General Solution to a Linear System Eigenvalues and Eigenvectors

 $\begin{array}{l} \text{If } \boldsymbol{b} \in \mathcal{C}\left(\mathbf{A}\right) \! : \ \boldsymbol{x}_g = \boldsymbol{x}_p + \boldsymbol{x}_n \ \text{ where } \\ \boldsymbol{x}_p \in \mathbb{R}^n \text{ and } \boldsymbol{x}_n \in \mathcal{N}\left(\mathbf{A}\right) . \end{array}$ 

Minimum Norm Solution

$$\boldsymbol{x}_r \in \mathcal{C}\left(\mathbf{A}^{\top}\right) \text{ where } \boldsymbol{x}_r = \operatorname{proj}_{\mathcal{C}\left(\mathbf{A}^{\top}\right)}\left(\boldsymbol{x}_q\right).$$

Least Squares (LS)

$$\begin{split} &\text{If } \boldsymbol{b} \notin \mathcal{C}\left(\mathbf{A}\right) : \, \boldsymbol{x} = \arg\min_{\boldsymbol{x}^* \in \mathbb{R}^n} \|\boldsymbol{b} - \mathbf{A} \boldsymbol{x}^*\|. \\ \boldsymbol{b} - \mathbf{A} \boldsymbol{x} \in \mathcal{N}\left(\mathbf{A}\right) \implies \mathbf{A}^\top (\boldsymbol{b} - \mathbf{A} \boldsymbol{x}) = \mathbf{0}. \\ &\mathbf{A}^\top \mathbf{A} \boldsymbol{x} = \mathbf{A}^\top \boldsymbol{b} \quad \text{(Normal Equations)} \end{split}$$

**Orthogonal Projection** 

$$\begin{aligned} \mathbf{P} &= \mathbf{A} \left( \mathbf{A}^{\top} \mathbf{A} \right)^{-1} \mathbf{A}^{\top} \\ \mathbf{P} &\boldsymbol{b} = \operatorname{proj}_{\mathcal{C}(\mathbf{A})} \left( \boldsymbol{b} \right) = \mathbf{A} \boldsymbol{x} \end{aligned}$$

 $\mathbf{P}$  is idempotent  $(\mathbf{P}^2 = \mathbf{P})$  and  $\mathbf{P}^{\top} = \mathbf{P}$ . Dependent Columns

If  $\operatorname{nullity}(\mathbf{A}) > 0$ , NE yields infinitely many solutions as  $\mathcal{N}(\mathbf{A}) = \mathcal{N}(\mathbf{A}^{\top}\mathbf{A})$ .

**Orthogonal Complement Projections** 

Given 
$$\mathbf{P} = \operatorname{proj}_V$$
:  $\mathbf{Q} = \operatorname{proj}_{V^{\perp}} = \mathbf{I} - \mathbf{P}$   
 $\boldsymbol{b} = \operatorname{proj}_V(\boldsymbol{b}) + \operatorname{proj}_{V^{\perp}}(\boldsymbol{b}) = \mathbf{P}\boldsymbol{b} + \mathbf{Q}\boldsymbol{b}$   
 $(\mathbf{P}\boldsymbol{b})^{\top} \mathbf{Q}\boldsymbol{b} = 0$ 

$$\mathbf{PQ} = \mathbf{0}$$
 (zero matrix)

Change of Basis

Given the basis  $W = \{ \boldsymbol{w}_1, \dots, \boldsymbol{w}_n \}$ 

$$\boldsymbol{b} = c_1 \boldsymbol{w}_1 + \dots + c_n \boldsymbol{w}_n$$

$$b = \mathbf{W} c \iff (b)_W = c.$$

## **Orthonormal Basis**

Normalised and orthogonal basis vectors. For  $Q = \{\boldsymbol{q}_1, \dots, \boldsymbol{q}_n\}, \, \boldsymbol{q}_i^{\top} \boldsymbol{q}_j = \delta_{ij}, \text{ where }$ 

$$\delta_{ij} = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases}$$
 $\mathbf{Q} c = b \iff \mathbf{Q}^{\mathsf{T}} b = c = (b)_{C}$ 

**Orthogonal Matrices** 

$$\mathbf{Q}^\top = \mathbf{Q}^{-1} \iff \mathbf{Q}^\top \mathbf{Q} = \mathbf{Q} \mathbf{Q}^\top = \mathbf{I}.$$

Projection onto a Vector

$$\operatorname{proj}_{oldsymbol{a}}(oldsymbol{b}) = oldsymbol{a} \left(oldsymbol{a}^{ op} oldsymbol{a} 
ight)^{-1} oldsymbol{a}^{ op} oldsymbol{b}$$
$$= rac{oldsymbol{a}}{\|oldsymbol{a}\|^2} oldsymbol{a} \cdot oldsymbol{b}$$

Using a unit vector q

$$\operatorname{proj}_{\boldsymbol{q}}\left(\boldsymbol{b}\right) = \boldsymbol{q}\left(\boldsymbol{q}\cdot\boldsymbol{b}\right)$$

## **Gram-Schmidt Process**

Converts the basis W that spans  $\mathcal{C}(\mathbf{A})$ to an orthonormal basis Q.

$$oldsymbol{v}_i = oldsymbol{w}_i - \sum_{j=1}^{i-1} oldsymbol{q}_j ig\langle oldsymbol{q}_j, \; oldsymbol{w}_i ig
angle \quad oldsymbol{q}_i = oldsymbol{v}_i / \lVert oldsymbol{v}_i 
Vert$$

V and Q span W, and V is orthogonal. **QR** Decomposition

A = QR

$$\mathbf{R} = \begin{bmatrix} \| \boldsymbol{v}_1 \| & \langle \boldsymbol{q}_1, \, \boldsymbol{w}_2 \rangle & \cdots & \langle \boldsymbol{q}_1, \, \boldsymbol{w}_n \rangle \\ 0 & \| \boldsymbol{v}_2 \| & \ddots & \vdots \\ \vdots & \ddots & \ddots & \langle \boldsymbol{q}_{n-1}, \, \boldsymbol{w}_n \rangle \\ 0 & \cdots & 0 & \| \boldsymbol{v}_n \| \end{bmatrix}$$

where  $\mathbf{Q}$  is found by applying the Gram-Schmidt process and  $\mathbf{R}$  is upper triangular.  $\mathbf{R} \mathbf{x} = \mathbf{Q}^{\mathsf{T}} \mathbf{b}$  solves LS.

$$\mathbf{A}\mathbf{v} = \lambda\mathbf{v} \iff (\lambda\mathbf{I} - \mathbf{A})\,\mathbf{v} = \mathbf{0}: \mathbf{v} \neq \mathbf{0}$$

Characteristic Polynomial

$$P(\lambda) = \det(\lambda \mathbf{I} - \mathbf{A}) = 0.$$

Eigen Decomposition

$$\begin{aligned} \mathbf{A}\mathbf{V} &= \mathbf{V}\mathbf{D} \iff \mathbf{A} &= \mathbf{V}\mathbf{D}\mathbf{V}^{-1} \\ \mathbf{V} &= \begin{bmatrix} \boldsymbol{v}_1 & \cdots & \boldsymbol{v}_n \end{bmatrix} \\ \mathbf{D} &= \mathrm{diag}\left(\lambda_1, \, \dots, \, \lambda_n\right). \end{aligned}$$

Algebraic Multiplicity  $\mu(\lambda_i)$ 

Multiplicity of  $\lambda_i$  in  $P(\lambda)$ , for  $d \leq n$ distinct eigenvalues,

$$\begin{split} P\left(\lambda\right) &= \left(\lambda - \lambda_1\right)^{\mu(\lambda_1)} \cdots \left(\lambda - \lambda_d\right)^{\mu(\lambda_d)}. \end{split}$$
 In general

$$1 \le \mu\left(\lambda_i\right) \le n$$
 
$$\sum_{i=1}^{d} \mu\left(\lambda_i\right) = n$$

If nullity  $(\mathbf{A}) > 0$ 

$$\exists k: \lambda_k = 0: \mu\left(\lambda_k\right) = \text{nullity}\left(\mathbf{A}\right)$$

Geometric Multiplicity  $\gamma(\lambda_i)$ 

Dimension of the eigenspace associated with  $\lambda_i$ .

$$\begin{split} \gamma\left(\lambda_{i}\right) &= \text{nullity}\left(\lambda_{i}\mathbf{I} - \mathbf{A}\right). \\ \text{Given } d &\leq n \text{ distinct eigenvalues,} \end{split}$$

$$1 \le \gamma(\lambda_i) \le \mu(\lambda_i) \le n$$
$$d \le \sum_{i=1}^{d} \gamma(\lambda_i) \le n.$$

Eigenvectors corresponding to distinct  $\overline{\mathbf{Truncated}}$   $\mathbf{SVD}$ eigenvalues are linearly dependent.

**Defective Matrix** 

A lacks a complete eigenbasis:

$$\exists k : \gamma(\lambda_k) < \mu(\lambda_k)$$

**Matrix Similarity** 

 ${\bf A}$  and  ${\bf B}$  are similar if

$$\mathbf{B} = \mathbf{P}^{-1} \mathbf{A} \mathbf{P}.$$

They share  $P(\lambda)$ , ranks, determinants, traces, and eigenvalues (also  $\mu$  and  $\gamma$ ).

Symmetric Matrices  $\mathbf{S}^{\top} = \mathbf{S}$ 

 ${f S}$  is always diagonalisable and has V is a vector space with vectors  ${m v} \in V$ found through QR: V = QR.

Skew-Symmetric Matrices  $\mathbf{K}^{\top} = -\mathbf{K}$ 

Eigenvalues are always purely imaginary.

Positive-Definite Matrices

**S** is (symmetric) positive definite (SPD) if all its eigenvalues are positive, likewise

$$\boldsymbol{x}^{\top}\mathbf{S}\boldsymbol{x} > 0 : \forall \boldsymbol{x} \in \mathbb{R}^n \setminus \{\mathbf{0}\}$$

**Matrix Functions** 

Given a nondefective matrix:

$$f(\mathbf{A}) = \mathbf{V}f(\mathbf{D})\mathbf{V}^{-1}$$

$$= \mathbf{V}\operatorname{diag}(f(\lambda_1), \dots, f(\lambda_n))\mathbf{V}^{-1}.$$
For the scalar multi-
• Closure:  $k\mathbf{u} \in V$ 

for an analytic function f. Cayley-Hamilton Theorem

$$\forall \mathbf{A} : P(\mathbf{A}) = \mathbf{0} \quad \text{(zero matrix)}$$

Singular Value Decomposition

$$\mathbf{A}\mathbf{V} = \mathbf{U}\mathbf{\Sigma} \iff \mathbf{A} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^{\top}$$
$$\mathbf{V}^{\top} = \mathbf{V}^{-1}. \quad \mathbf{U}^{\top} = \mathbf{U}^{-1}$$

 $\Sigma = \operatorname{diag}(\sigma_1, \ldots, \sigma_r, 0, \ldots, 0).$ Left singular vectors  $\mathbf{u}$ :  $\mathbf{U} \in \mathbb{R}^{m \times m}$ 

$$\mathcal{C}\left(\mathbf{A}\right)=\operatorname{span}\left(\left\{\boldsymbol{u}_{i\leq r}\right\}\right)$$

$$\mathcal{N}\left(\mathbf{A}^{ op}
ight) = \mathrm{span}\left(\left\{oldsymbol{u}_{r < i \leq m}
ight\}
ight)$$

$$\begin{split} \mathcal{N}\left(\mathbf{A}^{\top}\right) &= \operatorname{span}\left(\left\{\boldsymbol{u}_{r < i \leq m}\right\}\right) \\ \text{Right singular vectors } \boldsymbol{v} \colon \mathbf{V} \in \mathbb{R}^{n \times n} \end{split}$$

$$\mathcal{C}\left(\mathbf{A}^{\top}\right) = \mathrm{span}\left(\left\{ oldsymbol{v}_{i \leq r} 
ight\}\right)$$

$$\begin{split} \mathcal{N}\left(\mathbf{A}\right) &= \operatorname{span}\left(\left\{v_{r < i \leq n}\right\}\right) \\ \operatorname{Singular values} \ \sigma_i \colon \ \mathbf{\Sigma} \in \mathbb{R}^{m \times n} \end{split}$$

The eigenvalues of  $\mathbf{A}^{\top}\mathbf{A}$  and  $\mathbf{A}\mathbf{A}^{\top}$  are equal,  $\mathbf{\Sigma}^{\top}\mathbf{\Sigma}$  and  $\mathbf{\Sigma}\mathbf{\Sigma}^{\top}$  have the same diagonal entries, and when m = n,  $\mathbf{\Sigma}^{\top}\mathbf{\Sigma} = \mathbf{\Sigma}\mathbf{\Sigma}^{\top} = \mathbf{\Sigma}^{2}$ . To find  $\sigma_{i}$  compute:

$$\mathbf{A}^{ op}\mathbf{A} = \mathbf{V}\mathbf{\Sigma}^{ op}\mathbf{\Sigma}\mathbf{V}^{ op}$$

$$\mathbf{A}\mathbf{A}^{ op} = \mathbf{U}\mathbf{\Sigma}\mathbf{\Sigma}^{ op}\mathbf{U}^{ op}$$

so that  $\sigma_i = \sqrt{\lambda_i}$  where  $\sigma_1 \ge \cdots \ge \sigma_r > 0$ .

Reduced SVD

Ignores m-n "0" rows in  $\Sigma$  so that  $\mathbf{U} \in \mathbb{R}^{m \times n}$  and  $\mathbf{\Sigma} \in \mathbb{R}^{n \times n}$ .

Pseudoinverse

Consider the inverse mapping  $u_i \mapsto \frac{1}{\sigma_i} v_i$ 

$$\begin{split} \mathbf{A}^{\dagger} \boldsymbol{u}_i &= \frac{1}{\sigma_i} \boldsymbol{v}_i \iff \mathbf{A}^{\dagger} \boldsymbol{u}_i = \frac{1}{\sigma_i} \boldsymbol{v}_i \boldsymbol{u}_i^{\top} \boldsymbol{u}_i \\ \mathbf{A}^{\dagger} &= \sum_{i=1}^{r} \frac{1}{\sigma_i} \boldsymbol{v}_i \boldsymbol{u}_i^{\top} \iff \mathbf{A}^{\dagger} = \mathbf{V} \mathbf{\Sigma}^{\dagger} \mathbf{U}^{\top} \end{split}$$

where  $\Sigma^{\dagger} = \operatorname{diag}\left(\frac{1}{\sigma_1}, \ldots, \frac{1}{\sigma_r}, 0, \ldots, 0\right)$ .  $x = \mathbf{A}^{\dagger} \mathbf{b}$  solves LS.

Express **A** as the sum of rank-1 matrices:

$$\begin{split} \mathbf{A} &= \sum_{i=1}^n \sigma_i \boldsymbol{u}_i \boldsymbol{v}_i^\top \\ \mathbf{A} &= \sum_{i=1}^r \sigma_i \boldsymbol{u}_i \boldsymbol{v}_i^\top \qquad (\sigma_{r < i \leq n} = 0) \end{split}$$

Rank- $\nu$  approximation of **A**:

$$\mathbf{A} pprox ilde{\mathbf{A}} = \sum_{i=1}^{
u} \sigma_i oldsymbol{u}_i oldsymbol{v}_i^{ op}.$$

### General Vector Spaces

real eigenvalues with real orthogonal if the following 10 axioms are satisfied eigenvectors:  $\mathbf{S} = \mathbf{Q}\mathbf{D}\mathbf{Q}^{\mathsf{T}}$ , where  $\mathbf{Q}$  is for  $\forall \boldsymbol{u}, \boldsymbol{v}, \boldsymbol{w} \in V$  and  $\forall k, m \in \mathbb{F}$ , given an addition and scalar multiplication operation.

For the addition operation:

- Closure:  $u + v \in V$
- Commutativity:  $u + v = v + u \in V$
- Associativity:

$$u + (v + w) = (u + v) + w$$

- Identity:  $\exists 0 \in V : u + 0 = 0 + u = u$
- Inverse:  $\exists (-u) \in V : u + (-u) = 0$

For the scalar multiplication operation:

- Distributivity:  $k(\mathbf{u} + \mathbf{v}) = k\mathbf{u} + k\mathbf{v}$
- Distributivity:  $(k+m)\mathbf{u} = k\mathbf{u} + m\mathbf{u}$
- Associativity:  $k(m\mathbf{u}) = (km)\mathbf{u}$
- Identity:  $\exists 1 \in \mathbb{F} : 1u = u$

## **Examples of Vector Spaces**

multiplication.

The set of all functions  $\mathcal{F}(\Omega): \Omega \to \mathbb{R}$ with addition and scalar multiplication defined pointwise.

### Subspaces

The subset  $W \subset V$  is itself a vector space if it is closed under addition and scalar Isomorphism ( $\cong$ ) multiplication.

### **Examples of Subspaces**

## Subspaces of $\mathbb{R}^n$ :

• Lines, planes and higher-dimensional analogues in  $\mathbb{R}^n$  passing through the origin.

# Subspaces of $\mathcal{M}_{nn}$ :

- The set of all symmetric  $n \times n$ . matrices, denoted  $\mathcal{S}_n \subset \mathcal{M}_{nn}$ .
- The set of all skew symmetric  $n \times n$ matrices, denoted  $\mathcal{K}_n \subset \mathcal{M}_{nn}$ .

## Subspaces of $\mathcal{F}$ :

- The set of all polynomials of degree nor less, denoted  $\mathscr{P}_{n}(\Omega) \subset \mathscr{F}(\Omega)$ .
- The set of all continuous functions, denoted  $C(\Omega) \subset \mathcal{F}(\Omega)$ .
- The set of all continuous functions Inner Product Spaces with continuous nth derivatives, denoted  $C^{n}(\Omega) \subset C(\Omega)$ .
- The set of all functions f defined on For  $u, v, w \in V$  and  $k \in \mathbb{R}$ : [0,1] satisfying f(0) = f(1).

## General Vector Space Terminology

Let  $S = \{ \boldsymbol{v}_1, \ldots, \boldsymbol{v}_k \}$  and  $c_1, \ldots, c_k \in \mathbb{F}$ :

- The linear combination of S is a vector of the form  $\mathbf{v} = c_1 \mathbf{v}_1 + \dots + c_k \mathbf{v}_k$ .
- S is linearly independent iff  $c_1 \mathbf{v}_1 + \cdots +$  $c_k \mathbf{v}_k = \mathbf{0}$  has the trivial solution.
- $\operatorname{span}(S)$  is the set of all linear combinations of S.

S is a basis for a vector space V if

- S is linearly independent.
- $\operatorname{span}(S) = V.$

The number of basis vectors denotes the  $\underline{\text{For }f,\;g\in C}\left(\left[a,b\right]\right)$ : dimension of V.

C is infinite dimensional.

## **Examples of Standard Bases**

$$\begin{array}{l} \bullet \quad \mathcal{M}_{22} \colon \\ \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\} \\ \bullet \quad \mathcal{S}_{22} \colon \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\} \\ \bullet \quad \mathcal{K}_{22} \colon \left\{ \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \right\} \\ \bullet \quad \mathcal{R}_{3} \colon \left\{ 1, \, x, \, x^{2}, \, x^{3} \right\} \end{array}$$

## Linear Transformations

$$T: V \to W$$
 satisfying 
$$T(k\mathbf{u}) = kT(\mathbf{u})$$
 
$$T(\mathbf{u} + \mathbf{v}) = T(\mathbf{u}) + T(\mathbf{v})$$

Constructing  $\mathbf{A} = (T)_{B' \cup B}$ :

The set of all  $m \times n$  matrices  $\mathcal{M}_{mn}$  Consider the map of  $(\mathbf{v})_B = \mathbf{x}$  of  $\mathbf{v} \in V$  Given  $\mathbf{P}_{\mathcal{S}_n} = \operatorname{proj}_{\mathcal{S}_n}$  and  $\mathbf{P}_{\mathcal{R}_n} = \operatorname{proj}_{\mathcal{R}_n}$  with matrix addition and scalar matrix to  $(\mathbf{w})_{B'} = \mathbf{b}$  of  $\mathbf{w} \in W$ , where  $B = \mathbf{P}_{\mathcal{S}} = \mathbf{I} - \mathbf{P}_{\mathcal{K}}$  $\{oldsymbol{v}_1,\,\ldots,\,oldsymbol{v}_n\} ext{ and } B' = \{oldsymbol{w}_1,\,\ldots,\,oldsymbol{w}_m\}.$   $T\left(oldsymbol{v}\right) = oldsymbol{w}$ 

$$\begin{split} \left[T\left(\boldsymbol{v}_{1}\right) & \cdots & T\left(\boldsymbol{v}_{n}\right)\right]\boldsymbol{x} = \mathbf{W}\boldsymbol{b} \\ \left[\left(T\left(\boldsymbol{v}_{1}\right)\right)_{B'} & \cdots & \left(T\left(\boldsymbol{v}_{n}\right)\right)_{B'}\right]\boldsymbol{x} = \boldsymbol{b} \\ \mathbf{A}\boldsymbol{x} = \boldsymbol{b} \end{split}$$

 $T:V\to W$  is an isomorphism between Vand W if there exists a bijection between the two vector spaces.

 $\forall V : \dim(V) = n : V \cong \mathbb{R}^n, \, \mathcal{M}_{mn} \cong$  $\mathbb{R}^{mn}$  and  $\mathscr{P}_n \cong \mathbb{R}^{n+1}$ .

# Fundamental Subspaces of T

- The set of all vectors in V that map to •
- The set of all vectors in W that is mapped to by a vector in V is the range of T, denoted range (T).
- The set of all vectors in V that T maps to  $\mathbf{0}_W$  is the **kernel** of T, denoted

If finite, dim (range (T)) = rank (T) and  $\bullet$  For symmetric  $\mathbf{S} \in \mathbb{R}^{n \times n}$ :  $\dim (\ker (T)) = \text{nullity} (T).$ 

 $\operatorname{rank}(T) + \operatorname{nullity}(T) = \dim(V).$ 

$$\langle \cdot, \cdot \rangle : V \times V \to \mathbb{R}.$$

- Symmetry:  $\langle \boldsymbol{u}, \boldsymbol{v} \rangle = \langle \boldsymbol{v}, \boldsymbol{u} \rangle$
- Linearity:

$$\langle oldsymbol{u} + oldsymbol{v}, \ oldsymbol{w} 
angle = \langle oldsymbol{u}, \ oldsymbol{w} 
angle + \langle oldsymbol{v}, \ oldsymbol{w} 
angle$$

- Linearity:  $\langle k\boldsymbol{u}, \, \boldsymbol{v} \rangle = k \langle \boldsymbol{u}, \, \boldsymbol{v} \rangle$
- Positive semi-definitiveness:

$$\langle \boldsymbol{u}, \, \boldsymbol{u} \rangle \geq 0, \, \langle \boldsymbol{u}, \, \boldsymbol{u} \rangle = 0 \iff \boldsymbol{u} = \boldsymbol{0}$$

## For $\boldsymbol{u}, \boldsymbol{v} \in \mathbb{R}^n$ :

- $ullet \ \langle oldsymbol{u}, \, oldsymbol{v} 
  angle = oldsymbol{u} \cdot oldsymbol{v} = oldsymbol{u}^ op oldsymbol{v}.$
- $\langle \boldsymbol{u}, \, \boldsymbol{v} \rangle = \boldsymbol{u}^{\top} \mathbf{A} \boldsymbol{v}$  where **A** is SPD.

For  $\mathbf{A}, \mathbf{B} \in \mathcal{M}_{mn}$ :

•  $\langle \mathbf{A}, \mathbf{B} \rangle = \operatorname{Tr}(\mathbf{A}^{\top}\mathbf{B}).$ 

- $\langle f, g \rangle = \int_{a}^{b} f(x) g(x) dx$ .
- $\langle f, g \rangle = \int_a^b f(x) g(x) w(x) dx$ .

where  $w(x) > 0 : \forall x \in [a, b]$ .

# Norms

- $\|\boldsymbol{v}\| = \sqrt{\langle \boldsymbol{v}, \, \boldsymbol{v} \rangle}.$
- $\|v\| \ge 0$ , and  $\|v\| = 0 \iff v = 0$ .
- $||kv|| = |k|||v|| : \forall k \in \mathbb{R}.$
- $\|u + v\| \le \|u\| + \|v\|$ .

## Examples:

- $\forall \mathbf{A} \in \mathcal{M}_{mn} : \|\mathbf{A}\| = \sqrt{\sum_{i=1}^{m} \sum_{j=1}^{n} a_{ij}^2}.$
- $\forall f \in C([a,b]) : ||f|| = \sqrt{\int_a^b f(x)^2 dx}.$

### Orthogonality

$$\langle \boldsymbol{v}, \, \boldsymbol{v} \rangle = 0.$$

Orthogonal Complements of  $\mathcal{M}_n$ 

Given 
$$\mathbf{P}_{\mathcal{S}_n} = \operatorname{proj}_{\mathcal{S}_n}$$
 and  $\mathbf{P}_{\mathcal{H}_n} = \operatorname{proj}_{\mathcal{H}_n}$ 

$$\mathbf{P}_{\mathcal{S}_n} = \mathbf{I} - \mathbf{P}_{\mathcal{H}_n}$$

$$\mathbf{S} = \mathbf{P}_{\mathcal{S}_n} \mathbf{M} = \mathrm{proj}_{\mathbf{P}_{\mathcal{S}_n}} \left( \mathbf{M} \right) = \frac{\mathbf{M} + \mathbf{M}^\top}{2}$$

$$\begin{split} \mathbf{K} &= \mathbf{P}_{\mathscr{K}_n} \mathbf{M} = \mathrm{proj}_{\mathbf{P}_{\mathscr{K}_n}} \left( \mathbf{M} \right) = \frac{\mathbf{M} - \mathbf{M}^\top}{2} \\ \mathbf{S} &\in \mathscr{S}_n, \, \mathbf{K} \in \mathscr{K}_n, \, \mathrm{and} \, \mathbf{S} + \mathbf{K} = \mathbf{M} \in \mathscr{M}_n. \end{split}$$

- $\mathbf{A}^{\top}\mathbf{A}$  is always positive semi-definite, and  $\mathcal{N}(\mathbf{A}^{\top}\mathbf{A}) = \mathcal{N}(\mathbf{A})$  so that  $\operatorname{rank}(\mathbf{A}^{\top}\mathbf{A}) = \operatorname{rank}(\mathbf{A}).$  $\mathbf{A}^{\top}\mathbf{A}$  is positive definite and  $\mathbf{A}^{\mathsf{T}}\mathbf{A}$  is invertible when nullity  $(\mathbf{A}) = 0$ .
- When A is square and invertible,  $(\mathbf{A}^{\top}\mathbf{A})^{-1} = \mathbf{A}^{-1}\mathbf{A}^{-\top} \text{ and } \mathbf{P} = \mathbf{I}.$   $\mathbf{P}^2 = \mathbf{P} \wedge \mathbf{P}^{\top} = \mathbf{P} \iff \mathbf{P} = \operatorname{proj}_{\mathcal{C}(\mathbf{P})}.$
- W is the **image** of T, denoted im (T). If nullity  $(\mathbf{A}) = 0$ ,  $\mathbf{P} = \mathbf{Q}\mathbf{Q}^{\top}$  using
  - $\mathbf{A}^{\mathsf{T}}\mathbf{A}$  and  $\mathbf{A}\mathbf{A}^{\mathsf{T}}$  share eigenvalues,  $\mathbf{A}^{\top} \mathbf{A} \boldsymbol{v} = \lambda \boldsymbol{v}$

$$(\mathbf{A}\mathbf{A}^{\top})(\mathbf{A}\boldsymbol{v}) = \lambda(\mathbf{A}\boldsymbol{v}).$$

 $\mathbf{A}\mathbf{v} = \mathbf{0} \implies \lambda = 0$ , else  $\mathbf{w} = \mathbf{A}\mathbf{v}$  is an eigenvector of  $\mathbf{A}\mathbf{A}^{\top}$ .

$$\mathbf{S} = \sum_{i=1}^n \lambda_i \boldsymbol{q}_i \boldsymbol{q}_i^\top = \sum_{i=1}^n \lambda_i \operatorname{proj}_{\boldsymbol{q}_i}$$

• For  $\boldsymbol{w} = \mathbf{W} \in \mathbb{R}^{n \times 1}$ :

$$\mathbf{W} = [\hat{m{w}}] \left[ \| m{w} \| 
ight] \left[ 1 
ight] \ \mathbf{W}^{\dagger} = rac{\hat{m{w}}^{ op}}{\| m{w} \|}$$

## Identities

**Theorems** 

- $(\mathbf{A}\mathbf{B})^{\top} = \mathbf{B}^{\top}\mathbf{A}^{\top}$ .
- $(\mathbf{A}\mathbf{B})^{-1} = \mathbf{B}^{-1}\mathbf{A}^{-1}$  if  $\mathbf{A}$ ,  $\mathbf{B}$  invertible.
- $(\mathbf{A}^{\top})^{-1} = (\mathbf{A}^{-1})^{\top}$  if  $\mathbf{A}$  invertible:

$$\mathbf{A}^{\top} \left( \mathbf{A}^{-1} \right)^{\top} = \left( \mathbf{A}^{-1} \mathbf{A} \right)^{\top} = \mathbf{I}$$

$$\left(\mathbf{A}^{-1}
ight)^{ op}\mathbf{A}^{ op}=\left(\mathbf{A}\mathbf{A}^{-1}
ight)^{ op}=\mathbf{I}$$

•  $\langle \mathbf{A} \mathbf{x}, \mathbf{y} \rangle = \langle \mathbf{x}, \mathbf{A}^{\top} \mathbf{y} \rangle$ :

$$\left(\mathbf{A} oldsymbol{x}\right)^{ op} oldsymbol{y} = oldsymbol{x}^{ op} \left(\mathbf{A}^{ op} oldsymbol{y}\right)$$

- If **A** is triangular,  $\det(\mathbf{A}) = \prod_{i=1}^{n} a_{ii}$ .
- For  $\mathbf{A} \in \mathbb{R}^{n \times n}$ :

$$\operatorname{Tr}(\mathbf{A}) = \sum_{i=1}^{n} a_{ii} = \sum_{i=1}^{n} \lambda_{i}$$

$$\det\left(\mathbf{A}\right) = \prod_{i=1}^{n} \lambda_i$$

$$\det\left(\mathbf{A}^{\top}\mathbf{A}\right) = \det\left(\mathbf{A}\right)^{2} = \prod_{i=1}^{n} \sigma_{i}^{2}$$

• For  $\mathbf{A} \in \mathbb{R}^{m \times n}$ :

$$\operatorname{Tr}\left(\mathbf{A}^{\top}\mathbf{A}\right) = \sum_{j=1}^{m} \sum_{i=1}^{n} a_{ij}^{2}$$
$$= \sum_{i=1}^{n} \sigma_{i}^{2}$$

$$\det\left(\mathbf{A}^{\top}\mathbf{A}\right) = \prod_{i=1}^{n} \sigma_{i}^{2}$$