Full Name: Shadi Haddad E-mail: shhaddad@ucsc.edu Tel: +1 (831) 332-1640

EDUCATION

PhD in Applied Mathematics

Expected 2023

School of Engineering, University of California Santa Cruz

M.Sc. in Mechanical Engineering

January 2018

College of Mechanical Engineering, University of Tehran, Tehran, Iran
Thesis title: "Second order sliding mode tracking control of a piezoelectric tapered micro actuator with axial deflection and system nonlinearity"

B.Sc. in Mechanical Engineering

July 2015

College of Mechanical Engineering, Chamran University of Ahvaz, Ahvaz, Iran

RESEARCH INTEREST

Uncertain dynamical systems, Control theory, Robotic.

SELECTED RESEARCH AND ACADEMIC ACTIVITIES

- Dynamic modeling and vibration analysis of mechanical and micro/nano electromechanical systems (MEMS)
- Regulation and tracking control for variable structural and nonlinear mechanical and micro-electro-mechanical systems
- Modeling and vibration analysis of piezoelectric micro-actuators
- Nonlinear finite element method programming
- Observer-based sliding mode controllers and fault detection
- Inverse and forward kinematics of robot manipulators

JOURNAL PAPERS

- Shadi Haddad, Abhishek Halder and Baljeet Singh, "Density-Based Stochastic Reachability Computation for Occupancy Prediction in Automated Driving", Transactions on Intelligent Transportation Systems (Submitted), 2020.
- Shadi Haddad, Abhishek Halder. "The Convex Geometry of Integrator Reach Sets", American Control Conference, 2019.
- M. Mousavi, M. Rahnavard, S. Haddad, "Observer based fault reconstruction schemes using terminal sliding modes", International Journal of Control, 2018.
- S. Haddad, Sh. Siahpour, M. Moghimi Zand, "Dynamics behavior and stability of thin shallow micro shells considering the effect of squeeze film damping under electrostatic actuation," Submitted to Journal of Microsystem Technologies, 2018 (under review).
- S. Haddad, M. Baghani, "Analytical study on nonlinear 3D coupled deformations of tapered FG micro-beams accounting for size effects", Iranian Journal of Science and Technology, 2018.

Talks And Poster presentation

- Spot light talk and poster presentation "Understanding the Geometry of Integrator Reach Sets for Robotics Applications", Bay Area Robotics Symposium, University of California, Berkeley, 2019.
- American Control Conference, "The Convex Geometry of Integrator Reach Sets", 2020.

<u>Awards</u>

- Chancellor's Fellowship, University of California, Santa Cruz, 2019.
- Student Travel Award, American Control Conference, 2020.

COMPUTER AND PROGRAMMING SKILLS

• Programming Languages: MATLAB (Programming and Simulink), MAPLE, C++, ARDUINO, Python

• Software:

Engineering and Modeling: SOLIDWORKS
 Simulation and Analysis: ANSYS, ABAQUS

Grid Generation: ANSYS MeshingGeneral: MS-Word, MS-Excel, Latex