

# ASSIGNMENT- 1

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Download all python codes from

<https://github.com/Mastan1301/EE3025/Assignment-1/codes>

and latex-tikz codes from

<https://github.com/Mastan1301/EE3025/Assignment-1>

## 1 PROBLEM

The command

```
output_signal = signal.lfilter(b,a,
    output_signal)
```

in Problem 2.3 is executed through following difference equation

$$\sum_{m=0}^M a(m) y(n-m) = \sum_{k=0}^N b(k) x(n-k) \quad (1.0.1)$$

where input signal is  $x(n)$  and output signal is  $y(n)$  with initial values all 0. Replace **signal.filtfilt** with your own routine and verify

## 2 SOLUTION

Using the properties of z-transform

$$\mathcal{Z}\{x(n-k)\} = z^{-k} X(z) \quad (2.0.1)$$

$$\mathcal{Z}\{y(n-m)\} = z^{-m} Y(z) \quad (2.0.2)$$

where  $X(z)$  and  $Y(z)$  are the respective z-transforms of  $x(n)$  and  $y(n)$  respectively.

Applying z-transform on both sides in (1.0.1),

$$Y(z) \sum_{m=0}^M a(m) z^{-m} = X(z) \sum_{k=0}^N b(k) z^{-k} \quad (2.0.3)$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{k=0}^N b(k) z^{-k}}{\sum_{m=0}^M a(m) z^{-m}} \quad (2.0.4)$$

From the coefficients b,a and from (2.0.4), we obtain  $H(K)$ .

The np.fft function is used to compute DFT  $X(K)$

from  $x(n)$ .

To obtain  $y(n)$ , we first compute  $Y(K)$  from,

$$Y(K) = H(K) X(K) \quad (2.0.5)$$

Then, we use ifft function to compute  $y(n)$  from  $Y(K)$  and store the result in a wav file.

The python code for the problem is -

codes/ee18btech11039.py

Below is the soundfile constructed using own routine-

codes/Sound\_With\_ReducedNoise\_1.wav

The soundfile obtained using library function -

codes/Sound\_With\_ReducedNoise\_2.wav

## 3 VERIFICATION

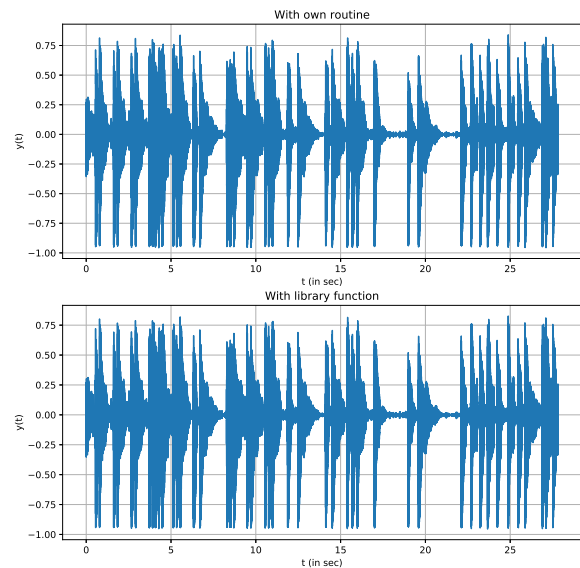


Fig. 0: Time domain response

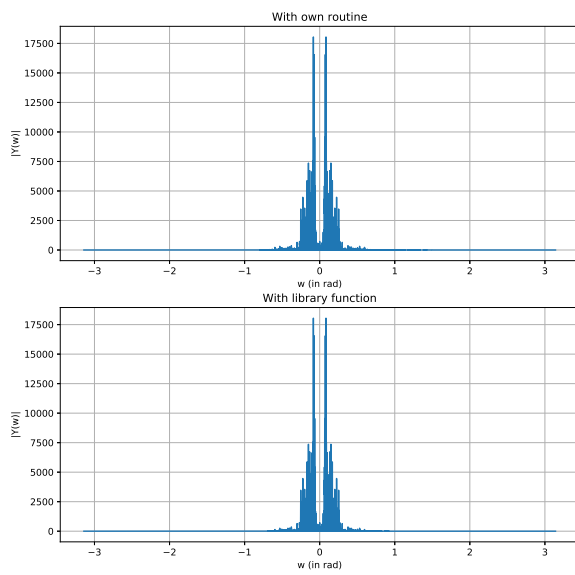


Fig. 0: Frequency domain response