## Foundations of Software Fall 2017

Week 3

## Review (and more details)

#### Recall: Simple Arithmetic Expressions

The set  $\ensuremath{\mathcal{T}}$  of terms is defined by the following abstract grammar:

#### Recall: Inference Rule Notation

More explicitly: The set  ${\mathcal T}$  is the  $\mathit{smallest}$  set  $\mathit{closed}$  under the following rules.

$$\label{eq:true} \begin{split} \text{true} &\in \mathcal{T} & \text{false} &\in \mathcal{T} & 0 \in \mathcal{T} \\ \frac{\textbf{t}_1 \in \mathcal{T}}{\text{succ } \textbf{t}_1 \in \mathcal{T}} & \frac{\textbf{t}_1 \in \mathcal{T}}{\text{pred } \textbf{t}_1 \in \mathcal{T}} & \frac{\textbf{t}_1 \in \mathcal{T}}{\text{iszero } \textbf{t}_1 \in \mathcal{T}} \\ & \frac{\textbf{t}_1 \in \mathcal{T} & \textbf{t}_2 \in \mathcal{T} & \textbf{t}_3 \in \mathcal{T}}{\text{if } \textbf{t}_1 \text{ then } \textbf{t}_2 \text{ else } \textbf{t}_3 \in \mathcal{T}} \end{split}$$

#### **Generating Functions**

Each of these rules can be thought of as a generating function that, given some elements from  $\mathcal{T}$ , generates some other element of  $\mathcal{T}$ . Saying that  $\mathcal{T}$  is closed under these rules means that  $\mathcal{T}$  cannot be made any bigger using these generating functions — it already contains everything "justified by its members."

$$\label{eq:true} \begin{split} & \text{true} \in \mathcal{T} & \text{false} \in \mathcal{T} & 0 \in \mathcal{T} \\ & \frac{t_1 \in \mathcal{T}}{\text{succ } t_1 \in \mathcal{T}} & \frac{t_1 \in \mathcal{T}}{\text{pred } t_1 \in \mathcal{T}} & \frac{t_1 \in \mathcal{T}}{\text{iszero } t_1 \in \mathcal{T}} \\ & \frac{t_1 \in \mathcal{T} & t_2 \in \mathcal{T} & t_3 \in \mathcal{T}}{\text{if } t_1 \text{ then } t_2 \text{ else } t_3 \in \mathcal{T}} \end{split}$$

Let's write these generating functions explicitly.

```
\begin{array}{lll} F_1(U) &=& \{ \text{true} \} \\ F_2(U) &=& \{ \text{false} \} \\ F_3(U) &=& \{ 0 \} \\ F_4(U) &=& \{ \text{succ } \mathbf{t}_1 \mid \mathbf{t}_1 \in U \} \\ F_5(U) &=& \{ \text{pred } \mathbf{t}_1 \mid \mathbf{t}_1 \in U \} \\ F_6(U) &=& \{ \text{iszero } \mathbf{t}_1 \mid \mathbf{t}_1 \in U \} \\ F_7(U) &=& \{ \text{if } \mathbf{t}_1 \text{ then } \mathbf{t}_2 \text{ else } \mathbf{t}_3 \mid \mathbf{t}_1, \mathbf{t}_2, \mathbf{t}_3 \in U \} \end{array}
```

Each one takes a set of terms  ${\cal U}$  as input and produces a set of "terms justified by  ${\cal U}$ " as output.

If we now define a generating function for the whole set of inference rules (by combining the generating functions for the individual rules),

$$F(U) = F_1(U) \cup F_2(U) \cup F_3(U) \cup F_4(U) \cup F_5(U) \cup F_6(U) \cup F_7(U)$$

then we can restate the previous definition of the set of terms  $\ensuremath{\mathcal{T}}$  like this:

#### Definition:

- ▶ A set U is said to be "closed under F" (or "F-closed") if  $F(U) \subseteq U$ .
- ▶ The set of terms  $\mathcal T$  is the smallest F-closed set. (I.e., if  $\mathcal O$  is another set such that  $F(\mathcal O)\subseteq \mathcal O$ , then  $\mathcal T\subseteq \mathcal O$ .)

Our alternate definition of the set of terms can also be stated using the generating function F:

$$S_0 = \emptyset$$

$$S_{i+1} = F(S_i)$$

$$S = \bigcup_i S_i$$

Compare this definition of  ${\cal S}$  with the one we saw last time:

$$\begin{array}{lll} \mathcal{S}_0 & = & \emptyset \\ \mathcal{S}_{i+1} & = & \left\{ \texttt{true}, \texttt{false}, 0 \right\} \\ & \cup & \left\{ \texttt{succ} \ \texttt{t}_1, \texttt{pred} \ \texttt{t}_1, \texttt{iszero} \ \texttt{t}_1 \ | \ \texttt{t}_1 \in \mathcal{S}_i \right\} \\ & \cup & \left\{ \texttt{if} \ \texttt{t}_1 \ \texttt{then} \ \texttt{t}_2 \ \texttt{else} \ \texttt{t}_3 \ | \ \texttt{t}_1, \texttt{t}_2, \texttt{t}_3 \in \mathcal{S}_i \right\} \end{array}$$

$$S = \bigcup_i S_i$$

We have "pulled out"  $\digamma$  and given it a name.

Note that our two definitions of terms characterize the same set from different directions:

- "from above," as the intersection of all F-closed sets;
- "from below," as the limit (union) of a series of sets that start from ∅ and get "closer and closer to being F-closed."

Proposition 3.2.6 in the book shows that these two definitions actually define the same set.

Warning: Hard hats on for the next slide!

#### Structural Induction

The principle of structural induction on terms can also be re-stated using generating functions:

```
Suppose T is the smallest F-closed set.
```

```
If, for each set U, from the assumption "P(u) holds for every u \in U" we can show "P(v) holds for any v \in F(U)," then P(t) holds for all t \in T.
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```

Why?

#### Structural Induction

#### Why? Because:

- ▶ We assumed that T was the *smallest F*-closed set, i.e., that  $T \subseteq O$  for any other F-closed set O.
- ▶ But showing

```
for each set U,
given P(u) for all u \in U
we can show P(v) for all v \in F(U)
```

amounts to showing that "the set of all terms satisfying P" (call it O) is itself an F-closed set.

▶ Since  $T \subseteq O$ , every element of T satisfies P.

#### Structural Induction

```
If, for each term s, given P(r) for all immediate subterms r of s we can show P(s), then P(t) holds for all t.
```

Recall, from the definition of  $\mathcal{S}$ , it is clear that, if a term  $\mathbf{t}$  is in  $\mathcal{S}_i$ , then all of its immediate subterms must be in  $\mathcal{S}_{i-1}$ , i.e., they must have strictly smaller depths. Therefore:

```
If, for each term s,
given P(r) for all immediate subterms r of s
we can show P(s),
then P(t) holds for all t.
```

#### Slightly more explicit proof:

- Assume that for each term s, given P(r) for all immediate subterms of s, we can show P(s).
- ► Then show, by induction on i, that P(t) holds for all terms t with depth i.
- ▶ Therefore, P(t) holds for all t.

# Operational Semantics and Reasoning

#### Recall: Abstract Machines

An abstract machine consists of:

- ▶ a set of *states*
- ▶ a transition relation on states, written →

For the simple languages we are considering at the moment, the term being evaluated is the whole state of the abstract machine.

#### Recall: Syntax for Booleans

#### Terms and values

#### Recall: Operational Semantics for Booleans

The evaluation relation  $t \longrightarrow t'$  is the smallest relation closed under the following rules:

```
\begin{array}{c} \text{ if false then } t_2 \text{ else } t_3 \longrightarrow t_3 \text{ (E-IFFALSE)} \\ \\ \frac{t_1 \longrightarrow t_1'}{\text{if } t_1 \text{ then } t_2 \text{ else } t_3 \longrightarrow \text{if } t_1' \text{ then } t_2 \text{ else } t_3} \text{ (E-IF)} \end{array}
```

if true then  $t_2$  else  $t_3 \longrightarrow t_2$  (E-IFTRUE)

#### Derivations

We can record the "justification" for a particular pair of terms that are in the evaluation relation in the form of a tree.

(on the board)

#### Terminology:

- ▶ These trees are called *derivation trees* (or just *derivations*).
- ▶ The final statement in a derivation is its *conclusion*.
- We say that the derivation is a witness for its conclusion (or a proof of its conclusion) — it records all the reasoning steps that justify the conclusion.

#### Observation

Lemma: Suppose we are given a derivation tree  ${\cal D}$  witnessing the pair  $({\bf t},{\bf t}')$  in the evaluation relation. Then either

- 1. the final rule used in  $\mathcal D$  is E-IFTRUE and we have t=if true then  $t_2$  else  $t_3$  and  $t'=t_2$ , for some  $t_2$  and  $t_3$ , or
- 2. the final rule used in  $\mathcal D$  is E-IFFALSE and we have  ${\sf t}={\sf if}$  false then  ${\sf t}_2$  else  ${\sf t}_3$  and  ${\sf t}'={\sf t}_3$ , for some  ${\sf t}_2$  and  ${\sf t}_3$ , or
- 3. the final rule used in  $\mathcal{D}$  is E-IF and we have  $\mathsf{t} = \mathsf{if}\ \mathsf{t}_1$  then  $\mathsf{t}_2$  else  $\mathsf{t}_3$  and  $\mathsf{t}' = \mathsf{if}\ \mathsf{t}'_1$  then  $\mathsf{t}_2$  else  $\mathsf{t}_3$ , for some  $\mathsf{t}_1$ ,  $\mathsf{t}'_1$ ,  $\mathsf{t}_2$ , and  $\mathsf{t}_3$ ; moreover, the immediate subderivation of  $\mathcal D$  witnesses  $(\mathsf{t}_1, \mathsf{t}'_1) \in \longrightarrow$ .

#### Induction on Derivations

We can now write proofs about evaluation "by induction on derivation trees."

Given an arbitrary derivation  $\mathcal D$  with conclusion  $t \longrightarrow t'$ , we assume the desired result for its immediate sub-derivation (if any) and proceed by a case analysis (using the previous lemma) of the final evaluation rule used in constructing the derivation tree.

E.g....

#### Induction on Derivations — Example

**Theorem:** If  $t \longrightarrow t'$ , i.e., if  $(t, t') \in \longrightarrow$ , then size(t) > size(t'). **Proof:** By induction on a derivation  $\mathcal{D}$  of  $t \longrightarrow t'$ .

- 1. Suppose the final rule used in  $\mathcal{D}$  is E-IFTRUE, with t=if true then  $t_2$  else  $t_3$  and  $t'=t_2$ . Then the result is immediate from the definition of  $\emph{size}$ .
- 2. Suppose the final rule used in  $\mathcal{D}$  is E-IFFALSE, with t=if false then  $t_2$  else  $t_3$  and  $t'=t_3$ . Then the result is again immediate from the definition of *size*.
- 3. Suppose the final rule used in  $\mathcal D$  is E-IF, with  $\mathbf t=\mathbf i\mathbf f$   $\mathbf t_1$  then  $\mathbf t_2$  else  $\mathbf t_3$  and  $\mathbf t'=\mathbf i\mathbf f$   $\mathbf t'_1$  then  $\mathbf t_2$  else  $\mathbf t_3$ , where  $(\mathbf t_1,\mathbf t'_1)\in\longrightarrow$  is witnessed by a derivation  $\mathcal D_1$ . By the induction hypothesis,  $\mathit{size}(\mathbf t_1)>\mathit{size}(\mathbf t'_1)$ . But then, by the definition of  $\mathit{size}$ , we have  $\mathit{size}(\mathbf t)>\mathit{size}(\mathbf t'_1)$ .

#### Normal forms

A *normal form* is a term that cannot be evaluated any further — i.e., a term t is a normal form (or "is in normal form") if there is no t' such that  $t \longrightarrow t'$ .

A normal form is a state where the abstract machine is halted — i.e., it can be regarded as a "result" of evaluation.

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Recall that we intended the set of *values* (the boolean constants true and false) to be exactly the possible "results of evaluation." Did we get this definition right?

#### Values = normal forms

**Theorem:** A term t is a value iff it is in normal form. **Proof:** 

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For the  $\longleftarrow$  direction, it is convenient to prove the contrapositive: If t is *not* a value, then it is *not* a normal form.

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For the  $\iff$  direction, it is convenient to prove the contrapositive: If t is *not* a value, then it is *not* a normal form. The argument goes by induction on t.

Note, first, that t must have the form if  $t_1$  then  $t_2$  else  $t_3$  (otherwise it would be a value). If  $t_1$  is true or false, then rule E-IFTRUE or E-IFFALSE applies to t, and we are done. Otherwise,  $t_1$  is not a value and so, by the induction hypothesis, there is some  $t_1'$  such that  $t_1 \longrightarrow t_1'$ . But then rule E-IF yields

if  $t_1$  then  $t_2$  else  $t_3 \longrightarrow \text{if } t_1'$  then  $t_2$  else  $t_3$ 

i.e., t is not in normal form.

#### Numbers

New syntactic forms

terms
constant zero
successor
predecessor
zero test

values numeric value

numeric values zero value successor value

New evaluation rules

 $\mathtt{t} \longrightarrow \mathtt{t}'$ 

$$\frac{\mathtt{t}_1 \longrightarrow \mathtt{t}_1'}{\mathtt{succ}\ \mathtt{t}_1 \longrightarrow \mathtt{succ}\ \mathtt{t}_1'} \tag{E-Succ}$$

$$pred 0 \longrightarrow 0$$
 (E-PREDZERO)

$$\texttt{pred (succ } nv_1) \longrightarrow nv_1 \quad \big(\text{E-PredSucc}\big)$$

$$\frac{\mathtt{t}_1 \longrightarrow \mathtt{t}_1'}{\mathtt{pred} \ \mathtt{t}_1 \longrightarrow \mathtt{pred} \ \mathtt{t}_1'} \tag{E-Pred}$$

$$\texttt{iszero 0} \longrightarrow \texttt{true} \qquad \big( \text{E-IszeroZero} \big)$$

$$\mathtt{iszero} \ (\mathtt{succ} \ \mathtt{nv}_1) \longrightarrow \mathtt{false} \big( E\text{-}\mathrm{IszeroSucc} \big)$$

$$\frac{t_1 \longrightarrow t_1'}{\text{iszero } t_1 \longrightarrow \text{iszero } t_1'} \qquad \text{(E-IsZero)}$$

#### Values are normal forms

Our observation a few slides ago that all values are in normal form still holds for the extended language.

Is the converse true? I.e., is every normal form a value?

#### Values are normal forms, but we have stuck terms

Our observation a few slides ago that all values are in normal form still holds for the extended language.

Is the converse true? I.e., is every normal form a value? No: some terms are  $\it stuck$ .

Formally, a stuck term is one that is a normal form but not a value. What are some examples?

Stuck terms model run-time errors.

#### Multi-step evaluation.

The multi-step evaluation relation,  $\longrightarrow$ \*, is the reflexive, transitive closure of single-step evaluation.

I.e., it is the smallest relation closed under the following rules:

$$\frac{t\longrightarrow t'}{t\longrightarrow^* t'}$$

$$\mathsf{t} \longrightarrow^* \mathsf{t}$$

$$\frac{t \longrightarrow^* t' \qquad t' \longrightarrow^* t''}{t \longrightarrow^* t''}$$

#### Termination of evaluation

**Theorem:** For every t there is some normal form t' such that

Proof:

#### Termination of evaluation

**Theorem:** For every t there is some normal form t' such that  $t \longrightarrow^* t'$ .

#### Proof:

► First, recall that single-step evaluation strictly reduces the size of the term:

if 
$$t \longrightarrow t'$$
, then  $\mathsf{size}(t) > \mathsf{size}(t')$ 

▶ Now, assume (for a contradiction) that

$$t_0, t_1, t_2, t_3, t_4, \dots$$

is an infinite-length sequence such that

$$t_0 \longrightarrow t_1 \longrightarrow t_2 \longrightarrow t_3 \longrightarrow t_4 \longrightarrow \cdots$$

Then

$$\mathit{size}(t_0) > \mathit{size}(t_1) > \mathit{size}(t_2) > \mathit{size}(t_3) > \dots$$

▶ But such a sequence cannot exist — contradiction!

#### **Termination Proofs**

Most termination proofs have the same basic form:

**Theorem:** The relation  $R \subseteq X \times X$  is terminating — i.e., there are no infinite sequences  $x_0$ ,  $x_1$ ,  $x_2$ , etc. such that  $(x_i, x_{i+1}) \in R$  for each i.

#### Proof:

- 1. Choose
  - ▶ a well-founded set (W,<) i.e., a set W with a partial order < such that there are no infinite descending chains  $w_0>w_1>w_2>\dots$  in W
  - ► a function f from X to W
- 2. Show f(x) > f(y) for all  $(x, y) \in R$
- Conclude that there are no infinite sequences x<sub>0</sub>, x<sub>1</sub>, x<sub>2</sub>, etc. such that (x<sub>i</sub>, x<sub>i+1</sub>) ∈ R for each i, since, if there were, we could construct an infinite descending chain in W.

## The Lambda Calculus

#### The lambda-calculus

- ▶ If our previous language of arithmetic expressions was the simplest nontrivial programming language, then the lambda-calculus is the simplest *interesting* programming language...
  - Turing complete
  - ▶ higher order (functions as data)
- ▶ Indeed, in the lambda-calculus, *all* computation happens by means of function abstraction and application.
- ▶ The e. coli of programming language research
- ▶ The foundation of many real-world programming language designs (including ML, Haskell, Scheme, Lisp, ...)

#### Intuitions

Suppose we want to describe a function that adds three to any number we pass it. We might write

```
plus3 x = succ (succ (succ x))
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That is, "plus3 x is succ (succ (succ x))."

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That is, "plus3 x is succ (succ (succ x))."
Q: What is plus3 itself?
A: plus3 is the function that, given x, yields
succ (succ (succ x)).
```

This function exists independent of the name plus3.

```
\lambda \mathtt{x.}\ \mathtt{t} is written "fun \mathtt{x}\,\rightarrow\,\mathtt{t}" in OCaml and "x \Rightarrow\,\mathtt{t}" in Scala.
```

plus3 =  $\lambda x$ . succ (succ (succ x))

So plus3 (succ 0) is just a convenient shorthand for "the function that, given x, yields succ (succ (succ x)), applied to succ 0."

```
plus3 (succ 0)
=
(λx. succ (succ (succ x))) (succ 0)
```

#### Abstractions over Functions

Consider the  $\lambda$ -abstraction

```
g = \lambda f. f (f (succ 0))
```

Note that the parameter variable  ${\tt f}$  is used in the *function* position in the body of  ${\tt g}$ . Terms like  ${\tt g}$  are called *higher-order* functions. If we apply  ${\tt g}$  to an argument like  ${\tt plus3}$ , the "substitution rule" yields a nontrivial computation:

```
g plus3
= (\lambda f. f (f (succ 0))) (\lambda x. succ (succ (succ x)))
i.e. (\lambda x. succ (succ (succ x)))
((\lambda x. succ (succ (succ x))) (succ 0))
i.e. (\lambda x. succ (succ (succ x)))
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i.e. succ (succ (succ (succ (succ (succ 0)))))
```

#### **Abstractions Returning Functions**

Consider the following variant of g:

```
double = \lambda f. \lambda y. f (f y)
```

I.e., double is the function that, when applied to a function f, yields a function that, when applied to an argument y, yields f (f y).

#### Example

#### The Pure Lambda-Calculus

As the preceding examples suggest, once we have  $\lambda\text{-abstraction}$  and application, we can throw away all the other language primitives and still have left a rich and powerful programming language.

In this language — the "pure lambda-calculus" —  $\ensuremath{\textit{everything}}$  is a function.

- ► Variables always denote functions
- ▶ Functions always take other functions as parameters
- ▶ The result of a function is always a function

## **Formalities**

### ${\sf Syntax}$

 $\begin{array}{cccc} t & ::= & & terms \\ & x & & variable \\ & \lambda x \cdot t & & abstraction \\ & t & t & application \end{array}$ 

#### Terminology:

- terms in the pure  $\lambda$ -calculus are often called  $\lambda$ -terms
- $\blacktriangleright$  terms of the form  $\lambda x$  . t are called  $\lambda\text{-}abstractions$  or just abstractions

#### Syntactic conventions

Since  $\lambda$ -calculus provides only one-argument functions, all multi-argument functions must be written in curried style.

The following conventions make the linear forms of terms easier to read and write:

► Application associates to the left

E.g., t u v means (t u) v, not t (u v)

 $\blacktriangleright$  Bodies of  $\lambda\text{-}$  abstractions extend as far to the right as possible

E.g.,  $\lambda x$ .  $\lambda y$ . x y means  $\lambda x$ .  $(\lambda y$ . x y), not  $\lambda x$ .  $(\lambda y$ . x) y

#### Scope

The  $\lambda$ -abstraction term  $\lambda x.t$  binds the variable x.

The scope of this binding is the body t.

Occurrences of x inside t are said to be bound by the abstraction.

Occurrences of x that are *not* within the scope of an abstraction binding x are said to be *free*.

Test:

 $\lambda$ x.  $\lambda$ y. x y z

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$$\lambda x. \lambda y. x y z$$
  
 $\lambda x. (\lambda y. z y) y$ 

#### Values

 $\mathbf{v} ::= \\ \lambda \mathbf{x.t}$ 

values abstraction value

#### **Operational Semantics**

Computation rule:

$$(\lambda x.t_{12}) \ v_2 \longrightarrow [x \mapsto v_2]t_{12}$$
 (E-AppAbs)

Notation:  $[x \mapsto v_2]t_{12}$  is "the term that results from substituting free occurrences of x in  $t_{12}$  with  $v_2$ ."

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Congruence rules:

$$rac{ t_1 \longrightarrow t_1'}{ t_1 \ t_2 \longrightarrow t_1' \ t_2}$$
 (E-App1)

$$\frac{\mathtt{t}_2 \longrightarrow \mathtt{t}_2'}{\mathtt{v}_1 \ \mathtt{t}_2 \longrightarrow \mathtt{v}_1 \ \mathtt{t}_2'} \tag{E-App2)$$

#### Terminology

A term of the form  $(\lambda x.t)$  v — that is, a  $\lambda$ -abstraction applied to a value — is called a redex (short for "reducible expression").

#### Alternative evaluation strategies

Strictly speaking, the language we have defined is called the *pure*, *call-by-value lambda-calculus*.

The evaluation strategy we have chosen —  $\it{call}$  by  $\it{value}$  —  $\it{reflects}$  standard conventions found in most mainstream languages.

Some other common ones:

- ► Call by name (cf. Haskell)
- ► Normal order (leftmost/outermost)
- ► Full (non-deterministic) beta-reduction

## Classical Lambda Calculus

#### Full beta reduction

The classical lambda calculus allows full beta reduction.

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$$\frac{\texttt{t}_2 \longrightarrow \texttt{t}_2'}{\texttt{t}_1 \ \texttt{t}_2 \longrightarrow \texttt{t}_1 \ \texttt{t}_2'} \tag{E-App2)$$

$$\frac{\mathtt{t} \longrightarrow \mathtt{t}'}{\lambda \mathtt{x.t} \longrightarrow \lambda \mathtt{x.t}'} \tag{E-Abs)}$$

#### Substitution revisited

Remember:  $[x \mapsto v_2]t_{12}$  is "the term that results from substituting free occurrences of x in  $t_{12}$  with  $v_2$ ."

This is trickier than it looks! For example:

$$\begin{array}{rcl} & (\lambda x. & (\lambda y. & x)) & y \\ \longrightarrow & [x \mapsto y] \lambda y. & x \\ = & ??? \end{array}$$

#### Substitution revisited

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This is trickier than it looks!

For example:

$$\begin{array}{rcl} & (\lambda \mathtt{x}. & (\lambda \mathtt{y}. & \mathtt{x})) \ \mathtt{y} \\ \longrightarrow & [\mathtt{x} \mapsto \mathtt{y}] \lambda \mathtt{y}. \ \mathtt{x} \\ & = & ??? \end{array}$$

Solution:

need to rename bound variables before performing the substitution.

$$(\lambda x. (\lambda y. x)) y$$

$$= (\lambda x. (\lambda z. x)) y$$

$$\longrightarrow [x \mapsto y]\lambda z. x$$

$$= \lambda z. y$$

#### Alpha conversion

Renaming bound variables is formalized as  $\alpha$ -conversion.

$$\frac{y \notin fv(t)}{\lambda x. \ t =_{\alpha} \lambda y. [x \mapsto y]t}$$
 (\alpha)

Equivalence rules:

$$\frac{\mathsf{t}_1 =_{\alpha} \mathsf{t}_2}{\mathsf{t}_2 =_{\alpha} \mathsf{t}_1} \qquad (\alpha \text{-SYMM})$$

$$\frac{\mathtt{t}_1 =_{\alpha} \mathtt{t}_2 \qquad \mathtt{t}_2 =_{\alpha} \mathtt{t}_3}{\mathtt{t}_1 =_{\alpha} \mathtt{t}_3} \qquad \qquad (\alpha\text{-Trans})$$

Congruence rules: the usual ones.

#### Confluence

Full  $\beta$ -reduction makes it possible to have different reduction paths.

Q: Can a term evaluate to more than one normal form?

#### Confluence

Full  $\beta$ -reduction makes it possible to have different reduction paths.

Q: Can a term evaluate to more than one normal form?

The answer is no; this is a consequence of the following

#### **Theorem** [Church-Rosser]

Let t,  $t_1$ ,  $t_2$  be terms such that  $t \longrightarrow^* t_1$  and  $t \longrightarrow^* t_2$ . Then there exists a term  $t_3$  such that  $t_1 \longrightarrow^* t_3$  and  $t_2 \longrightarrow^* t_3$ .

Programming in the Lambda-Calculus

#### Multiple arguments

Consider the function  ${\tt double}$ , which returns a function as an argument.

```
double = \lambda f. \lambda y. f (f y)
```

This idiom — a  $\lambda$ -abstraction that does nothing but immediately yield another abstraction — is very common in the  $\lambda$ -calculus.

In general,  $\lambda x$ .  $\lambda y$ . t is a function that, given a value v for x, yields a function that, given a value u for y, yields t with v in place of x and u in place of y.

That is,  $\lambda x$ .  $\lambda y$ . t is a two-argument function.

(Recall the discussion of currying in OCaml.)

#### The "Church Booleans"

```
\begin{array}{rclcrcl} & \text{tru} & = & \lambda \text{t. } \lambda \text{f. t} \\ & \text{fls} & = & \lambda \text{t. } \lambda \text{f. f} \end{array}
\begin{array}{rclcrcl} & & \text{tru } & \text{v} & \text{w} \\ & = & (\lambda \text{t.} \lambda \text{f.t.}) & \text{v} & \text{w} \\ & \rightarrow & (\lambda \text{f. v}) & \text{w} & \text{reducing the underlined redex} \end{array}
\begin{array}{rclcrcl} & & \text{fls } & \text{v} & \text{w} \\ & = & (\lambda \text{t.} \lambda \text{f.f.}) & \text{v} & \text{w} \\ & \rightarrow & (\lambda \text{f. f. f.}) & \text{w} & \text{orducing the underlined redex} \end{array}
\begin{array}{rclcrcl} & & \text{tru } & \text{v} & \text{w} & \text{orducing the underlined redex} \\ & \rightarrow & \text{w} & \text{reducing the underlined redex} \end{array}
```

#### Functions on Booleans

```
\mathtt{not} \quad = \quad \lambda\mathtt{b.} \ \mathtt{b} \ \mathtt{fls} \ \mathtt{tru}
```

That is, not is a function that, given a boolean value v, returns fls if v is tru and tru if v is fls.

#### Functions on Booleans

```
and = \lambdab. \lambdac. b c fls
```

That is, and is a function that, given two boolean values v and w, returns w if v is tru and fls if v is fls

Thus and v w yields tru if both v and w are tru and fls if either v or w is fls.

### Pairs

```
\begin{array}{l} \text{pair} = \lambda \text{f.} \lambda \text{s.} \lambda \text{b. b f s} \\ \text{fst} = \lambda \text{p. p tru} \\ \text{snd} = \lambda \text{p. p fls} \end{array}
```

That is, pair v w is a function that, when applied to a boolean value b, applies b to v and w.

By the definition of booleans, this application yields v if b is tru and w if b is fls, so the first and second projection functions fst and snd can be implemented simply by supplying the appropriate boolean.

#### Example

#### Church numerals

Idea: represent the number n by a function that "repeats some action n times."

```
\begin{array}{l} c_0 \; = \; \lambda s. \;\; \lambda z. \;\; z \\ c_1 \; = \; \lambda s. \;\; \lambda z. \;\; s \;\; z \\ c_2 \; = \; \lambda s. \;\; \lambda z. \;\; s \;\; (s \; z) \\ c_3 \; = \; \lambda s. \;\; \lambda z. \;\; s \;\; (s \; (s \; z)) \end{array}
```

That is, each number n is represented by a term  $c_n$  that takes two arguments, s and z (for "successor" and "zero"), and applies s, n times, to z.

#### Functions on Church Numerals

Successor:

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plus =  $\lambda$ m.  $\lambda$ n.  $\lambda$ s.  $\lambda$ z. m s (n s z)

#### Functions on Church Numerals

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Multiplication:

#### Functions on Church Numerals

```
Successor:
```

```
scc = \lambda n. \ \lambda s. \ \lambda z. \ s \ (n \ s \ z) Addition: plus = \lambda m. \ \lambda n. \ \lambda s. \ \lambda z. \ m \ s \ (n \ s \ z)
```

Multiplication:

times =  $\lambda$ m.  $\lambda$ n. m (plus n) c<sub>0</sub>

#### Functions on Church Numerals

```
Successor:
```

```
scc = \lambdan. \lambdas. \lambdaz. s (n s z)
Addition:
plus = \lambdam. \lambdan. \lambdas. \lambdaz. m s (n s z)
```

plus //m: //m: //b: //2: m 5 (m 5 2)

Multiplication:

times =  $\lambda$ m.  $\lambda$ n. m (plus n) c<sub>0</sub>

Zero test:

#### Functions on Church Numerals

Successor:

$$scc = \lambda n. \lambda s. \lambda z. s (n s z)$$

Addition:

plus = 
$$\lambda$$
m.  $\lambda$ n.  $\lambda$ s.  $\lambda$ z. m s (n s z)

Multiplication:

times = 
$$\lambda m$$
.  $\lambda n$ . m (plus n)  $c_0$ 

Zero test:

iszro =  $\lambda$ m. m ( $\lambda$ x. fls) tru

#### Functions on Church Numerals

Successor:

$$scc = \lambda n. \ \lambda s. \ \lambda z. \ s \ (n \ s \ z)$$

Addition:

plus = 
$$\lambda m$$
.  $\lambda n$ .  $\lambda s$ .  $\lambda z$ .  $m$   $s$   $(n$   $s$   $z)$ 

Multiplication:

times = 
$$\lambda$$
m.  $\lambda$ n. m (plus n) c<sub>0</sub>

Zero test:

iszro =  $\lambda$ m. m ( $\lambda$ x. fls) tru

What about predecessor?

#### Predecessor

```
zz = pair c_0 c_0 ss = \lambda p. pair (snd p) (scc (snd p)) prd = \lambda m. fst (m ss zz)
```

## Recursion in the Lambda-Calculus

#### Recursion and divergence

Recursion and divergence are intertwined, so we need to consider divergent terms.

```
omega = (\lambda x. x x) (\lambda x. x x)
```

Note that omega evaluates in one step to itself! So evaluation of omega never reaches a normal form: it *diverges*.

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```
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```

Note that omega evaluates in one step to itself! So evaluation of omega never reaches a normal form: it diverges.

Being able to write a divergent computation does not seem very useful in itself. However, there are variants of omega that are *very* useful...

#### Recall: Normal forms

- A normal form is a term that cannot take an evaluation step.
- A stuck term is a normal form that is not a value.

Does every term evaluate to a normal form?

No, omega is not in normal form.

#### Recall: Normal forms

- A normal form is a term that cannot take an evaluation step.
- A stuck term is a normal form that is not a value.

Does every term evaluate to a normal form?

No, omega is not in normal form.

But are there any stuck terms in the pure  $\lambda$ -calculus?

#### Towards recursion: Iterated application

Suppose  ${\tt f}$  is some  $\lambda\text{-abstraction,}$  and consider the following variant of  ${\tt omega:}$ 

```
Y_f = (\lambda x. f (x x)) (\lambda x. f (x x))
```

#### Towards recursion: Iterated application

Suppose  ${\tt f}$  is some  $\lambda\text{-abstraction,}$  and consider the following variant of  ${\tt omega:}$ 

```
Y_f = (\lambda x. f (x x)) (\lambda x. f (x x))
```

Now the "pattern of divergence" becomes more interesting:

```
\begin{array}{c} Y_f \\ = \\ (\lambda x. \ f \ (x \ x)) \ (\lambda x. \ f \ (x \ x)) \\ \longrightarrow \\ f \ ((\lambda x. \ f \ (x \ x)) \ (\lambda x. \ f \ (x \ x))) \\ \longrightarrow \\ f \ (f \ ((\lambda x. \ f \ (x \ x)) \ (\lambda x. \ f \ (x \ x))))) \\ \longrightarrow \\ f \ (f \ ((\lambda x. \ f \ (x \ x)) \ (\lambda x. \ f \ (x \ x))))) \\ \longrightarrow \\ \end{array}
```

 $Y_f$  is still not very useful, since (like omega), all it does is diverge. Is there any way we could "slow it down"?

#### Delaying divergence

```
{\tt poisonpill} \ = \ \lambda {\tt y. \ omega}
```

Note that poisonpill is a value — it it will only diverge when we actually apply it to an argument. This means that we can safely pass it as an argument to other functions, return it as a result from functions, etc.

```
\begin{array}{c} (\lambda \texttt{p. fst (pair p fls) tru) poisonpill} \\ \longrightarrow \\ \texttt{fst (pair poisonpill fls) tru} \\ \longrightarrow^* \\ & \underbrace{ \begin{array}{c} \\ \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \end{array} \begin{array}{c}
```

#### A delayed variant of omega

Here is a variant of omega in which the delay and divergence are a bit more tightly intertwined:

$$\begin{array}{rcl} & \text{omegav} & = \\ \lambda \mathbf{y}. & (\lambda \mathbf{x}. & (\lambda \mathbf{y}. & \mathbf{x} & \mathbf{y})) & (\lambda \mathbf{x}. & (\lambda \mathbf{y}. & \mathbf{x} & \mathbf{y})) & \mathbf{y} \end{array}$$

Note that  ${\tt omegav}$  is a normal form. However, if we apply it to any argument v, it diverges:

```
omegav v = \frac{(\lambda y. \ (\lambda x. \ (\lambda y. \ x \ x \ y)) \ (\lambda x. \ (\lambda y. \ x \ x \ y)) \ y) \ v}{\longrightarrow} \frac{(\lambda x. \ (\lambda y. \ x \ x \ y)) \ (\lambda x. \ (\lambda y. \ x \ x \ y))}{\longrightarrow} \ v
(\lambda y. \ (\lambda x. \ (\lambda y. \ x \ x \ y)) \ (\lambda x. \ (\lambda y. \ x \ x \ y)) \ y) \ v
= \frac{(\lambda y. \ (\lambda x. \ (\lambda y. \ x \ x \ y)) \ (\lambda x. \ (\lambda y. \ x \ x \ y)) \ y) \ v}{=} 
omegav v
```

#### Another delayed variant

Suppose  ${\tt f}$  is a function. Define

```
z_f = \lambda y. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y
```

This term combines the "added  $\mathbf{f}$ " from  $\mathbf{Y}_f$  with the "delayed divergence" of omegav.

If we now apply  $z_f$  to an argument v, something interesting happens:

```
z_f v
 (\lambda y. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y) v
          \underline{(\lambda \mathtt{x. f} \ (\lambda \mathtt{y. x x y})) \ (\lambda \mathtt{x. f} \ (\lambda \mathtt{y. x x y}))} \ \mathtt{v}
f (\lambda y. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y) v
                                             f z_f v
```

Since  $\mathbf{z}_f$  and  $\mathbf{v}$  are both values, the next computation step will be the reduction of f  $z_f$  — that is, before we "diverge," f gets to do some computation.

Now we are getting somewhere.

#### Recursion Let

```
f = \lambda f ct.
            if n=0 then 1
            else n * (fct (pred n))
```

 ${f f}$  looks just the ordinary factorial function, except that, in place of a recursive call in the last time, it calls the function fct, which is passed as a parameter.

N.b.: for brevity, this example uses "real" numbers and booleans, infix syntax, etc. It can easily be translated into the pure lambda-calculus (using Church numerals, etc.).

We can use z to "tie the knot" in the definition of f and obtain a real recursive factorial function:

```
z_f 3
                  f z_f 3
          (\lambdafct. \lambdan. ...) z<sub>f</sub> 3
if 3=0 then 1 else 3 * (z_f (pred 3))
           3 * (z_f (pred 3)))
                3 * (z_f 2)
               3 * (f z_f 2)
```

#### A Generic z

If we define

i.e., 
$$\mathbf{z} = \\ \lambda \mathbf{f}. \ \lambda \mathbf{y}. \ (\lambda \mathbf{x}. \ \mathbf{f} \ (\lambda \mathbf{y}. \ \mathbf{x} \ \mathbf{x} \ \mathbf{y})) \ (\lambda \mathbf{x}. \ \mathbf{f} \ (\lambda \mathbf{y}. \ \mathbf{x} \ \mathbf{x} \ \mathbf{y})) \ \mathbf{y}$$

 $z = \lambda f. z_f$ 

then we can obtain the behavior of  $z_f$  for any f we like, simply by applying z to f.

 ${ t z}$  f  $\longrightarrow$   ${ t z}_f$ 

#### **Technical Note**

The term z here is essentially the same as the  $\mathtt{fix}$  discussed the book

```
 \begin{split} \mathbf{z} &= \\ \lambda \mathbf{f}. \ \lambda \mathbf{y}. \ (\lambda \mathbf{x}. \ \mathbf{f} \ (\lambda \mathbf{y}. \ \mathbf{x} \ \mathbf{x} \ \mathbf{y})) \ (\lambda \mathbf{x}. \ \mathbf{f} \ (\lambda \mathbf{y}. \ \mathbf{x} \ \mathbf{x} \ \mathbf{y})) \ \mathbf{y} \\ \mathbf{fix} &= \\ \lambda \mathbf{f}. \ (\lambda \mathbf{x}. \ \mathbf{f} \ (\lambda \mathbf{y}. \ \mathbf{x} \ \mathbf{x} \ \mathbf{y})) \ (\lambda \mathbf{x}. \ \mathbf{f} \ (\lambda \mathbf{y}. \ \mathbf{x} \ \mathbf{x} \ \mathbf{y})) \end{split}
```

z is hopefully slightly easier to understand, since it has the property that z f v  $\longrightarrow^*$  f (z f) v, which fix does not (quite) share.