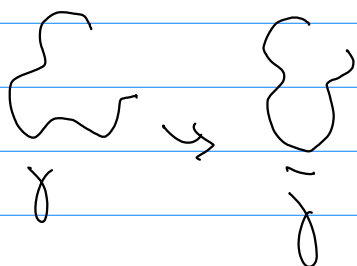


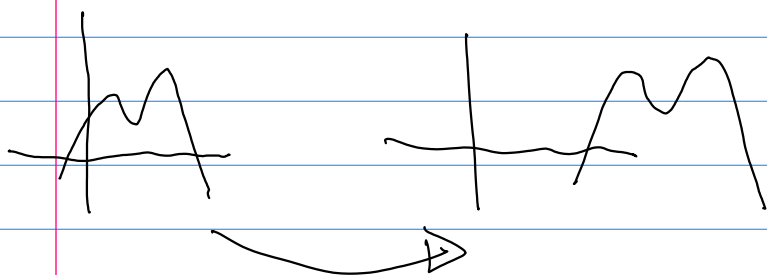
Dada la curvatura $\leadsto \gamma = \gamma(s)$
 $K = K(s)$ única salvo movimientos rígidos
 con curvatura K .

\rightarrow Resuelve (en parte) el problema de reconocer cuándo 2 curvas
 coinciden salvo un movimiento rígido.



$$K = K(s)$$

$$\bar{K} = \bar{K}(\bar{s})$$



K y \bar{K} difieren en una traslación.

Objetivo: Reconocer si 2 curvas no necesariamente p.p.a. difieren en
 un mov. rígido.

$$K = K(t) = \frac{\det(\gamma', \gamma'')}{\|\gamma'\|^3} \text{ o permite calcular la curv. si la curva no está p.p.a.}$$

$$K = K(s(t))$$

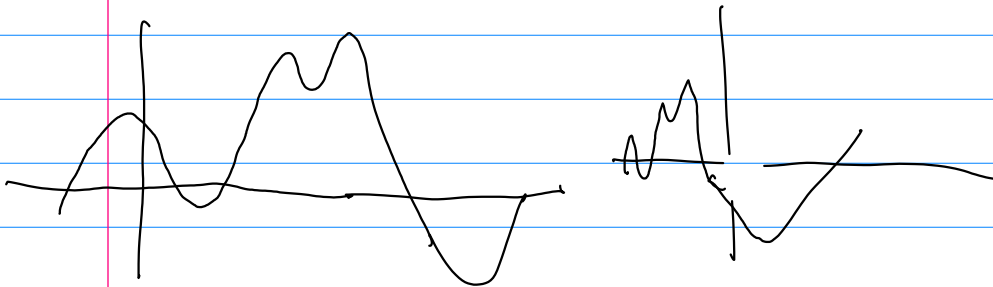
$$s(t) \equiv \text{long. de arco}; \quad s(t) = \int_{t_0}^t \|\gamma'(\xi)\| d\xi$$

$$\gamma = \gamma(t)$$

$$K = K(t)$$

$$\bar{\gamma} = \bar{\gamma}(\bar{t})$$

$$\bar{K} = \bar{K}(\bar{t})$$



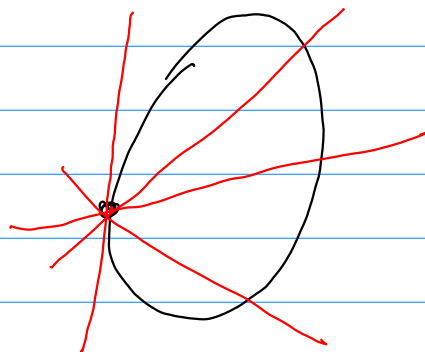
Ejemplo: Elipse

$$C: \frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

$$\begin{cases} x = a \cos t \\ y = b \sin t \end{cases} \quad (\text{no es p.p.a.})$$

Param. usando curvas racionales:

Dado un pt. $P_0 \in C$



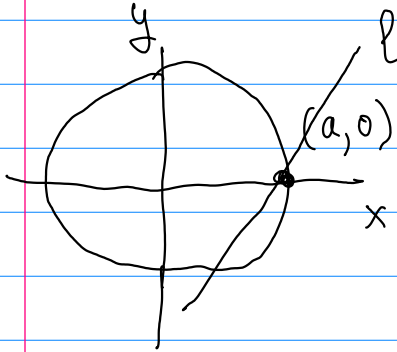
Denomamos el haz de rectas por p_0 , $\text{Haz}(p_0)$

$$\forall l \in \text{Haz}(p_0)$$

$$l \cap C = \{p_0, p\}$$

$$\text{Haz}(p_0) \rightarrow C$$

$$l \mapsto p$$



$$l_0: x - a = 0$$

$$l_1: y = 0$$

$$l: y = t(x - a)$$

$$\left\{ \begin{array}{l} x^2/a^2 + y^2/b^2 = 1 \\ y = t(x - a) \end{array} \right.$$

$$x^2/a^2 + \frac{t^2(x-a)^2}{b^2} = 1$$

$$y = t(x - a)$$

$$x^2 \left(\frac{1}{a^2} + \frac{t^2}{b^2} \right) - \frac{2t^2}{b^2} ax + \frac{t^2 a^2}{b^2} = 1.$$

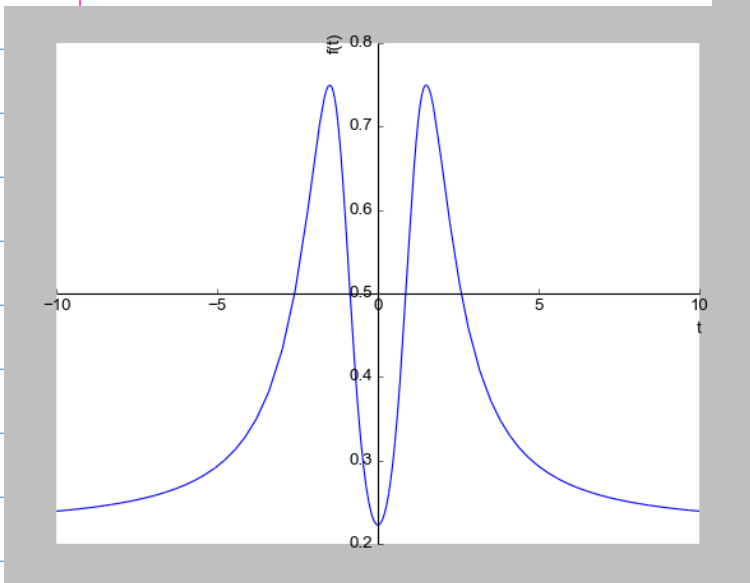
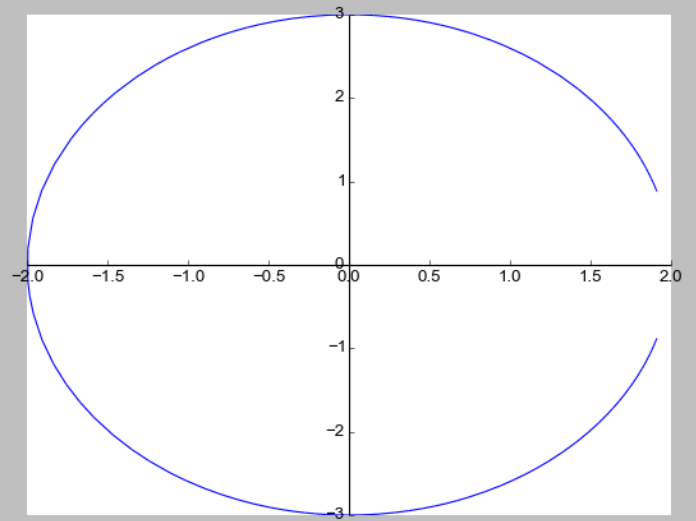
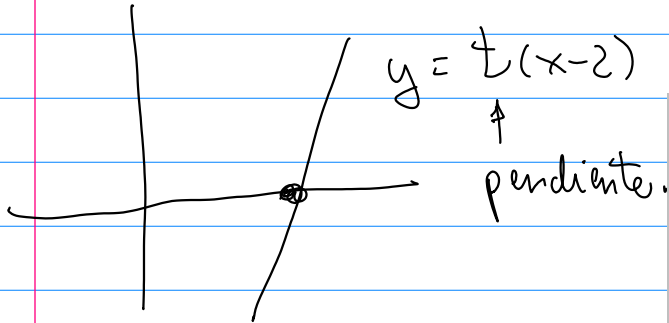
$$a=2, b=3$$

$$\gamma(t) = \left(\frac{8t^2 - 18}{4t^2 + 9}, -\frac{36t}{4t^2 + 9} \right) \text{ param. racional.}$$

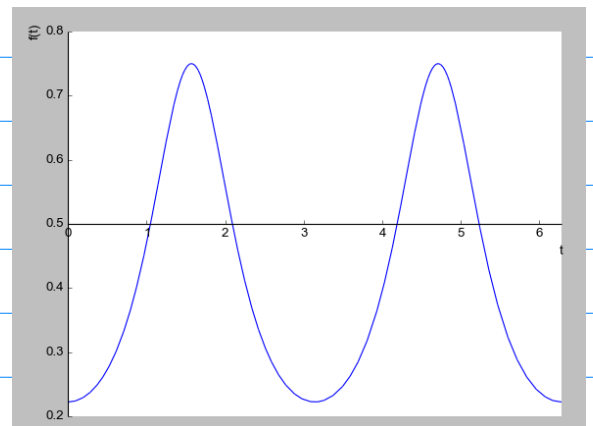
\rightarrow es rápida de calcular.

$$\gamma(t) = (8t^2 - 18 : -36t : 4t^2 + 9) \text{ param. en } \mathbb{P}^2,$$

$\begin{matrix} \text{"} & \text{"} & \text{"} \\ x & y & z \end{matrix}$



Curv. de la elipse como
curv. racional.



Curv. de la elipse
como curva trig.