Reading Talk Categorical approach to diffeological spaces

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Disclaimer: The content of these notes is not original but is heavily based on the works of Blohmann[Blo24], Baez Hoffnung[BH11], and the entries on the nLab. In other words, it's a reading seminar!

Abstract

Diffeological spaces are a class of geometric structures that generalize the notion of smooth manifolds; in this sense, they provide an instance of a generalized space. They consist of a set X equipped with a collection of plots — maps from open Euclidean subsets to X — satisfying three simple axioms. While an individual diffeological space can exhibit behaviour far more pathological than a smooth manifold, the category $\mathbb{Dfl}g$ of all diffeological spaces enjoys many desirable properties not possessed by the category of smooth manifolds.

This talk concisely reviews the notions of diffeological spaces, concrete sites, and sheaves. We will show that Dflg is a category of "concrete sheaves on a concrete site" — also known as "generalized spaces" — and we will employ the rest of our time to exhibit the properties owned by this class of categories. The upshot is that any category of concrete sheaves on a concrete site — and thus the category of diffeological spaces — turns out to be a quasitopos, possessing all limits and colimits (among many other convenient properties).

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While this may be an unfortunate choice, we will denote an arbitrary category by \mathbb{C} . The field of complex numbers will never appear in this text.

1 Prerequisites

1.1 Presheaves

Let \mathbb{C} be an arbitrary category¹.

Definition 1: Presheaf over \mathbb{C} [nLa24b]

A preshef is a functor $F: \mathbb{C}^{op} \to \mathbb{S}et$.

The collection of all presheaves forms the category $[\mathbb{C}^{op}, \mathbb{S}et]$ whose objects are presheaves and morphisms are natural transformations.

Example: 1: Yoneda Embedding[nLa24d]

For \mathbb{C} a locally small category, every object $c \in \mathbb{C}$ induces a presheaf Y(c) called the representable presheaf represented by c. This assignment extends to a functor called Yoneda embedding

(1)

Hence Y sends any object $c \in \mathbb{C}$ to the the representable presheaf [nLa24c] which assigns to any other object $d \in \mathbb{C}$ the hom-set of morphisms from d into c.

The celebrated $Yoneda\ lemma$ [?] implies that this functor is full and faithful and hence realizes \mathbb{C} as a full subcategory inside its category of presheaves.

Example: 2

Let X be a topological space, one can introduce the category of open sets:

$$\mathbb{Op}(X) \rightsquigarrow \begin{cases} Obj = \\ Arr = \end{cases}$$

where objects are elements of the topology of X, and morphisms are the inclusion of an open set into another one. A presheaf $\mathbb{Op}(X)^{\mathrm{op}} \to \mathbb{Set}$ is exactly what we call a presheaf in topology.

In topology, a sheaf is defined as a presheaf that satisfies a specific gluing condition. This condition can be formalized in the categorical language by introducing the notion of *site*.

1.2 Sites

Let \mathbb{C} be any small category.

Definition 2: Site

A site is a small category equipped with a coverage.

Definition 3: Coverage

A Coverage is the assignment to each object $U \in \mathbb{C}$ of a collection of families of arrows $\{f_i : U_i \to U\}_{i \in I}$, called *covering families*, such that

¹All categories considered are locally small.

1. For any given $\{f_i: U_i \to U\}_{i \in I}$ covering family and $g: V \to U$ morphism, there exists a covering family $\{h_j: V_j \to V\}$ such that each composite $g \circ h_j$ factors through some f_i .

$$\begin{array}{ccc}
V_j & \xrightarrow{k} & U_i \\
\downarrow^{h_j} & & \downarrow^{f_i} \\
V & \xrightarrow{g} & W
\end{array}$$

(NB. The logic here is: $\forall f$ covering family , $\forall g$ morphism, $\exists h$ covering family such that $\forall j, \exists i, \exists k$: such that the above commutes.)

Example: 3

Given a topological space X, the category $\mathbb{Op}(X)$ is a site. Here a covering family for an open set U is a family of open sets $U_i \hookrightarrow U$ such that $\bigcup_{i \in I} U_i = U$.

A Grothendieck pretopology is a coverage with some extra properties.

Definition 4: Grothendieck pretopology

A Grothendieck pretopology on $\mathbb C$ is an assignment to each object U of $\mathbb C$ of a collection of families $\{U_i \to U\}$ of morphisms, called *covering families* such that

- 1. (Stability under base changes.) The collection of covering families is stable under pullback: if $\{U_i \to U\}$ is a covering family and $f: V \to U$ is any morphism in \mathbb{C} , then $\{f^*U_i \to V\}$ exists and is a covering family;
- 2. (Stability under composition.) If $\{U_i \to U\}_{i \in I}$ is a covering family and for each i also $\{U_{i,j} \to U_i\}_{j \in J_i}$ is a covering family, then also the family of composites $\{U_{i,j} \to U_i \to U\}_{i \in I, j \in J_i}$ is a covering family.
- 3. (Isomorphisms cover.) Every family consisting of a single isomorphism $\{V \xrightarrow{\cong} U\}$ is a covering family;

N.b. condition 1. in definition 4 corresponds to definition 3.

1.3 Sheaves

Definition 5: Sheaf

Let (\mathbb{C}, J) be a site in the form of a small category \mathbb{C} equipped with a coverage J. A presheaf $A \in [\mathbb{C}^{op}, \mathbb{Set}]$ is a *sheaf* with respect to J if

- for every covering family $\{p_i: U_i \to U\}_{i \in I}$ in J;
- and for every compatible family of elements, given by tuples $(s_i \in A(U_i))_{i \in I}$ such that for all $j, k \in I$ and all morphisms $U_j \stackrel{f}{\leftarrow} K \stackrel{g}{\rightarrow} U_k$ in C with $p_j \circ f = p_k \circ g$ we have $A(f)(s_j) = A(g)(s_k) \in A(K)$

then

• there is a unique element $s \in A(U)$ such that $A(p_i)(s) = s_i$ for all $i \in I$.

Definition 6: Subcanonical sites

We call a site \mathbb{C} subcanonical if every representable functor $Y(c):\mathbb{C}^{\mathrm{op}}\to\mathbb{S}\mathrm{et}$ is a sheaf.

The category of all sheaves on a site is extremely nice: it is a topos.

1.4 Concrete sites

A concrete site is a site whose objects can be thought of as sets with extra structure.

Definition 7: Concrete site

A concrete site is a site \mathbb{C} such that

- 1. \mathbb{C} has a terminal object *;
- 2. the functor of points $|\cdot| = Hom_{\mathbb{C}}(*, -) : \mathbb{C} \to \mathbb{Set}$ is faithful;
- 3. for every covering family $\{f_i: U_i \to U\}$ in $\mathbb C$ the morphism

$$\coprod_{i} Hom_{\mathbb{C}}(*, f_{i}) : \coprod_{i} Hom_{\mathbb{C}}(*, U_{i}) \to Hom_{\mathbb{C}}(*, U)$$

is surjective^a.

In a category of presheaves on a concrete site one can consider concrete presheaves.

Remark:

Let \mathbb{C} be a concrete site. For any presheaf X and fixed point $u \in |U| = Hom_{\mathbb{C}}(*, U)$ one has the following diagram

$$\begin{array}{cccc}
* & | * | & X(*) \\
\downarrow^{u} & & \uparrow^{X(u)} \\
U & | U | & X(U) \xrightarrow{\alpha_{U}} & Hom_{\text{Set}}(|U|, X(*))
\end{array}$$

In other words, any $U \in \mathbb{C}$ gives rise to the following set theoretic function

$$\alpha_U: X(U) \longrightarrow Hom_{\mathbb{S}et}(|U|, X(*))$$

$$p \longmapsto \left(h_p: (x \xrightarrow{u} U) \mapsto X(U)|_p\right)$$
(2)

More! it's a natural transformatioN!

FIG 3

Definition 8: Concrete presheaf

^aRecall that the coproduct [] in Set is given by the disjoint union.

A presheaf $X: \mathbb{C}^{op} \to \mathbb{S}$ et on a concrete site \mathbb{C} is called a *concrete presheaf* if, for each $U \in \mathbb{C}$, the map α_U given in equation (2) is injective.

Remark:

What does it mean for a presheaf to be concrete? We can regard a concrete presheaf as a set equipped with additional structure.

When regarding a sheaf as a space defined by how it is probed by test spaces, a concrete sheaf is a generalized space that has an underlying set of points out of which it is built. So a concrete sheaf models a space that is given by a set of points and a choice of which morphisms of sets from concrete test spaces into it count as "structure preserving" (e.g. count as smooth, when the sheaf models a smooth space).

First, for $U \in \mathbb{C}$, let $|U| = Hom_{\mathbb{C}}(*, U)$ denote the underlying set. Note that we can regard $Hom_{\mathbb{C}}(U, V) \subseteq Hom_{\mathbb{S}\text{et}}(|U|, |V|)$, since the functor $Hom_{\mathbb{C}}(*, \cdot)$ is faithful. A concrete presheaf X is then given by:

- a set |X|,
- for each $U \in \mathbb{C}$, a |U|-ary relation $X(U) \subset Hom_{\mathbb{S}et}(|U|,|X|)$

such that:

- 1. For any morphism $f: U \to V$ in \mathbb{C} , $g \in X(V)$ implies $g \circ f \in X(U)$,
- 2. X(*) = |X|.

This data defines a concrete presheaf $X : \mathbb{C}^{op} \to \mathbf{Set}$, and every concrete presheaf is isomorphic to one of this form.

To define a natural transformation between concrete presheaves $X \Rightarrow Y$ is to give a function $|X| \to |Y|$ that preserves the relations.

Definition 9: Concrete Sheaves on Concrete Sites

Let $Conc(Sh(\mathbb{C})) \hookrightarrow Sh(\mathbb{C})$ denote the *full subcategory* of the *category of sheaves* consisting of concrete sheaves.

The category of concrete sheaves on a concrete site is also nice, but slightly less so: it is a 'quasitopos'.

Definition 10: Quasitopos [BH11, Def. 3.1]

A quasitopos is a locally Cartesian closed category with finite colimits and a weak subobject classifier.

Theorem 1.1 ([BH11, Thm. 5.25]) For any concrete site \mathbb{D} , the category of concrete sheaves over \mathbb{D} is a quasitops with all (small) limits an colimits.

1.5 Sites with Pullbacks

If a category $\mathbb C$ has *pullbacks*, it is natural to impose the following stronger condition²:

²Alternatively, one can impose the weaker condition that the pullbacks of covering families exist and are themselves covering families, even if not all pullbacks exist in \mathbb{C} .

Definition 11: Cartesian coverage

Let \mathbb{C} be a category with pullbacks. A coverage is said to be *cartesian* if for any $\{f_i: U_i \to U\}_{i \in I}$ covering family and $g: V \to U$ morphism, then the family of pullbacks $\{g^*(f_i): g^*U_i \to V\}$ is a covering family of V.

Via a certain "saturation condition", in a category with pullbacks, every coverage is equivalent to one satisfying this stronger condition. (cf. condition 1. in definition 4).

Definition 12: Cartesian Sites

A $Cartesian \ site$ is a small category \mathbb{C} equipped with a cartesian coverage, which is finitely complete and admits coproducts^a.

In a Cartesian sites the condition of being subcanonical can be expressed as follows

Lemma 1.1 ([Blo24, Pag. 20, Prop. 2.1.13]) Let \mathbb{C} be a Cartesian site. The site \mathbb{C} is subcanonical iff for every covering family $\{U_i \to U\}$ the following diagram is a coequalizer

$$\coprod_{i,j} U_i \times_U U_j \Longrightarrow \coprod_i U_i \longrightarrow U \tag{3}$$

In the category given in example 2, the pullback $U_i \times_U U_j = U_i \cap U_j$ is given by the intersection, so that the coequalizer can be interpreted geometrically as glueing the open subsets U_i along their intersections. A sheaf is a contravariant functor that preserves this glueing. When $\mathbb C$ has pullbacks (of covering families), the condition for a presheaf X to be a sheaf can be expressed more familiarly as follows.

Lemma 1.2 Let \mathbb{C} be a Cartesian site. A functor $X : \mathbb{C}^{op} \to \mathbb{S}\text{et}$ is a sheaf if, for any covering family $\{f_i : U_i \to U\}_{i \in I}$, the following diagram is an equalizer:

$$X(U) \longrightarrow \prod_{i \in I} X(U_i) \Longrightarrow \prod_{j,k \in I} X(U_j \times_U U_k)$$
 (4)

^aThis definition is not completely standard. Usually a category is said to be *Cartesian* when it admits all finite limits, i.e. finitely complete.

2 Diffeological Spaces as a Category of Concrete Sheaves

The foundational observation for a categorical approach to diffeological spaces is that a diffeology \mathbb{D} on a set X can be understood as a presheaf on the category of open subsets of Euclidean spaces, with smooth maps as morphisms. Specifically, to each open set $U \subseteq \mathbb{R}^n$, it assigns a subset of $Hom_{\mathbb{S}\text{et}}(U,X)$, the set of all functions from U to X prescribed to be "smooth". A diffeological space is then defined as a set equipped with a diffeology.

Definition 13: Euclidean Site

We call Euclidean site the category $\mathbb{E}uc\mathbb{I}$ whose objects are the open subsets of Euclidean spaces \mathbb{R}^n , for any $n \geq 0$, and whose morphisms are smooth maps between them.

$$\mathbb{E}\mathrm{uc}\mathbb{I} \leadsto \begin{cases} Obj = U \subset \mathbb{R}^n & \mathrm{Open}, \forall n \geq 0 \\ Arr = f : U \to V & \mathrm{smooth\ in\ the\ euclidean\ sense.} \end{cases}$$

Open covers define a Grothendieck pretopology^a.

^aI.e. the following three conditions are satisfied: (i) Isomorphisms are covers. (ii) The cover of a cover is a cover. (iii) The pullback of a cover along a smooth map is a cover.

Proposition 2.1 The Euclidean site Eucl enjoys the following properties:

- Eucl is a Cartesian site (def: definition 11);
- Eucl is subcanonical (lem: lemma 1.1);
- Eucl is concrete (def: definition 7).

Proof:

Theorem 2.1 ([Blo24, Thm: 2.1.11]) The category of diffeological spaces \mathbb{D} flg is equivalent to the category of concrete sheaves over \mathbb{E} ucl.

Proof:

Theorem 2.1 provides a bridge between two equivalent descriptions of diffeological spaces, each offering distinct advantages. The geometric definition, based on plots, excels in explicit computations, describing examples, and connecting with classical methods of analysis and differential geometry. In contrast, the categorical definition, framed in terms of concrete sheaves, is more effective for abstract structural analysis, understanding universal properties, and exploring developments in areas like homotopy theory and higher geometric structures.

Remark:

Open sets in \mathbb{R}^n can be naturally seen as diffeological spaces. In other terms, one has a full and faithful functor [Blo24, Prop. 2.1.14]

 $y: \mathbb{E}\mathrm{ucl} \to \mathbb{D}\mathrm{flg}$.

3 Some categorical Properties of Dflg

In category theory, a category is referred to as "convenient" if it has specific properties that enhance its utility for abstract mathematical constructions. This section discusses the characteristics that make $Conc(Sh(\mathbb{E}uclidean)) \cong \mathbb{D}flg$ a convenient category. For more details, see Proposition 2.1.12 in [Blo24] and [BH11].

3.1 Cartesian closed – Mapping spaces

The category \mathbb{D} flg is locally cartesian closed. This means that for every object $X \in \mathbb{D}$ flg, the overcategory \mathbb{D} flg $\downarrow X$ is cartesian closed (see definition 19 and definition 21).

When X=*, it follows from the definition of concreteness that $\mathbb{Dflg}\downarrow *\cong \mathbb{Dflg}$, and the fiber product reduces to the usual product in \mathbb{Dflg} . The exponential objects (see definition 20) in \mathbb{Dflg} are denoted by

$$Hom_{\mathbb{D}flg}(X,Y)\cong Y^X$$

and are called the $diffeological\ mapping\ spaces.$

The diffeology on Y^X , determined by the universal property

$$Hom_{\mathbb{D}flg}\Big(U, Hom_{\mathbb{D}flg}(X, Y)\Big) \cong Hom_{\mathbb{D}flg}\Big(U \times X, Y\Big)$$

is known as the $functional\ diffeology$. Its plots correspond to the smooth homotopies of morphisms of diffeological spaces.

3.2 Forgetful functor – (in)discrete diffeology

The category \mathbb{D} flg has a terminal object given by $* = \mathbb{R}^0$. The (forgetful) functor of points

$$|\cdot|: \mathbb{D}flg \longrightarrow \mathbb{S}et$$

$$X \longmapsto Hom_{\mathbb{D}flg}(*,X)$$

has left and right adjoints.

- The *left adjoint* equips a set S with the *discrete diffeology*, where the plots are the locally constant maps. The discrete diffeology on S will be denoted by \ddot{S} , where the double dots symbolize discrete points.
- The right adjoint equips S with the indiscrete diffeology, where every map is considered a plot. The indiscrete diffeology on S will be denoted by \overline{S} .

For a diffeological space X with underlying set |X|, we simplify notation by dropping the vertical bars and writing:

$$\ddot{X} \equiv |\ddot{X}|, \quad \overline{X} \equiv \overline{|X|}.$$

3.3 Limits

Dflg is a complete and cocomplete category, i.e. it has all finite limits and colimits.

Proposition 3.1 ([Blo24, Prop 2.1.38]) The limit of a diagram $X : \mathbb{I} \to \mathbb{D}flg$, $i \mapsto X_i$, is given by the set $\lim_{i \in \mathbb{I}} |X_i|$ equipped with the diffeology such that a map $p : |U| \to \lim_{i \in \mathbb{I}} |X_i|$ is a plot if and only if the compositions with all maps of the limit cone,

$$|U| \xrightarrow{p} \lim_{i \in \mathbb{I}} |X_i| \xrightarrow{\operatorname{pr}_i} |X_i|$$

are plots for all $i \in \mathbb{I}$.

Example: 4: Pullbacks

Let $X_1 \xrightarrow{f} Y \xleftarrow{g} X_2$ be morphisms of diffeological spaces. A map $p: |U| \to |X_1 \times_Y X_2|$ is a plot if and only if:

$$p_1 = |\operatorname{pr}_1| \circ p$$
, $p_2 = |\operatorname{pr}_2| \circ p$, and $|f| \circ p_1 = |g| \circ p_2$

are plots.

Proposition 3.2 ([Blo24, Prop. 2.1.43]) The colimit of a diagram $X : \mathbb{I} \to \mathbb{D}$ flg is given by the colimit of the underlying sets:

$$|\operatorname{colim}_i X_i| = \operatorname{colim}_i |X_i|$$

with the diffeology such that a map $p: |U| \to |\operatorname{colim}_i X_i|$ is a plot if, for every $u_0 \in U$, there exists a neighborhood $U_0 \subseteq U$ and a plot $p_0: U_0 \to X_i$ for some $i \in I$ such that $p|_{U_0} = p_0$.

Remark:

The colimit in Set is given explicitly by the quotient:

$$|\operatorname{colim}_{i} X_{i}| = \left(\bigsqcup_{i \in \mathbb{I}} |X_{i}| \right) / \sim,$$

where \sim is the equivalence relation generated by:

$$x \sim y \iff \exists f \in Mor(\mathbb{I}) : (X(f))(x) = y$$
,

for all $x, y \in \coprod_i |X_i|$.

Example: 5: Pushouts

Let $X \stackrel{f}{\leftarrow} Z \stackrel{g}{\rightarrow} Y$ be morphisms of diffeological spaces. The pushout $X \sqcup_Z Y$ is the coequalizer:

$$Z \xrightarrow{f} X \sqcup Y \xrightarrow{h} X \sqcup_Z Y$$

A map $p: |U| \to |X \sqcup_Z Y|$ is a plot if every $u_0 \in U$ has a neighborhood U_0 such that $p|_{U_0}$ factors through either a plot $q: U_0 \to X$ or $q: U_0 \to Y$.

3.4 Class of Morphisms

Proposition 3.3 ([Blo24, Prop. 2.1.20]) A smooth map $f: X \to Y$ of diffeological spaces (i.e. $f \in Hom_{\mathbb{Dflg}}(X,Y)$) is a:

- ullet monomorphism if and only if f is injective,
- epimorphism if and only if f is surjective.

Definition 14: Pullback Diffeology

Let Y be a diffeological space and $S \to |Y|$ a map of sets, which we can view as a morphism $f: \overline{S} \to \overline{Y}$, where \overline{S} and \overline{Y} denote the indiscrete diffeology. Then the pullback diffeology on S is

defined as:

$$f^*Y := Y \times_{\overline{Y}} \overline{S}.$$

Definition 15: Pushforward Diffeology

Let X be a diffeological space and $|X| \to S$ a map of sets, which we view as a morphism $f: \ddot{X} \to \ddot{S}$, where \ddot{S} and \ddot{x} denote the discrete diffeology. Then the *pushforward diffeology* on S is defined as:

$$f_*X := \ddot{S} \sqcup_{\ddot{X}} X.$$

Definition 16: Subspace and Quotient Diffeologies

The pullback diffeology along a monomorphism is also called the *subspace diffeology*, while the pushforward diffeology along an epimorphism is called the *quotient diffeology*.

Remark:

Diffeologies on a given set X are partially ordered by inclusion:

$$\mathbb{D} \subseteq \mathbb{D}'$$
 if and only if $\mathbb{D}(U) \subseteq \mathbb{D}'(U)$ for all $U \in \mathbb{E}ucl$.

In this case, \mathbb{D} is referred to as *smaller* or *finer* than \mathbb{D}' , while \mathbb{D}' is called *larger* or *coarser* than \mathbb{D} .

This relationship is analogous to the ordering of topologies: a topology \mathcal{T} on X is said to be finer than \mathcal{T}' if there are fewer \mathcal{T} -continuous maps than \mathcal{T}' -continuous maps into X.

Proposition 3.4 • The pullback diffeology f^*Y is the largest diffeology on the set |X| such that |f| is smooth.

• The pushforward diffeology f_*X is the smallest diffeology on |Y| such that |f| is smooth.

Definition 17: Induction and Subduction

- A monomorphism $f: X \to Y$ of diffeological spaces such that the diffeology on X is the pullback diffeology is called an *induction* [IZ13, Sec. 1.29].
- An epimorphism $f: X \to Y$ such that the diffeology on Y is the pushforward diffeology is called a *subduction* [IZ13, Sec. 1.46].

Appendix: Basic stuff

In this section, we gather fundamental definitions for reference.

Definition 18: Concrete category

A category \mathbb{C} is called *concrete* if it is equipped with a faithful functor

$$|\cdot|:\mathbb{C}\to\mathbb{S}$$
et.

This functor, referred to as the forgetful functor, assigns to each object $c \in \mathbb{C}$ its underlying set |c|.

Remark:

In practice, the objects of a concrete category are sets equipped with additional structure, and the morphisms are structure-preserving maps between these sets.

If \mathbb{C} has a terminal object *, the concrete structure is often determined by the functor of points, given by $(c \mapsto Hom_{\mathbb{C}}(*,c))$.

Definition 19: Over category

The slice category or over category $\mathbb{C}\downarrow c$ of a category \mathbb{C} over an object $c\in\mathbb{C}$ is defined as follows:

- Its objects are arrows $f \in \mathbb{C}$ such that $(\operatorname{cod}(f) = c)$.
- Its morphisms $g: X \to X' \in \mathbb{C}$ between $(f: X \to c)$ and $(f': X' \to c)$ satisfy $(f' \circ g = f)$.

The structure of the slice category $\mathbb{C} \downarrow c$ is summarized by the following diagram:

$$\mathbb{C} \downarrow c = \left\{ X \xrightarrow{g} X' \atop f \atop c \atop f' \right\}$$

Definition 20: Exponential object

Let X and Y be objects of a category $\mathbb C$ such that all binary products with Y exist. (Usually, C actually has all binary products.) Then an *exponential object* is an object X^Y equipped with an evaluation map $\operatorname{ev}: X^Y \times Y \to X$ which is universal in the sense that, given any object Z and map $e: Z \times Y \to X$, there exists a unique map $u: Z \to X^Y$ such that

$$Z \times Y \stackrel{u \times \mathrm{id}_Y}{\to} X^Y \times Y \stackrel{\mathrm{ev}}{\to} X$$

equals e.

Equivalently, this data can be repackaged as a natural isomorphism $\hom_C(-, X^Y) \cong \hom_C(-\times Y, X)$ (where ev is the image of the identity arrow on X^Y), so that exponential objects are representations of the latter as a representable functor. The map u is known by various names such as currying of e.

As with other universal constructions, an exponential object, if any exists, is unique up to unique isomorphism].

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Definition 21: Cartesian closed category[Mac78]

The category \mathbb{C} is called Cartesian closed if and only if it satisfies the following three properties:

- It has a terminal object.
- Any two objects X and Y of $\mathbb C$ have a product $X \times Y$ in $\mathbb C$.
- Any two objects Y and Z of $\mathbb C$ have an exponential object Z^Y in $\mathbb C$.

Remark:

The first two conditions can be combined into the single requirement that any finite (possibly empty) family of objects of $\mathbb C$ admits a product in $\mathbb C$, due to the natural associativity of the categorical product and the fact that the *empty product* in a category is the terminal object of that category. The third condition is equivalent to the requirement that the functor $-\times Y$ (i.e., the functor from $\mathbb C$ to $\mathbb C$ that maps objects X to $X\times Y$ and morphisms φ to $\varphi\times \mathrm{id}_Y$) has a right adjoint, usually denoted $-\frac{Y}{Y}$, for all objects Y in $\mathbb C$.

For *locally small categories*, this can be expressed by the existence of a (set-theoretic) *bijection* between the *hom-sets*:

$$Hom_{\mathbb{C}}(X \times Y, Z) \cong Hom_{\mathbb{C}}(X, Z^Y),$$

which is natural in X, Y, and Z [nLa24a].

Definition 22: Locally cartesian closed category

The category \mathbb{C} is called *locally Cartesian closed* iff for any $c \in \mathbb{C}$ the overcategory $\mathbb{C} \downarrow c$ is Cartesian closed.

Definition 23: Equivalence of categories [Mac78, Theorem IV.4.1]

A functor $F: \mathbb{C} \to \mathbb{D}$ yields an equivalence of categories if and only if it is simultaneously:

• full, i.e., for any two objects c_1 and c_2 of \mathbb{C} , the map

$$Hom_{\mathbb{C}}(c_1, c_2) \to Hom_{\mathbb{D}}(F(c_1), F(c_2))$$

induced by F is **surjective**;

• faithful, i.e., for any two objects c_1 and c_2 of \mathbb{C} , the map

$$Hom_{\mathbb{C}}(c_1, c_2) \to Hom_{\mathbb{D}}(F(c_1), F(c_2))$$

induced by F is **injective**;

• essentially surjective (dense), i.e., each object d in \mathbb{D} is isomorphic to an object of the form F(c), for some $c \in \mathbb{C}$.

Definition 24: Diffeological Spaces [IZ13, Def. 1.5]

A diffeological space is a set X together with a collection of maps $p: U \to X$, called plots, for all open subsets $U \subset \mathbb{R}^n$, $n \ge 0$, that satisfy the following conditions:

- 1. Every constant map $p: U \to X$ is a plot.
- 2. Let $U \subset \mathbb{R}^n$ be an open subset and $\{U_i\}_{i \in I}$ an open cover. If $p|_{U_i}: U_i \to X$ is a plot for

- every $i \in I$, then p is a plot.
- 3. If $p:U\to X$ is a plot and $f:V\to U$ is a smooth map from an open subset $V\subset\mathbb{R}^m$, then $p\circ f$ is a plot.

A morphism of diffeological spaces $f: X \to Y$ is a map of sets such that for every plot $p: U \to X$, the map $f \circ p: U \to Y$ is a plot. The category of diffeological spaces is denoted by $\mathbb{D}flg$.

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