main components represented by green rounded rectangles: 'DeepSoccer Simulation', '2v2 Soccer', 'Object Detection', and 'Object Following'. 'Object Detection' and 'Basic Motion' both have arrows pointing to 'Object Following'. 'Object Following' then has an arrow pointing to '2v2 Soccer'. Finally, 'DeepSoccer Simulation' has an arrow pointing to '2v2 Soccer'.

Overall Project Deliverable	Progress
Basic Movement	In progress
Image recognition	In progress
New sensor implementation	Not started
Ball Striking	Not started
Co-op and Versus	Not started
Github with documentation	Not started
Summary and report	Not started

Project is On Schedule

[illegible]

Previous Meeting Action Items:

Item	Description	Owner	Target Date	Status
1	Get familiar with car and previous years' work	Everyone	Jan 22	In progress
2	Move to Sharepoint	Arjun	Jan 19	Done
3	Kanban & Gantt Chart	Julie	Jan 22	Done
4	Car CAD Models	Cooper	Feb 12	In progress
5	Fill out inventory form – initial inventory	Jarod, Arjun, Casey, Julie	Jan 22	Done
6	Reach out to stakeholders and establish weekly meetings	Arjun	Jan 19	Done
7	Unity soccer simulation training	Casey	Jan 31	In progress

Biweekly Action Items:

Item	Description	Owner	Target Date	Status
1	Get all cars working with manual movement	Everyone	Feb 9	In progress
2	Move at least 1 car autonomously	Everyone	Jan 31	In progress
3	Redo hardware attachment to cars	Everyone	Feb 12	In progress
4	Demonstrate image processing	Everyone	Jan 31	In progress
5	Start working on Unity AI model to play soccer	Everyone	Jan 31	Not started



Significant Roadblocks/ Non-developing Items:

- Not all cars move forwards/backwards or can be controlled
- Documentation and diagrams from previous years are hard to figure out

Request for teaching staff:Budget:

Total Proposed	Plan to Date	Used to Date	Used Vs Plan
\$3500 USD	\$0 USD	\$0 USD	+/- \$0 USD

Short Term Schedule:

Jan											
22					29		31			5	
											
							Have image recognition and autonomous movement			Start research on new sensor	

	A	B	C	D	E	F	G	H	I	J
1	Team Members:	Team Lead: Jarod Marshel (jarodmar@uw.edu) Budget Manager: Casey Rittenhouse (caseyrit@uw.edu) Point of Contact: Arjun Simha (arjunsim@uw.edu) Mason Kang (masonny1@uw.edu) K Gupta (kshitiig@uw.edu) Julie Ham (jham2417@uw.edu) Cooper Ritter (ritter4x@uw.edu)			Instructions: Insert new rows at bottom of week >> copy last row with entries >> paste into new rows >> fill in appropriate information. Hover over cells if information is too long to view Dates and information can change everyweek on meeting with NN					
2	Not Started	In progress	Complete	2 - High	3 - Med	1 - Critical				
3	Status	Priority	Task #	People	Goal Date	Last Update	Task	Task Response / Deliverable	Notes	Milestone/Goal
4	Current Week --		Week 3							
5	Complete	2 - High	3	ALL	1/18/2024	1/18/2024	Contact industry sponsor and faculty mentor to set up weekly meet	Meetings: industry Mon 1p, faculty Mon 1:30p		
6	Complete	2 - High	3	ALL	1/18/2024	1/18/2024	Contact Dalton for laptop password.	Password and laptop work		
7	Complete	2 - High	3	ALL	1/22/2024		Fill out inventory sheet			
8	In progress	2 - High	3	ALL	1/22/2024		Figure out tasks.			
9	In progress	2 - High	3	ALL	1/22/2024		Review previous years Githubs to become familiar with project.			
10	Not Started	2 - High	3	ALL	1/22/2024		Biweekly Report due by Monday (1/22)			
11			Week 4							
12	Not Started	2 - High	4	ALL	1/31/2024		Start Training in Unity 5 Engine (JetRacer Soccer 2v2)			
13	Not Started	2 - High	4	ALL	1/29/2024		Biweekly Report due by Monday (1/29)			
14	Not Started	2 - High	4	ALL	1/31/2024		Demonstrate basic motion of JetRacer			
15	Not Started	2 - High	4	ALL	1/31/2024		Demonstrate JetRacer Image Recognition of JetRacer			
16			Week 5							
17	Not Started		5	ALL						
18	Not Started		5	ALL						
19	Not Started		5	ALL						
20	Not Started		5	ALL						
21	Not Started		5	ALL						
22			Week 6							
23	Not Started	3 - Med	6	ALL	2/29/2024		Trade study of possible sensor additions			
24	Not Started	3 - Med	6	ALL	2/29/2024		Preliminary Design Review			
25	Not Started		6	ALL						
26	Not Started		6	ALL						
27	Not Started		6	ALL						
28	Not Started		6	ALL						
29	Not Started		6	ALL						
30	Not Started		6	ALL						
31			Week 7							
32	Not Started		7	ALL						
33	Not Started		7	ALL						
34	Not Started		7	ALL						
35			Week 8							
36	Not Started		8	ALL						
37			Week 9							
38	Not Started	3 - Med	9	ALL			Showcase Vehicle Scoring Soccer Ball in the Goal in Real-World			
39	Not Started		9	ALL						
40			Week 10							

Kanban for task planning and timelines
(will continue to update)

ENGINE TEAM JetRacer INVENTORY										
BUDGET MANAGER CONTACT INFO										
NAME:			Casey Rittenhouse							
EMAIL			caseyrit@uw.edu							
PHONE - CELL			(925)-490-5868							
ITEM	ITEM DESCRIPTION	SOURCE	COST	WARRANTY		PURCHASE/ACQUIRE DATE	MANUFACTURER	SERIAL NO.	LOCATION STORED	CONDITION
				YES	VALID THRU					
JetRacer Car 1		Lockheed Martin				1/9/2024				
JetRacer Car 2		Lockheed Martin				1/9/2024				
JetRacer Car 3		Lockheed Martin				1/9/2024				
JetRacer Car 4		Lockheed Martin				1/9/2024				
4 R/C Controllers		Lockheed Martin				1/9/2024				
2 Soccer Balls		Lockheed Martin				1/9/2024				
1 Plant		ENGINE Lab				1/19/2024				
1 Keyboard		Lockheed Martin				1/9/2024				
1 ScrewDriver Power Tool (Pink)		Lockheed Martin				1/9/2024				
2 Krylon Spraypaint cans		Lockheed Martin				1/9/2024				
3 X4 LIDARs		ENGINE Lab				1/19/2024				
1 Jetson Nano (Working)		Lockheed Martin				1/9/2024				
1 Jetson Nano (Fried)		Lockheed Martin				1/9/2024				
4 Anker Portable Charger		Lockheed Martin				1/9/2024				
3 Battery Packs		Lockheed Martin				1/9/2024				
Metal Brackets		Lockheed Martin				1/9/2024				
2 wired mice		Lockheed Martin				1/9/2024				
2 Battery Pack Charger		Lockheed Martin				1/9/2024				
SD Car Reader		Lockheed Martin				1/9/2024				
2 Soccer Goals		Lockheed Martin				1/9/2024				
2 car covers		Lockheed Martin				1/9/2024				

Current inventory spreadsheet with source of each item

Team Roles

- **Project Manager** - Jarod
- **Point of Contact** - Arjun
- **Budget Manager** - Casey

- **ROS/Hardware (Layout, PCB, CAD, LIDAR):**
 - Cooper, Casey, Jarod
- **Unity Team:**
 - Mason
- **CV/Image Recognition Team:**
 - K, Julie, Arjun

Previous Year's Work

- Built and gained full range of motion of 4 JetRacers using software
- Set up a simulation environment to virtually train the agents
- Structured a reward system for the reinforcement learning model
- Implemented object detection model that identifies a soccer ball, opponent, and goal
- Implemented software to follow and strike a ball
- Developed logic process for striking a ball into a goal
- Simulation results with reward structure demonstrate that agents can be trained to efficiently compete in a 2v2 soccer match
- Created a GitHub page documenting the hardware and software instructions to setup JetRacers, a summary of the work completed, and plans for future work

Our Final Deliverables

- Demonstrate basic motion of JetRacer: 01/2024
- Demonstrate JetRacer Image Recognition for soccer play: 01/2024
- Trade study of possible sensor additions: 02/2024
- Preliminary Design Review: 02/2024
- Showcase vehicle scoring soccer ball in the goal in real-world: 03/2024
- Add additional agents in the real world: 04/2024
- Final Data Review: 05/2024