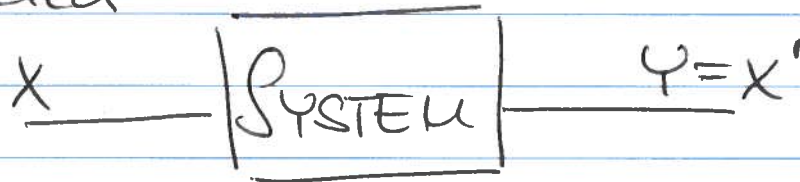


5th LECTURE

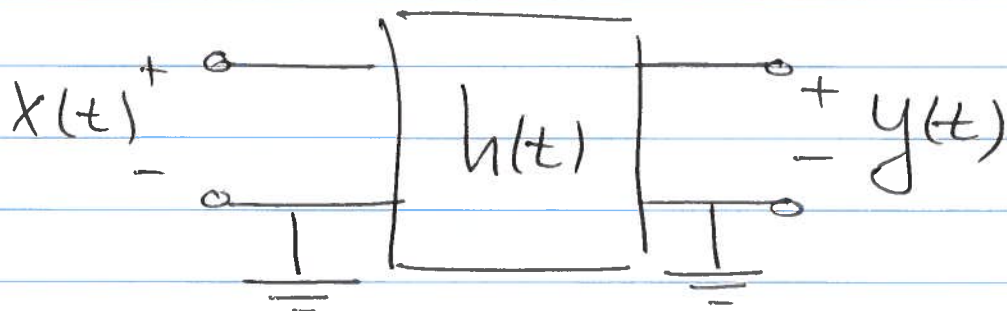
A SHORT INTRODUCTION TO ANALOG FILTERS

A "FILTER" is a **System** which can eliminate specific parts of a signal while other parts are left (almost) unaffected

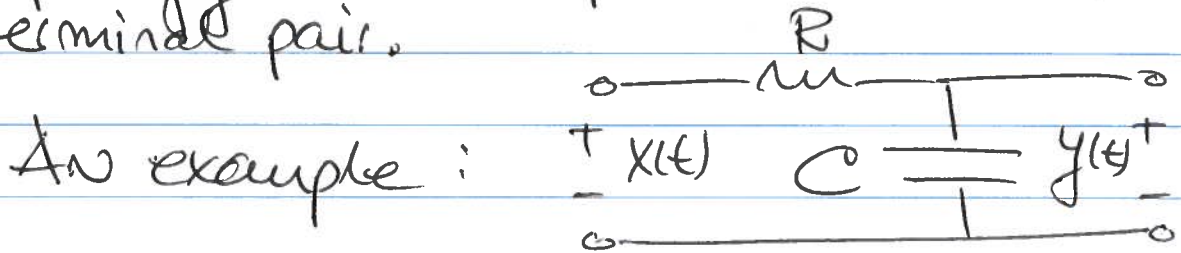


In our context, this system consists of an **electrical circuit** with resistors, capacitors, inductors, and eventually active components such as OpAmps.

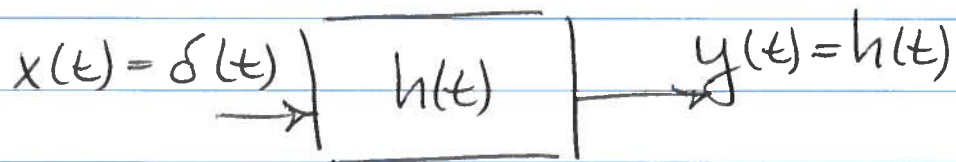
The input is an electrical signal denoted $x(t)$. The system $h(t)$ modify $x(t)$ into an output $y(t) = f(x(t)) = h(t) * x(t)$.



Since $x(t)$, $y(t)$, and $h(t)$ are all continuous-time functions, the filter is denoted a **Continuous-time filter**, or an **analog filter**, i.e., a specific circuit topology with an input - and an output terminal pair.



We know from previous discussions that a continuous-time system $h(t)$ which is excited with an **impulse $\delta(t)$** , responds with its **impulse response**



For any given input $x(t)$, the response can be calculated by the **Convolution integral**

$$y(t) = \int_{-\infty}^{\infty} x(\tau) \cdot h(t-\tau) d\tau$$

- Therefore, given $h(t)$ the system is completely defined/described.

However, $h(t)$ in itself does not tell us the complete story — if we want to know the system's characteristics, we need to take $h(t)$ to the frequency domain.

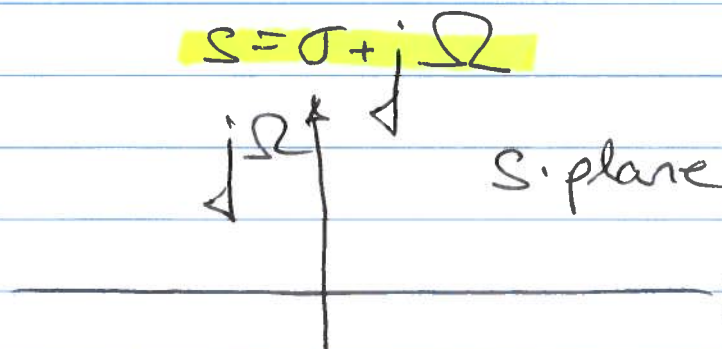
- Keyword here is the Laplace transform.

$$X(s) = \mathcal{L}\{x(t)\}, Y(s) = \mathcal{L}\{y(t)\} \text{ and } H(s) = \mathcal{L}\{h(t)\}$$

$$X(s) \longrightarrow \boxed{H(s)} \longrightarrow Y(s)$$

$$Y(s) = H(s) \cdot X(s)$$

- $H(s)$ is known as the system's Transfer function, or system function, where



- For $\sigma = 0$, $s = j\Omega$ i.e., the infinite freq. axis

$$H(s) = H(\sigma + j\Omega) = H(j\Omega) \Big|_{\sigma=0}$$

$\Omega = 2\pi f$ is the continuous angle-frequency (f is the frequency), and $H(j\Omega)$ is known as the FREQUENCY RESPONSE

Since the frequency response is a complex-valued function, it makes sense defining its modulus and argument;

$$H(j\Omega) = |H(j\Omega)| \cdot \text{Arg}(H(j\Omega))$$

$|H(j\Omega)|$: AMPLITUDE RESPONSE

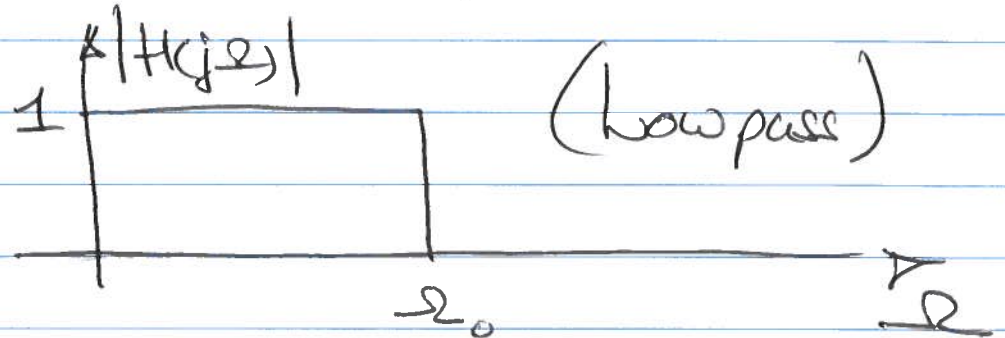
$\text{Arg}(H(j\Omega))$: PHASE RESPONSE

Often, the amplitude response is expressed as

$$20 \cdot \log_{10} |H(j\Omega)| \quad [\text{dB}]$$

BUTTERWORTH APPROXIMATION

In the ideal situation, we would like to design a "Brickwall Filter", i.e., a filter which has an amplitude response such as;



This is : $|H(j\Omega)| = \begin{cases} 1 & |\Omega| \leq \Omega_0 \\ 0 & \text{otherwise} \end{cases}$

Unfortunately, such a filter exists only as a mathematical definition – it cannot be implemented physically.

Therefore, we want to find an approximation to the ideal amplitude response, $|H(j\Omega)|$

Even better though, we may use $|H(j\Omega)|^2$ because this is a rational function in Ω^2 , which may be an advantage when we have to find the poles in $H(j\Omega)$.

6.

Therefore, let's define the squared amplitude response;

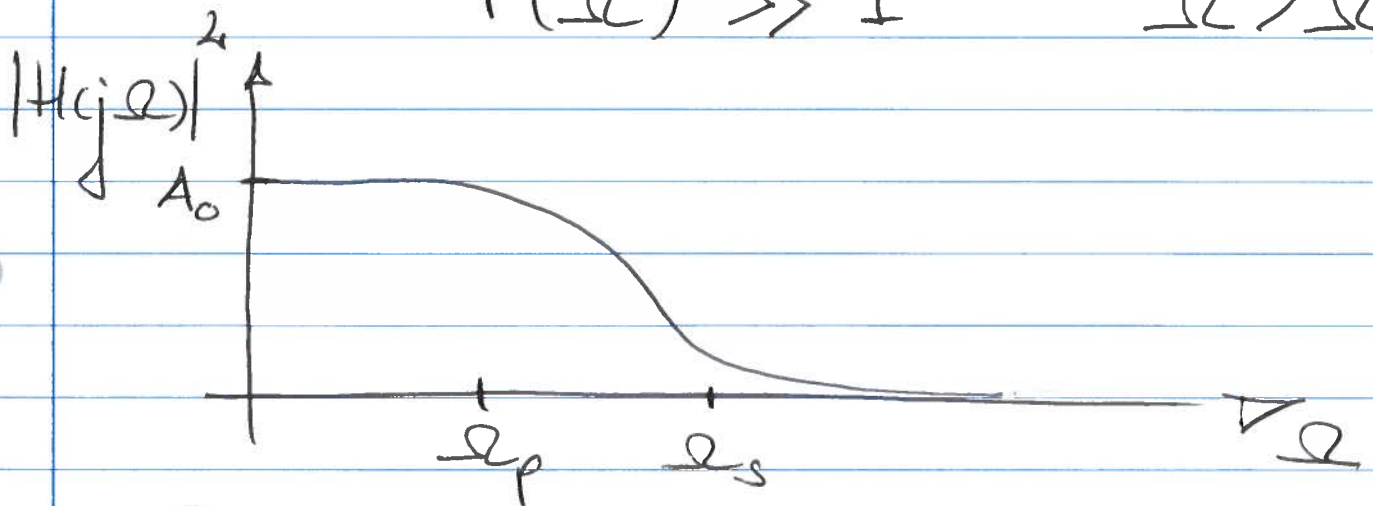
$$|H(j\Omega)|^2 = \frac{A_0}{1 + F(\Omega^2)}$$

where A_0 is the DC gain ($\Omega = 0$).

Find an expression for $F(\Omega^2)$ such that

$$F(\Omega^2) \ll 1 \quad 0 < \Omega < \Omega_p$$

$$F(\Omega^2) \gg 1 \quad \Omega > \Omega_s$$



One possible solution could be

$$F(\Omega^2) = \Omega^{2n}, \text{ where } n \text{ denotes the FILTER ORDER}$$

$$|H(j\Omega)|^2 = \frac{1}{1 + \Omega^{2n}} \quad |_{\Lambda_0=1}.$$

This function is known as the squared amplitude response for the normalized n^{th} order Butterworth Lowpass Filter. It has the following characteristics;

$$|H(j0)|^2 = 1 \text{ (0 dB) for all } n.$$

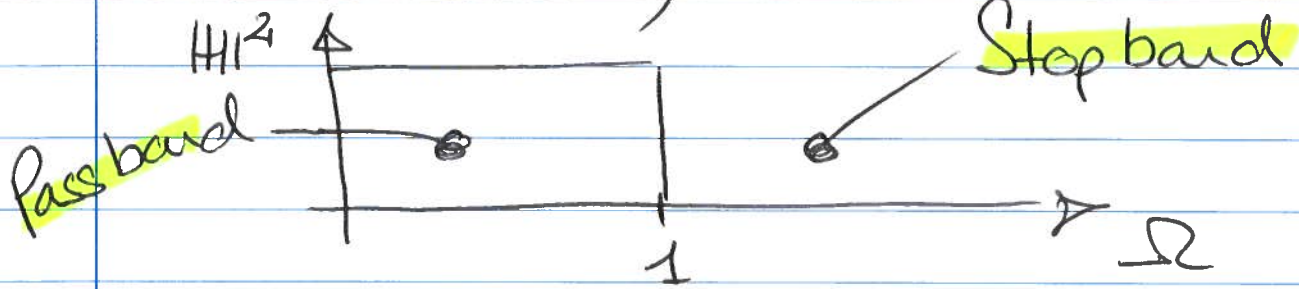
$$|H(j \cdot 1)|^2 = \frac{1}{2} \text{ for all } n.$$

$$\Downarrow |H(j \cdot 1)| = \frac{1}{\sqrt{2}}$$

$$\Downarrow |H(j \cdot 1)|_{\text{dB}} = 20 \cdot \log_{10} \left(\frac{1}{\sqrt{2}} \right) \approx -3 \text{ dB}$$

The frequency $\Omega=1$ is known as the cut-off frequency (på dansk "kædet-frekvens") or just the "3 dB frequency".

Other terms ;



The approximation to the Brickwall filter becomes better as n increases;

Assume $n_1 \gg n_2$

• In the passband; $\Omega^{2n_1} \ll \Omega^{2n_2}$

• In the stopband; $\Omega^{2n_1} \gg \Omega^{2n_2}$

Applying this in $|H(j\Omega)| = \frac{1}{\sqrt{1 + \Omega^{2n_1}}}$ we

clearly see that the approximation to the Brickwall filter becomes better the larger the filter order n is.

- Similarly, we may rewrite $|H(j\Omega)|$ in terms of a Taylor series;

$$|H(j\Omega)| = \frac{1}{\sqrt{1+\Omega^{2n}}} = 1 - \frac{1}{2}\Omega^{2n} + \frac{3}{8}\Omega^{4n} - \frac{5}{16}\Omega^{6n} \dots$$



$$\frac{\partial^k |H(j\Omega)|}{\partial^k \Omega} = 0 \Big|_{\Omega=0}, \quad k=1, 2, \dots, 2n-1$$

and

$$\frac{\partial^k |H(j\Omega)|}{\partial^k \Omega} = \frac{1}{2} \Big|_{\Omega=0} \quad k=2n$$

So, all derivatives for $k=1 \dots 2n$ are equal to 0 (for $\Omega=0$), except for one, which is a constant.

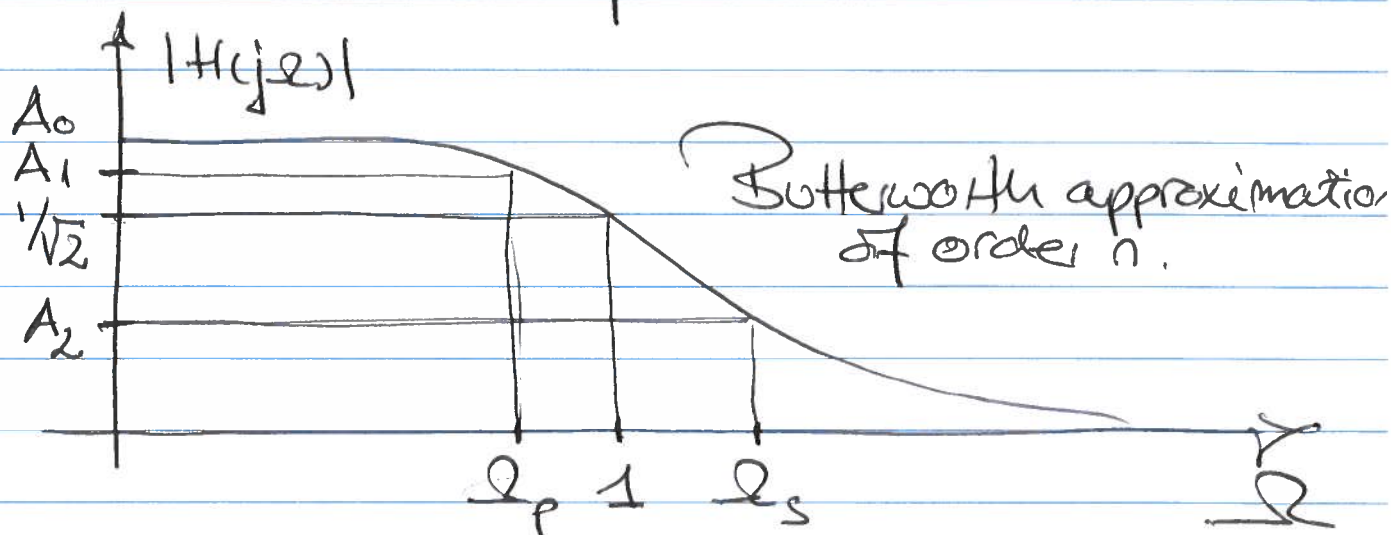


MAXIMAL FLAT AMPLITUDE RESPONSE

Choosing the filter order n .

10

Let's take as an outset the example in the textbook p. 29.



First we realize that both Ω_p and Ω_s will approach 1 as n increases.

Therefore, our task is to find the smallest value of n , for which given design specifications are met.

Specifications $\begin{matrix} \text{p} \\ \text{s} \end{matrix}$

(Ω_p, α_p) , (Ω_s, α_s) and $\frac{\Omega_s}{\Omega_p}$

where $\alpha_p = 20 \cdot \log_{10} \left(\frac{A_0}{A_1} \right)$

$\alpha_s = 20 \cdot \log_{10} \left(\frac{A_0}{A_2} \right)$

express the attenuation in dB.

Note that Ω_p and Ω_s so far are unknown.

Let's find an expression for the gain [dB]

$$\text{Amplification}(\Omega) = 10 \cdot \log_{10} |H(j\Omega)|^2$$

$$= 10 \cdot \log_{10} \left(\frac{\frac{A_0}{1+\Omega^{2n}}}{A_0} \right)$$

Here the amplification (gain) is normalized as compared to DC (A_0).

$$\text{Amp}(\Omega) = -10 \cdot \log_{10} (1 + \Omega^{2n}) \text{ [dB]}$$

from the example we have that

• passband attenuation $\alpha_p = 1 \text{ dB}$

• stopband attenuation $\alpha_s = 25 \text{ dB}$

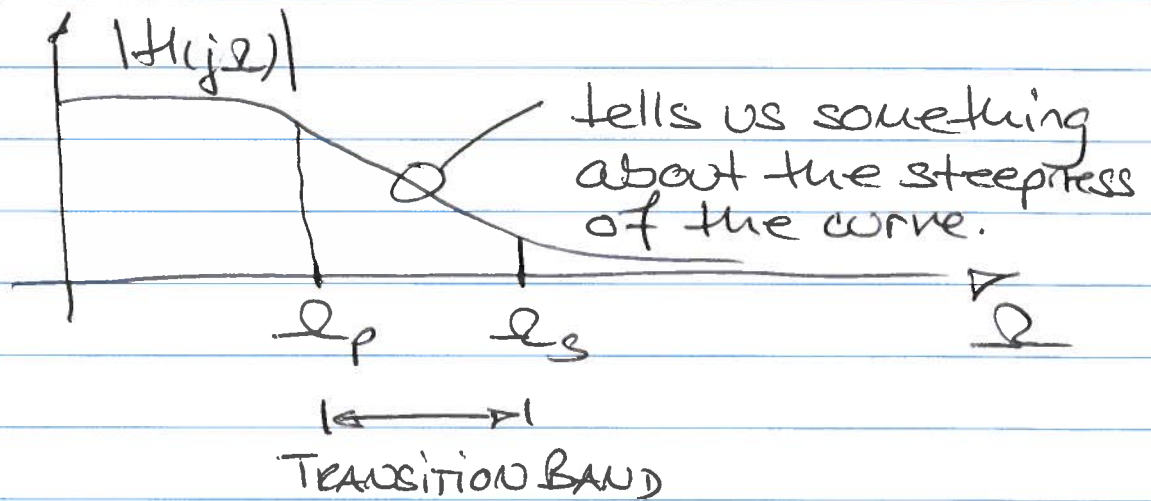
$$\left\{ \begin{array}{l} -10 \cdot \log_{10} (1 + \Omega_p^{2n}) = -1 \\ -10 \cdot \log_{10} (1 + \Omega_s^{2n}) = -25 \end{array} \right.$$

$$\left\{ \begin{array}{l} \Omega_p^{2n} = 10^{0.1} - 1 \\ \Omega_s^{2n} = 10^{2.5} - 1 \end{array} \right.$$

2 equations with 3 unknown.

6

In order to solve this issue, we use the "Transition Band Relation".



$$\frac{\omega_s}{\omega_p} = 1.5 \quad (\text{according to the example})$$

 \Downarrow

$$\left(\frac{\omega_s}{\omega_p}\right)^{2n} = \frac{\omega_s^{2n}}{\omega_p^{2n}} = (1.5)^{2n}$$

 \Downarrow

$$\frac{10^{2.5} - 1}{10^{0.1} - 1} = 1.5^{2n}$$

 \Downarrow

$$n = 8.761\dots$$

The order however, must be an integer

 \Downarrow

$$n = \lceil 8.761\dots \rceil = 9$$

For this value of n , we can now find ω_p and ω_s .

$$\Downarrow \Omega_p^{2n} = 10^{0.1} - 1$$

$$\log_{10}(10^{0.1} - 1)$$

Specs fulfilled
at Ω_p !

$$\Omega_p = 10^{\frac{\log_{10}(10^{0.1} - 1)}{2n}} = \underline{\underline{0.928...}} \Big|_{n=9}$$

and since $\frac{\Omega_s}{\Omega_p} = 1.5$, we find that

$$\Omega_s = 1.5 \cdot 0.928... = \underline{\underline{1.392...}}$$

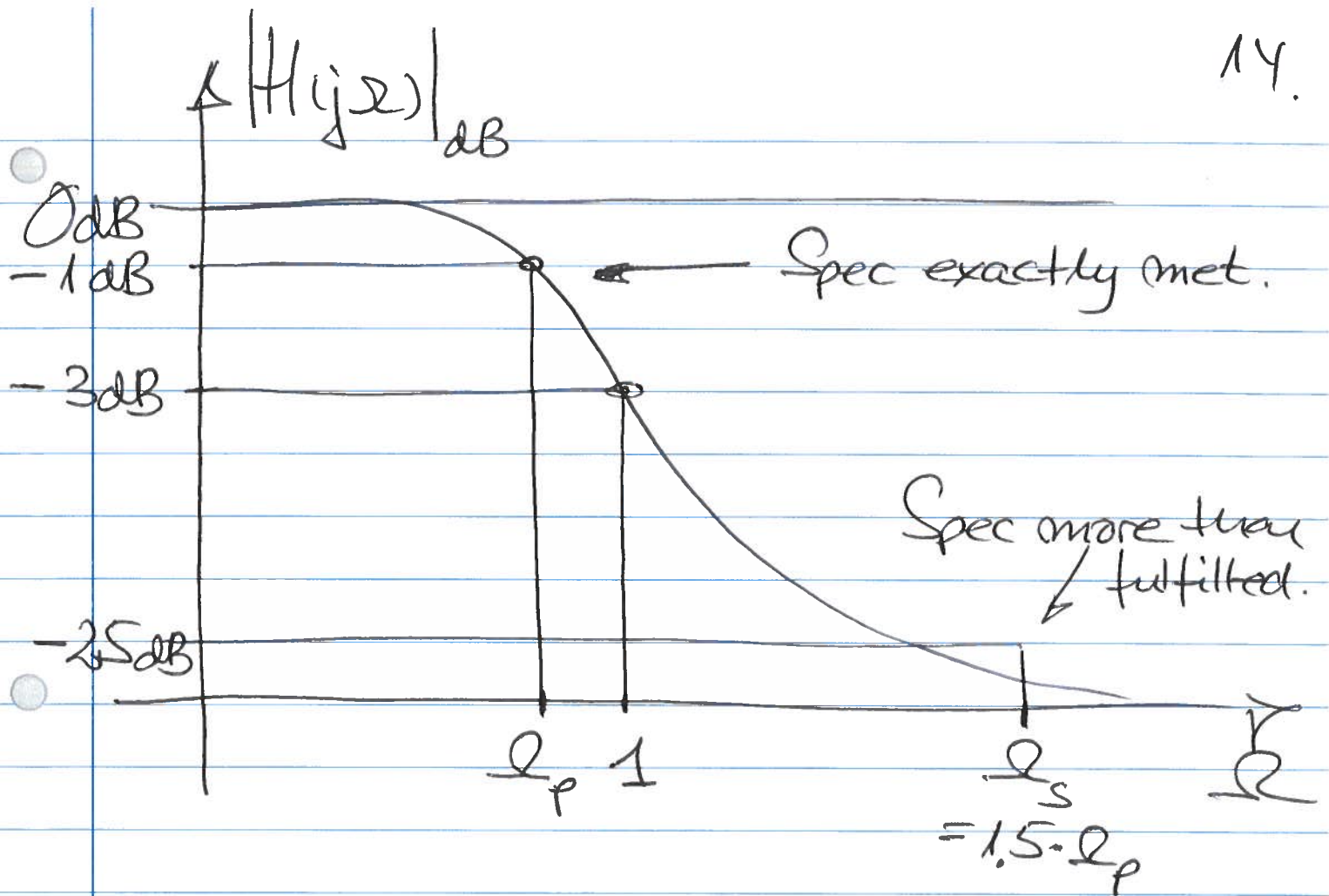
We need however, to check whether the specifications are fulfilled at Ω_s for $n=9$.

$$\alpha_s = 20 \cdot \log_{10} \left(\frac{A_0}{A_2} \right)$$

$$= 20 \cdot \log_{10} \left| \frac{1}{1 + \Omega_s^{2n}} \right|^{\frac{1}{2}}$$

$$= 10 \cdot \log_{10} (1 + \Omega_s^{2n})$$

$$= 25.84 \text{ dB} \Big|_{\substack{n=9 \\ \Omega_s = 1.5 \Omega_p}}$$



$$|H(j\Omega)|^2 = \frac{1}{1 + \Omega^{18}}$$

finally, we need to discuss how the filter should be realized.

"Network Function"

Basically, the purpose is to derive a transfer function $H(s)$

Amplitude response \rightarrow Transfer function

$$|H(j\omega)| \rightarrow H(s)$$

Known!

For a complex number, we have;

$$|x|^2 = x \cdot \bar{x} \quad (\sim x \cdot x^*)$$

$$|H(j\omega)|^2 = H(j\omega) \cdot H^*(j\omega)$$

Assuming now that we evaluate the transfer function $H(s)$ on the frequency axis $s = j\omega$, then we have;

$$|H(j\omega)|^2 = H(s) \cdot H^*(s) \Big|_{s=j\omega}$$

$$= H(s) \cdot H(-s)$$

Since we know $|H(j\omega)|^2$, we can now find $H(s)$.

$$\bullet \quad |H(j\Omega)|^2 = \frac{1}{1+\Omega^{2n}} = H(s) \cdot H(-s) \Big|_{s=j\Omega}$$

$$\Downarrow \quad H(s) \cdot H(-s) = \frac{1}{1+\left(\frac{s}{j}\right)^{2n}} \Big|_{s=j\Omega \quad (\Omega=\frac{s}{j})}$$

$$\bullet \quad \begin{cases} H(s) \cdot H(-s) = \frac{1}{1+(-1)^n s^{2n}} \\ H(s) = \frac{P(s)}{Q(s)} \end{cases}$$

$$\Downarrow \quad Q(s) \cdot Q(-s) = 1+(-1)^n \cdot s^{2n}$$

• We now search for the roots in this polynomial;

$$1+(-1)^n \cdot s^{2n} = 0$$

$$\Downarrow \quad (-1)^n \cdot (s^2)^n = -1$$

$$\Downarrow \quad (-s^2)^n = -1 = e^{j(\pi+2k\pi)}$$

\Downarrow

↑ Euler.
k is an integer.

$$(-s^2)^n = e^{j(2k+1)\pi}$$

$$\Downarrow n \cdot \ln(-s^2) = \ln \left\{ e^{j(2k+1)\pi} \right\}$$

$$\Downarrow \ln(-s^2) = j \frac{2k+1}{n} \cdot \pi$$

$$\Downarrow -s^2 = e^{j \frac{2k+1}{n} \cdot \pi}$$

$$\Downarrow s^2 = e^{j \frac{2k+1}{n} \pi - \pi}$$

... and then we redo everything once more in order to isolate s ;

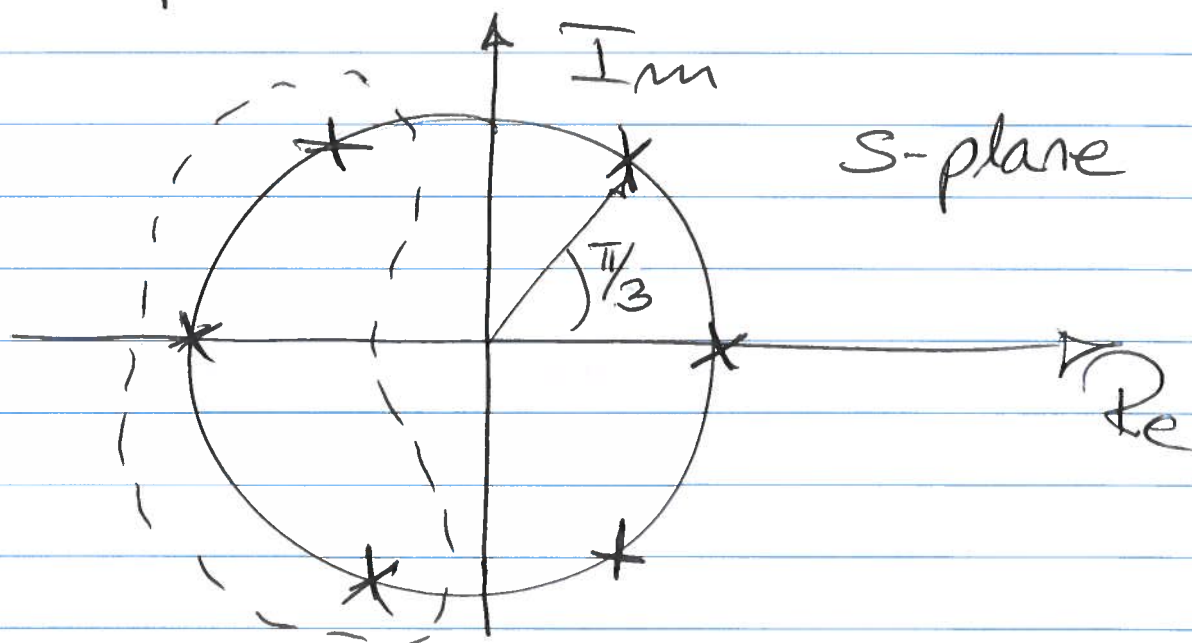
$$j \frac{2k+1}{2n} \cdot \pi - \frac{\pi}{2}$$

$$s_k = e^{j \frac{2k+1}{2n} \cdot \pi - \frac{\pi}{2}} \quad k=1, 2, \dots, 2n$$

Now we know the roots in $Q(s) \cdot Q(-s)$ and thus we have the poles in $H(s) \cdot H(-s)$.

These $2n$ poles are equally distributed on a circle with center in origo and radius 1.

Example: $n = 3$



We now select the poles located in the left half of the s-plane, since these poles represent a STABLE system $H(s)$!