

CS217 – Algorithm Design and Analysis

Homework 4

Not Strong Enough

April 19, 2020

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Suppose the edges e_1, \dots, e_m are sorted by their cost. Show how to solve MCP in time $O(n + m)$.

Solution. The algorithm is executed in iterations. Suppose that $c(e_1) \geq c(e_2) \geq \dots \geq c(e_m)$. In iteration i , consider e_i .

There is a set of vertices which is reachable from s , and the initial status of the set is $\{s\}$. Each vertex has an predecessor recording the predecessor in the path by which s reaches the vertex. Its initial status is *null*. Each vertex also has a set of unresolved edges whose start point is the vertex. Its initial status is \emptyset .

In each iteration, denote the edge we are handling by $e = (u, v)$.

If u is not reachable, simply add e into the unresolved edge set of u .

If u, v are already reachable, nothing needs to be done.

If u is already reachable but v is not, set v reachable and set its predecessor to u . Then handle all unresolved edges of v . (Let the end point of each edge be reachable if it is not.) Since this may introduce new reachable vertices, handle them too. This procedure is like a BFS.

Once t is reached, the algorithm terminates, and the cost of the newly introduced edge is the cost of MCP. Using the predecessor of each vertex, the maximum capacity path from s to t can be generated. \square

First prove that each vertex in the reachable set is really reachable(so it is well-defined):

Proof. The reachable set has the property that, except for s , all vertices in the set have a predecessor also in the set.

This is trivial since when we add a vertex to the reachable set, we set its predecessor by a reachable vertex.

Using this property, since its predecessor is reachable, the vertex itself is reachable as well. \square

Then prove that all reachable vertices using $\{e_1, \dots, e_n\}$ are in reachable set after iteration n :

Proof. Assume that there is a path from s to v using edges $e_{i_1}, e_{i_2} \dots e_{i_k}, (i_1, i_2 \dots i_k \in \{1, 2, \dots, n\})$. And $\forall j \in \{1, 2 \dots k\}, e_{i_j} = (u_j, u_{j+1}); u_1 = s, u_{k+1} = v$. Let $M_j = \max\{i_1, i_2 \dots i_j\}$, $m_j = \min\{i_1, i_2 \dots i_j\}$

Assume that after iteration M_{q-1} $u_1, u_2 \dots u_q$ are in reachable set and u_q is added in iteration M_{q-1} . If $i_q < M_{q-1}$, e_q is in unresolved set of u_q . So in iteration $M_{q-1} = M_q$, when adding u_q in reachable set, all unresolved edges of u_q are handled so u_{q+1} is added as well. If $i_q > M_{q-1}$, in iteration $M_q = i_q$, u_q is in reachable set so u_{q+1} is added in reachable set.

Consider the initial status that after iteration $M_1 = i_1$, $u_1 = s, u_2$ are in reachable set and u_2 is added in iteration M_1 .

By induction, it is proved that after iteration M_k , $u_1, u_2 \dots u_{k+1}$ are all in reachable set. \square

Now it is trivial to prove the correctness of the algorithm:

If the cost of MCP is $c^* = e_n$, then the path only uses edges in $\{e_1, \dots e_n\}$, so exactly in iteration n , t is reachable.

Then prove the complexity of the algorithm is $O(n + m)$:

Proof. Consider an arbitrary edge $e_k = (u, v)$. If in iteration k , u is already reachable, it is not added into the unresolved set so it will not be visited. Otherwise, it is added into the unresolved set of u , and when u is added into the reachable set, it will then be visited.

Since u can only be added to reachable set once, e_k is visited at most twice. So the complexity is $O(m)$.

In the initial step, each vertex is initialized, so the complexity is $O(n)$.

Combine the two steps together, the total complexity is $O(n + m)$. \square