

Analysis II

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1 The vector space \mathbb{R}^n

1.1 Operations

Addition and scalar multiplications are defined as follows:

$$\mathbf{x} + \mathbf{y} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} + \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} = \begin{pmatrix} x_1 + y_1 \\ \vdots \\ x_n + y_n \end{pmatrix}$$

$$\lambda \mathbf{x} = \lambda \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} \lambda x_1 \\ \vdots \\ \lambda x_n \end{pmatrix}$$

$$\lambda \mathbf{x} + \mathbf{y} = \lambda \mathbf{x} + \lambda \mathbf{y}$$

Scalar product, $\langle \cdot, \cdot \rangle : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$, in the vector space \mathbb{R}^n is defined as:

$$\langle \mathbf{x}, \mathbf{y} \rangle = \sum_{k=1}^n x_k y_k = \mathbf{x}^T \mathbf{y} = (x_1 \ \cdots \ x_n) \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$$

The scalar product satisfies the following properties:

1. Positive definiteness: $\langle \mathbf{x}, \mathbf{x} \rangle \geq 0 \forall \mathbf{x}$ with $\langle \mathbf{x}, \mathbf{x} \rangle = 0 \iff \mathbf{x} = \mathbf{0}$
2. Symmetry: $\langle x, y \rangle = \langle y, x \rangle$
3. Bilinearity: $\langle \alpha x + \beta y, z \rangle = \alpha \langle x, z \rangle + \beta \langle y, z \rangle \ \forall x, y, z \in \mathbb{R}^n$ and $\forall \alpha, \beta \in \mathbb{R}$

1.2 Euclidean Norm on \mathbb{R}^n

The function $\|\cdot\|_2 : \mathbb{R}^n \rightarrow \mathbb{R}$ is defined by

$$\|x\|_2 = \sqrt{\langle x, x \rangle} = \left(\sum_{k=1}^n x_k^2 \right)^{\frac{1}{2}}$$

The Euclidean norm on \mathbb{R}^n has the following properties:

1. Non-negativity: $\|x\|_2 \geq 0$ for all $x \in \mathbb{R}^n$, with equality $\iff \mathbf{x} = \mathbf{0}$.
2. Homogeneity: $\|\lambda \cdot \mathbf{x}\|_2 = |\lambda| \cdot \|\mathbf{x}\|_2$ for all $\lambda \in \mathbb{R}$ and $\mathbf{x} \in \mathbb{R}^n$
3. Triangle inequality: $\|\mathbf{x} + \mathbf{y}\|_2 \leq \|\mathbf{x}\|_2 + \|\mathbf{y}\|_2 \forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ (also called Cauchy Schwartz inequality)

$$|\langle x, y \rangle| \leq \|x\|_2 \|y\|_2 \text{ (Angle Formula)}$$

if \mathbf{x} and \mathbf{y} are orthogonal then:

$$\|x + y\|_2^2 = \|x\|_2^2 + \|y\|_2^2 \text{ (Pythagoras)}$$

Definition:

The Euclidean distance on \mathbb{R}^n is the function $d(., .) : \mathbb{R}^n \times \mathbb{R}^n \rightarrow [0, \infty)$ given by:

$$d(\mathbf{x}, \mathbf{y}) := \|\mathbf{x} - \mathbf{y}\|_2 = \sqrt{(x_1 - y_1)^2 + \dots + (x_n - y_n)^2}$$

This function outputs the distance between two points in \mathbb{R}^n and it satisfies the following 3 properties:

1. Non-negativity: $d(\mathbf{x}, \mathbf{y}) \geq 0$ for all $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$, with equality $\iff \mathbf{x} = \mathbf{y}$.
2. Symmetry: $d(\mathbf{x}, \mathbf{y}) = d(\mathbf{y}, \mathbf{x})$.
3. Triangle inequality: $d(\mathbf{x}, \mathbf{y}) \leq d(\mathbf{x}, \mathbf{z}) + d(\mathbf{z}, \mathbf{y})$.

1.3 Topology on \mathbb{R}^n Definition: Open Ball

Let $\mathbf{a} \in \mathbb{R}^n$ and $r > 0$. The set

$$B(\mathbf{a}, r) = \{\mathbf{x} \in \mathbb{R}^n : d(\mathbf{x}, \mathbf{a}) < r\}$$

is called the open ball of radius r centered at \mathbf{a} .

If \mathbf{x} and \mathbf{y} are two distinct points then: if $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ and $\mathbf{x} \neq \mathbf{y}$ then we can find a sufficiently small open ball centered in \mathbf{x} and another centered in \mathbf{y} such that the two balls don't touch. Open balls are open sets¹

Definition: Open set

A subset $U \subseteq \mathbb{R}^n$ is open if $\forall \mathbf{x} \in U \exists \varepsilon > 0$: the open ball $B(\mathbf{x}, \varepsilon)$ is contained in U .

Example of an open set:

1. if $a < b$ are real numbers then the interval

$$(a, b) = \{x \in \mathbb{R} : a < x < b\}$$

is an open set.

Proof: take $r = \min\{x - a, b - x\}$ (both a and b are strictly positive), the minimum is positive and the ball $B(x, r) = \{y \in \mathbb{R} : |x - y| < r\}$ is a subset of (a, b) . As \mathbf{x} is arbitrary, that works $\forall \mathbf{x} \in (a, b)$ and so it satisfies the definition of an open set.

2. The infinite interval (a, ∞) and $(-\infty, b)$ are also open but the intervals

$$(a, b] = \{x \in \mathbb{R} : a < x \leq b\} \quad \text{and} \quad [a, b] = \{x \in \mathbb{R} : a \leq x \leq b\}$$

¹An open set is a set with the property that if \mathbf{x} is a point in the set then all points that are sufficiently near to it also belong to the set.

are not open sets.

3. the rectangle $(a, b) \times (c, d) = \{(x, y) \in \mathbb{R}^2 : a < x < b, c < y < d\}$ is an open set.

Definition: Closed Set

A subset $C \subseteq \mathbb{R}^n$ is closed if its complement $\mathbb{R}^n \setminus C$ is open.

Convention: The empty set and the space \mathbb{R}^n are the only two spaces both open and closed at the same time.

Definition: Closed Ball

Let $\mathbf{a} \in \mathbb{R}^n$ and $r > 0$. The set

$$\overline{B(\mathbf{a}, r)} = \{\mathbf{x} \in \mathbb{R}^n : d(\mathbf{x}, \mathbf{a}) \leq r\}$$

is called the closed ball of radius r centered at \mathbf{a} and it is a closed set. Example of a closed set:

1. The closed interval $[a, b] = \{x \in \mathbb{R} : a \leq x \leq b\}$ is a closed set and its complementary $\mathbb{R} \setminus [a, b] = (-\infty, a) \cup (b, \infty)$ is an open set.

2. Infinite intervals with closed boundary $[a, \infty)$ and $(-\infty, b]$ are closed sets.

3. Halfopen intervals such as $[a, b)$ or $(a, b]$ are neither closed nor open sets.

4. Any set consisting of only finitely many points is a closed set.

Propositions:

- if $U \subseteq \mathbb{R}^n$ is open and $C \subseteq \mathbb{R}^n$ is closed then $U \cap C$ is open. (Open \cap Closed = Open)
- if $U \subseteq \mathbb{R}^n$ is closed and $C \subseteq \mathbb{R}^n$ is open then $U \cap C$ is closed. (Closed \cap Open = Closed)
- if $U_1, \dots, U_k \subseteq \mathbb{R}^n$ are open then $U_1 \cup \dots \cup U_k$ and $U_1 \cap \dots \cap U_k$ are open.
- if $C_1, \dots, C_k \subseteq \mathbb{R}^n$ are open then $C_1 \cup \dots \cup C_k$ and $C_1 \cap \dots \cap C_k$ are closed².

²intersezione e unione di sottoinsiemi chiusi (rispettivamente aperti) danno un sottoinsieme ancora chiuso (rispettivamente aperto).

2 Allegati

2.1 Dimostrazione 1