The Gradient

We've given a formal definition for differentiability of a function $f: \mathbb{R}^2 \to \mathbb{R}$

Definition 1. Consider the function $f : \mathbb{R}^2 \to \mathbb{R}$, and suppose that the partial derivatives f_x and f_y are defined at the point (x, y) = (a, b). Define the linear function

$$h(x,y) = f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b).$$

We say that f is differentiable at (x, y) = (a, b) if

$$\lim_{(x,y)\to(a,b)}\frac{f(x,y)-h(x,y)}{\|(x,y)-(a,b)\|}=0.$$

If either of the partial derivatives $f_x(a,b)$ and $f_y(a,b)$ do not exist, or the above limit does not exist or is not 0, then f is not differentiable at (a,b).

The idea behind this definition is that h(x, y) will be a "good" linear approximation to f(x, y) near (a, b) if f is differentiable at (a, b).

We would now like to define differentiability for scalar-valued functions of more than two variables, so functions $\mathbb{R}^n \to \mathbb{R}$. This definition will closely resemble our definition above, which handles the case n=2. For example, in the case n=3, we will use the linear function

$$h(x,y,z) = f(a,b,c) + f_x(a,b,c)(x-a) + f_y(a,b,c)(y-b) + f_z(a,b,c)(z-c).$$

For larger n, we'll define a similar function h, but this notation will quickly become unwieldy! In order to simplify notation, we'll now introduce a new object to organize our partial derivatives: the gradient of a scalar-valued function.

The gradient

In order to organize our information about partial derivatives, and streamline our definition of differentiability for functions $\mathbb{R}^n \to \mathbb{R}$, we now define the gradient of a scalar-valued function.

Definition 2. Consider a function $f: \mathbb{R}^n \to \mathbb{R}$. The gradient of f is the function $\nabla f: \mathbb{R}^n \to \mathbb{R}^n$, defined by

$$\nabla f = \left(\frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}, ..., \frac{\partial f}{\partial x_n}\right).$$

Learning outcomes: Author(s):

The gradient vector will be a useful computation tool in general, not only for defining differentiability.

Example 1. For $f(x, y, z) = x^2 + ye^z$, we can compute the partial derivatives

$$f_x(x, y, z) = 2x,$$

$$f_y(x, y, z) = e^z,$$

$$f_z(x, y, z) = ye^z.$$

Then the gradient of f is

$$\nabla f = (2x, e^z y e^z).$$

Problem 1 Find the gradient of each function.

$$f(x, y, z) = \sin(xyz)$$

$$\nabla f(x,y,z) = \boxed{(yz\cos(xyz),xz\cos(xyz),xy\cos(xyz))}$$

$$g(x,y) = x^2 e^y + y$$

$$\nabla g(x,y) = \boxed{(2xe^y, x^2e^y + 1)}$$

$$h(x_1, x_2, x_3, x_4) = x_1^2 x_2 + x_1 x_3 + x_2 x_4$$

$$\nabla h(x_1, x_2, x_3, x_4) = \boxed{(2x_1x_2 + x_3, x_1^2 + x_4, x_1, x_2)}$$

Differentiability

Now that we've defined the gradient, let's revisit our definition of differentiability for a function from \mathbb{R}^2 to \mathbb{R} . We used the function

$$h(x,y) = f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b).$$

Looking at the terms $f_x(a,b)(x-a) + f_y(a,b)(y-b)$, we can rewrite this as a dot product of two vectors:

$$f_x(a,b)(x-a) + f_y(a,b)(y-b) = (f_x(a,b), f_y(a,b)) \cdot (x-a,y-b).$$

The first vector is the gradient of f evaluated at (a, b), so we can rewrite this as

$$(f_x(a,b), f_y(a,b)) \cdot (x-a, y-b) = \nabla f(a,b) \cdot (x-a, y-b).$$

If we take $\vec{x} = (x, y)$ and $\vec{a} = (a, b)$, we can write this as

$$\nabla f(\vec{a}) \cdot (\vec{x} - \vec{a}).$$

With these notational changes in mind, we now define differentiability for a function $f: \mathbb{R}^n \to \mathbb{R}$.

Definition 3. Consider a function $f: \mathbb{R}^n \to \mathbb{R}$. For a point $\vec{a} \in \mathbb{R}^n$, define

$$h(\vec{x}) = f(\vec{a}) + \nabla f(\vec{a}) \cdot (\vec{x} - \vec{a}).$$

We say that f is differentiable at \vec{a} if

$$\lim_{\vec{x} \to \vec{a}} \frac{f(\vec{x}) - h(\vec{x})}{\|\vec{x} - \vec{a}\|} = 0.$$

If f is differentiable, we say that $h(\vec{x})$ is the tangent hyperplane to f at \vec{a} .

If any of the partial derivatives of f do not exist, or the above limit does not exist or is not 0, then f is not differentiable at \vec{a} .

Example 2. We'll use this definition of differentiability to prove that the function f(x, y, z) = xy + z is differentiable at (1, 1, 1).

First, we find the gradient of f.

$$\nabla f(x, y, z) = (y, x, 1)$$

At the point (1,1,1), we have

$$\nabla f(1,1,1) = (1,1,1)$$

From this, we find the formula for h(x, y, z).

$$h(x, y, z) = f(1, 1, 1) + \nabla f(1, 1, 1) \cdot ((x, y, z) - (1, 1, 1))$$
$$= 2 + (1, 1, 1) \cdot (x - 1, y - 1, z - 1)$$
$$= \boxed{x + y + z - 1}$$

Next, we evaluate the limit

$$\begin{split} \lim_{(x,y,z)\to(1,1,1)} \frac{f(x,y,z)-h(x,y,z)}{\|(x,y,z)-(1,1,1)\|} &= \lim_{(x,y,z)\to(1,1,1)} \frac{(xy+z)-(x+y+z-1)}{\sqrt{(x-1)^2+(y-1)^2+(z-1)^2}} \\ &= \lim_{(x,y,z)\to(1,1,1)} \frac{xy-x-y+1}{\sqrt{(x-1)^2+(y-1)^2+(z-1)^2}}. \end{split}$$

To evaluate this limit, we switch to translated spherical coordinates

$$x = 1 + \rho \cos \theta \sin \phi,$$

$$y = 1 + \rho \sin \theta \sin \phi,$$

$$z = 1 + \rho \cos \phi.$$

Making this change, we obtain

$$\lim_{(x,y,z)\to(1,1,1)} \frac{xy - x - y + 1}{\sqrt{(x-1)^2 + (y-1)^2 + (z-1)^2}} = \lim_{\rho\to 0} \frac{(1+\rho\cos\theta\sin\phi)(1+\rho\sin\theta\sin\phi) - (1+\rho\cos\theta\sin\phi) - (1+\rho\cos\phi\sin\phi) - (1+\rho\phi\cos\phi) - (1+\rho\phi\cos\phi) - (1+\rho\phi\phi) - (1$$

Since $-|\rho| \leq \frac{\rho^2 \cos \theta \sin \theta \sin^2 \phi}{|\rho|} \leq |\rho|$, we use the squeeze theorem to obtain

$$\lim_{\rho \to 0} \frac{\rho^2 \cos \theta \sin \theta \sin^2 \phi}{|\rho|} = 0.$$

Thus, we have shown that f(x, y, z) = xy + z is differentiable at (1, 1, 1).