

Project 1: 15-Puzzle Game

CS-UY 4563

By: Tomas David and Mateo Castro

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Instructions

1. Install python on your console with “Brew” or “pip” on your root directory as such:

“Brew install python”

2. Download the entire folder as it is. Then navigate to the directory “15PuzzleAIProject” as such:

“cd 15PuzzleAIProject”.

3. Then run “python 15PuzzleProblem.py”.
4. You will be prompted to enter an input file name, until a match is found. Press enter once you have written it down in the console. Note: only files in the root of the project directory will be found, otherwise you must include the relative path to this directory.
5. The generated output will be written down in “sampleoutput.txt”. Note: this file gets re-written every time the algorithm is run with a new input. If you want to keep a record of the output, make a copy of “sampleoutput.txt” before re-running the code.
6. The output files of “InputFile1”, “InputFile2”, “InputFile3”, have been included in the directory for your convenience.

Source Code

```
from queue import PriorityQueue
import copy
import sys

# state: 2D array (str)
# parent: Node
# action: int representing action (1-8)
# path_cost: Cost from root to node n (int)
class Node:
    # Node Constructor
    def __init__(self, state, parent=None, action=None,
path_cost=0):
        self.state = state
        self.parent = parent
        self.action = action
        self.path_cost = path_cost

    # Overwrites Less Than Operator (Used for priority queue)
    def __lt__(self, other):
        self_mag = sumOfChessboardDistances(self.state) +
self.path_cost
        other_mag = sumOfChessboardDistances(other.state) +
other.path_cost
        return self_mag < other_mag

# initial: Initial State
# goal: Goal State
# actions: All possible actions (int array)
# action_cost: Action cost for all actions (always 1 for this
problem)
class Problem:
    def __init__(self, initial, goal, actions):
        self.initial = initial
        self.goal = goal
        self.actions = actions
        self.action_cost = 1

    def isGoal(self, state):
        return state == goal

    # Returns new_state resulting from doing action on state
    def result(self, state, action):
        new_state = copy.deepcopy(state)

        blank_row = -1
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blank_col = -1

for i in range(0, 4, 1):
    for j in range(0, 4, 1):
        if(new_state[i][j] == '0'):
            blank_row = i
            blank_col = j

# Define each action depending on where the blank
space is gonna move to
if(action == 1):
    if(blank_col == 0):
        return new_state
        new_state[blank_row][blank_col] =
new_state[blank_row][blank_col - 1]
        new_state[blank_row][blank_col - 1] = '0'
    elif(action == 2):
        if(blank_row == 0 or blank_col == 0):
            return new_state
            new_state[blank_row][blank_col] =
new_state[blank_row - 1][blank_col - 1]
            new_state[blank_row - 1][blank_col - 1] = '0'
        elif(action == 3):
            if (blank_row == 0):
                return new_state
                new_state[blank_row][blank_col] =
new_state[blank_row - 1][blank_col]
                new_state[blank_row - 1][blank_col] = '0'
            elif(action == 4):
                if (blank_row == 0 or blank_col == 3):
                    return new_state
                    new_state[blank_row][blank_col] =
new_state[blank_row - 1][blank_col + 1]
                    new_state[blank_row - 1][blank_col + 1] = '0'
                elif(action == 5):
                    if (blank_col == 3):
                        return new_state
                        new_state[blank_row][blank_col] =
new_state[blank_row][blank_col + 1]
                        new_state[blank_row][blank_col + 1] = '0'
                elif (action == 6):
                    if (blank_row == 3 or blank_col == 3):
                        return new_state
                        new_state[blank_row][blank_col] =
new_state[blank_row + 1][blank_col + 1]
                        new_state[blank_row + 1][blank_col + 1] = '0'
                    elif (action == 7):
                        if (blank_row == 3):
                            return new_state
                            new_state[blank_row][blank_col] =
new_state[blank_row + 1][blank_col]

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        new_state[blank_row + 1][blank_col] = '0'
    elif (action == 8):
        if (blank_row == 3 or blank_col == 0):
            return new_state
        new_state[blank_row][blank_col] =
new_state[blank_row + 1][blank_col - 1]
        new_state[blank_row + 1][blank_col - 1] = '0'

    return new_state

# A* Algorithm
def bestFirstSearch(prob):
    node = Node(prob.initial)

    # Priority Queue
    #  $f(n) = h(n) + g(n)$  (see __lt__ in Node)
    frontier = PriorityQueue()
    frontier.put(node)

    # Lookup table
    # Using str of list as key
    reached = {}
    reached[str(prob.initial)] = node

    num_nodes = 0

    while not frontier.empty():
        node = frontier.get()

        if(prob.isGoal(node.state)):
            return (node, num_nodes)

        for child in expand(prob, node):
            curr_state = child.state

            if(str(curr_state) not in reached or
child.path_cost < reached[str(curr_state)].path_cost):
                # num_nodes updated here
                num_nodes += 1
                reached[str(curr_state)] = child
                frontier.put(child)

    return None

# Expands a node
def expand(problem, node):
    curr_state = node.state
    ret = []

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    for action in problem.actions:
        new_state = problem.result(curr_state, action)
        cost = node.path_cost + problem.action_cost
        ret.append(Node(new_state, node, action, cost))
    yield Node(new_state, node, action, cost)

# Calculates the Chessboard Distance of a single tile
def chessboardDistance(tile, row, col):
    goal_row = goal_dict[tile][0]
    goal_col = goal_dict[tile][1]

    row_dist = abs(goal_row - row)
    col_dist = abs(goal_col - col)

    return max(row_dist, col_dist)

# Heuristic Function - Used to order frontier
def sumOfChessboardDistances(curr_state):
    sum = 0

    for i in range(0, 4, 1):
        for j in range(0, 4, 1):
            if(curr_state[i][j] != "0"):
                curr_dist =
chessboardDistance(curr_state[i][j], i, j)
                sum += curr_dist

    return sum

# ----- Main -----
initial = []
goal = []

# Ask to initialize the file until found

while True:
    print("\nEnter the name of the input, ensuring that you
type .txt afterwards.\n\nOutput will be written in
sampleoutput.txt. Please check your directory. ")
    file_name = input();
    try:
        input_file = open(file_name)
        if input_file:
            break
    except IOError:
        print ("There is no such a file, please try again")

input_str = input_file.read()

```

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# Splits with each new line
split_input = input_str.split('\n')

# Clean the output file
file = open("sampleoutput.txt", "r+")
file.truncate(0)
file.close()

# Open output file for writing
sys.stdout = open("sampleoutput.txt", "w")

switch = False

# Splits with each space
# Appends to initial if switch = False
# else appends to goal
for arr in split_input:
    if arr == ' ':
        switch = True
        continue

    if not switch:
        initial.append(arr.split(" "))
    else:
        goal.append(arr.split(" "))

# Dictionary for chessboard distance
goal_dict = {}
for row in range(0, 4, 1):
    for col in range(0, 4, 1):
        if goal[row][col] != "0":
            goal_dict[goal[row][col]] = (row, col)

# Solving the problem
p = Problem(initial, goal, [1, 2, 3, 4, 5, 6, 7, 8])
sol = bestFirstSearch(p)
node = sol[0]
num_of_nodes = sol[1]

# Actions and f values
# d number of actions
# d + 1 number of f values
acts = []
fs = []
while True:
    if (node.parent == None):
        fs.insert(0, sumOfChessboardDistances(node.state))
        break

```

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        acts.insert(0, node.action)
        fs.insert(0, sumOfChessboardDistances(node.state))
        node = node.parent

depth = len(acts)

# Prints the initial and goal states
for row in range(0, 4, 1):
    for col in range(0, 4, 1):
        print(initial[row][col], end = " ") # n
    print()

print()

for row in range(0, 4, 1):
    for col in range(0, 4, 1):
        print(goal[row][col], end = " ") # m
    print()

print()

# d
print(depth)

# N
print(num_of_nodes)

# A
for a in acts:
    print(a, end=" ")

print()

# F
for f in fs:
    print(f, end=" ")

print()

input_file.close()
sys.stdout.close()

```

Input Files and Output Files

Input File 1

```
1 5 3 13
8 0 6 4
15 10 7 9
11 14 2 12

1 5 3 13
0 7 6 4
8 10 9 2
11 15 14 12
```

Output File 1

```
1 5 3 13
8 0 6 4
15 10 7 9
11 14 2 12

1 5 3 13
0 7 6 4
8 10 9 2
11 15 14 12

6
31
6 5 8 1 2 3
6 5 4 3 2 1 0
```

Input File 2

```
9 13 7 4
12 3 0 1
2 15 5 6
14 10 11 8

9 3 7 1
13 5 4 6
12 15 0 10
14 2 11 8
```

Output File 2

```
9 13 7 4
12 3 0 1
2 15 5 6
14 10 11 8

9 3 7 1
13 5 4 6
12 15 0 10
14 2 11 8

11
106
7 8 2 3 4 7 5 4 7 7 1
10 10 9 8 7 6 5 4 3 2 1 0
```

Input File 3

```
9 13 7 4
12 3 0 1
2 15 5 6
14 10 11 8

9 3 7 1
13 5 4 6
12 15 0 10
14 2 11 8
```

Output File 3

```
13 12 2 11
10 1 8 9
0 3 15 14
6 4 7 5

0 10 12 11
3 13 1 2
6 15 5 8
4 14 7 9

16
203
7 5 4 5 3 2 1 8 6 7 4 6 3 2 1 2
15 14 13 13 12 11 10 9 8 7 6 5 4 3 2 1 0
```