1

ASSIGNMENT- 1

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Download all python codes from

https://github.com/Mastan1301/EE3025/tree/main/ Assignment-1/codes

and latex-tikz codes from

https://github.com/Mastan1301/EE3025/tree/main/ Assignment-1

1 Problem

The command

output_signal = signal.lfilter(b,a, output_signal)

in Problem 2.3 is executed through following difference equation

$$\sum_{m=0}^{M} a(m) y(n-m) = \sum_{k=0}^{N} b(k) x(n-k)$$
 (1.0.1)

where input signal is x(n) and output signal is y(n) with intial values all 0. Replace **signal.filtfilt** with your own routine and verify

2 Solution

Using the properties of z-transform

$$Z\{x(n-k)\} = z^{-k}X(z)$$
 (2.0.1)

$$Z{y(n-m)} = z^{-m}Y(z)$$
 (2.0.2)

where X(z) and Y(z) are the respective z-transforms of x(n) and y(n) respectively.

Applying z-transform on both sides in (1.0.1),

$$Y(z)\sum_{m=0}^{M}a(m)z^{-m} = X(z)\sum_{k=0}^{N}b(k)z^{-k}$$
 (2.0.3)

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{k=0}^{N} b(k) z^{-k}}{\sum_{m=0}^{M} a(m) z^{-m}}$$
(2.0.4)

From the coefficients b,a and from (2.0.4), we obtain H(K).

The np.fft function is used to compute DFT X(K)

from x(n).

To obtain y(n), we first compute Y(K) from,

$$Y(K) = H(K)X(K)$$
 (2.0.5)

Then, we use ifft function to compute y(n) from Y(K) and store the result in a way file.

The python code for the problem is -

codes/ee18btech11039.py

Below is the soundfile constructed using own routine-

codes/Sound_With_ReducedNoise_1.wav

The soundfile obtained using library function -

codes/Sound With ReducedNoise 2.way

3 VERIFICATION

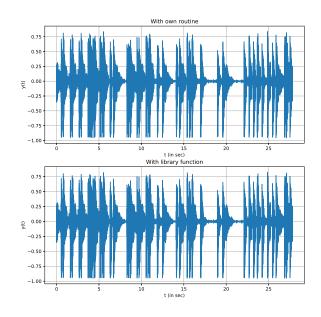


Fig. 0: Time domain response

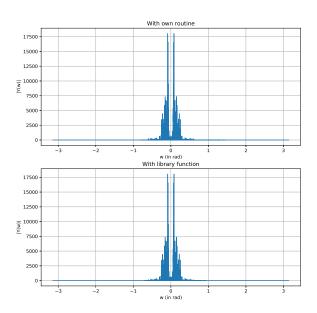


Fig. 0: Frequency domain response