

Elements of Bayesian Decision Theory

Prior probability (prior)

Classes

ω_1 - sea bass

ω_2 - salmon

a two-class problem

Prior probabilities:

$P(\omega_1)$ - probability of finding sea bass

$P(\omega_2)$ - probability of finding salmon

A simple decision rule (when no other information is available):

$$\begin{cases} \omega_1, & \text{if } P(\omega_1) > P(\omega_2) \\ \omega_2, & \text{otherwise} \end{cases}$$

Where do you get the prior probabilities?

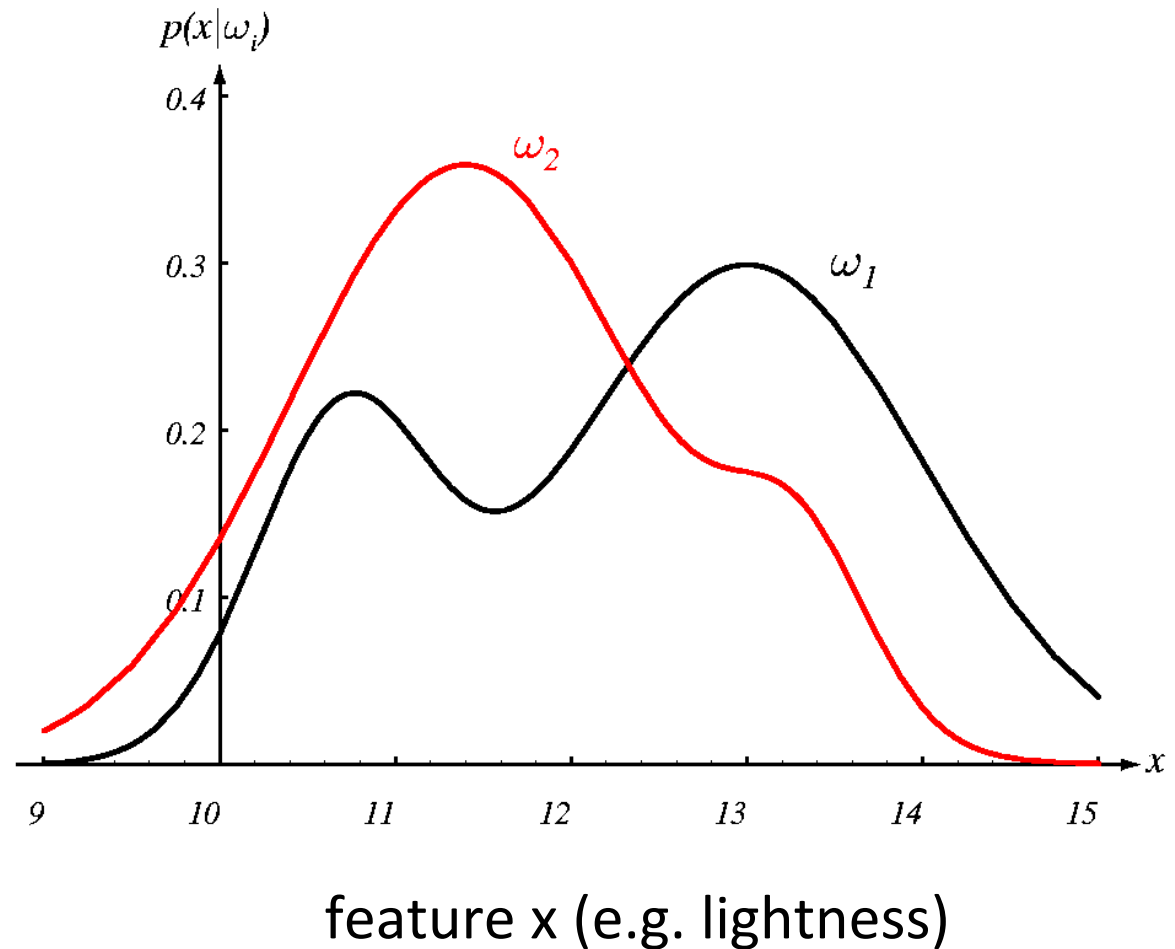
Answer: mostly from previous empirical observations or some theoretical considerations (e.g. 0.5 chance to throw tail/head of a fair coin).

Class conditional probability density function and likelihood

$$p(x | \omega_1)$$

$$p(x | \omega_2)$$

Likelihood –
pdf as a function of
the second argument
(class) with the first
argument (feature
value x) fixed



Bayes formula/rule

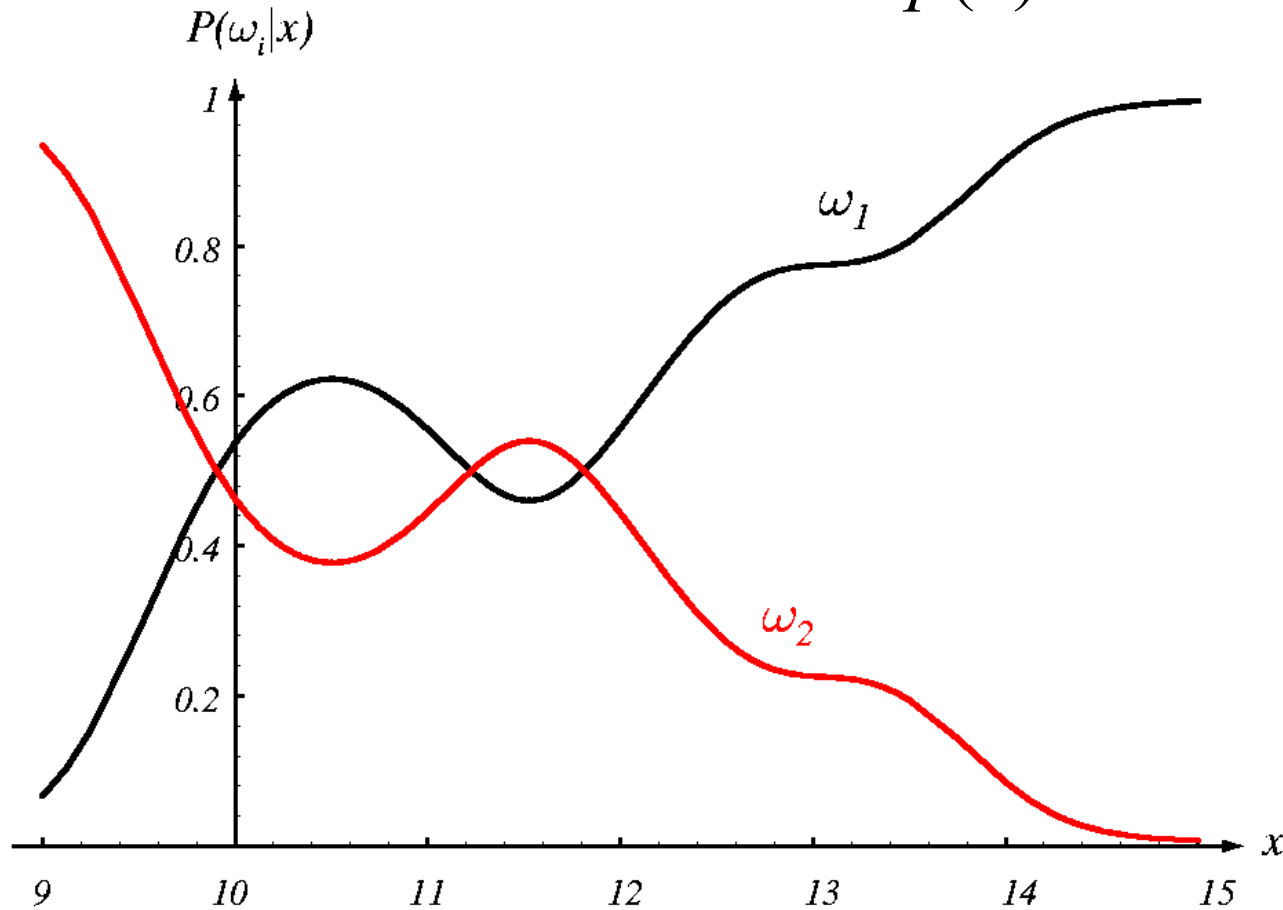
$$P(\omega_j | x) = \frac{p(x | \omega_j) P(\omega_j)}{p(x)}$$

$$p(x) = p(x | \omega_1) P(\omega_1) + p(x | \omega_2) P(\omega_2)$$

$$\textit{posterior} = \frac{\textit{likelihood} \times \textit{prior}}{\textit{evidence}}$$

Posterior probability

$$P(\omega_j | x) = \frac{p(x | \omega_j) P(\omega_j)}{p(x)}$$



$$P(\omega_1) = 2/3$$

$$P(\omega_2) = 1/3$$

For any x , use priors as coefficients of likelihoods and normalize so that their sum is 1.

(from Duda, Hart, Stork (2001) Pattern classification)

Bayes decision rule

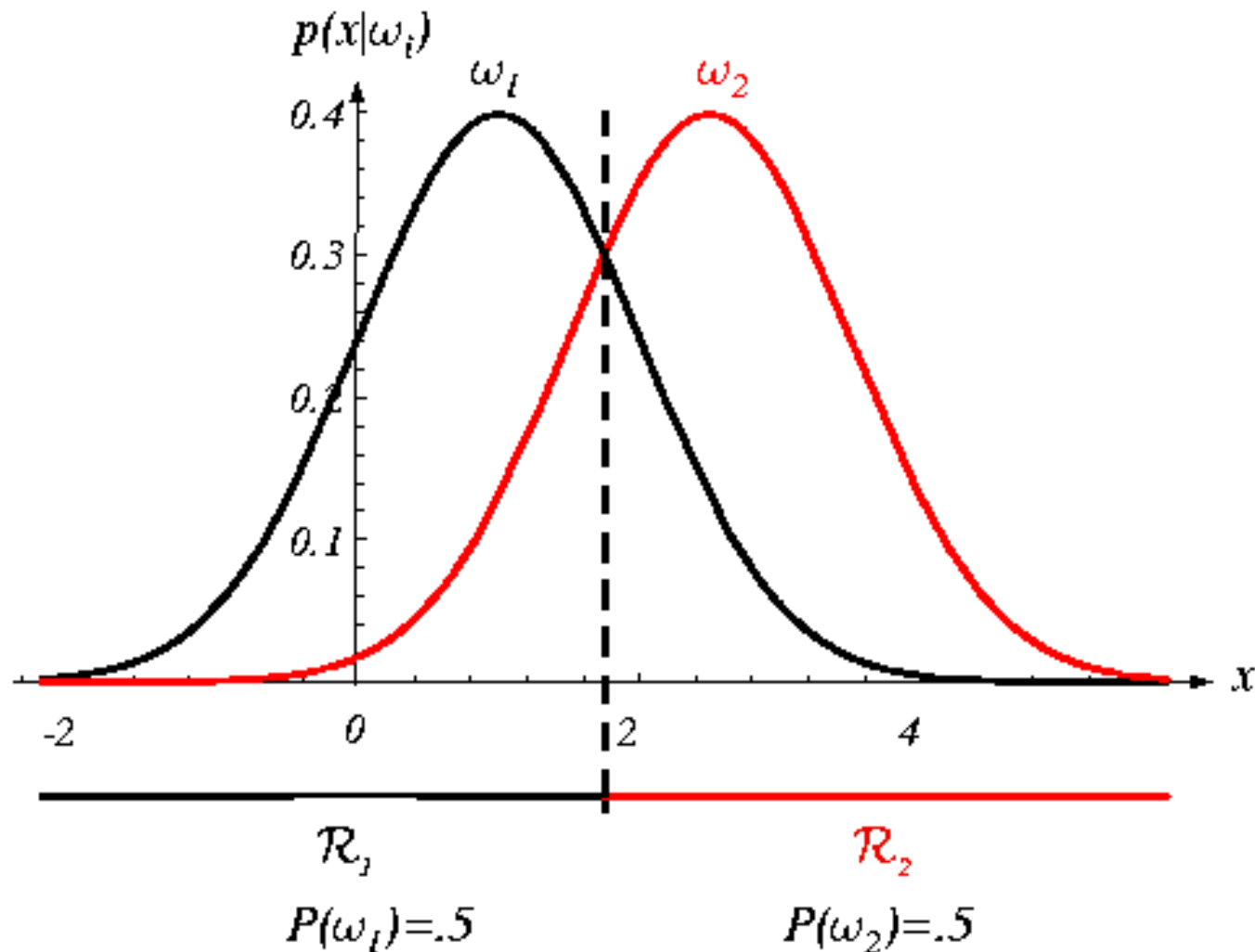
Probability of making an error:

$$P(\text{error} | x) = \begin{cases} P(\omega_1 | x), & \text{if we decide } \omega_2 \\ P(\omega_2 | x), & \text{if we decide } \omega_1 \end{cases}$$

Bayes decision rule:

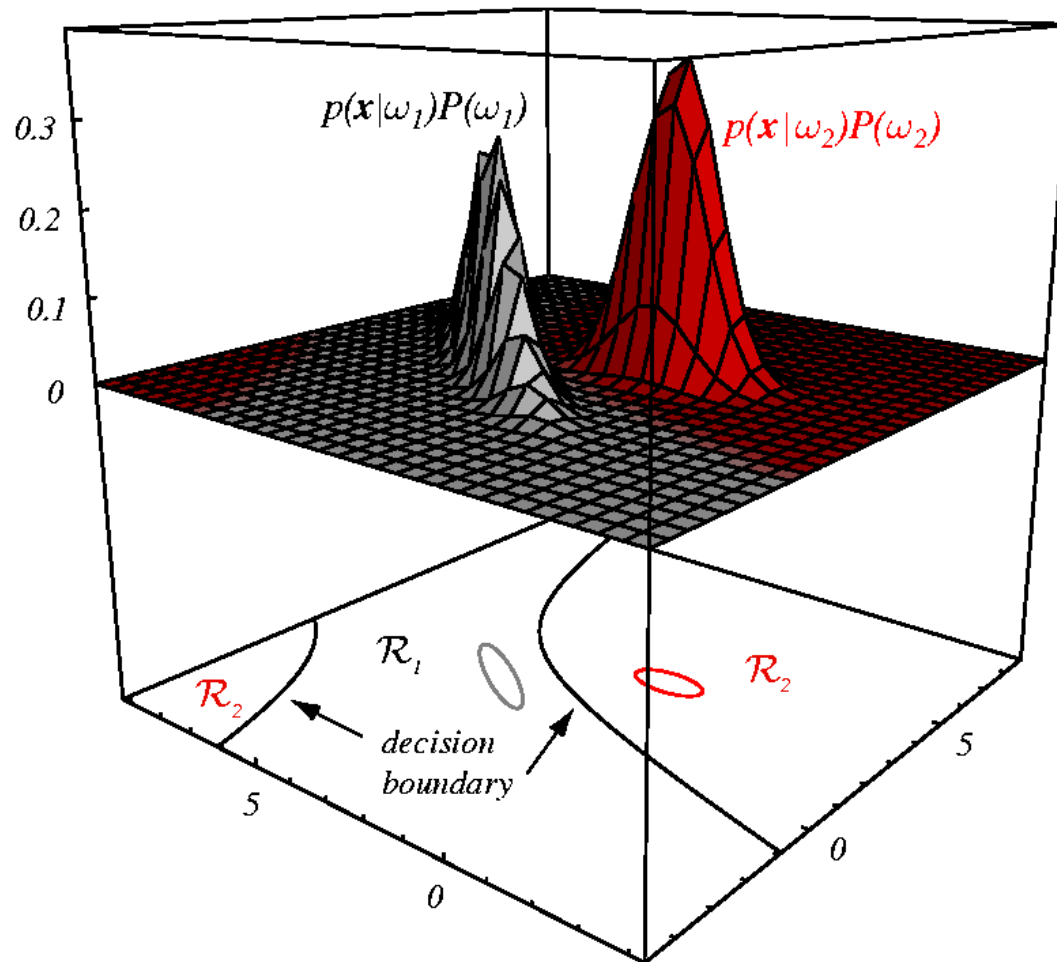
$$\begin{cases} \omega_1, & \text{if } P(\omega_1 | x) > P(\omega_2 | x) \\ \omega_2, & \text{otherwise} \end{cases}$$

Example of a decision criterion in a one-dimensional feature space



from Duda, Hart, Stork (2001) Pattern classification

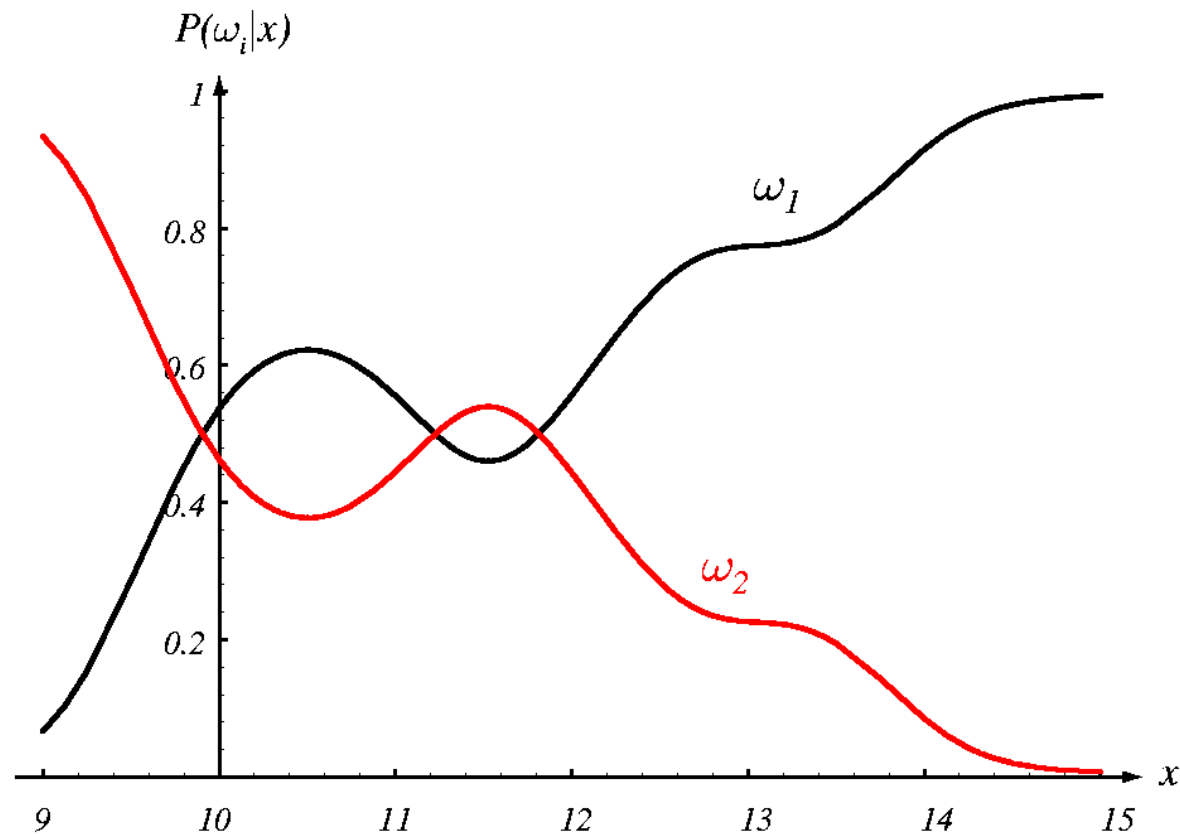
Example of a decision boundary in a two-dimensional feature



from Duda, Hart, Stork (2001) Pattern classification

Error probability of Bayes decision rule

$$P(\text{error} \mid x) = \min[P(\omega_1 \mid x), P(\omega_2 \mid x)]$$



(from Duda, Hart, Stork (2001) Pattern classification)

Generalizations of Bayesian Decision Theory

1. We replace the scalar x with the *feature vector* $\mathbf{x} \in \mathbb{R}^d$.
2. We introduce a *cost* or a *loss function* λ which states how costly each classification decisions is.

Let

$\{\omega_1, \omega_2, \dots, \omega_c\}$ - categories (classes)

$\{\alpha_1, \alpha_2, \dots, \alpha_c\}$ - possible actions

The loss function $\lambda(\alpha_i | \omega_j)$ describes the loss incurred for taking action α_i when the category is ω_j .

Bayes formula

$$P(\omega_j | \mathbf{x}) = \frac{p(\mathbf{x} | \omega_j) P(\omega_j)}{p(\mathbf{x})}$$

Evidence

$$p(\mathbf{x}) = \sum_{j=1}^c p(\mathbf{x} | \omega_j) P(\omega_j)$$

Generalized Bayesian decision theory

Taking action α_i , the loss/cost, also called *conditional risk*, is:

$$R(\alpha_i | \mathbf{x}) = \sum_{j=1}^c \lambda(\alpha_i | \omega_j) P(\omega_j | \mathbf{x})$$

Rule to minimize the expected loss/cost:

Select that action which minimizes the conditional risk.

Generalized Bayesian decision theory

Let $P(\text{melanoma} \mid x) = 0.1$ and $P(\text{benign nevus} \mid x) = 0.9$

Bayesian classification: benign nevus (due to higher probability)

Let now consider the actions: 1 – remove, 2 – do not remove

With costs in Euro

$a_{1,\text{mel}} = 50$	$a_{1,\text{nev}} = 50,$
$a_{2,\text{mel}} = 100000$	$a_{2,\text{nev}} = 0$

Expected cost (weighted average over many cases with x):

$$C_1 = a_{1,\text{mel}} P(\text{melanoma} \mid x) + a_{1,\text{nev}} P(\text{benign nevus} \mid x) = 50*0.1 + 50*0.9 = 50$$

$$C_2 = a_{2,\text{mel}} P(\text{melanoma} \mid x) + a_{2,\text{nev}} P(\text{benign nevus} \mid x) = 100000*0.1 + 0*0.9 = 10000$$

-> we choose for the action with lower costs, i.e. ‘remove’

Summary of concepts and facts

- Prior probability
- Class conditional probability density function, likelihood
- Posterior probability
- Bayes formula/rule for posteriors
- Bayes decision rule
- Minimum loss/risk classification