

GOAL

Our goal is to introduce foliations as a useful framework to formalise transfer learning (TL), and foster more precise, foundational and deliberate discourse and enquiry of the TL problem.

TRANSFER LEARNING

Transfer learning is an aspect of machine learning (ML) that has garnered relatively recent interest. It deals with the problem of transferring learned knowledge between *related tasks*. For example, consider the RL problem in Figure 1.

Many experimentally successful works exist in this space [1, 2]. However, these do not present transfer (or meta) learning through a formal framework. We cannot understand why nor when they would work.

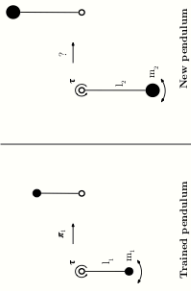


Figure 1: Example of transfer with a pendulum

REPRESENTATION, RELATEDNESS AND SIMILARITY

Representation A representation is a scheme by which we can describe a set of abstract objects. For example, the abstract number 42 can be written as ‘forty-two’ in English, 42 in decimal and 101010 in binary. In ML, we want to find an *approximate description* of a map in terms of a *chosen representation* scheme (the model), from the given data. The representation scheme reflects our assumptions about the problem.

Relatedness This definition of relatedness borrows from [3]. We define 2 tasks f, g in a set of tasks T to be related if, given a group of transformations Π that act on T , there exists $\pi \in \Pi$ such that $\pi(f) = g$, and $\pi^{-1}(g) = f$. Relatedness is a transformative notion.

Equivariance We can further assume that if two tasks are *related*, then their solution in the space of models M are also *related*. That is, the learning algorithm, is an *equivariant map*. See Figure 2.

Similarity We can make similarity distinct from relatedness. 2 tasks $f, g \in T$ are ϵ -similar, if, under some metric ρ on T , $\rho(f, g) \leq \epsilon$. Similarity is a geometric notion. See Figure 3.

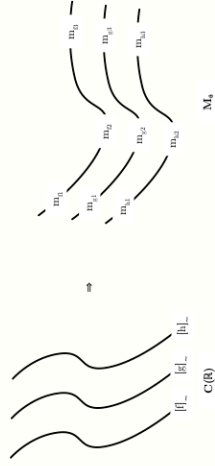


Figure 2: Assumption of equivariance

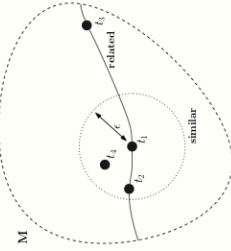


Figure 3: Relatedness vs Similarity

RELATED TASKS, INVARIANT QUANTITIES AND PARALLEL SPACES

How can we build a representation scheme that reflects a notion of relatedness, as defined?

Set of related tasks Under Π , we can find an equivalence class of tasks. That is, $[f]_{\sim} \subseteq T$, is an equivalence class containing $f \in T$ where equivalence relation \sim is given by $f \sim g \iff f = \pi(g)$ for some $\pi \in \Pi$. These sets are the orbits of the group action of Π .

Invariant quantities A quantity on T is a map $q : T \rightarrow \mathbb{R}$. This quantity is invariant w.r.t a group of transformations Π if the value of the quantity does not change under any $\pi \in \Pi$.

If the action of the transformation group is *regular*, then the number of independent invariant quantities is completely determined by the dimension of the orbit. The collection of invariant quantities then give us a notion of *what is the invariant structure within a set of related tasks*.

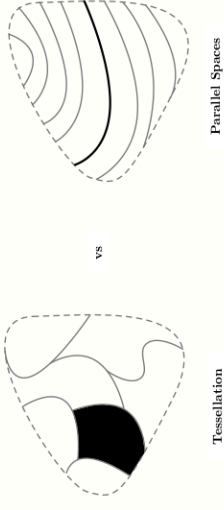


Figure 4: Partitioning of T under similarity vs relatedness.

FOLIATIONS

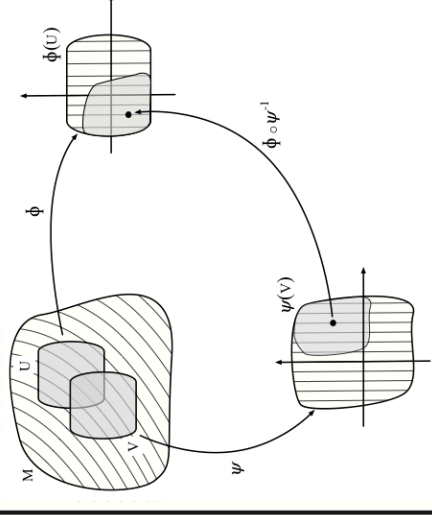


Figure 5: Foliations

A foliation is a formal way of mathematically describing a notion of parallel spaces. It is an additional structure that can be placed on a (smooth) manifold. A foliation is defined by a restriction on the atlas of the manifold.

In particular, a foliation defines a way to consistently define a locally rectified coordinate system on the manifold. That is, we choose an atlas, where the chart transitions keep some coordinates fixed. These consistency requirements mean that when the local open sets are glued together, we get back parallel spaces. In its theory, these parallel spaces are called *leaves*.

Foliations naturally define locally invariant quantities. This is because, locally on a leaf, a subset of the dimensions of the coordinates must, by definition, remain constant.

REFERENCES

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CONTACT INFORMATION

Email: jpetangoda@gmail.com
Twitter: @janithpet