

Penalised Splines BART

Adding smoothness to Bayesian Additive Regression Trees



Mateus Maia, Keefe Murphy and Andrew Parnell



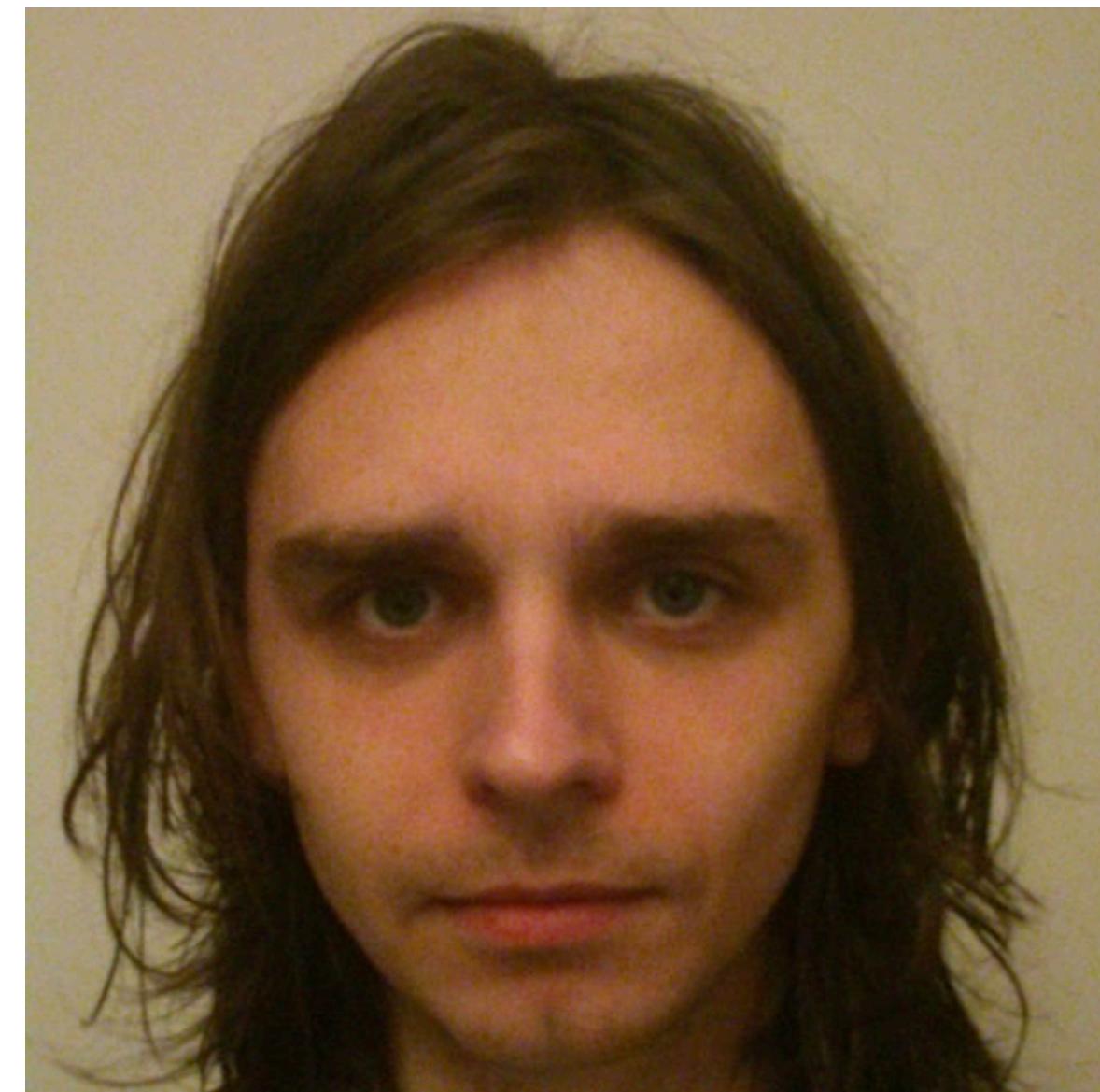
Maynooth University, Ireland.

CASI 2023

A joint work



Andrew C. Parnell



Keefe Murphy

Bayesian Additive Regression Trees (BART)

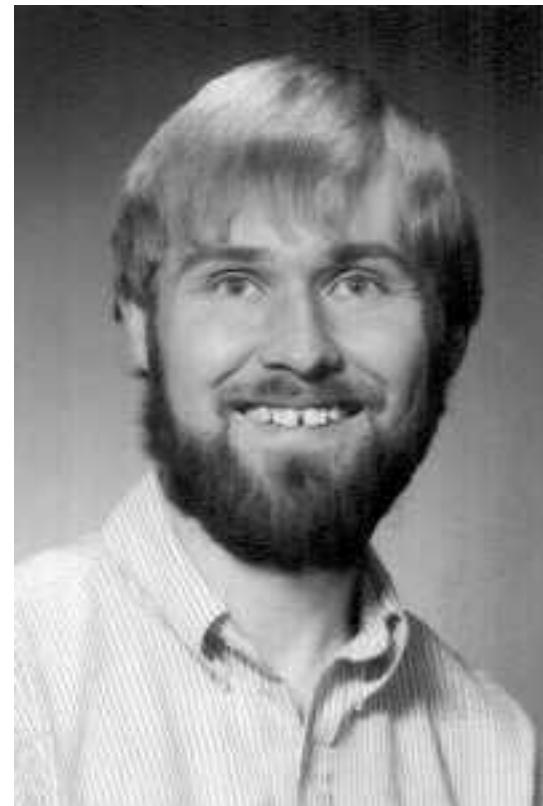
Bayesian Additive Regression Trees (BART)

March 2010

BART: Bayesian additive regression trees

Hugh A. Chipman, Edward I. George, Robert E. McCulloch

Ann. Appl. Stat. 4(1): 266-298 (March 2010). DOI: 10.1214/09-AOAS285



Hugh A. Chipman



Edward I. George



Robert E. McCulloch

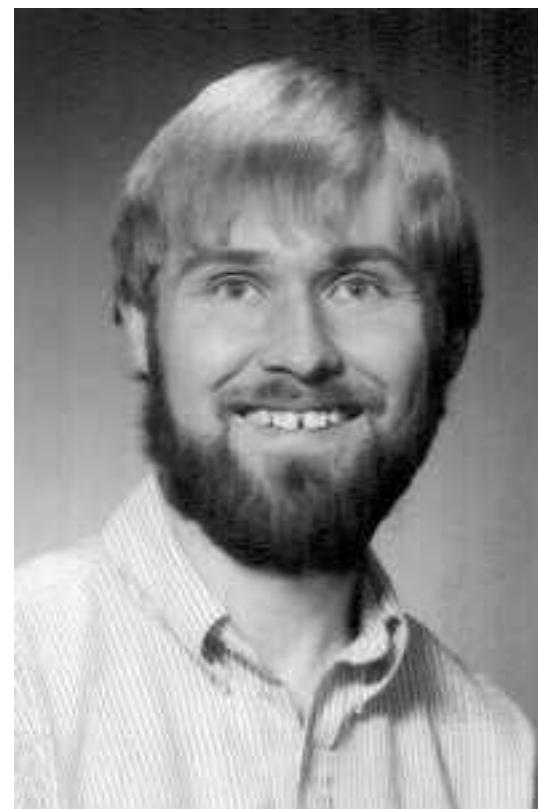
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BART and 2016 Causal Inference Data Analysis Challenge (Dorie et. al, 2019)

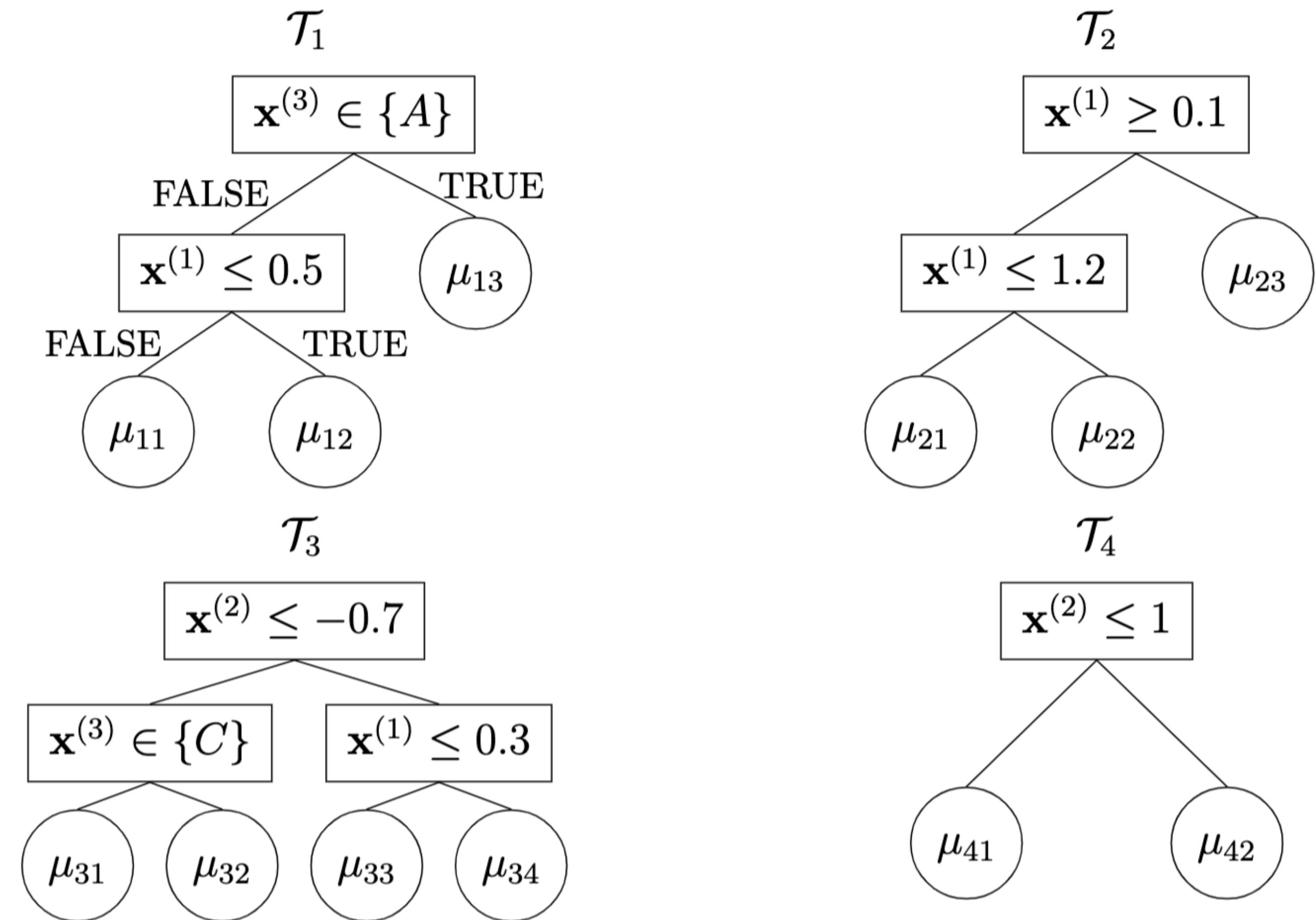
BART

$$y_i | \mathbf{x}_i \sim \mathcal{N} \left(\sum_{t=1}^T h \left(\mathbf{x}_i; \mathcal{T}_t, \mathbf{L}_t \right), \tau^{-1} \right)$$

μ_{ℓ_t} priors:

$$\mu_{t\ell} | \mathcal{T}_t, \tau \sim \mathcal{N}(0, \tau_\mu^{-1})$$

$$\tau_\mu = 4k^2 T$$



BART

Algorithm 1: BART sampling algorithm

Input: \mathbf{X} , \mathbf{y} , T , N_{MCMC} , and all hyperparameters of the priors.

Initialise: T tree stumps, $\tau = 1$.

for *iterations m from 1 to N_{MCMC}* **do**

for *trees t from 1 to T* **do**

Calculate the partial residuals \mathbf{R}_t ;

Propose a new tree \mathcal{T}_t^* by a grow, change, or prune move;

Accept and update $\mathcal{T}_t = \mathcal{T}_t^*$ with probability

$$\gamma^*(\mathcal{T}_t, \mathcal{T}_t^*) = \min \left\{ 1, \frac{\pi(\mathbf{R}_t | \mathcal{T}_t^*, \tau_\mu, \tau) \pi(\mathcal{T}_t^*)}{\pi(\mathbf{R}_t | \mathcal{T}_t, \tau_\mu, \tau) \pi(\mathcal{T}_t)} \right\}$$

for *terminal nodes l from 1 to b_t* **do**

| Update μ_{tl}

end

end

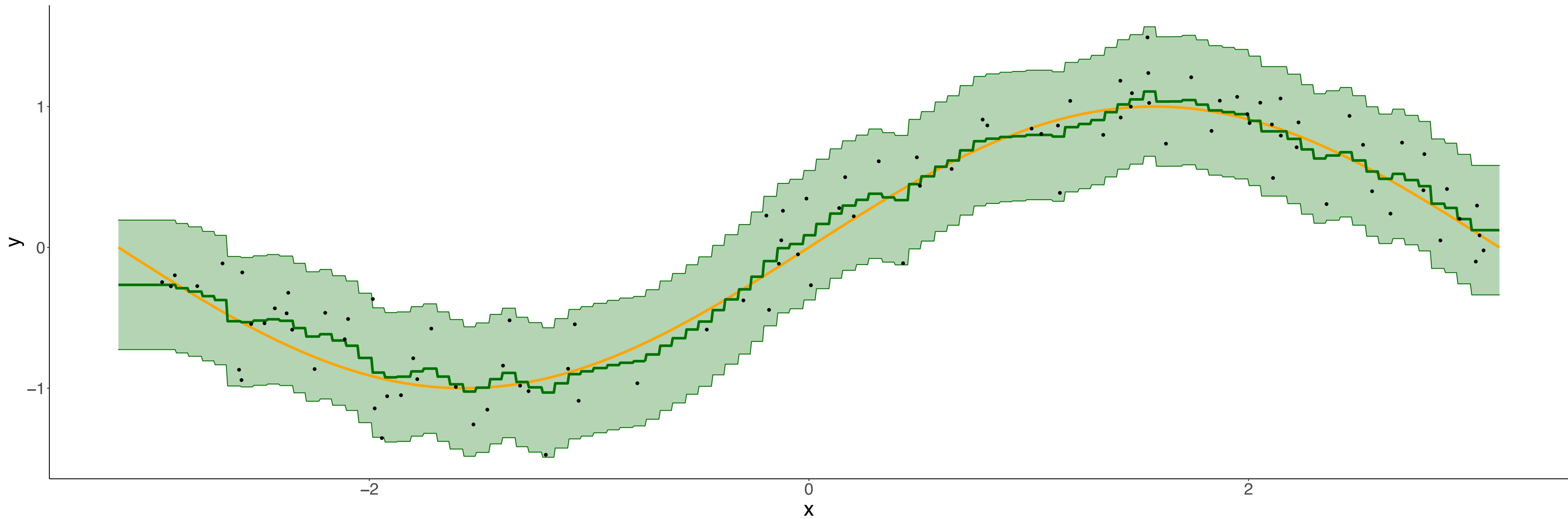
Update τ

end

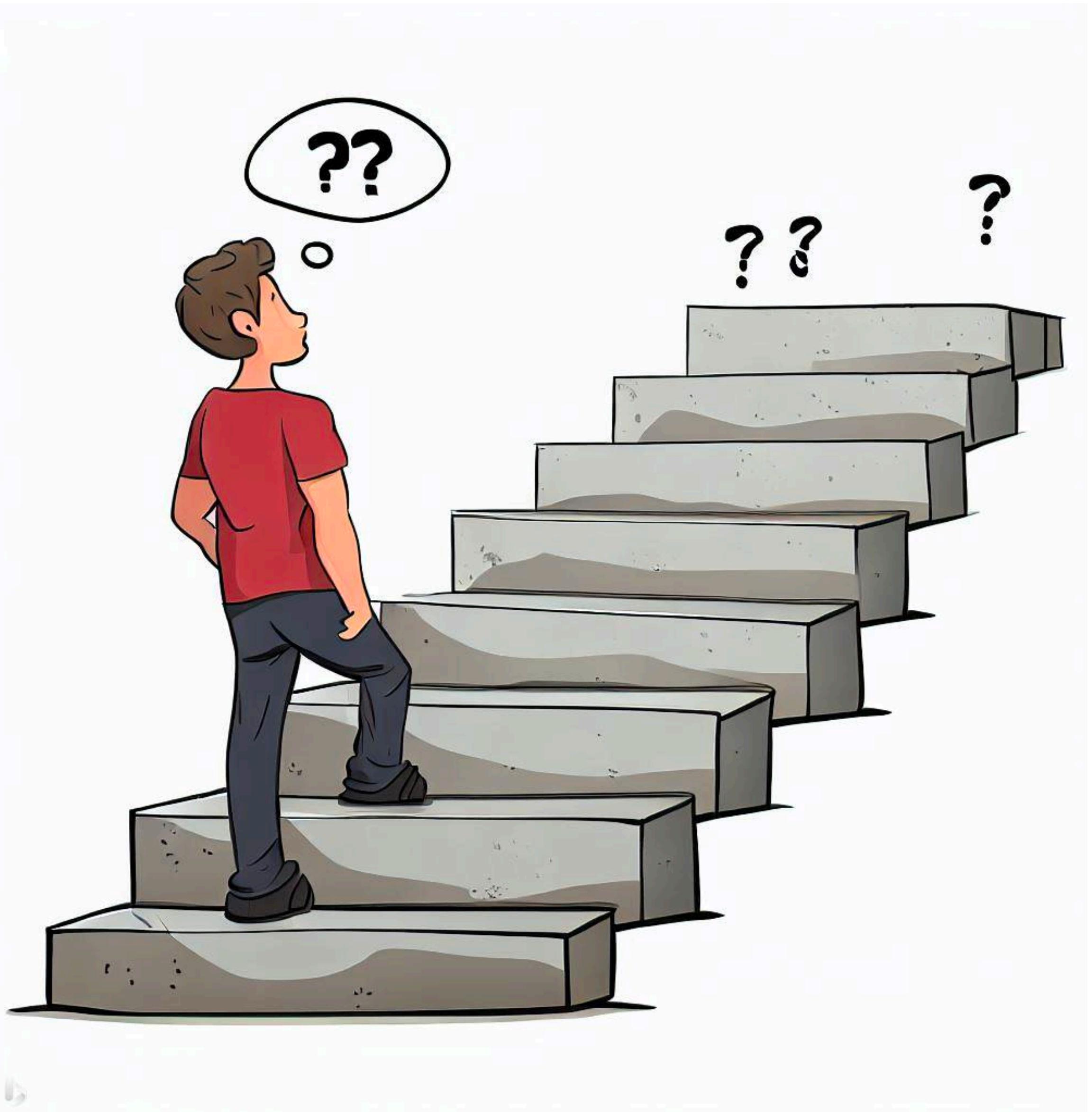
Output: Approx. samples from $\pi((\mathcal{T}_1, \mathbf{G}_1), \dots, (\mathcal{T}_T, \mathbf{G}_T), \tau | \mathbf{y})$.

BART

$$y = \sin(x) + N(0, \sigma^2)$$



How to overcome the inherent step- wise behaviour from BART?



BART extensions

- **Piecewise-constant nature from the model ($\mu_{t\ell}$)**
 - **Soft-BART** - Linero, A. R., & Yang, Y. (2018). Bayesian regression tree ensembles that adapt to smoothness and sparsity Series B Statistical methodology.
 - **MOTR-BART** - Prado, E. B., Moral, R. A., & Parnell, A. C. (2021). Bayesian additive regression trees with model trees. Statistics and Computing, 31(3), 1-13.
 - **GP-BART** - Maia, M., Murphy, K., & Parnell, A. C. (2022). GP-BART: a novel Bayesian additive regression trees approach using Gaussian processes. arXiv preprint arXiv:2204.02112.

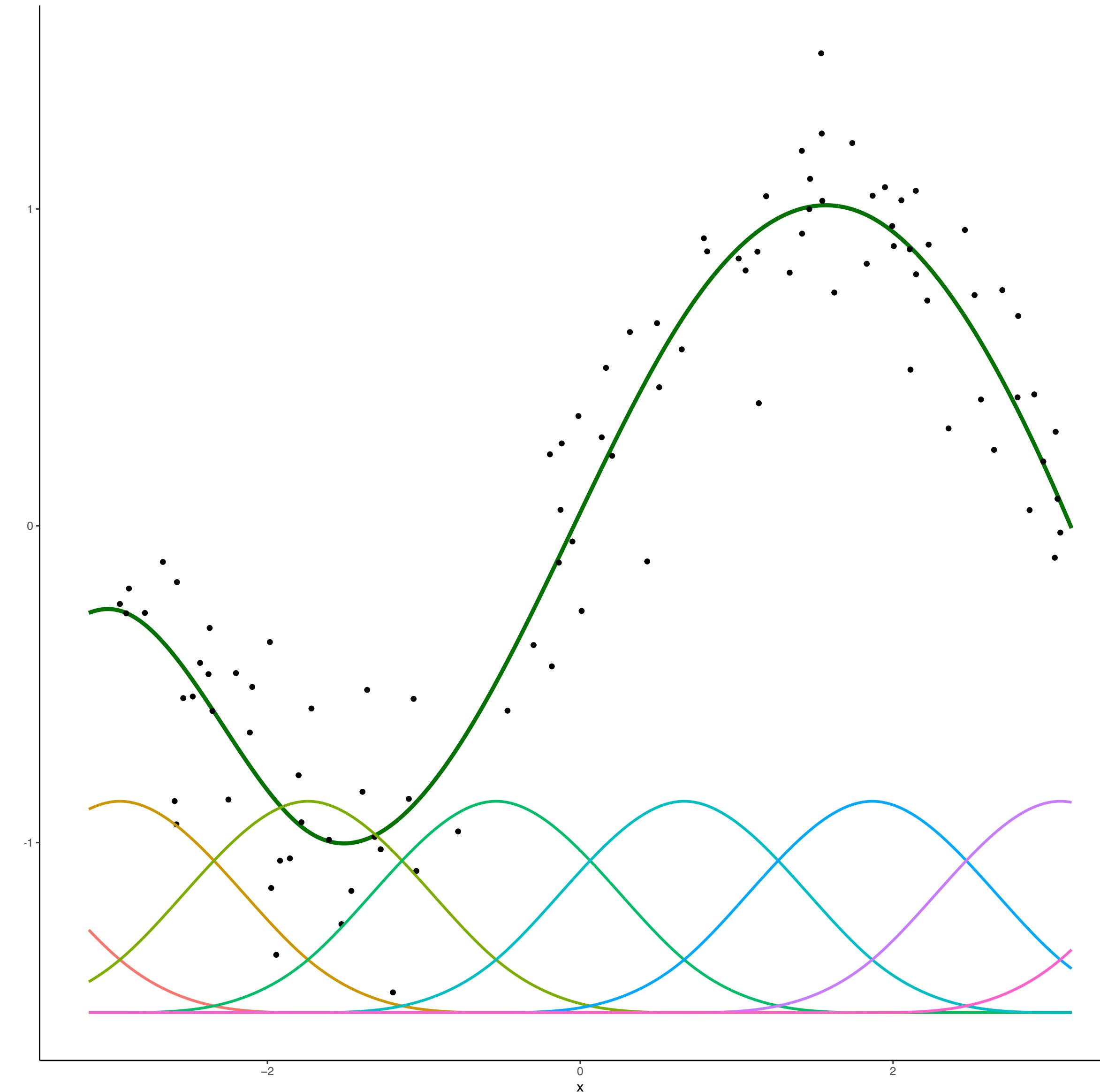
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Penalised Splines BART

Splines

- “In words, a **k-th** order spline is a piecewise polynomial function of **degree $k - 1$** , that is continuous and has **continuous derivatives** of orders $1, \dots, k$, at its **knot points**”.

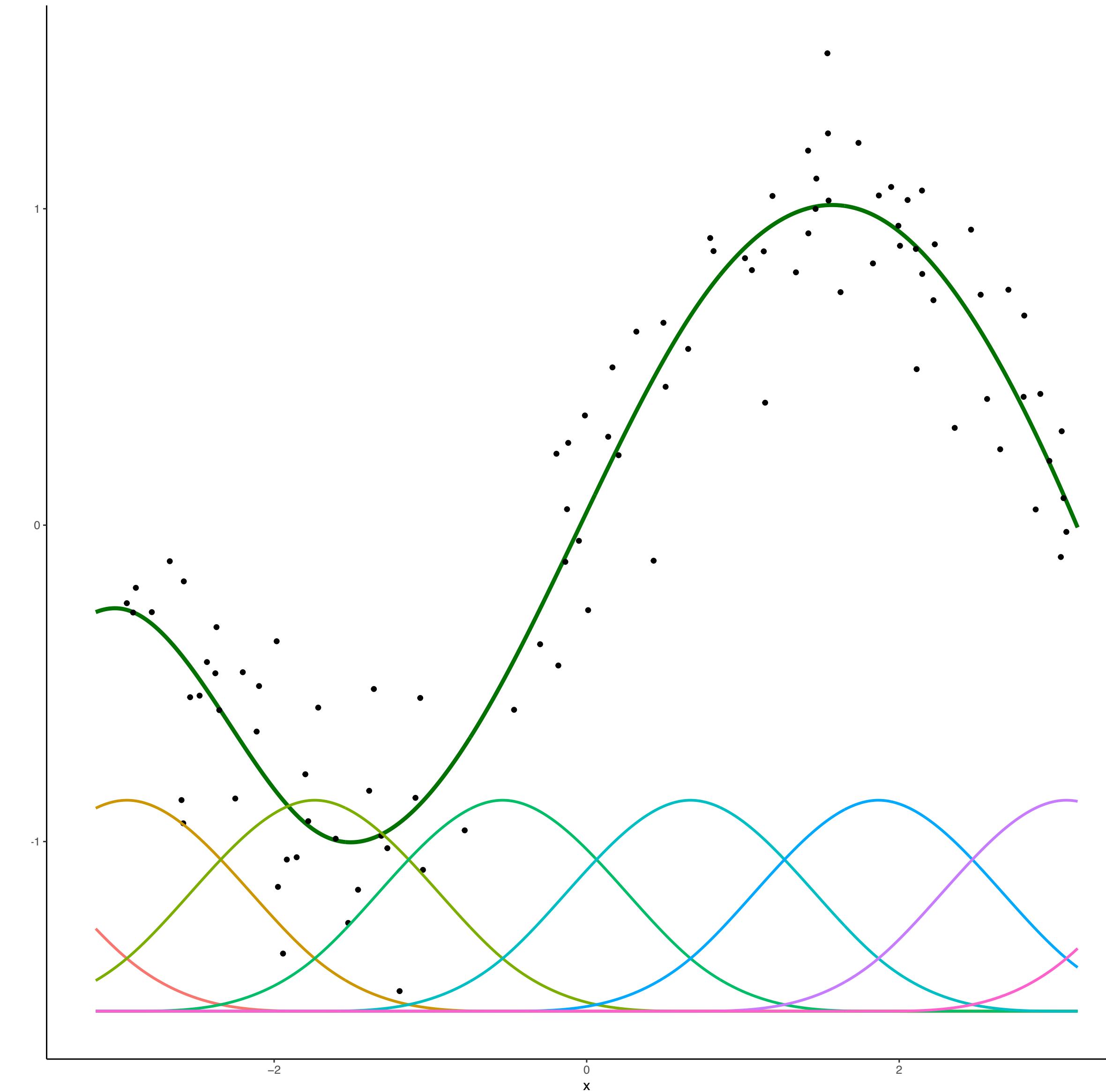


Splines

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P-Splines

- Eilers, P. H., & Marx, B. D. (1996).
- “...choosing the optimal number and positions of knots is a **complex task**.”



Splines BART (sBART)

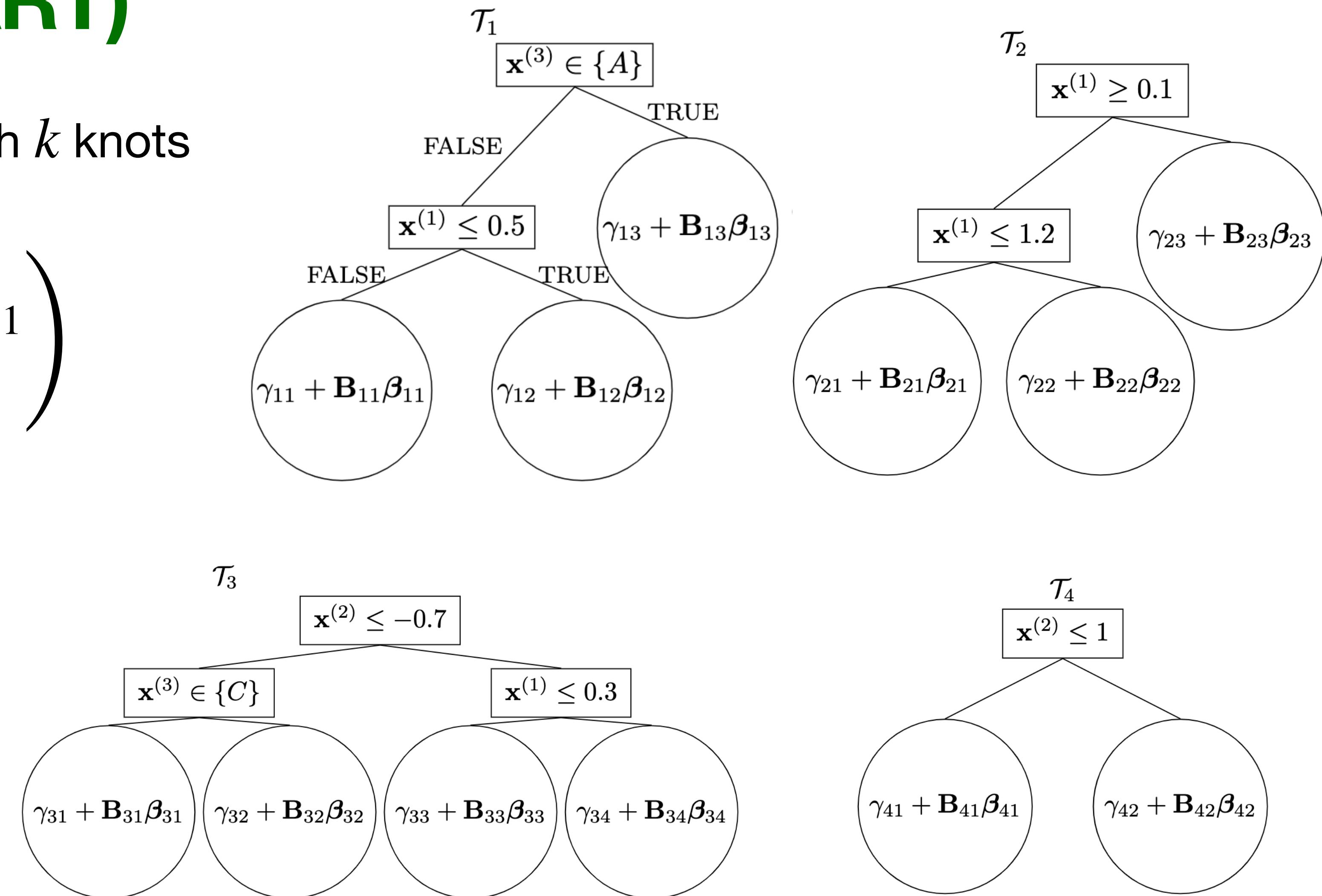
Build a natural B-spline \mathbf{B} matrix with k knots

$$y_i | \mathbf{x}_i \sim N \left(\sum_{t=1}^T b \left(\mathbf{x}_i; \mathcal{T}_t, \mathbf{L}_t \right), \tau^{-1} \right)$$

$\beta_{\ell t}$ and $\gamma_{t\ell}$ priors:

$$\beta_{t\ell} \sim N \left(0, \tau_\beta^{-1} \mathbf{I}_p \right)$$

$$\gamma_{t\ell} \sim N \left(0, \tau_\gamma^{-1} \right)$$



Penalised Splines BART (sBART)

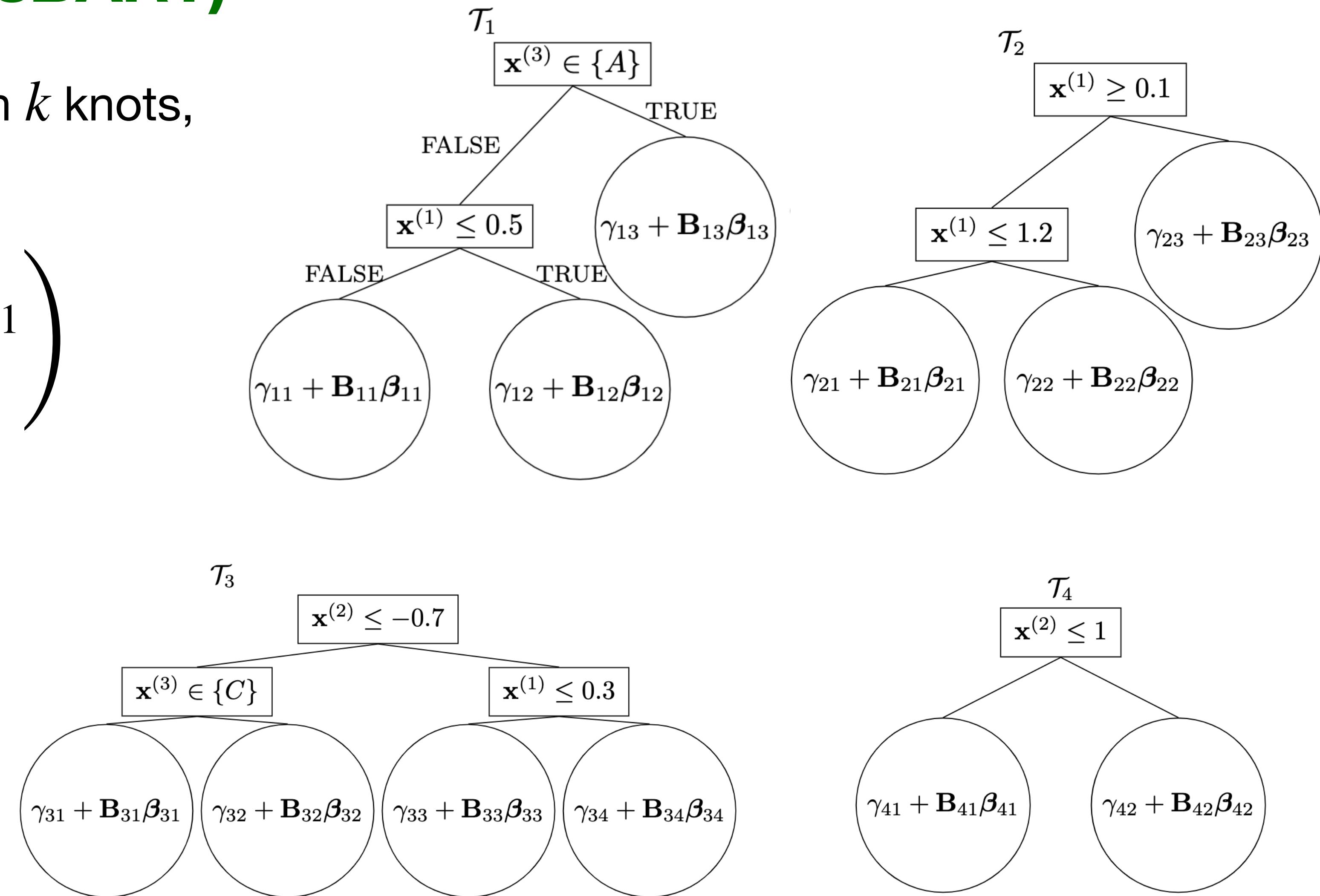
Build a natural B-spline \mathbf{B} matrix with k knots,
penalising the $\beta_{t\ell}$ differences

$$y_i | \mathbf{x}_i \sim N \left(\sum_{t=1}^T b \left(\mathbf{x}_i; \mathcal{T}_t, \mathbf{L}_t \right), \tau^{-1} \right)$$

$\beta_{\ell t}$ and $\gamma_{t\ell}$ priors:

$$\beta_{t\ell} \sim N \left(0, \tau_\beta^{-1} \mathbf{P}^{-1} + \tau_0^{-1} \mathbf{P}_0^{-1} \right)$$

$$\gamma_{t\ell} \sim N \left(0, \tau_\gamma^{-1} \right)$$



Penalised Splines BART (sBART)

Build a natural B-spline \mathbf{B} matrix with k knots,
penalising the $\beta_{t\ell}$ differences

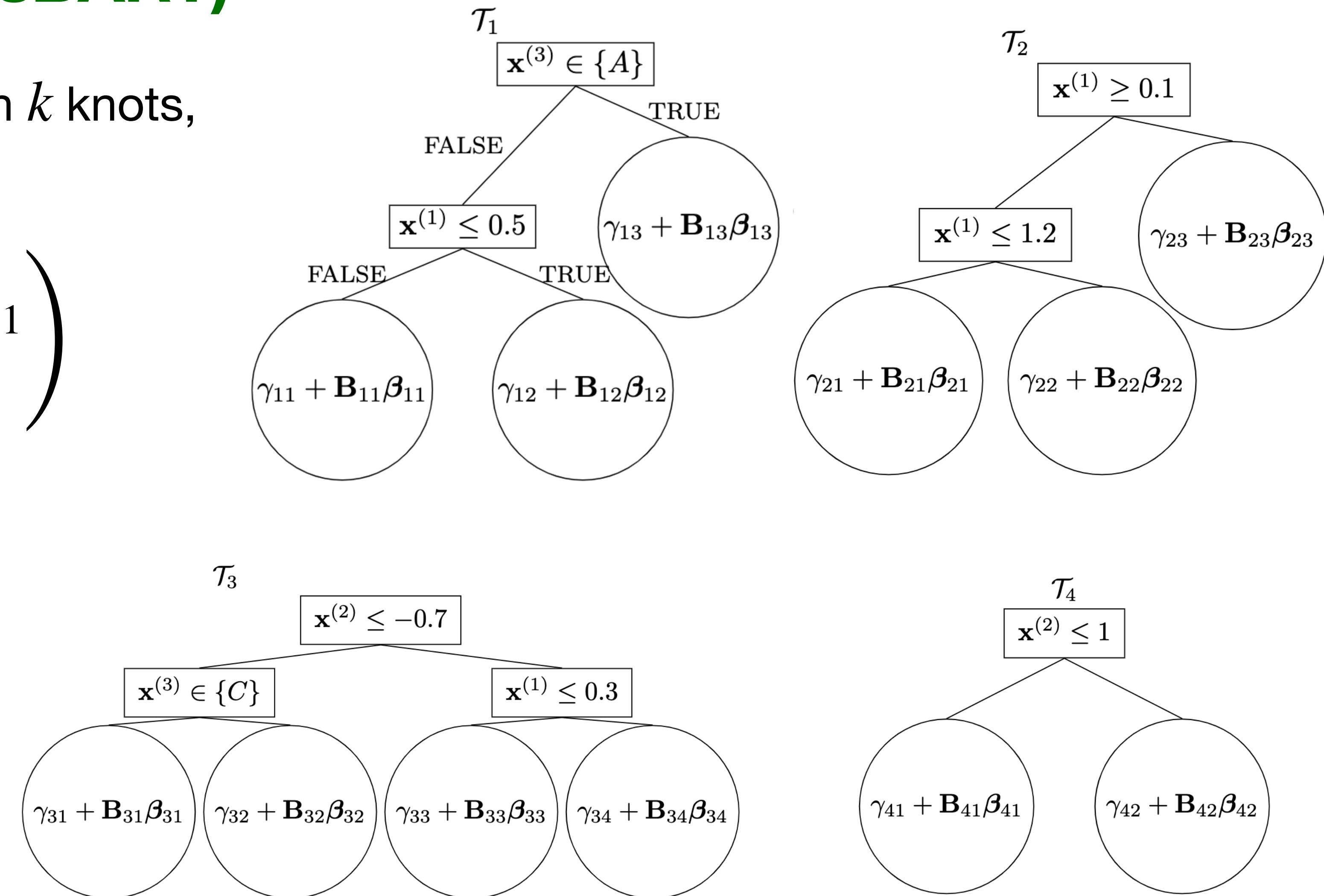
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$$\gamma_{t\ell} \sim N \left(0, \tau_\gamma^{-1} \right)$$

$$\tau_\gamma = 4k^2 T$$



Penalised Splines BART

(Priors)

Penalised Splines BART

(Priors)



Penalised Splines BART (Priors)

$\beta_{t\ell}$ priors

$$\beta_{t\ell} \sim N\left(0, \tau_\beta^{-1} \mathbf{P}^{-1} + \tau_0^{-1} \mathbf{P}_0^{-1}\right)$$

$$\tau_\beta | \delta \sim \text{Gamma}\left(\frac{\nu}{2}, \frac{\delta\nu}{2}\right)$$

$$\delta \sim \text{Gamma}(a_\delta, d_\delta)$$

$$\tau_0 \sim \text{Gamma}(a_\eta, d_\eta)$$

$\gamma_{t\ell}$ priors

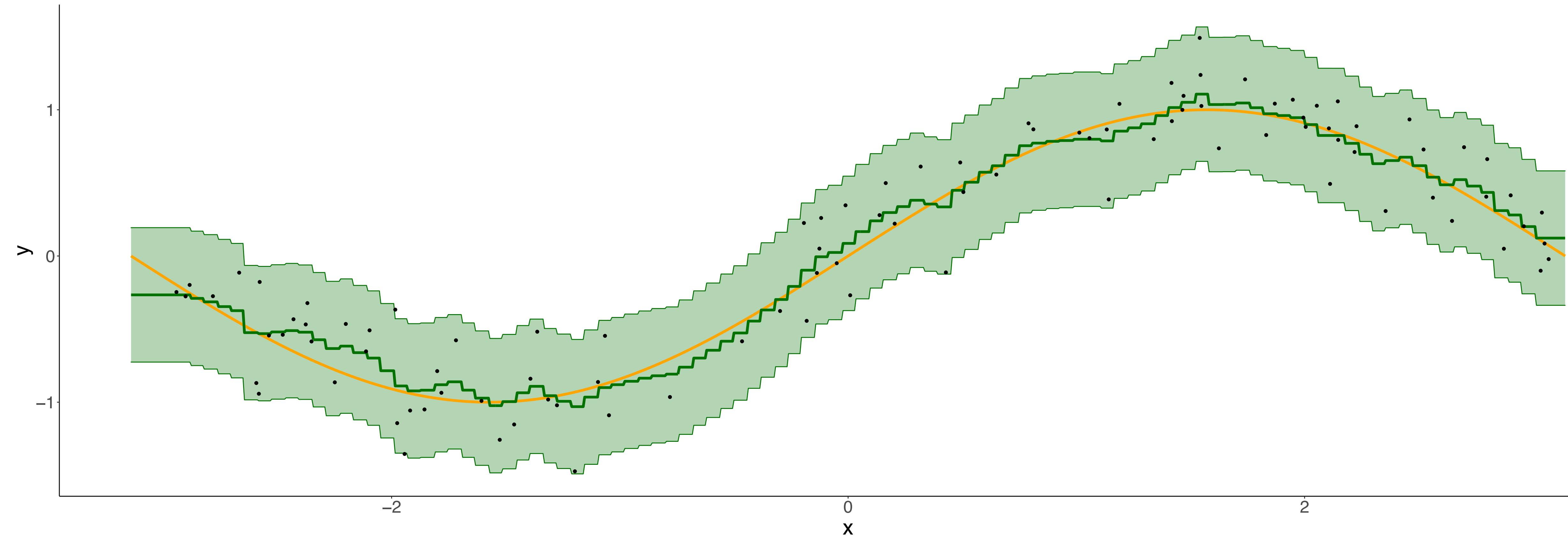
$$\gamma_{t\ell} \sim N\left(0, \tau_\gamma^{-1}\right)$$

$$\tau_\gamma = 4k^2 T$$

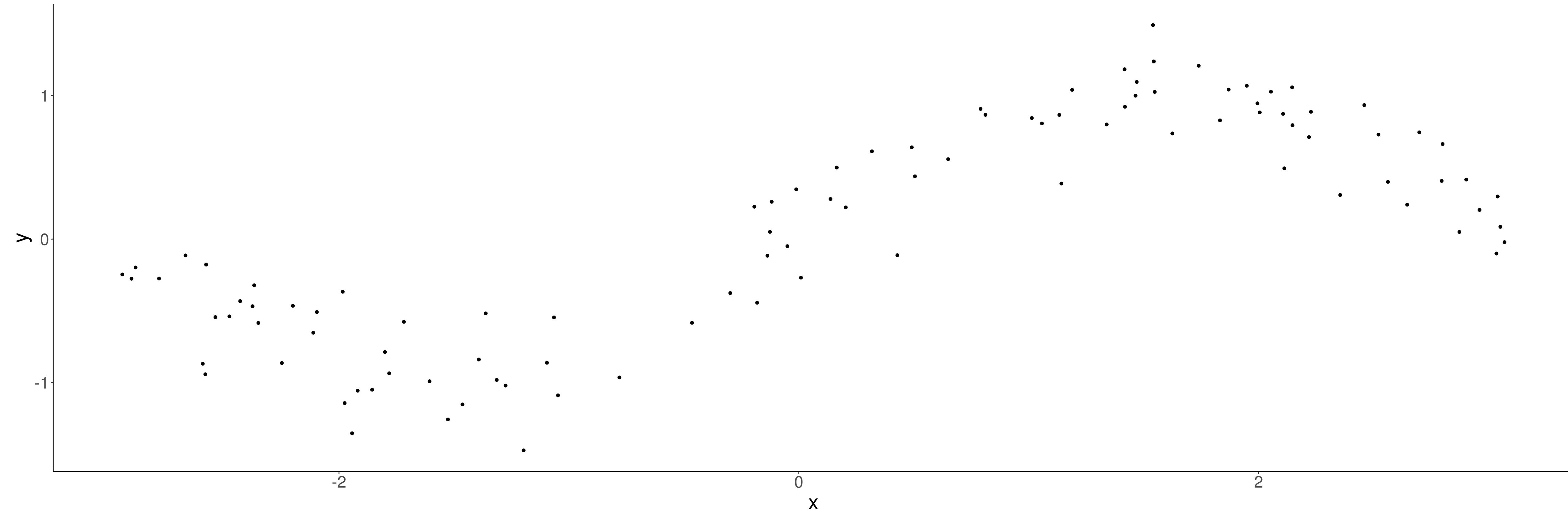
Illustrating psBART in action

BART

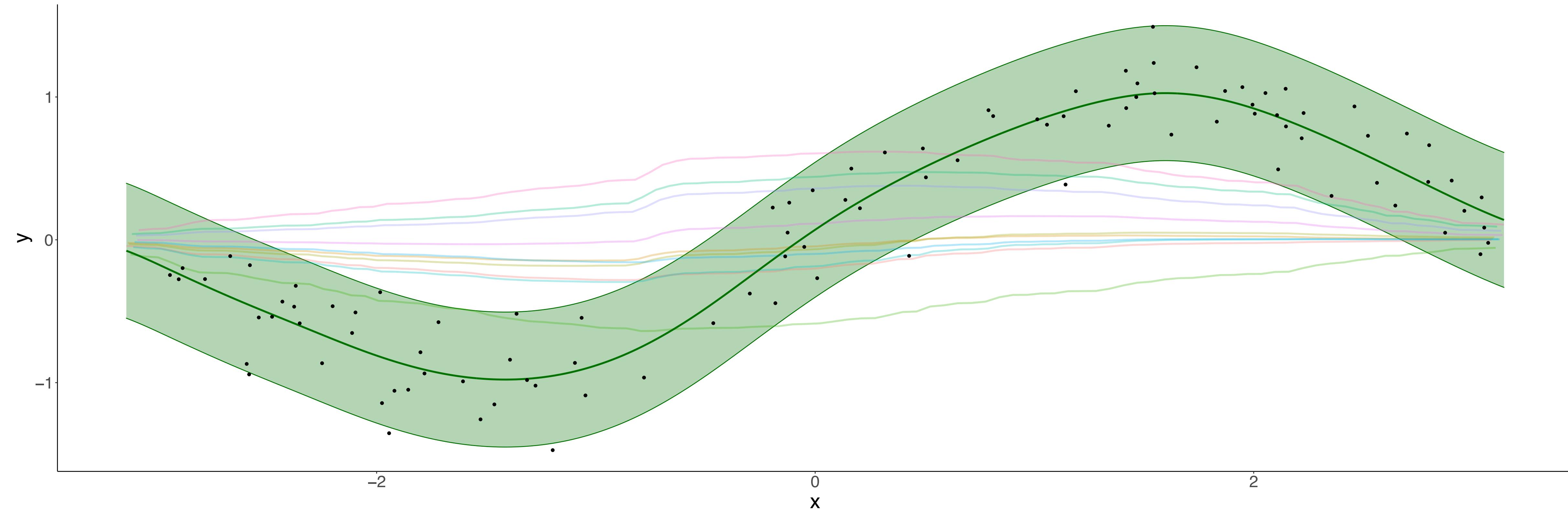
$$y = \sin(x) + N(0, \sigma^2)$$



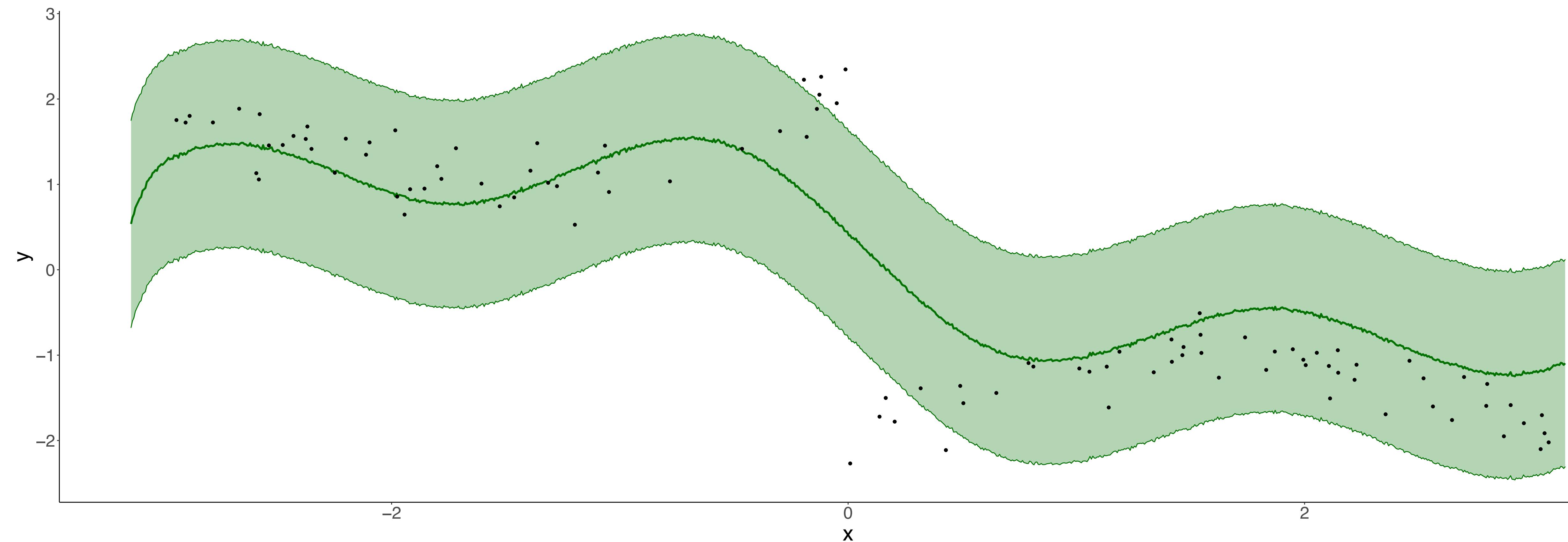
psBART



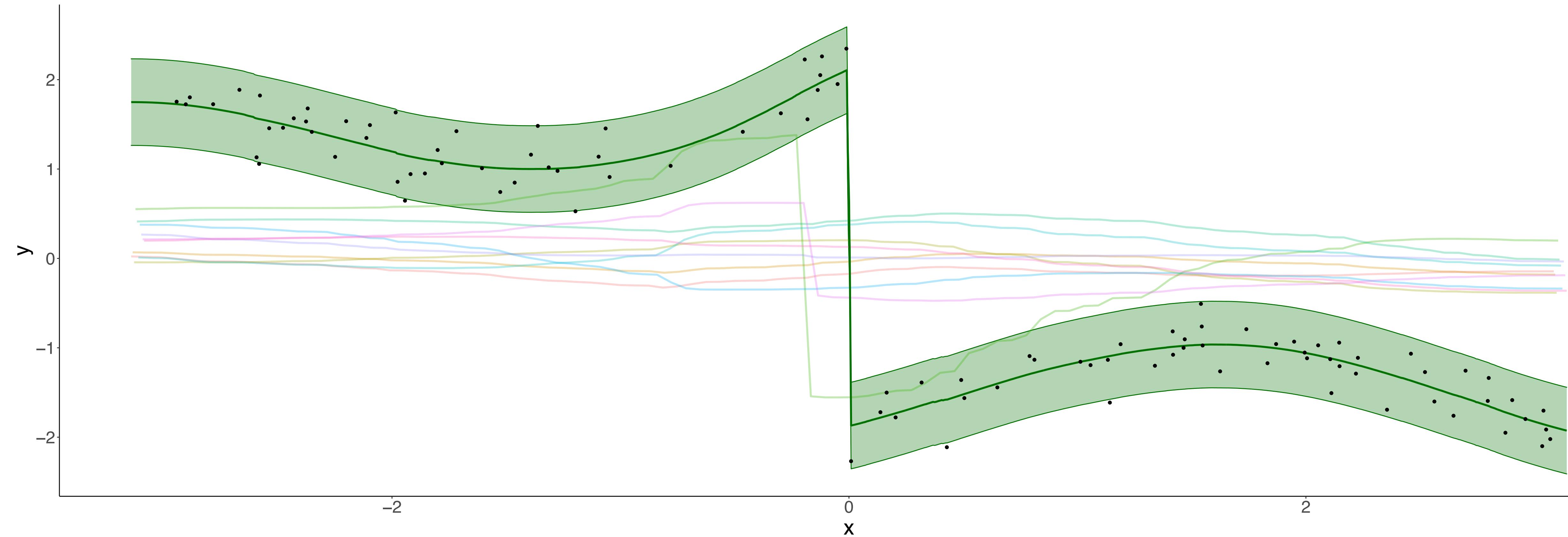
psBART



A spline model would be enough?



psBART



Final Remarks

Remarks

- The extension of BART using splines seems to be a good choice to tackle the lack of smoothness from the standard formulation.
- Despite satisfactory results on first trials over the real dataset benchmarking, a extensive and exhaustive comparison using a broader range of datasets is required.
- The choice of priors hyper parameters and the effect over the interactions in the model is still a ongoing challenge to be investigated.

Thank you for the attention!
Questions?

Acknowledgements

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Fondúireacht Eolaíochta Éireann
Dá bhfuil romhainn

Science Foundation Ireland
For what's next

References

- Dorie, Vincent, et al. "**Automated versus do-it-yourself methods for causal inference: Lessons learned from a data analysis competition.**" (2019): 43-68.
- Eilers, Paul HC, and Brian D. Marx. "**Flexible smoothing with B-splines and penalties.**" Statistical science 11.2 (1996): 89-121.
- Chipman, Hugh A., Edward I. George, and Robert E. McCulloch. "**BART: Bayesian additive regression trees.**" (2010): 266-298.