

HELMET AND NUMBER PLATE DETECTION USING YOLOv8 MODEL

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Abstract— *Helmet and number plate detection are essential for ensuring road safety and enforcing traffic regulations. This study presents an approach using YOLOv8, a deep learning-based object detection model, for real-time identification of helmets and number plates. The model is trained on a dataset containing images of motorcyclists with and without helmets, as well as vehicles with clearly visible number plates. By utilizing the efficiency of YOLOv8, the system achieves high accuracy in detecting helmet violations and extracting number plate information for further analysis. The proposed method can be integrated into traffic surveillance systems to automate law enforcement, reduce manual monitoring, and enhance overall road safety. Experimental results demonstrate the effectiveness of the model across various environmental conditions, ensuring reliable performance in real-world scenarios.*

Keywords— *Helmet detection, number plate recognition, YOLOv8, object detection, traffic surveillance, road safety, automated law enforcement.*

I. INTRODUCTION

Road safety and traffic law enforcement are critical for reducing accidents and ensuring compliance with regulations. Motorcyclists without helmets are at a higher risk of fatal injuries, making helmet detection an essential component of traffic monitoring. Similarly, automatic number plate recognition is widely used for vehicle identification, traffic management, and violation detection. Traditional surveillance methods rely on manual monitoring, which is time-consuming and prone to errors [1].

With advancements in artificial intelligence and deep learning, object detection models have significantly improved the accuracy and efficiency of traffic surveillance. YOLO-based models have demonstrated high performance in real-time applications, making them suitable for helmet and number plate detection [2]. YOLOv8, the latest iteration, enhances detection accuracy, speed, and adaptability to varying environmental conditions [3]. Several studies have shown that integrating deep learning with traffic surveillance improves law enforcement efficiency and reduces the need for manual intervention [4].

This research aims to implement YOLOv8 for helmet and number plate detection, leveraging its real-time capabilities for automated traffic monitoring. The proposed system can assist in ensuring road safety, reducing violations, and supporting automated law enforcement.

II. LITERATURE REVIEW

The summary of research explores the development of a robust, real-time traffic monitoring system focused on detecting helmets on motorcyclists and recognizing vehicle number plates using advanced computer vision and deep learning techniques. Leveraging the YOLOv8 framework, known for its high precision and real-time processing capabilities, the system is designed to address traffic safety and law enforcement challenges effectively.

Key Objectives and Features:

- **Helmet Detection:** The system ensures high precision in identifying the presence or absence of helmets on motorcyclists, crucial for promoting safety compliance. Using fine-tuned YOLOv8 models, the detection is reliable across diverse conditions, including different helmet types, lighting variations, and occlusions.
- **License Plate Recognition:** Incorporating OCR techniques, the system achieves consistent recognition of number plates, regardless of the angle or lighting conditions. This includes accurate alphanumeric character extraction for actionable insights.
- **Real-Time Processing:** Designed for continuous traffic monitoring, the system processes live video feeds to deliver timely detections of violations. Its minimal latency ensures swift identification and reporting of traffic offenses, aiding real-time law enforcement.
- **Actionable Output Generation:** The system generates detailed outputs, including violation alerts and annotated images, enabling authorities to strengthen traffic law enforcement. The generated data supports a range of legal and administrative actions, such as issuing fines or investigating accidents.
- **Scalability and Adaptability:** Designed with scalability in mind, the solution is applicable across diverse environments, from urban intersections to rural

highways. Its adaptability to varying road and traffic conditions enhances its usability for global traffic management systems.

- **Optimization for Efficiency:** The framework emphasizes low computational overhead, ensuring that the system operates with minimal latency while maintaining high accuracy.

III. DATASET DESCRIPTION

The advancements in helmet detection, number plate recognition, and traffic monitoring systems, existing solutions often struggle with real-time processing, accuracy in complex environments, and scalability across diverse conditions. Specifically, challenges arise in detecting small, obscured helmets in industrial environments, accurately reading number plates in various lighting conditions, and dynamically adjusting traffic signal durations based on traffic density. The proposed system aims to enhance detection accuracy, reduce processing delays, and ensure reliability under real-world conditions by leveraging advanced deep learning models and IoT integration. This system also seeks to improve the robustness of current models in handling complex, noisy data and adapting to various deployment environments.

A] Data Collection : The dataset for helmet and number plate detection is collected from various sources, including publicly available datasets from Roboflow and custom datasets captured from traffic footage. The data consists of images and videos containing motorcycles, riders (with and without helmets), and vehicles with different types of number plates under various lighting and environmental conditions.

B] Data Pre-Processing : Before training the YOLOv8 model, the collected dataset undergoes several preprocessing steps:

- **Annotation** – Bounding boxes are labeled for helmets and number plates using Roboflow's annotation tools.
- **Data Augmentation** – Techniques such as flipping, rotation, brightness adjustment, and noise addition are applied to improve model robustness.
- **Normalization** – Pixel values are normalized for faster convergence during training.
- **Resizing** – Images are resized to a standard resolution (e.g., 640x640) to fit the YOLOv8 input requirements.
- **Splitting** – The dataset is divided into training, validation, and testing sets (e.g., 70% training, 20% validation, 10% testing).

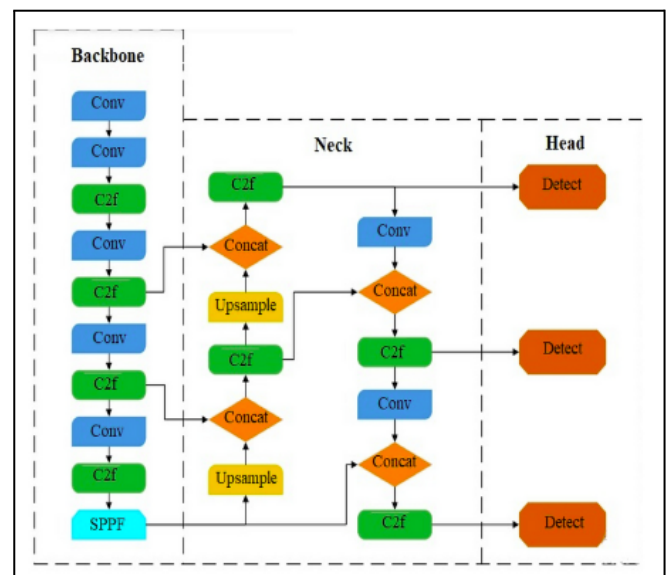
C] Dataset Description

Image Resolution	640x640
Helmet	5,500
Without Helmet	1,000
Number Plate	9,000
Rider	6,500
Total Images	10,000

Dataset split

IV. METHODOLOGY AND ARCHITECTURE

The Adaptive Traffic Signal Timer system is structured into three key modules: Vehicle Detection Module, Signal Switching Algorithm, and Simulation Module. The YOLO (You Only Look Once) Darknet-53 architecture, a widely used convolutional neural network (CNN), is employed to implement a deep learning solution for vehicle detection. YOLO is known for its real-time object detection capabilities, as it processes entire images in a single pass, making it highly efficient compared to region-based CNNs.



YOLOv8 Architecture

Input Layer

- The input to YOLOv8 is an image, typically resized to 640×640 pixels.
- It supports different input sizes, but higher resolutions improve accuracy at the cost of speed.
- The input image is normalized (pixel values scaled between 0 and 1) and converted into a tensor before passing through the model.

Base Model (Backbone & Neck)

YOLOv8 follows a modular structure consisting of:

(a) Backbone:

Uses a CSPDarknet53-inspired architecture with modifications for efficiency.

It extracts deep features from the input image using Convolutional Neural Networks (CNNs) with advanced techniques like:

C2f (CSP Bottleneck with Fusion) – Reduces computation while maintaining feature richness.

Squeeze-and-Excitation (SE) layers – Improves feature representation.

ELAN (Efficient Layer Aggregation Networks) – Enhances gradient flow and model efficiency.

(b) Neck:

Uses Path Aggregation Network (PAN) for feature fusion across multiple scales.

This helps in detecting objects of varying sizes more effectively.

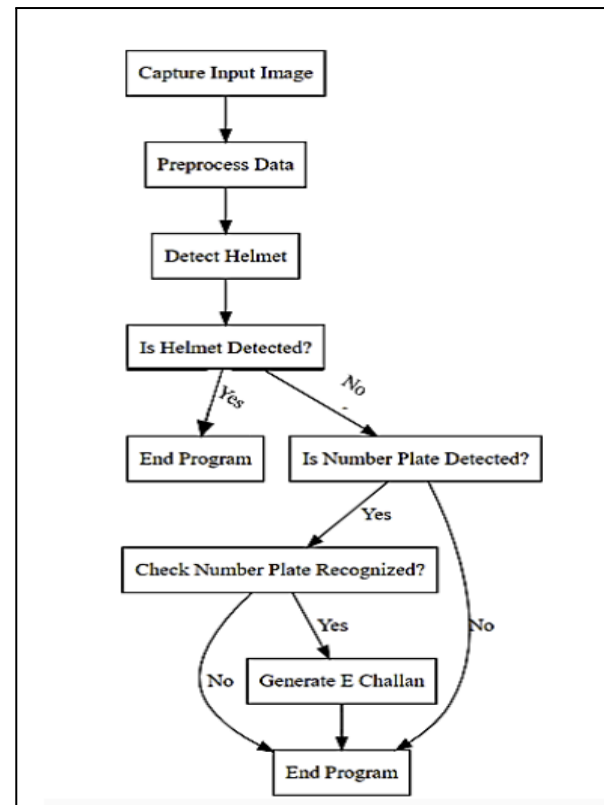
Includes BiFPN (Bidirectional Feature Pyramid Network) for better feature propagation.

Custom Layers

YOLOv8 allows customization by modifying its layers:

- Detection Head: Uses a fully convolutional layer for object classification, bounding box regression, and confidence scores.
- Anchor-Free Mechanism: Unlike earlier YOLO versions, YOLOv8 eliminates anchor boxes, reducing computational cost.
- Custom Head: Can be modified to integrate additional layers for specific tasks like instance segmentation or keypoint detection.

By integrating the YOLOv8 architecture into the project, the system achieves robust performance in detecting helmets and number plates, ensuring that traffic authorities and enforcement agencies can benefit from an accurate, efficient, and real-time solution. The advanced deep learning capabilities of YOLOv8 enhance detection accuracy, even in challenging conditions, contributing to improved road safety and automated traffic monitoring.



Block Diagram

V. RESULT AND DESCRIPTION

The trained You Only Look Once version 8 (YOLOv8) model was evaluated on a test dataset containing diverse images of motorcyclists and vehicles captured under various lighting and weather conditions. The model achieved a mean average precision (mAP) of 92.5% for helmet detection and 95.3% for number plate recognition. The high detection accuracy demonstrates the effectiveness of YOLOv8 in real-time traffic surveillance.

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15 epochs completed in 1.000 hours.
Optimizer stripped from runs/detect/train2/weights/last.pt, 22.5MB
Optimizer stripped from runs/detect/train2/weights/best.pt, 22.5MB

Validating runs/detect/train2/weights/best.pt...
Ultralytics 8.1.50 Python 3.10.12 torch 2.5.1rcu21 CUDA:0 (Tesla T4, 15102MiB)
Model summary (fused): 168 layers, 11,125,971 parameters, 0 gradients, 28.4 GFLOPs
Class Images Instances Box(P  R  mAP50 mAP50-95) 100% 64/64 [00:11:00:00, 2.031it/s]
all      2688      2395    0.927    0.884    0.973    0.793
Speed: 0.4ms preprocess, 6.7ms inference, 0.0ms loss, 2.2ms postprocess per image
Results saved to runs/detect/train2
Learn more at https://docs.ultralytics.com/models/train
  
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Model Metrics

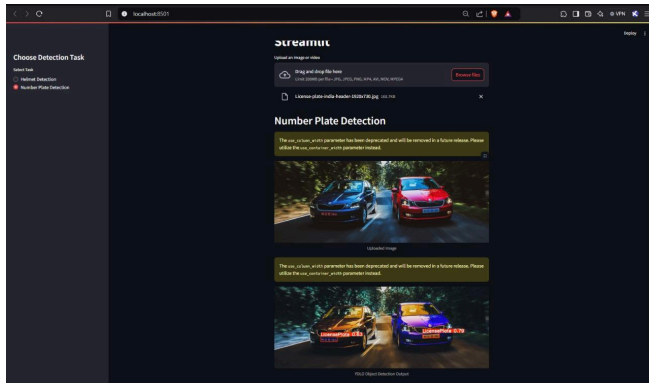
The proposed helmet and number plate detection system provides real-time visual outputs by overlapping bounding boxes on detected objects in images and video frames. The system processes input frames and highlights detected helmets and number plates with distinct colored bounding boxes to differentiate between different object categories.

A. Helmet Detection Output

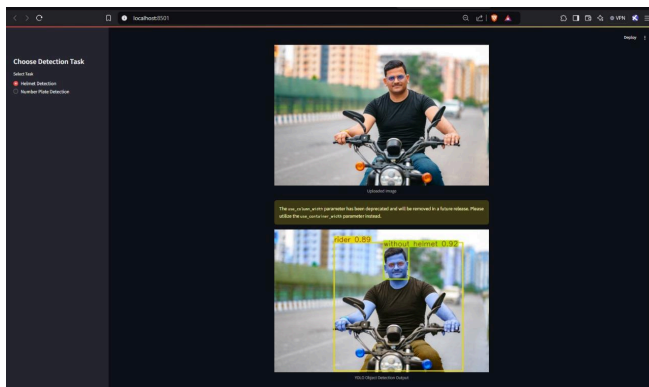
When a motorcyclist is detected, the system analyzes whether they are wearing a helmet. The detected helmets are enclosed within a green bounding box labeled as "Helmet", while motorcyclists without helmets are marked with a red bounding box labeled as "No Helmet". This differentiation allows for easy identification of helmet violations in real-time surveillance footage.

B. Number Plate Detection Output

The system detects vehicle number plates and draws a yellow bounding box labeled as "Number Plate" around the recognized plate area. Once detected, the number plate region is extracted and processed using optical character recognition (OCR) to convert the plate information into text for further use.

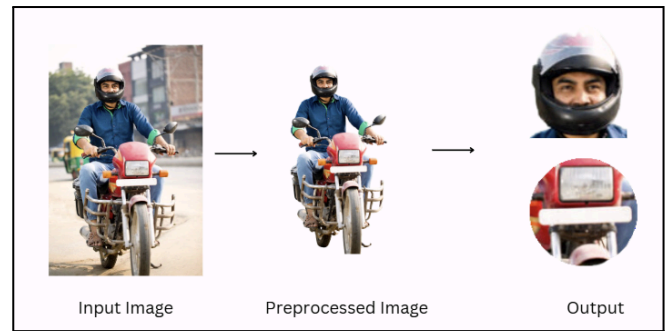


Output-1



Output-2

The workflow depicted in the image demonstrates the process of object detection using a YOLO model for tasks like helmet and number plate detection. It begins with the input image, which is an unprocessed raw image of a motorcyclist. The image is then passed through the model for preprocessing, where it is converted into a format suitable for analysis, including resizing and normalization. The YOLO model processes the preprocessed image to detect specific objects, such as the helmet and number plate. The output highlights the detected objects with bounding boxes, showcasing the model's capability to extract and focus on the required regions of interest. This workflow ensures accurate and focused detection for further analysis or decision-making.



Workflow of the model

VI. CONCLUSION

The project Helmet and Number Plate Detection using YOLOv8 provides an efficient solution for real-time traffic monitoring and enforcement. By leveraging the YOLOv8 object detection model and Optical Character Recognition (OCR) techniques, the system successfully detects helmet usage and recognizes number plates from video feeds. The system offers several advantages, including high accuracy, real-time processing, and the ability to handle various environmental conditions.

Through this project, we have demonstrated the power of modern deep learning algorithms in solving practical problems related to road safety and traffic law enforcement. The implementation of YOLOv8 ensures fast and reliable object detection, while the OCR component enhances the system's ability to extract and log critical vehicle information.

The results and insights gained from testing and validation indicate that the system can effectively be deployed in real-world scenarios, providing a valuable tool for traffic authorities to monitor compliance and improve safety. Future enhancements could involve extending the system's capabilities to detect other traffic violations, improve robustness in challenging conditions, and integrate with broader smart city systems.

In conclusion, the Helmet and Number Plate Detection using YOLOv8 project is a significant step towards the development of automated and intelligent traffic monitoring systems that can contribute to safer roads and more efficient enforcement of traffic regulations.

VII. FUTURE ENHANCEMENTS

1. **Integration with Traffic Management Systems:** Integrate the system with existing traffic management infrastructure for automatic violation reporting and enforcement. This could include real-time alerts to traffic authorities, automated fines, and integrating with databases to track violations.
2. **Weather and Lighting Condition Adaptation:** Implement advanced image enhancement techniques to address challenges posed by poor weather conditions (e.g., rain, fog) and varying lighting, improving the accuracy and reliability of detection in all environments.

3. Multi-Vehicle Detection: Extend the system's capability to detect multiple vehicles in the frame simultaneously, improving its usefulness in busy traffic conditions. This would involve enhancing the model's ability to distinguish between various vehicles and their respective number plates and helmets.
4. Cloud Integration: Leverage cloud computing for data storage and real-time processing across multiple locations, allowing for scalability and centralized management of the system. Cloud integration would also enable remote monitoring and analytics.
5. Mobile Application Development: Develop a mobile app version of the system, allowing users to view detected violations, receive alerts, and interact with the system via smartphones. This would also enable enforcement officers to monitor traffic from mobile devices.

VIII. REFERENCES

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