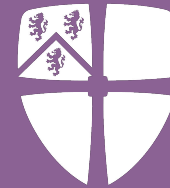


# Machine Learning

Intelligence and Learning:  
From Nature to Machine

Dr Chris Willcocks

*Department of Computer Science*



Durham  
University

# Lecture Overview

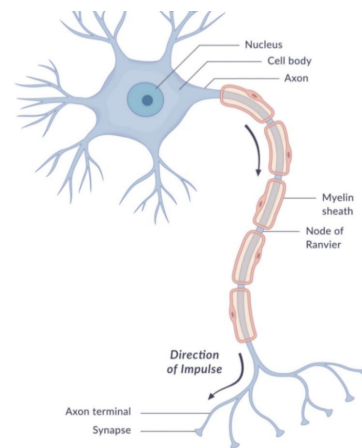
## Course teaching style

- Concept driven, hands-on, practical/useful techniques
- Focus on recent research advances



## Today's lecture

- Definitions of “artificial intelligence” and “machine learning”
- How learning works in nature (neuropsychology)
- How the brain works, how neurons work
- Neuroplasticity and Hebbian theory
- Basics of artificial neurons
- Fundamental (high-level) principles of machine learning
  - Introduction to “tensors”
  - Introduction to loss functions and so on

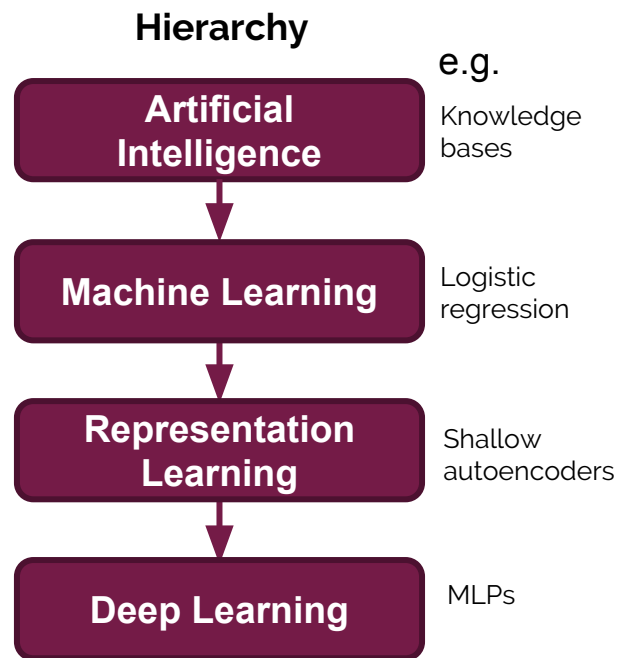


# Artificial Intelligence

- **Intelligence** is generally ill-defined:
  - “The ability to **acquire** and apply **knowledge** and **skills**”
  - “The **capacity** for **logic**, **understanding**, **self-awareness**, **learning**, **emotional knowledge**, **reasoning**, **planning**, **creativity**, and **problem solving**.”
  - “The **ability to learn** or **understand** or to deal with **new** or trying **situations**”
- **Artificial Intelligence** (or **Machine Intelligence**)
  - Intelligence demonstrated by machines (in contrast to **natural intelligence**)



Progressive training of GANs



# Are these tasks intelligent?

The ability to succeed at goals?

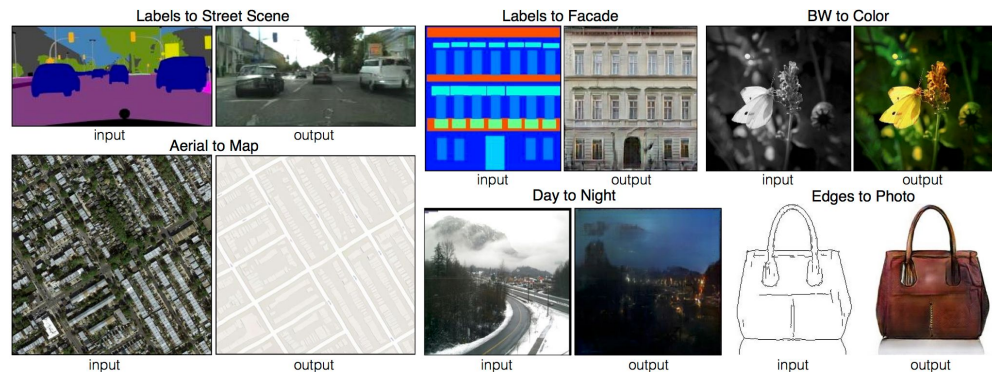
The ability to generalise?

The ability to create?

The ability to infer to new tasks?

The ability to comprehend?

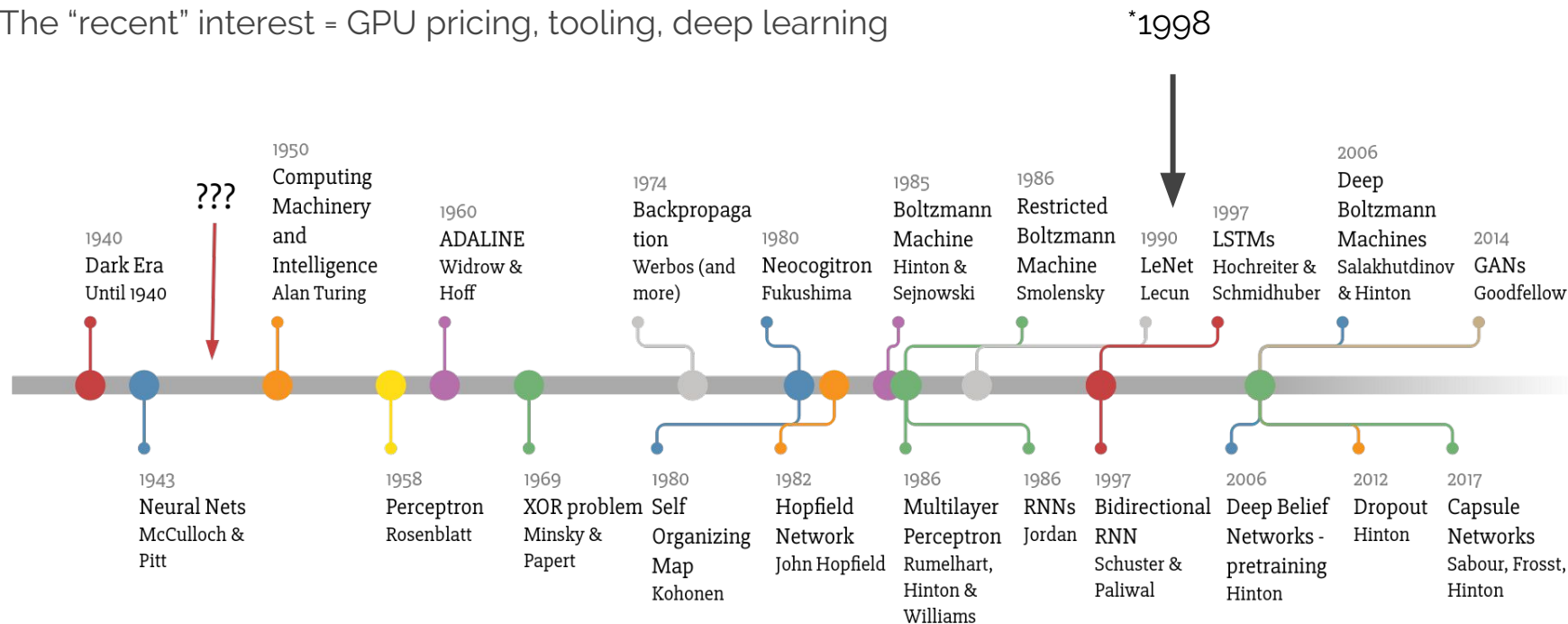
What is creativity?



Style transfer in videos, neural doodle

# The Waves of Artificial Intelligence

The “recent” interest = GPU pricing, tooling, deep learning



# What is Learning?



## Environment

### Experiences

Delicious  
Cold  
Warm  
Burning

### Actions

Put in mouth  
Get closer  
Touch

### Changed Actions

Eat it again!  
Don't touch.

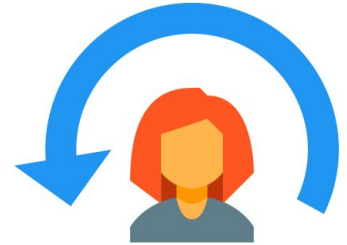


Time

# What is Learning?

"We define learning as the **transformative process** of taking in information that—when internalized and mixed with what we have **experienced**—changes **what we know** and builds on **what we do**. It's based on input, process, and reflection. It is what changes us."

*—From The New Social Learning by Tony Bingham and Marcia Conner.*



"Learning is the relatively permanent **change** in a person's **knowledge** or **behavior** due to **experience**. This definition has three components: 1) the duration of the change is long-term rather than short-term; 2) the locus of the change is the content and structure of knowledge in memory or the behavior of the learner; 3) the cause of the change is the learner's experience in the environment rather than fatigue, motivation, drugs, physical condition or physiologic intervention."

*—From Learning in Encyclopedia of Educational Research, Richard E. Mayer.*

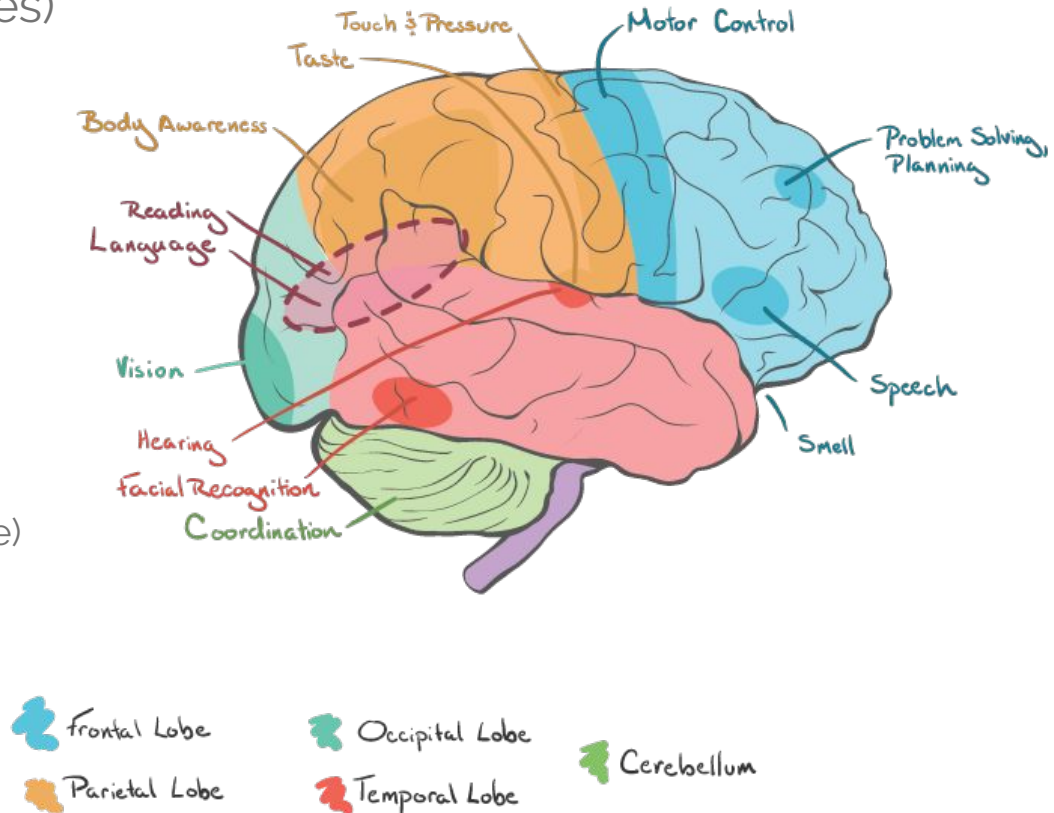


# How does the Brain Work?

- Right side/left side (hemispheres)

- Lobes

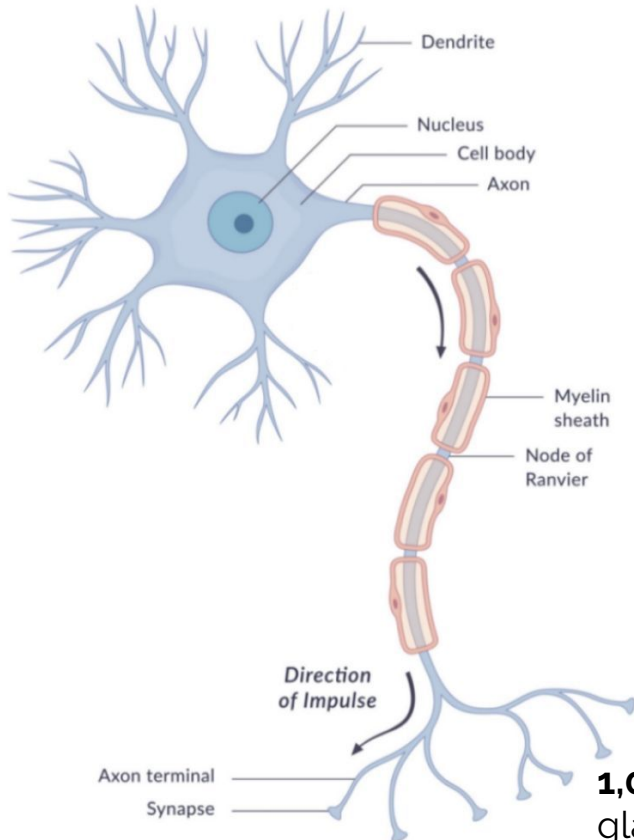
- Frontal lobe
  - Executive functions
  - Memory
  - Learning
  - Planning
- Parietal lobe
  - Sensation
  - Spatial awareness
- Temporal lobe (banana shape)
  - Hearing
  - Language functions
- Occipital lobe at back
  - Vision from front along optic nerves



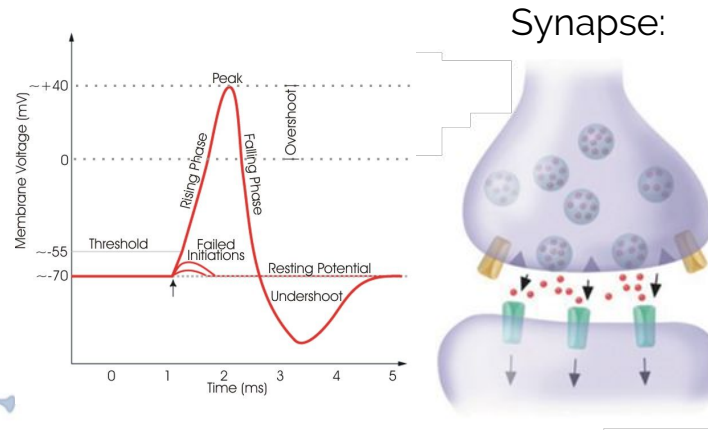


# How does the Brain Work?

**1,000's** of inputs (other neurons, sensory neurons e.g. taste buds from a salt or sugar molecule...)



- Neurons send out branches called **dendrites**, and a large output called an **axon**
- The axon is coated in myelin that helps it conduct electrical impulses.
- The places where the nerve cells make their connections with each other is called a **synapse**.



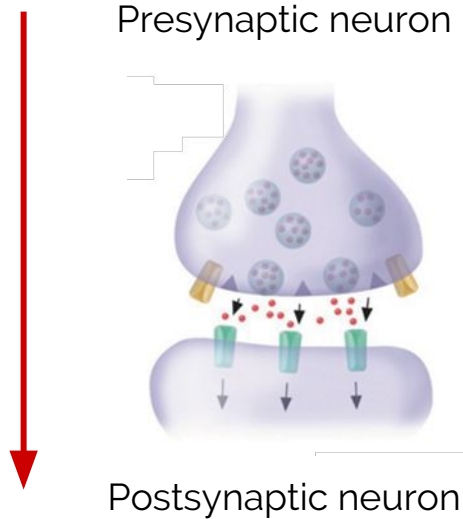
"Synapse" (from the greek meaning "to clasp together")  
**Signals** get **summed up**, and travel to the hillock (Axon neck)

- If large enough, triggers an action potential travels down axon

**1,000's** of targets (e.g. other neurons, muscle cells, gland cells, blood vessels to release hormones...)

Figure by wetcake (left) and Andrej Kral (right)

# Synaptic Plasticity



- What's very cool is that with frequent repeated stimulation, the same level of presynaptic stimulation converts into **greater** postsynaptic potential.
  - In other words, as a neuron gets a lot of practice sending signals to a specific target neuron, it gets better at sending those signals (the synapse strength increases).
    - Increased strength that lasts for a long time (from minutes to many months) is called **Long Term Potentiation** (weakening is **Long Term Depression**).
  - As synapses are strengthened and retain strength, we're able to more easily recall previous experiences.

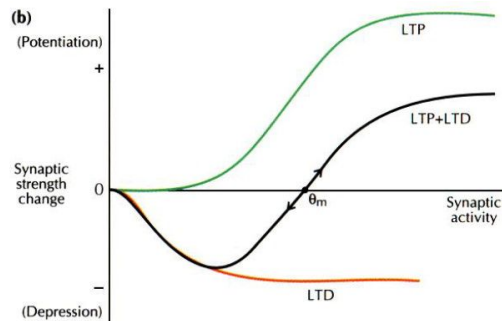
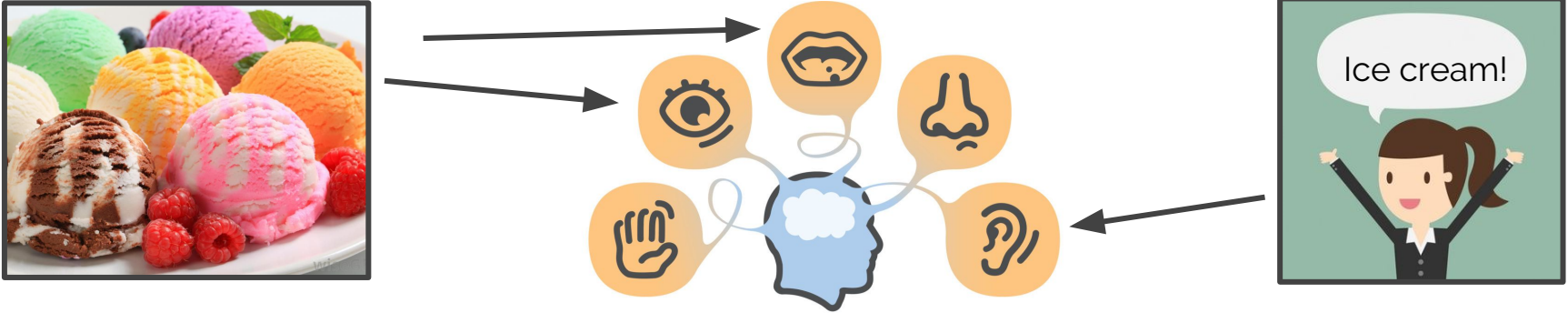


Figure from: "Synaptic Plasticity: A molecular mechanism for metaplasticity", Journal of Current Biology.

# Hebbian Theory



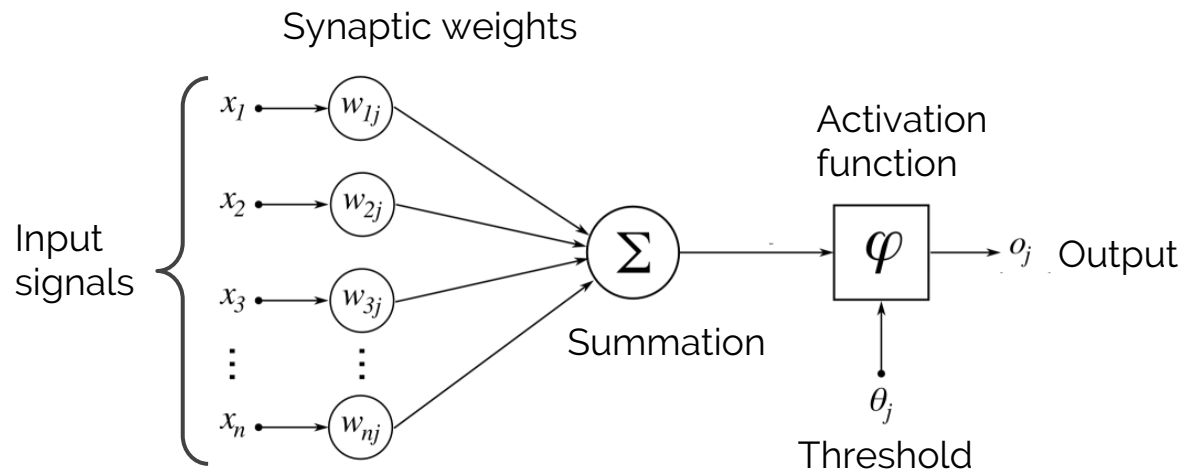
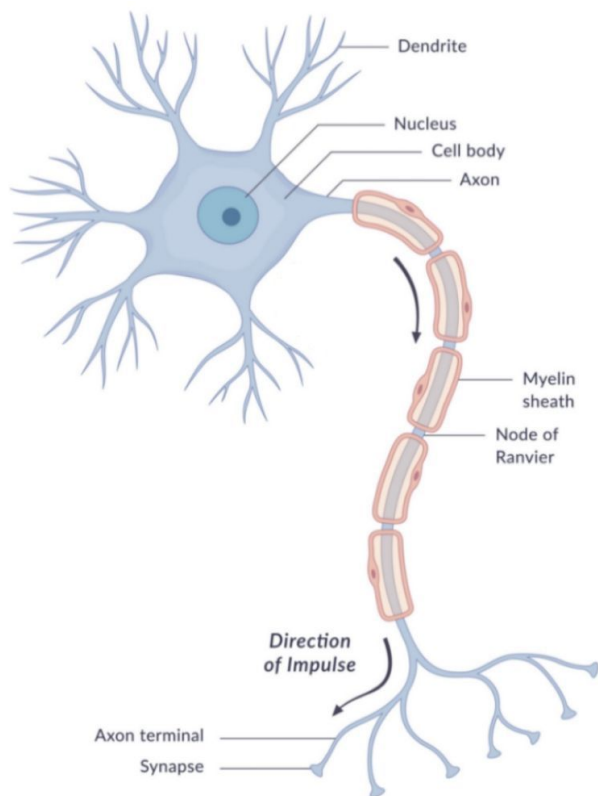
- **Hebbian theory**

- If two neurons fire at the same time, the connections between them are strengthened, and thus are more likely to fire again together in the future.
- If two neurons fire in an uncoordinated manner, their connections are weakened and their more likely to act independently in the future.

- **Updated hebbian hypothesis based on recent findings**

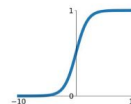
- If the presynaptic neuron fires within a window of 20ms before the postsynaptic neuron, the synapse will be strengthened.
- However if the presynaptic neuron fires within a window of 20ms after the postsynaptic neuron, the synapse will be weakened.

# Artificial Neurons



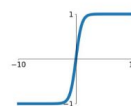
**Sigmoid**

$$\sigma(x) = \frac{1}{1+e^{-x}}$$



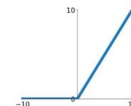
**tanh**

$$\tanh(x)$$



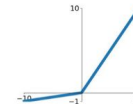
**ReLU**

$$\max(0, x)$$



**Leaky ReLU**

$$\max(0.1x, x)$$

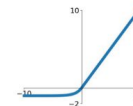


**Maxout**

$$\max(w_1^T x + b_1, w_2^T x + b_2)$$

**ELU**

$$\begin{cases} x & x \geq 0 \\ \alpha(e^x - 1) & x < 0 \end{cases}$$



# What is Machine Learning?

**...learning, but with a machine!** (*ok throw in some stats, calculus, geometry, ...*)

“A computer program is said to learn from experience ***E*** with respect to some class of tasks ***T*** and performance measure ***P***, if its performance at tasks in ***T*** as measured by ***P***, improves with experience ***E***”

Mitchell, 1997

So we have 3 components:

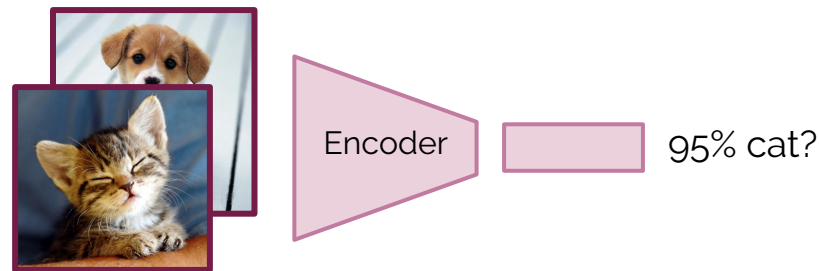
1. The Task ***T***
2. The Experience ***E***
3. The Performance Measure ***P***



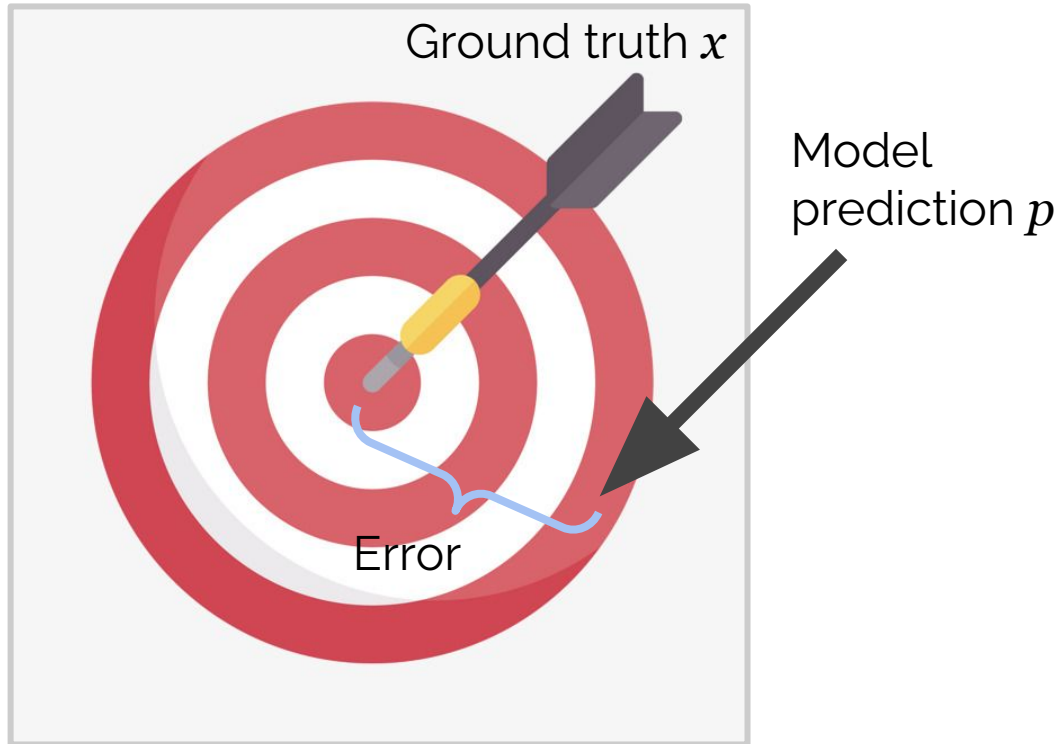
# Tasks $T$

There is a large set of tasks, here's some listed by Goodfellow:

1. Classification
2. Regression
3. Transcription (image to characters, audio to characters)
4. Translation (english characters to french characters)
5. Anomaly detection (flag stuff that is unusual)
6. Synthesis (generating new examples similar to the training data)
7. Inpainting (with some data removed, can predict value of missing entries)
8. Denoising
9. Density estimation (learn where examples cluster tightly and where they are unlikely occur)



# The Performance Measure $P$

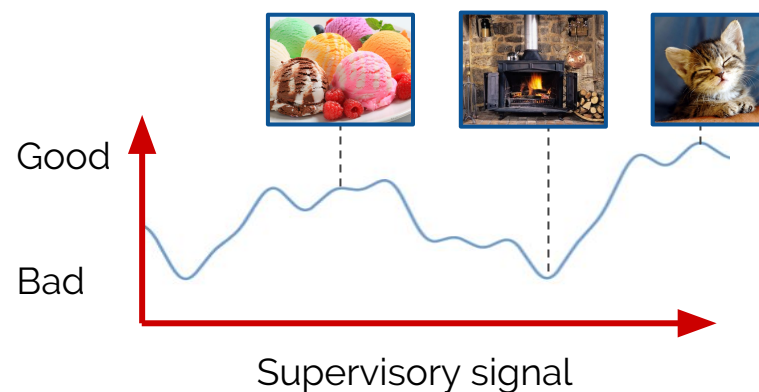


- We need to define a quantitative measure of performance
- Typically we want it to give a **continuous**-valued score for each example
- Can be difficult to define for certain tasks



# The Experience *E*

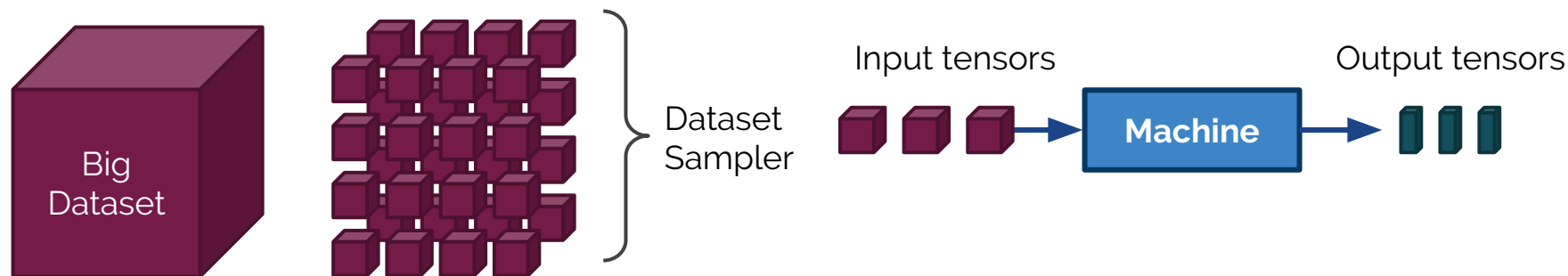
- Supervised
  - Supervisory signal/labels  
Guide the learning
- Unsupervised
  - Clustering
  - Dimensionality reduction
  - Generative models
- Semi-supervised
- Reinforcement learning
- One-shot learning
- Batch learning vs Online (incremental) learning



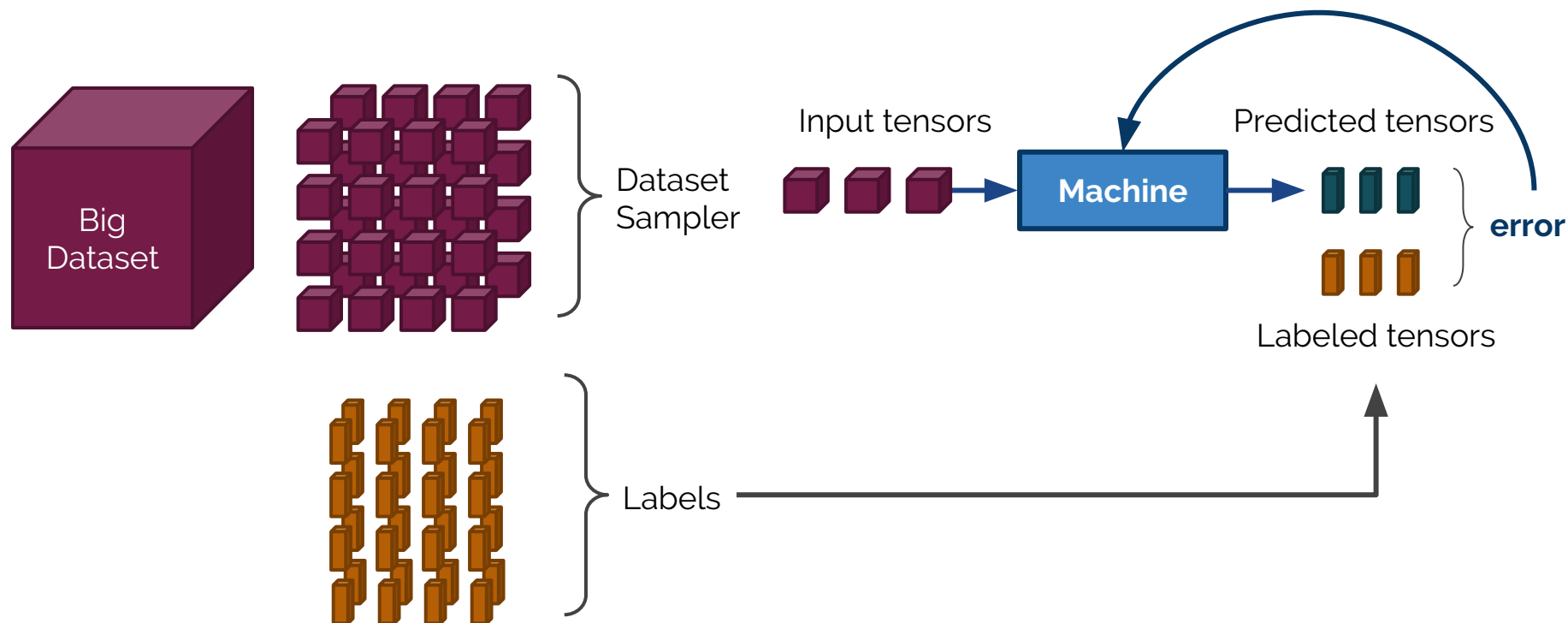
# Experiencing a Dataset

In **machine** learning in practice, we have constraints:

- In most practical ML applications we don't have access to a continuous influx of **data over time**
- We have a static dataset that we wish to learn from, which can be quite large
- The **machine** we want to use has a “tiny” amount of available memory
  - Therefore we split our dataset down into **tensors** represented as multidimensional arrays

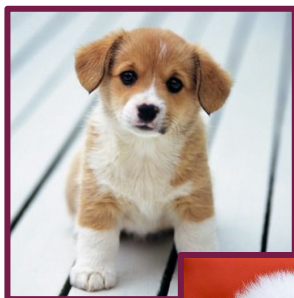


# Supervised Learning



# Classification Example

Dataset of 35,000 images of animals



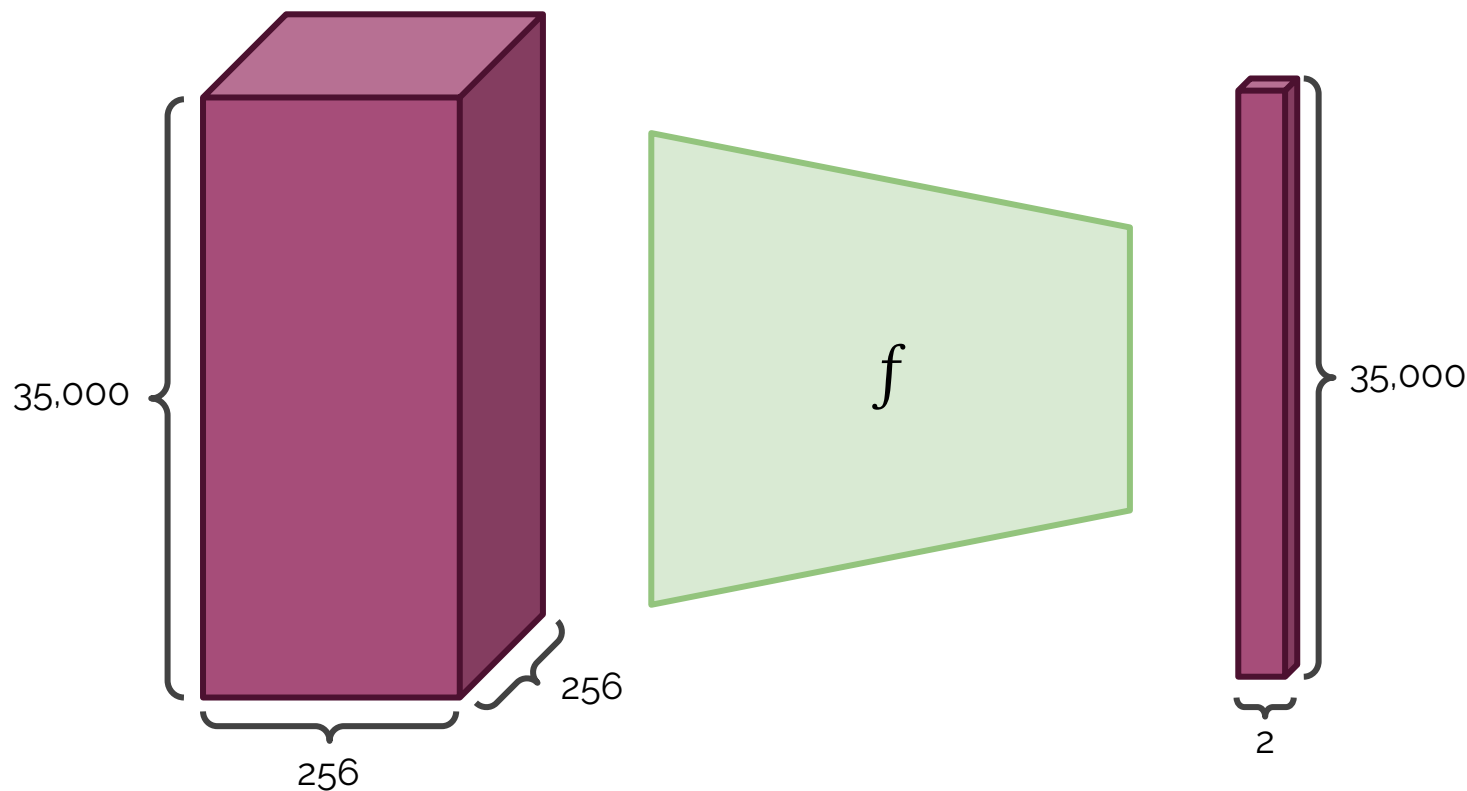
function(**image**) → **int** class

Puppy

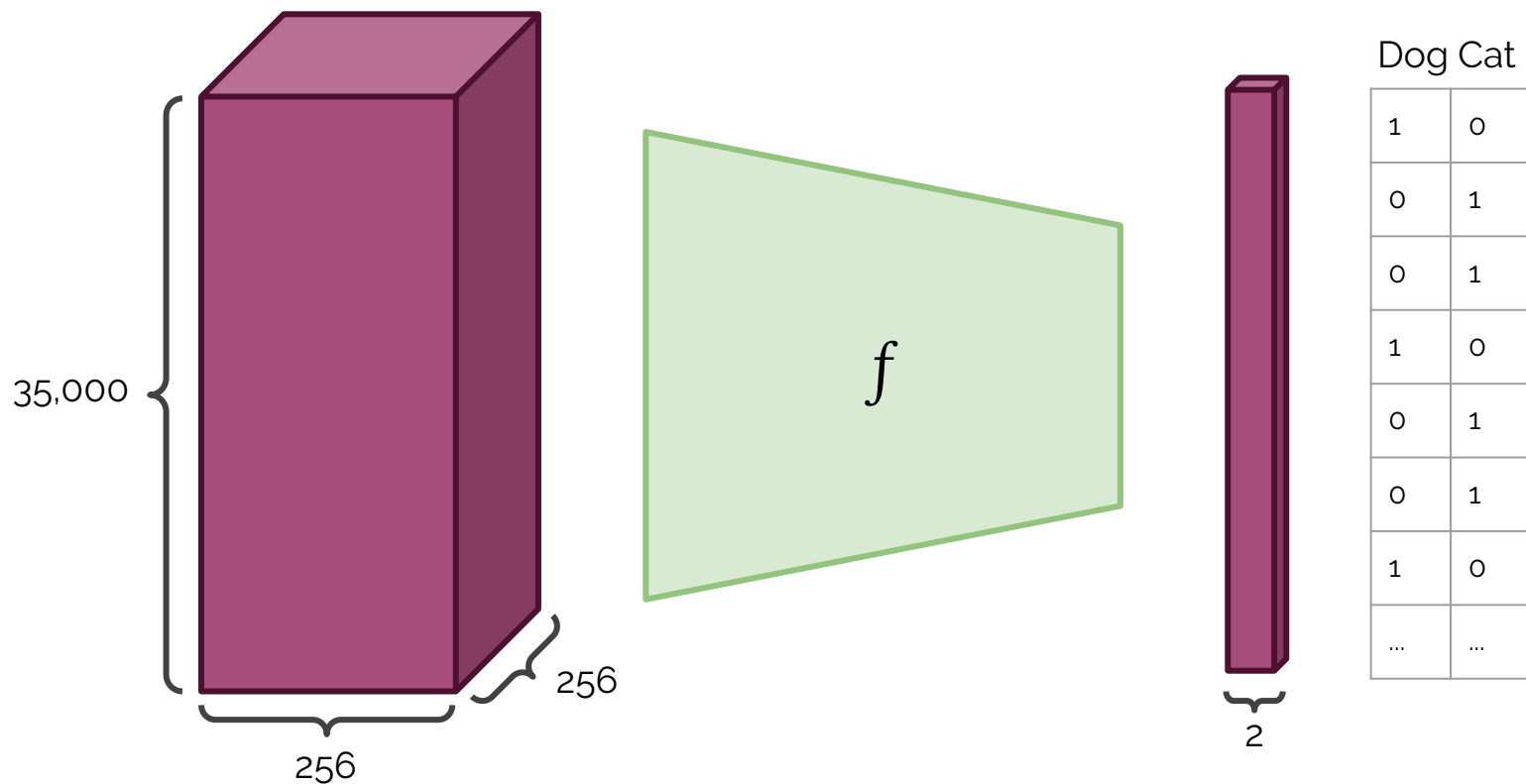
Puppy

Kitten

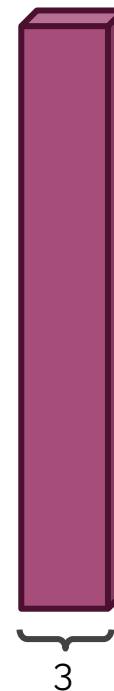
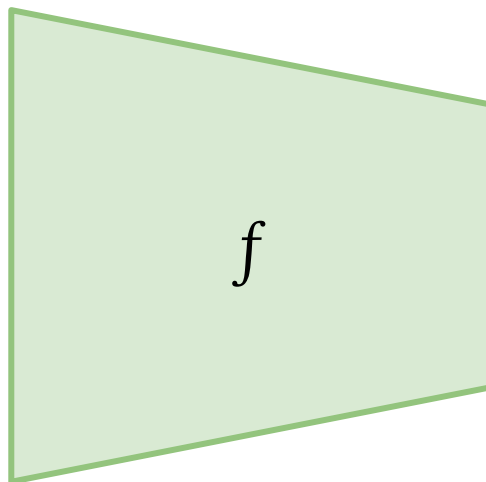
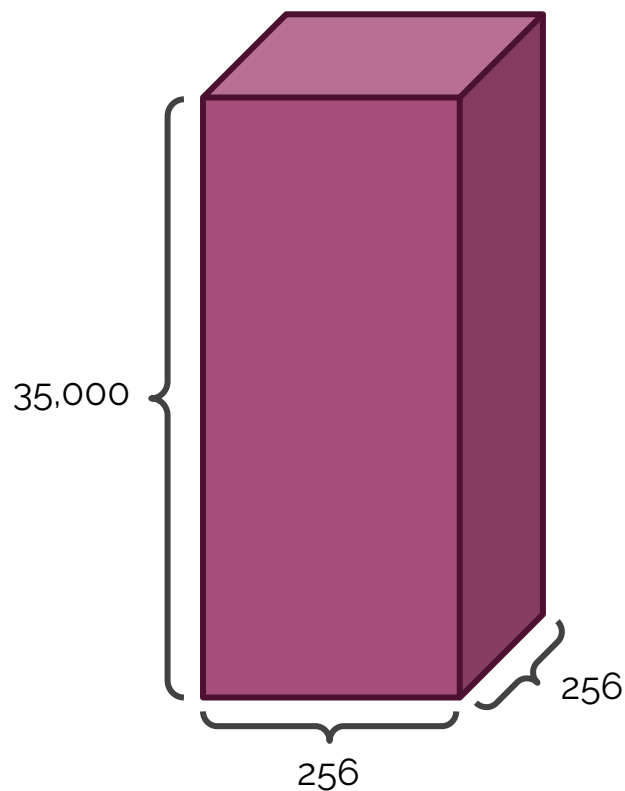
# Tensors: Images $\rightarrow$ Classes



# Tensors: Images $\rightarrow$ Classes



# Tensors: Images $\rightarrow$ Classes

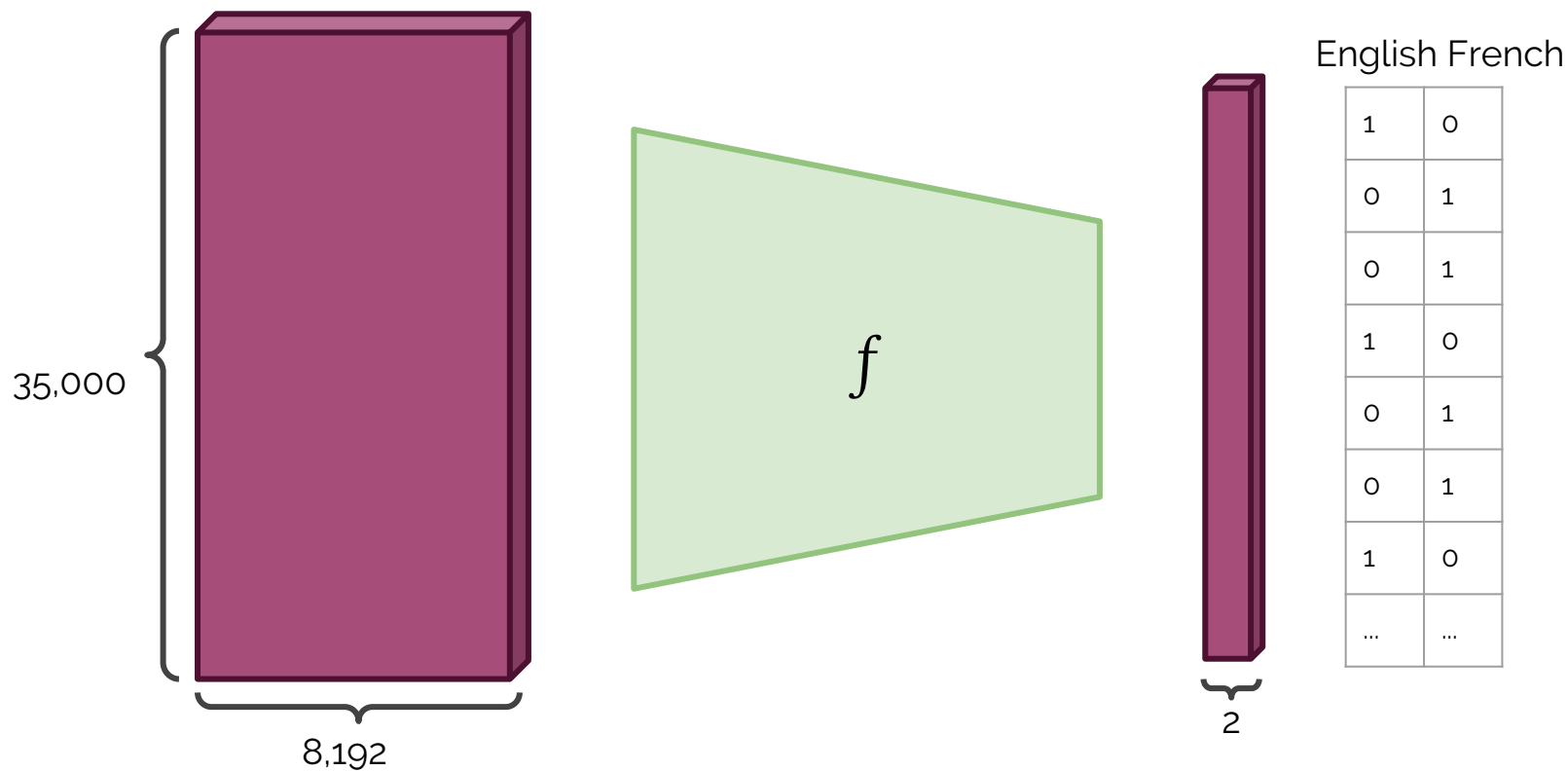


Dog Cat Fish

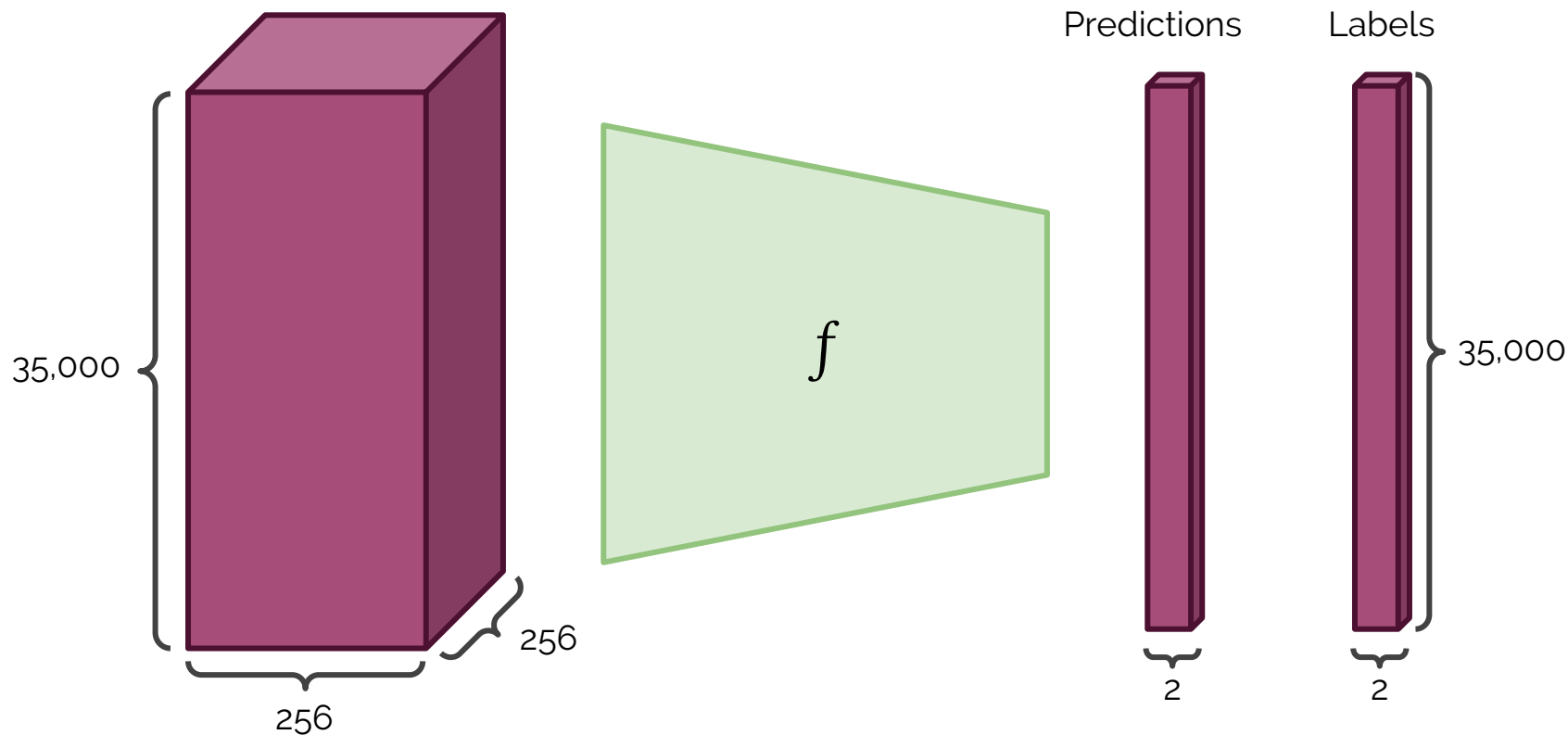
0	0	1
1	0	0
0	1	0
0	0	1
0	1	0
0	0	1
0	1	0
...	...	



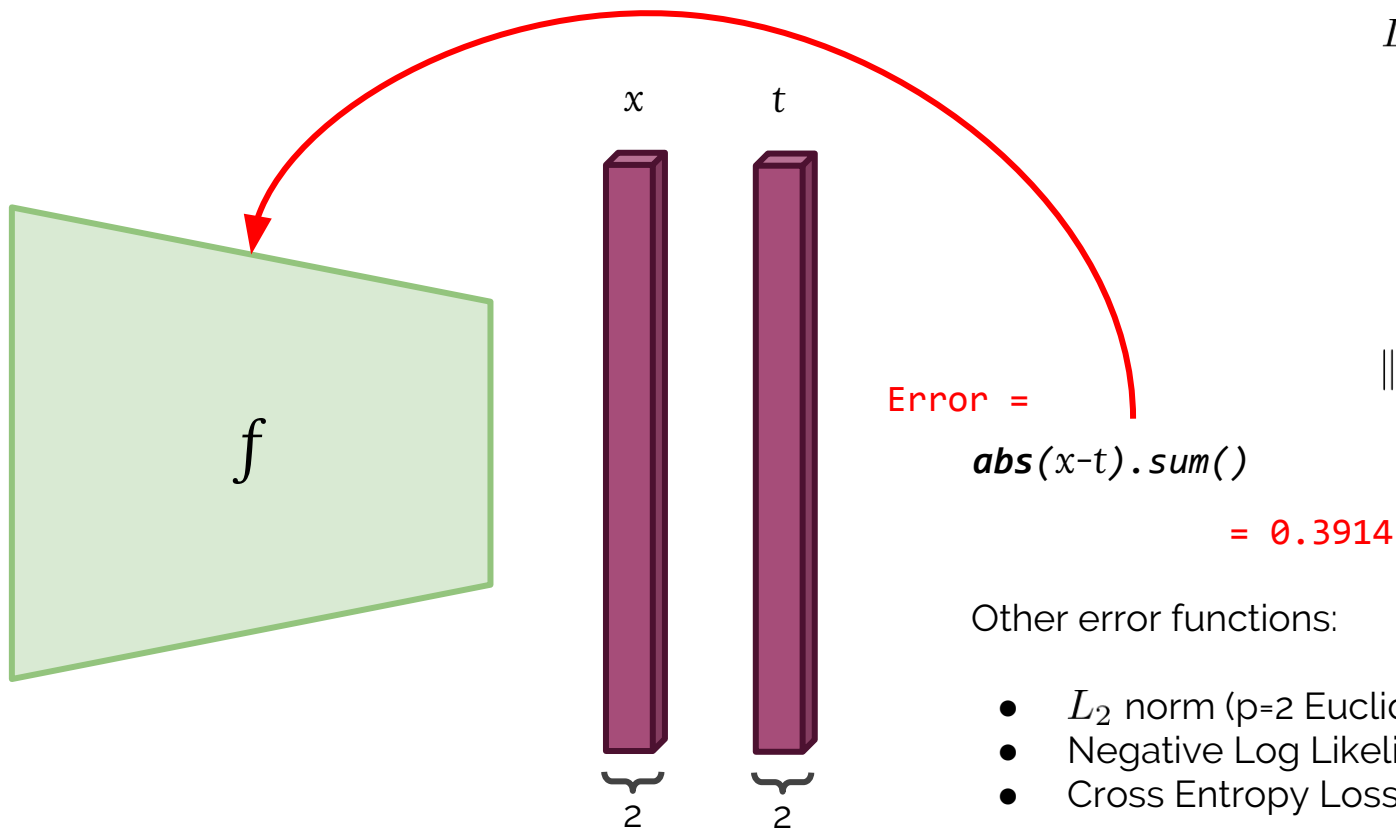
# Tensors: Audio $\rightarrow$ Classes



# Predictions and Labels



# Norms and Loss Functions



$L_p$  norm:

$$\|x\|_p = \left( \sum_i |x_i|^p \right)^{\frac{1}{p}}$$

$$\|x\|_1 = \sum_i |x_i|$$

$$\|x\| = \|x\|_2 = \sqrt{\sum_i x_i^2}$$

Other error functions:

- $L_2$  norm (p=2 Euclidean norm)
- Negative Log Likelihood
- Cross Entropy Loss

...

# More loss functions

<https://pytorch.org/docs/stable/nn.html#loss-functions>

Docs > torch.nn

## CrossEntropyLoss

**CLASS** `torch.nn.CrossEntropyLoss(weight=None, size_average=None, ignore_index=-100, reduce=None, reduction='mean')` [\[SOURCE\]](#)

This criterion combines `nn.LogSoftmax()` and `nn.NLLLoss()` in one single class.

It is useful when training a classification problem with  $C$  classes. If provided, the optional argument `weight` should be a 1D *Tensor* assigning weight to each of the classes. This is particularly useful when you have an unbalanced training set.

The *input* is expected to contain scores for each class.

*input* has to be a *Tensor* of size either  $(minibatch, C)$  or  $(minibatch, C, d_1, d_2, \dots, d_K)$  with  $K \geq 2$  for the  $K$ -dimensional case (described later).

This criterion expects a class index (0 to  $C-1$ ) as the *target* for each value of a 1D *Tensor* of size *minibatch*

The loss can be described as:

$$\text{loss}(x, \text{class}) = -\log \left( \frac{\exp(x[\text{class}])}{\sum_j \exp(x[j])} \right) = -x[\text{class}] + \log \left( \sum_j \exp(x[j]) \right)$$

or in the case of the `weight` argument being specified:

$$\text{loss}(x, \text{class}) = \text{weight}[\text{class}] \left( -x[\text{class}] + \log \left( \sum_j \exp(x[j]) \right) \right)$$

The losses are averaged across observations for each minibatch.

Can also be used for higher dimension inputs, such as 2D images, by providing an input of size  $(minibatch, C, d_1, d_2, \dots, d_K)$  with  $K \geq 2$ , where  $K$  is the number of dimensions, and a target of appropriate shape

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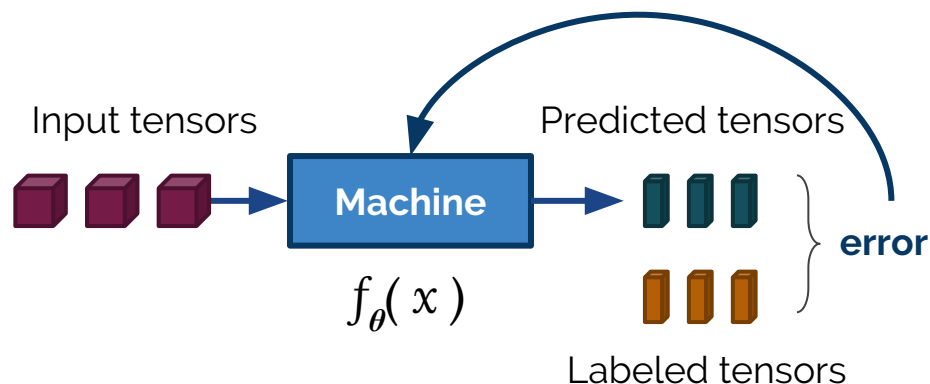
Shortcuts

- + Pooling layers
- + Padding layers
- + Non-linear activations (weight sum, nonlinearity)
- + Non-linear activations (other)
- + Normalization layers
- + Recurrent layers
- + Linear layers
- + Dropout layers
- + Sparse layers
- + Distance functions
- Loss functions

- L1Loss
- MSELoss
- CrossEntropyLoss
- CTCLoss
- NLLLoss
- PoissonNLLLoss
- KLDivLoss
- BCELoss
- BCEWithLogitsLoss
- MarginRankingLoss
- HingeEmbeddingLoss
- MultiLabelMarginLoss
- SmoothL1Loss
- SoftMarginLoss
- MultiLabelSoftMarginLoss
- CosineEmbeddingLoss
- MultiMarginLoss
- TripletMarginLoss

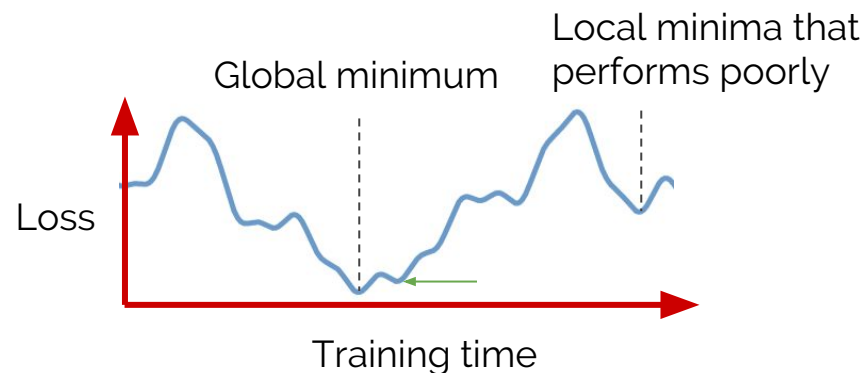
} Further reading

# Optimization

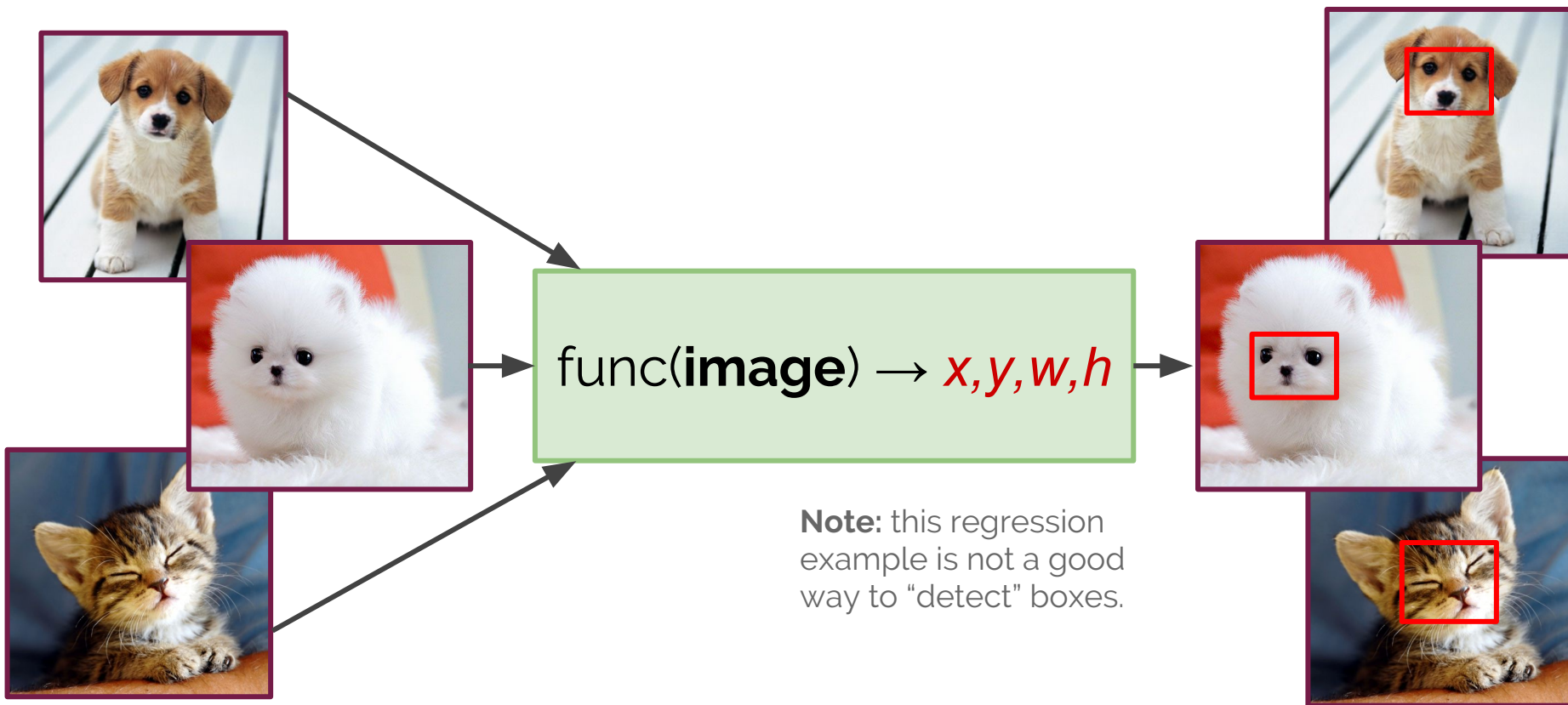


- We update the machine parameters  $\theta$  such as to minimise the objective function.
- We can choose an optimisation strategy based on the shape of the output space.

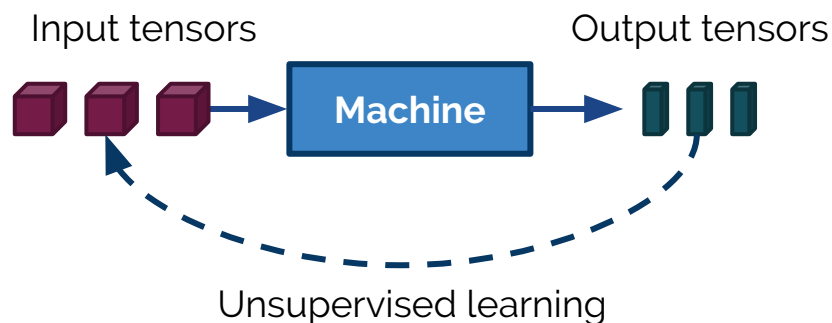
- We don't always want to find the global minimum - often this means the machine has simply memorised the input dataset
- Instead a **good local minima** such as the green arrow, may be sufficient.



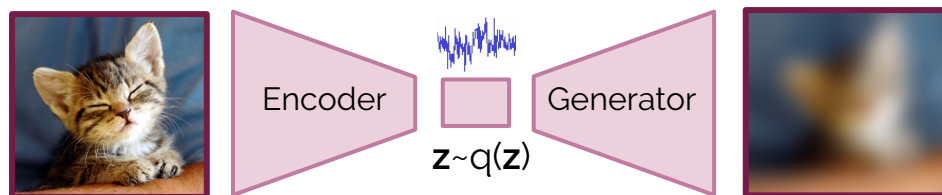
# Regression Example



# Unsupervised Learning



**Example:** reconstructive autoencoder

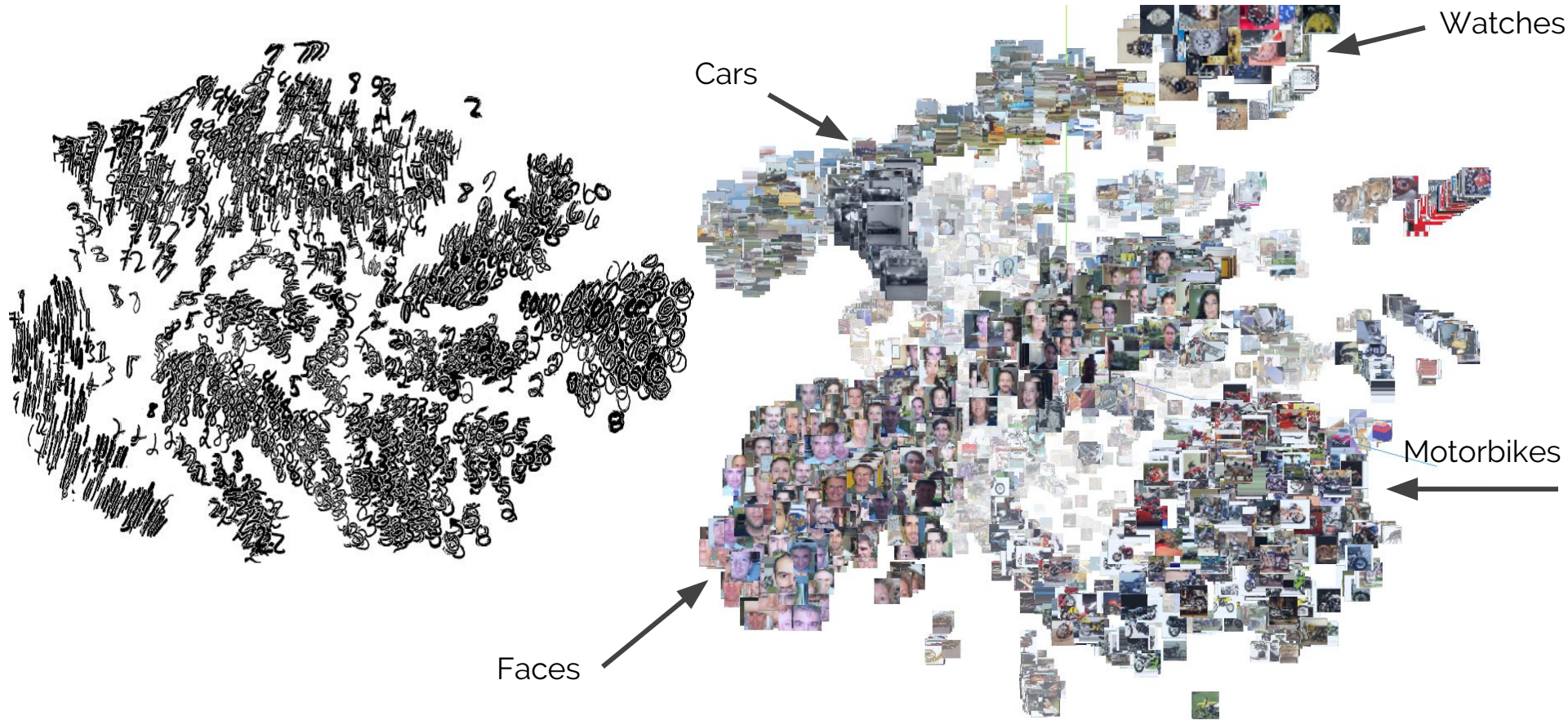


*Example tasks:*

- Generating new examples similar to the training data
- Inpainting (with some data removed, can predict value of missing entries)
- Denoising
- Density estimation (learn where examples cluster tightly and where they are unlikely occur)



# Manifolds, Density Estimation, and Dimensionality Reduction

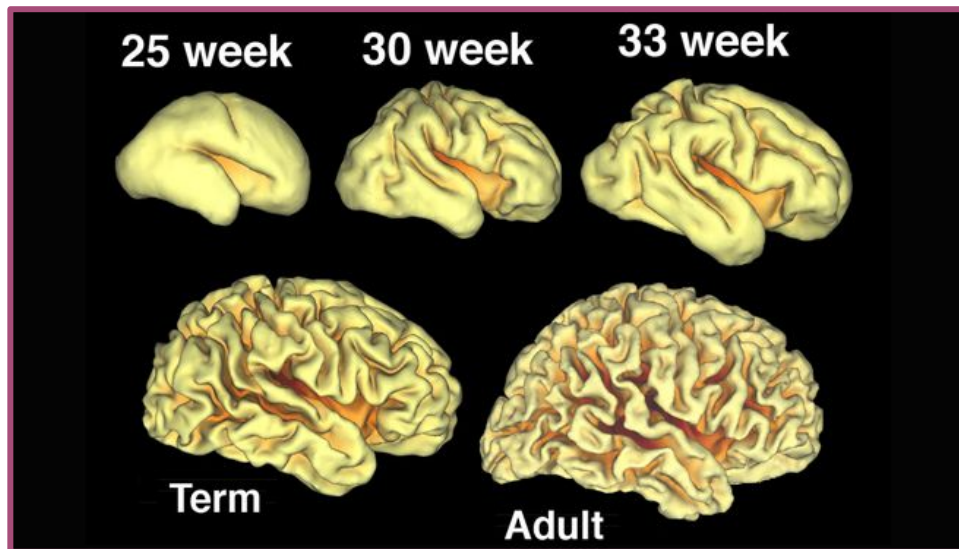


# Transfer Learning

```
63 # Load the model
64 model = torch.nn.DataParallel(resnet.resnet34(pretrained=True)).cuda()
```

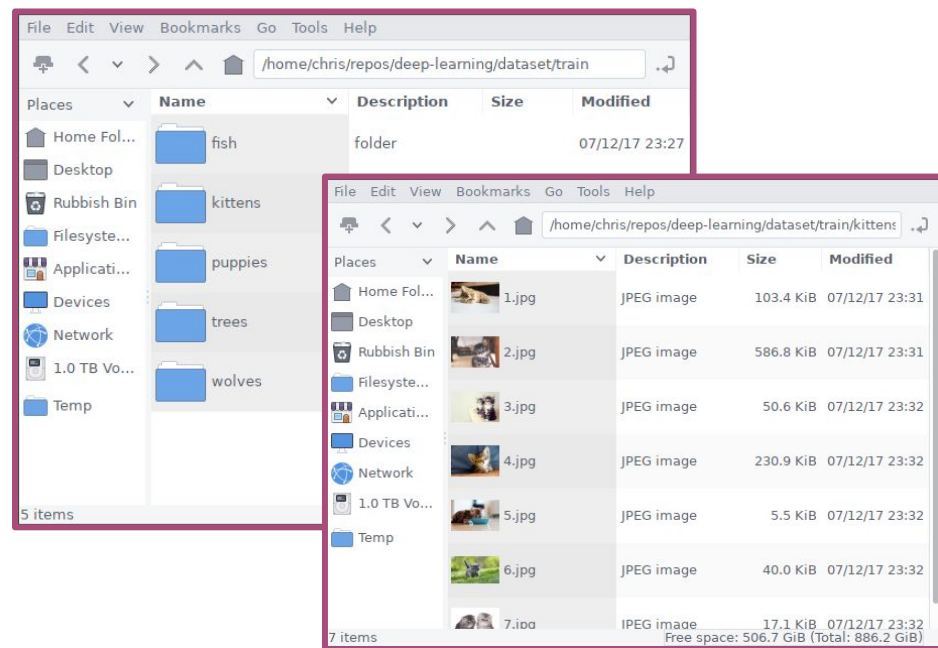
Nice!

- Is it easier to train a **baby** to detect cancer or an **adult** to detect cancer?
- Train model on complex tasks with **lots** of public data (even until they outperform humans)
- Then change the data to our tasks, and continue training



# The Dataset

- Preparing a **good dataset is hard**
  - Garbage in, garbage out
- Learning the data distribution
- Train, test, and validate
- Overfitting and underfitting
- Bias
- Balance
- Augmentation



Source: <https://github.com/albu/albumentations>

# Take away points

- Machine learning has lots of crossover with learning in nature
- Most research is very different and uses overly simplistic models
- Mainly advances in compute hardware and tooling have given rise of the past waves
  - GPUs
  - Automatic differentiation
- The field is currently mostly data driven
  - Especially for supervised learning
  - It's very easy to think a model is doing well, when it is actually just overfitting
- Next week, PyTorch!

Good books:

1. Deep Learning Book, Goodfellow
2. Pattern Recognition and Machine Learning, Bishop

