$$\begin{split} i(t) &= i_{ac}(t) + i_{dc}(t) \\ &= \frac{\sqrt{2}V}{Z} \big[\sin{(\omega t + \alpha - \theta)} - \sin{(\alpha - \theta)} e^{-t/T} \big] \quad \text{A} \end{split}$$

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$$i_{\rm ac}(t) = \frac{\sqrt{2}V}{Z}\sin(\omega t + \alpha - \theta)$$
 A

$$i_{dc}(t) = -\frac{\sqrt{2V}}{Z}\sin(\alpha - \theta)e^{-\theta T} \quad A$$

$$Z = \sqrt{R^2 + (\omega L)^2} = \sqrt{R^2 + X^2} \quad \Omega$$

$$Z = \sqrt{R^2 + (\omega L)^2} = \sqrt{R^2 + X^2}$$

$$\theta = \tan^{-1} \frac{\omega L}{R} = \tan^{-1} \frac{X}{R}$$

$$T = \frac{L}{R} = \frac{X}{\omega R} = \frac{X}{2\pi f R}$$

$$\begin{split} I_{rms}(t) &= \sqrt{[I_{ac}]^2 + [I_{dc}(t)]^2} \\ &= \sqrt{[I_{ac}]^2 + [\sqrt{2}I_{ac}e^{-t/T}]^2} \\ &= I_{ac}\sqrt{1 + 2e^{-2t/T}} \quad A \end{split}$$

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 X''_d = direct axis subtransient reactance

 X'_d = direct axis transient reactance

 X_d = direct axis synchronous reactance

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Component	Instantaneous Current (A)	rms Current (A)
Symmetrical (ac)	(7.2.1)	$I_{ac}(t) = E_g \left[\left(\frac{1}{X_d''} - \frac{1}{X_d'} \right) e^{-t/T_d'} \right]$
		$+\left(\frac{1}{X_d'}-\frac{1}{X_d}\right)\!e^{-t/T_d'}+\frac{1}{X_d}\right]$
Subtransient		$I'' = E_g/X_d''$
Transient		$I' = E_g/X'_d$
Steady-state		$I = E_g/X_d$
Maximum dc offset	$i_{dc}(t) = \sqrt{2}I''e^{-\delta T_{A}}$	
Asymmetrical (total)	$i(t) = i_{ac}(t) + i_{dc}(t)$	$I_{rms}(t) = \sqrt{I_{ac}(t)^2 + i_{dc}(t)^2}$
		with maximum dc offset:
		$I_{rms}(t) = \sqrt{I_{ac}(t)^2 + [\sqrt{2}I''e^{-t/T_a}]^2}$

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T= temps de durec

$$a^4 = a = 1/120^\circ$$

$$a^2 = 1/240^\circ$$

$$a^3 = 1 / 0^{\circ}$$

$$1+a+a^2=0$$

$$1 - a = \sqrt{3} / -30^{\circ}$$

$$1 - a^2 = \sqrt{3/-30}$$

$$1 - a^2 = \sqrt{3/+30}$$

$$a^2 - a = \sqrt{3/270^\circ}$$

$$ja = 1 / 210^{\circ}$$

$$1 + a = -a^2 = 1/60^\circ$$

$$1 + a^2 = -a = 1 / -60^\circ$$

$$a + a^2 = -1 = 1/180^\circ$$

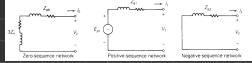
$$a^2 = (1/120^\circ) (1/120^\circ) = 1/240^\circ,$$

a= 120° de déphasage

As shown in (8.2.13), the zero-sequence voltage V_0 depends only on the zero-sequence current I_0 and the impedance $(Z_V + 3Z_o)$. This impedance is called the zero-sequence impedance and is designated Z_0 . Also, the positive-sequence voltage V_1 depends only on the positive-sequence current I_1 and an impedance $Z_1 = Z_V$ called the positive-sequence impedance. Similarly, V_2 depends only on I_2 and the negative-sequence impedance $Z_2=Z_{\rm Y}$.

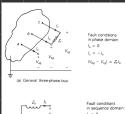
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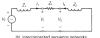




Machines synchrone P. 511

une stail phase qui est conneller au grand denne le shému (b) P. 553 $I_0 = I_1 = I_2 = \frac{V_{\rm F}}{Z_0 + Z_1 + Z_2 + (3Z_{\rm F})}$ Transforming (9.2.7) to the phase domain via (8.1.20), $I_a = I_0 + I_1 + I_2 = 3I_1 = \frac{3V_F}{Z_0 + Z_1 + Z_2 + (3Z_F)}$ Note also from (8.1.21) and (8.1.22), $I_b = (I_0 + a^2I_1 + aI_2) = (1 + a^2 + a)I_1 = 0$ $I_c = (I_0 + aI_1 + a^2I_2) = (1 + a + a^2)I_1 = 0$





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$$I_1 = -I_2 = \frac{V_F}{(Z_1 + Z_2 + Z_F)}$$
 $I_0 = 0$ (9.3.1)

Transforming (9.3.10) to the phase domain and using the identity $(a^2-a)=-j\sqrt{3}$, the fault current in phase b is

$$I_b = I_0 + a^2I_1 + aI_2 = (a^3 - a)I_1$$

$$= -j\sqrt{3}I_1 = \frac{-j\sqrt{3}V_F}{(Z_1 + Z_2 + Z_F)}$$
(9.3.11)

(9.3.12)

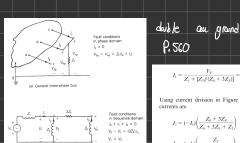
(9.4.13)

Note also from (8.1.20) and (8.1.22) that

$$I_a = I_0 + I_1 + I_2 = 0$$

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$$I_c = I_0 + aI_1 + a^2I_2 = (a - a^2)I_1 = -I_b$$



 $I_1 = \frac{V_{\rm F}}{Z_1 + [Z_2 /\!\!/ (Z_0 + 3Z_{\rm F})]} = \frac{V_{\rm F}}{Z_1 + \left[\frac{Z_2 (Z_0 + 3Z_{\rm F})}{Z_2 + Z_0 + 3Z_{\rm F}}\right]}$ (9.4.12)

Using current division in Figure 9.12(b), the negative- and zero-sequence fault currents are

$$I_2 = (-I_1) \left(\frac{Z_0 + 3Z_F}{Z_0 + 3Z_F + Z_2} \right)$$

$$= (-I_1) \left(\frac{Z_0 + 3Z_F}{Z_0 + 3Z_F + Z_2} \right)$$

$$I_0 = (-I_1) \left(\frac{Z_2}{Z_0 + 3Z_F + Z_2} \right)$$

(9.4.14)