Lecture notes on Analysis and Geometry on Manifolds

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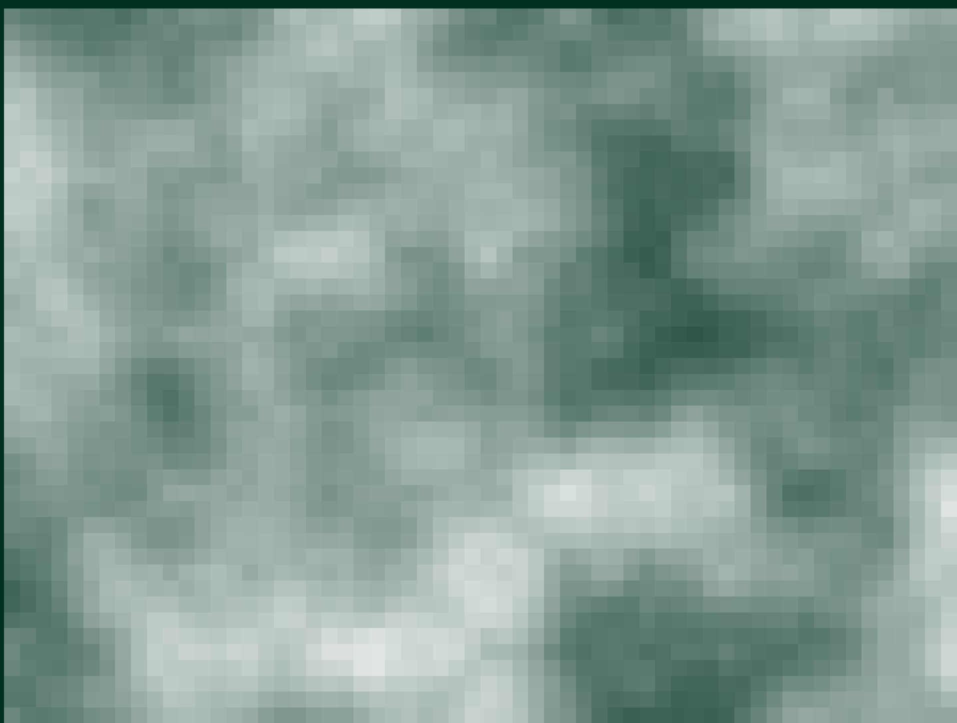

University of Bonn
Winter semester 2024/2025
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Contents

Chapter 0:
Manuel's notes

Warning

These are unofficial lecture notes written by a student. They are messy, will almost surely contain errors, typos and misunderstandings and may not be kept up to date! I do however try my best and use these notes to prepare for my exams. Feel free to email me any corrections to mh@mssh.dev or s6mlhinz@uni-bonn.de.
Happy learning!

General Information

- Basis: Basis
- Website: https://www.math.uni-bonn.de/~lcote/V3D3_2024.html
- Time slot(s): **Tuesday: 14-16** Nussallee Anatomie B and **Friday: 12-14** GHS
- Exams: Tuesday **11.02.2025, 9-11**, Großer Hörsaal, Wegelerstraße 10 and Friday **21.03.2025, 9-11**, Großer Hörsaal, Wegelerstraße 10
- Deadlines: **Friday before noon**

0.1 Organization

Start of lecture 01 (08.10.2024)

- Four exercise classes, in the break come to the front and sign up.
- First homework is due this Friday
- Exercise sheets are due on Fridays, every week electronically (groups, at most 2)
- No published lecture notes by him!
- 5 Minute break right before the full hour
- Friday after class for questions

0.2 Course overview

He assumes we already know about

- Analysis on $\mathbb{R}^n$
- Basic point set topology

For this class: **smooth manifolds** based on [2]

- Intersection between analysis and topology
- Exiting: Connections between those two point of views

Main topics:

Topic 00: Topological manifolds

Topic 01: Basic theory of smooth manifolds

Topic 02: Vector fields on smooth manifolds

Topic 03: Tensor calculus and Stokes' theorem

Topic 04: Lie groups, symplectic and Riemannian geometry

I would also recommend [4] and the notes of Gabriel Ong[**other˙notes˙of˙F4D1**], which are also based on this course

Chapter 1: Topological manifolds

1.1 Some point set topology

Some (set theoretical) conventions for the whole course:

- $A \subset B$ means A subset (not necessarily proper!) of B, i.e. $\subset = \subseteq$
- A **neighborhood** of some point $p \in X$ means *an open set $U \subset X$ containing p*
- Given $p = (p_1, \dots, p_n) \in \mathbb{R}^n, r > 0$, $B_r^n(p) := \{(x_1, \dots, x_n) \mid \sum_{x_i - p_i}^2 < r^2\}$. Often while $B_s = B_s^n(0) \subset \mathbb{R}^n$

1.1.1 Locally Euclidean spaces

Definition. *A topological space X is called **locally Euclidean of dimension** $n \geq 0$, if every point of X is contained in a neighborhood homeomorphic to some open subset of $\mathbb{R}^n$.*

Remark. *When we speak of a topological space as being **locally Euclidean**. The dimension is fixed and implicit.*

Definition. *Assume that X is locally Euclidean. A **chart** is a pair U, ϕ, where $U \subset X$, $\phi : U \to \mathbb{R}^n$ is a homeomorphism into its image. Given $p \in X$, we say that U, ϕ is **centered at** p if $p \in U$ and $\phi(p) = 0 \in \mathbb{R}^n$*

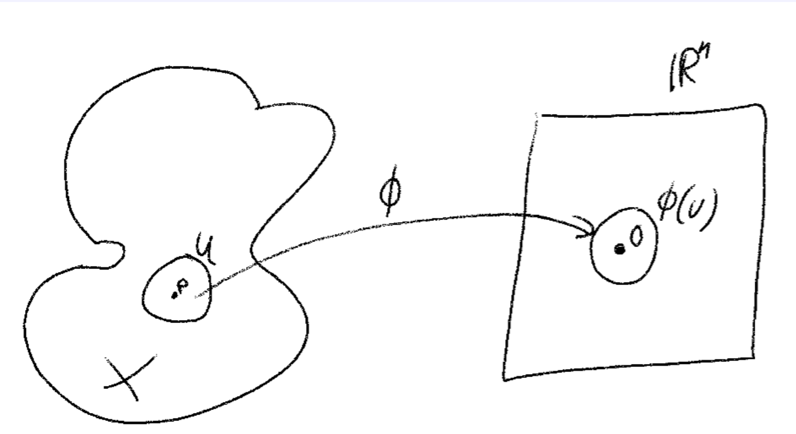

Figure 1.1: Sketch 1.01

Lemma 1.1. *The following are equivalent (TFAE):*

- *X is locally Euclidean*
- *For any $p \in X$, there is a chart U, ϕ centered at p with image $\phi(U) = B_1$*

- *For any $p \in X$, there is a chart U, ϕ centered at p with image $\phi(U) = \mathbb{R}^n$*

Proof. 2. and 3. are equivalent, since $B_1 \simeq \mathbb{R}^n$ are homeomorphic ($B_1^n \ni x \mapsto \frac{x}{1-\|x\|}$)
2. $\implies$ 1. is tautological
1. $\implies$ 2. given $p \in X$, since X is locally Euclidean, there exists **some** chart U, ψ, $p \in U$.
$\psi : U \to \mathbb{R}^n$, homeo onto its image $\psi(U) = O \subset \mathbb{R}^n$. By translativity $\mathbb{R}^n \ni x \mapsto x - \psi(p)$, one can assume $\psi(p) = 0 \in \mathbb{R}^n$. By scaling $\mathbb{R}^n(x \mapsto \lambda x, \lambda > 0)$, can assume $B_1 \subset \psi(U)$. Let $U' = \psi^{-1}(B_1)$, then (U, ψ) as claimed. □

1.1.2 Hausdorff spaces

Definition. *A topological space X is called Hausdorff, if given any $p_1 \neq p_2$,$p_1, p_2 \in X$, there exist neighborhoods $p_1 \in U_1, p_2 \in U_2$ s.t. $U_1 \cap U_2 = \emptyset$.*

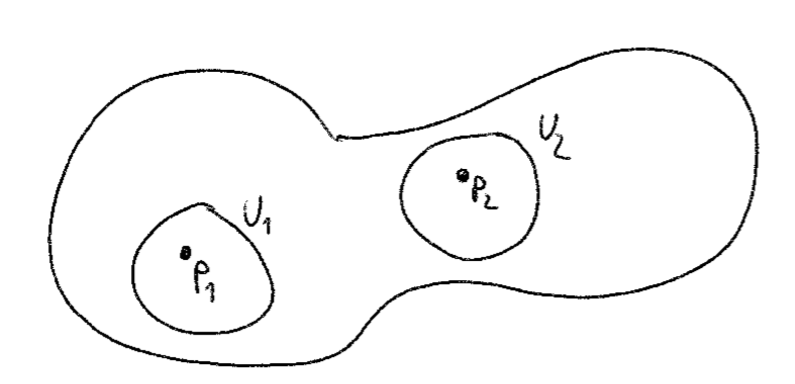

Figure 1.2: Sketch 1.02

Example.
- $\mathbb{R}^n$
- *CW complexes*
- *most reasonable spaces*

Example (Not Hausdorff)**.** *$X = \{0, 1\}$, open subsets $\emptyset, \{0\}, \{0, 1\}$*

Remark. *X is homeomorphic to $\mathbb{R}/\mathbb{R}^*$ (quotient topology), $R^*, (s, x \mapsto sx)$*

Lemma 1.2. *Let X be Hausdorff.*

(a) point sets $\{x\}$ are closed

(b) convergent sequences have unique limits. ($x_n \to p, x_n \to q \implies p = q$)

(c) compact sets are closed

Proof. (c) $\implies$ (a)
For (c): Let $K \subset X$ be compact. Want to show K^c is open. Pick $p \in K^c$. For each $q \in K$, we can choose $U_q \ni q, U_p \ni p : U_q \cap U_p = \emptyset$ Since K is compact, it can be covered by $U_{q_1}, \ldots, U_{q_l}$. Then $\bigcap_{i=1}^l U_{q_i}$ is oen and contains p, disjoint, then $\bigcup_{i=1}^l U_{q_i} \supset K$.

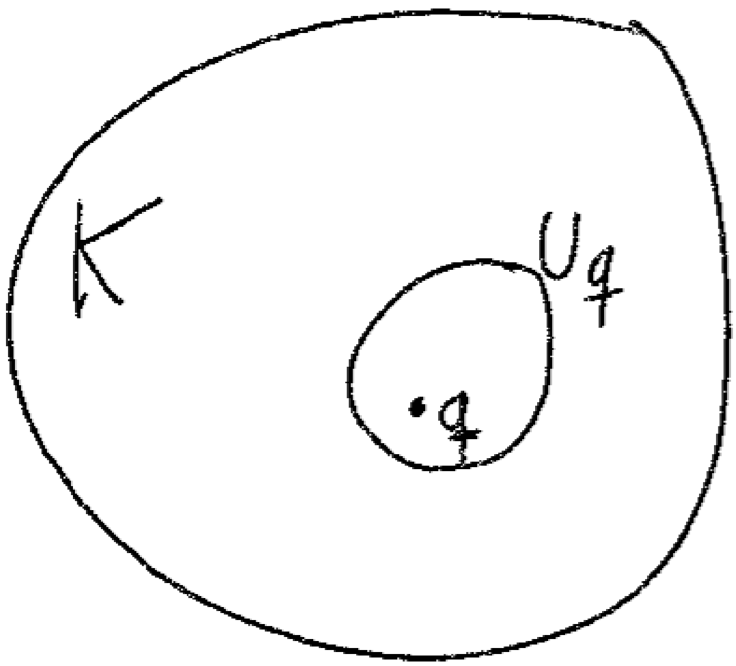

Figure 1.3: Sketch 1.03

(b) Suppose for contradiction that $x_i \to p, x_i \to q$ and $p \neq q$. Since X is Hausdorff, $\exists U \ni p, O \ni q, U \cap O = \emptyset$. But for $N >> 0 x_i \in U, x_i \in O \forall i > N$ $\square$

1.1.3 Basis and covers

Let X be a topological space.

Definition. *A collection $\mathcal{B}$ of subsets of X is called a* ***basis(base)*** *for X, if for any $p \in X$ and any neighborhood $U \ni p$, there exists an element $\mathcal{U} \in \mathcal{B}$ s.t. $p \in \mathcal{U} \subset U$.*

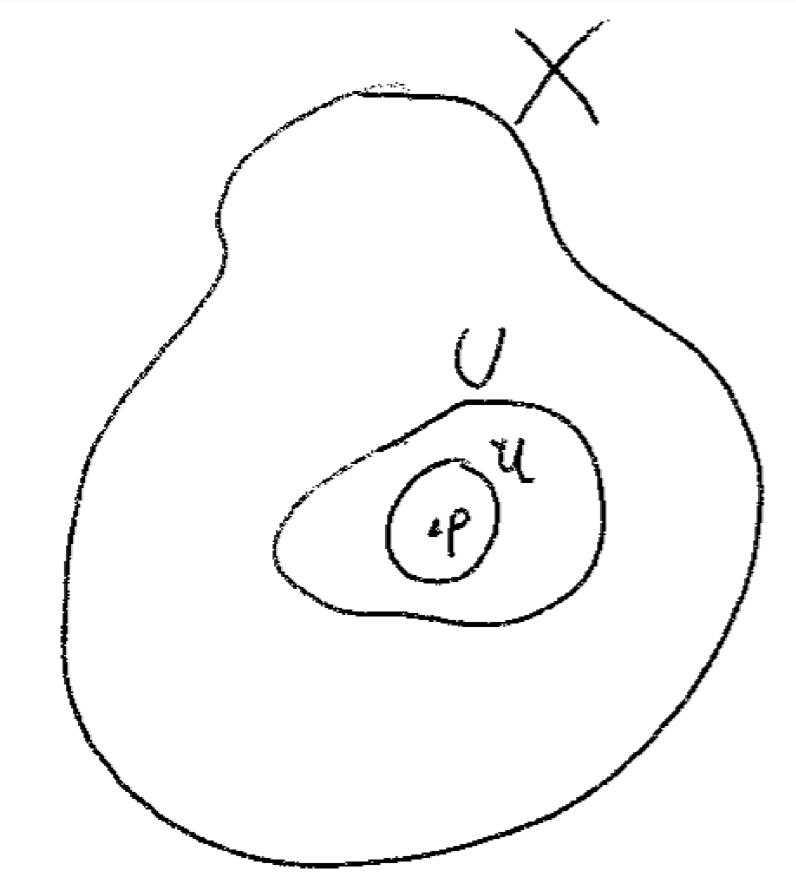

Figure 1.4: Sketch 1.04

Lemma 1.3. *$\mathcal{B}$ is a basis for $X \iff$ every open set of X is a union of elements of $\mathcal{B}$.*

Proof. Trivial. □

Definition. *A topological space X is* ***second-countable*** *if it admits a countable basis.*

Example.
- $\mathbb{R}^n$, $\mathcal{B} = \{B^n_s(p) \mid s \in \mathbb{Q}_+, p = (p_1, \dots, p_n) \in \mathbb{Q}^n \subset \mathbb{R}^n\}$

Lemma 1.4. *The property of being second-countable is closed under*

(a) subspaces

(b) countable disjoint unions

(c) countable products

Remark. *The property of being second-countable is not closed under arbitrary quotients $q : A \to A/B$. An obvious sufficient conditions is for q to be an open map. (Since it is a pushforward)*

When constructing manifolds via quotients, check that it is still second-coutable!

Lemma 1.5. *If X is second countable, then any open cover of X admits a countable subcover.*

Proof. Let $\mathcal{B}$ be a countable basis for X. Let $\mathcal{C}$ be an open cover. Let $\tilde{\mathcal{B}} \subset \mathcal{B}$ be the collection of basis elements U, which are contained in some $\mathcal{U} \in \mathcal{C}$. Observe (key!) $\tilde{\mathcal{B}}$ is a cover of X. For each $U \in \tilde{\mathcal{B}}$, choose $\mathcal{U}_U \in \mathcal{C}$ such that $U \subset \mathcal{U}_U$. Then $\{\mathcal{U}_U\}$ is a countable subcover of $\mathcal{C}$. □

Definition. *Let X be a topological space. An* ***exhaustion of X by compact subsets*** *is a sequence $\{K_i\}_{i\in\mathbb{N}}$, where $K_i \subset X$ compact and $K_i \subset int(K_{i+1})$ and $\bigcup_{i=1}^{\infty} K_i = X$.*

Recall given $A \subset X$. $\mathrm{int}(A) \coloneqq \{x \in A \mid x \text{ in a neighborhood } U \subset A\}$.

Lemma 1.6. *If X is locally Euclidean, Hausdorff[a] and second countable. Then X admits an exhaustion by compact subsets.*

[a]not needed

Proof. Since X is locally Euclidean, admits a basis $\mathcal{B}$ of open subsets having compact closure.

That is take the close of $B_{\frac{1}{2}} \subset \mathbb{R}^n$

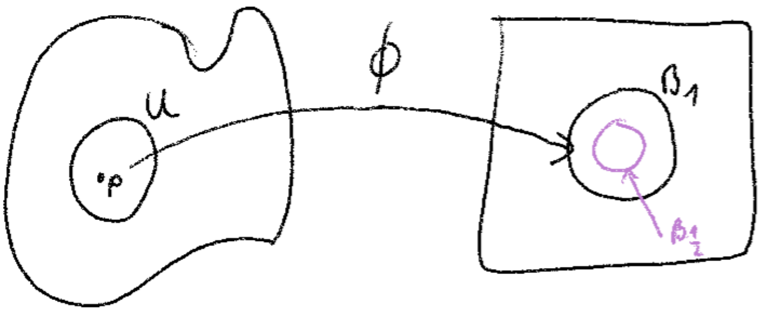

Figure 1.5: Sketch 1.05

By Lemma 1.5, one can extract a countable subcover $\{U_i\}_{i=1}^{\infty}$. Set $K_1 = \overline{U_1}$. Assume that we already constructed $K_1, \ldots, K_k$ such that $U_j \subset K_j$ and $K_{j-1} \subset \operatorname{int}(K_j), j \geq 2$. Since K_k is compact and $K_k \subset X = \bigcup_{i=1}^{\infty} U_i$, then there exists some m_k such that $K_k \subset X = \bigcup_{i=1}^{m_k} U_i$ by compactness. Might as well assume that $m_k \geq k$. Set

$$K_{k+1} = \overline{\bigcup_{i=1}^{m_k} U_i} = \bigcup_{i=1}^{m_k} \overline{U_i}.$$

By construction K_{k+1} is compact, $K_k \subset \operatorname{int}(K_{k+1})$. We get $\{K_j\}_{j=1}^{\infty}$, $U_j \subset K_j$ (because $m_j \geq j$) $\implies \bigcup_{i=1}^{\infty} U_i = \bigcup_{i=1}^{\infty} K_i$ □

Start of lecture 02 (11.10.2024)

Definition. *Let X be a topological space. Let $\mathcal{C}$ be a collection of subsets of X. We say that $\mathcal{C}$ is* ***locally finite*** *if for every $x \in X$ there exists a neighborhood $U \ni x$ such that the intersection of U with all but finitely many elements of $\mathcal{C}$ is empty.*

Example (Example for local finiteness)**.** *Take $X = \mathbb{R}$, $\mathcal{C} = \{(i-1, i+1)\}_{i \in \mathbb{Z}}$.*

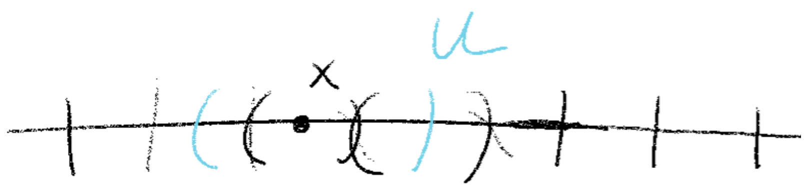

Figure 1.6: Sketch 1.06

Example (Non-example for local finiteness)**.** $X = \mathbb{R}$, $\mathcal{C} = (q-1, q+1)_{q \in \mathbb{Q}}$

Definition. *Let X be a topological space. Let $\mathcal{C}$ be a cover of X. A cover $\mathcal{C}'$ of X is called a* ***refinement of $\mathcal{C}$****, if for all elements $U \in \mathcal{C}'$, there exists such $V \in \mathcal{C}$: $U \subset V$.*

Example (Example of Refinement)**.** *In the proof of lemma 1.5, we showed that any open cover admits a refinement by basis elements.*

Definition. *A topological space X is called* **paracompact** *if every open cover admits a locally finite refinement.*

Whats up with the word **para**compact? It's like compact, but weaker! It is necessary that it only admits a locally finite refinement!

Lemma 1.7. *Let X be Hausdorff and suppose that X admits an exhaustion by compact subsets. Then X is paracompact.In fact, we will show that given any basis $\mathcal{B}$ of X, any open cover admits a locally finite refinement by elements of $\mathcal{B}$.*

Proof. By assumption, $\{K_i\}_{i\in\mathbb{N}}$, K_i compact, $K_i \subset \operatorname{int}(K_{i+1}), \bigcup_{i=1}^{\infty} K_i = X$. Let, for $j \in \mathbb{Z} : V_j = K_{j+1} \setminus \int(K_j)$ if $j \leq 0 : K_j = \emptyset$[1].

Careful! There are many definitions of exhaustion by compact sets ...

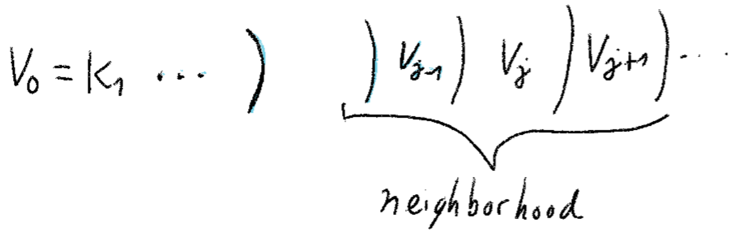

Figure 1.7: Sketch 1.07

Notice:

- V_j is compact, since we take the intersection of a compact set and a closed set. $(\operatorname{int}(K_j)^c$ is closed)
- $\bigcup_{j\in\mathbb{Z}} V_J = X$, since $\bigcup_{j\leq n} = \bigcup_{j\leq n+1} K_j = K_{j+1}$
- The compact sets V_j are intersecting (along their boundary?) $V_j \cap V_{j-1} = \partial K_j := K_j \setminus \operatorname{int}(K_j)$

Evidently $\{U_\alpha \cap \operatorname{int}(K_{j+1}) \cap \operatorname{int}(K_{j-1})^c\}_{\alpha\in\mathcal{A}}$ covers $V_j = K_{j+1} - \setminus K_{j-1}^c$, where the $\{U_\alpha\}_{\alpha\in\mathcal{A}}$ is an open cover. Since $\mathcal{B}$ is a basis, we can find a refinement of this cover by basis elements. Since V_j are compact, we can extract a finite subcover $\{V_l^j\}_{l=1,\dots,k_j}$. Let's consider: $\{V_l^j\}_{j\in Z, l=1,\dots,k_j}$. This subcover works, i.e.

Here we use Hausdorffness

- obviously a cover, since the V_j cover X, obviously a refinement of $\{U_\alpha\}$
- locally finite: given $x \in X, x \in V_j$, hence $x \in \operatorname{int}(K_{K_{j+2}}) \cap K_{j-1}^c =: U$. If $U \cap V_l^k$, then we must have $j-2 \leq k \leq j+2$. But $\{V_l^k\}_{j-2\leq k\leq j+2}$ is finite. □

Corollary 1.8. *If X is locally Euclidean, Hausdorff and second countable $\implies$ X is paracompact.*

Proof. By lemma 1.6 (exhaustion by compact subsets) and lemma 1.7 $\implies$ paracompact. □

Corollary 1.8'. *Let X be Euclidean amd Hausdorff. Then X is second countable iff X has countably many components and X is paracompact.*

Remark. *There are different definitions of manifolds. They differ in either forcing second countability or paracompactness. This lemma shows that there only is a difference if there are uncountably many components.*

Proof. Corollary 1.8 and the bonus homework problem from sheet 01. □

Remark. *Basis elements are open.*

1.2 Topological manifolds

[1]He writes $-$ for $\setminus$

Definition. *A* ***topological*** n***-manifold*** M *is a topological space with the following properties:*

(i) M *is locally Euclidean (of dimension* n*)*

(ii) M *is Hausdorff*

(iii) M *is second countable*

Morally we only really need condition (i). Why do we need the others? For (ii) you will not get a useful theory without it, while (iii) can be replaced by paracompactness (see corollary 1.8').

Definition. *Let* Man^0 *be the category of topological manifolds with*

1. *objects: topological manifolds*
2. *morphisms: continuous functions*

Remark. Man^0 *full subcategory of Top.*

Remark. *By definition,* $M, N \in Man^0$*, then* M, N *are isomorphic iff* M, N *are homeomorphic.*

1.2.1 Examples of topological manifolds

Example (Spaces isomorphic to R^n)**.** $\mathbb{R}^n, n \geq 0$ *More generally, if* V *a finite dimensional* $\mathbb{R}$*-vector space, then* V *is a topological* n*-manifold.*

Example. *Any open subset of* $\mathbb{R}^n$

Example (Graphs)**.** *Let* $U \subseteq \mathbb{R}^n$ *open, let* $f : U \to \mathbb{R}^n$ *be a continuous function. We set*

$$M \coloneqq \mathit{graph}(f) \coloneqq \{(x, y) \in U \times \mathbb{R}^n \mid y = f(x)\}.$$

Then M *is a manifold. The map* $M \to U$ *by* $(x, y) \mapsto U$ *gives a global chart.*

Example (Spheres)**.** *Let* $S^n \coloneqq \{x_0^2 + \cdots + x_n^2 = 1\} \subset \mathbb{R}^{n+1}$*. Then* S^n *is a manifold. We define charts*

$$\phi_i^\pm : U_i^\pm = \{(x_0, \dots, x_n) \in S^n \mid \pm x_i > 0\} \to B_1^n(0)$$

by $(x_0, \dots, x_n) \mapsto (x_0, \dots, \hat{x}_i, \dots, x_n) \coloneqq (x_0, \dots, x_{i-1}, x_{i+1}, \dots, x_n)$

Here we no longer have a global chart (for topological reasons)

Figure 1.8: Sketch 1.08

Example (spheres'). *Let* $C^n := \partial([-1,1]^{n+1}) = [-1,1]^{n+1} \setminus int([-1,1]^{n+1})$. *Homework:* $C^n \simeq S^n$ *(homeomorphic)*

Example (n-torus). *Let* $\Pi^n := \mathbb{R}^n/\mathbb{Z}^n$ *with the quotient topology. Then this is a manifold (exercise).*

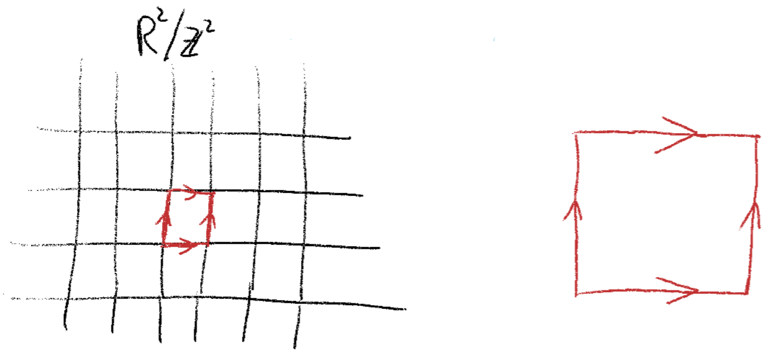

Figure 1.9: Sketch 1.09

Example ($\mathbb{RP}^n := S^n/\{x \sim -x\}$). $\mathbb{RP}^n$ *are also manifolds (called the real projective spaces).*

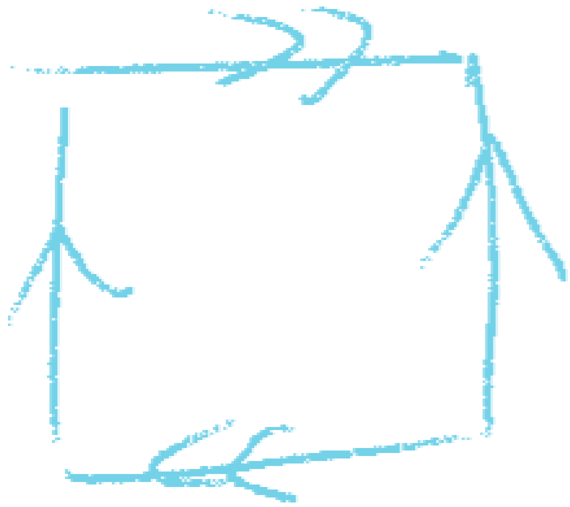

Figure 1.10: Sketch 1.10

Example (Klein bottle)**.**

Remark. $\mathbb{RP}^2$ *or generally* $\mathbb{RP}^{2n}$ *and the Klein bottle are not orientable.*

1.2.2 Brief interlude: Why do we need Hausdorffness?

- Back in the day (Riemann)
- There is no hope to classify even 1d locally Euclidean, second-countable NOT Hausdorff spaces (See the line with two origins)
- With Hausdorff: Only 1d manifolds are $\mathbb{R}, S^1$ (see website)

Why do we need second countability?

- Subspaces of $\mathbb{R}^n$ are second countable
- We want partitions of unity (paracompactness suffices for that)

1.2.3 Manifolds with boundary

Let $\mathbb{H}^n := \{(x_1, \dots, x_n) \in \mathbb{R}^n \mid x_n \geq 0\}$.

Definition. *A* ***manifold with boundary*** *is a topological space with the following properties:*

(i) Every point has a neighborhood homeomorphic to an open subset of $\mathbb{H}^n$

(ii) Hausdorff

(iii) second countable

Clearly every manifold is also a manifold with boundary.

Example. $\mathbb{H}^n$ *is a manifold with boundary, but not a manifold. Since for points on the boundary, there are no neighborhoods homeomorphic to Euclidean space.*

Example. $S^n \cap \mathcal{H}^{n+1}, S^n \subset \mathbb{R}^{n+1}$, $[a, b], [0, \infty)$

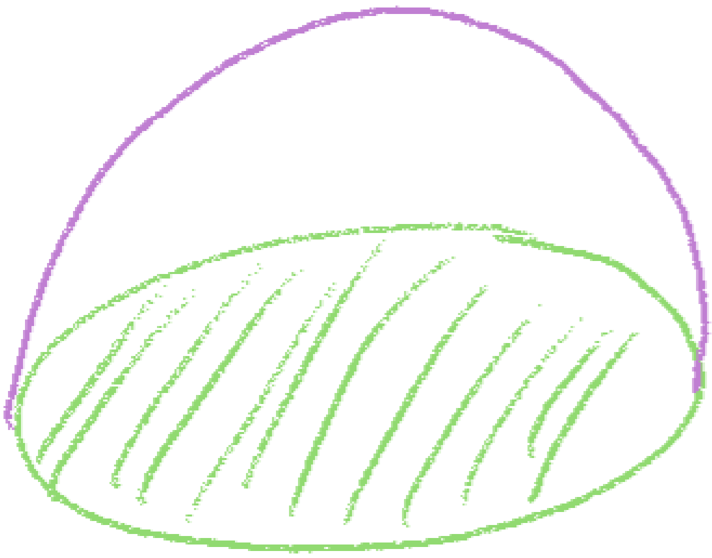

Figure 1.11: Sketch 1.12

Definition. *If M manifold with boundary, we say x is a* ***boundary point****, if $x \in M \setminus int(M)$ (i.e. it has no neighborhood homeomorphic to Euclidean space?), otherwise x is an iterior point. We let $\partial M := \{boundary\ points\}$.*

Start of lecture 03 (15.10.2024)

Remark. *Most of what he says in the course can be generalized to manifolds with boundary (unless it makes no sense). Those results are only stated (and proofed) for manifolds. it might be a good exercise to go through the notes and generalize the statements to manifolds with boundary.*

1.2.4 Elementary topological properties of topological manifolds

Not proved here, but we are welcome to use

- A manifold is connected iff it is path connected
- For manifolds, all forms of compactness (ordinary compactness (every open cover has a finite subcover), limit point compactness, sequential compactness) are equivalent
- All manifolds are metrizable (Urysohn metrization theorem + second countable $\implies$ metrizable)
- Any manifold is homotopy equivalent to a countable CW complex (Milner?) $\pi_k(M)$ are countable

The first two point were proven on the first sheet. The last two use countability

1.3 Classification of topological manifolds (proofs are not examinable)

1.3.1 Classification of 1-dimensional manifolds

Theorem 1.9. *Any connected one dimensional manifold is homeomorphic to*

- $\mathbb{R}^1$ *or*
- $\mathbb{H}^1$

Proof. See Course website: [1] in the form of a take-home exam □

Remark. *If you allow a boundary, then you also have* $[0,1], [0,1)$.

1.3.2 Classification of 2-dimensional manifolds

2-dimensional manifolds are often called surfaces

- $S^2 = \{(x_0, x_1, x_2) \in \mathbb{R}^3 \mid \sum_{i=0}^2 x_i^2 = 1\}$
- $\Pi^2 \coloneqq \mathbb{R}^2/\mathbb{Z}^2$
- $\mathbb{RP}^2 = S^2/\{x \sim -x\}$

Construction(Connected sum of surfaces):

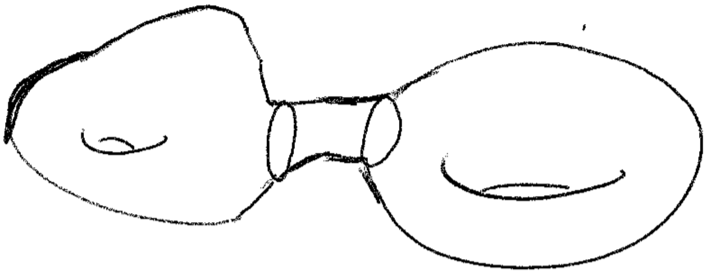

Figure 1.12: Sketch 1.14

Let M_1, M_2 be surfaces (i.e. 2-dimensional manifolds). Choose charts $M_i \supset U_i \xrightarrow{\phi_i} B_1 \subset \mathbb{R}^2$. Let $\mathring{M}_i = M_i \setminus \phi_i^{-1}(B_{\frac{1}{2}})$. Let $M_1 \# M_2 \coloneqq \mathring{M}_1 \perp \mathring{M}_2/\sim$, where $X \in \mathring{M}_1 \sim y \in \mathring{M}_2$ if $x \in \phi_1^{-1}(\partial \overline{B_{\frac{1}{2}}})$ and $y = (\phi_2^{-1} \circ \phi_1)(x)$
Facts:

- If M_1, M_2 are connected, then $M_1 \# M_2$ is well defined up to homeomorphism.
- The operation of connected sum is also well defined for connected n-manifolds
- (for the future) The operation of connected sum also works in the smooth category.

Theorem 1.10 (Classification of surfaces)**.** *Every compact, connected surface is homeomorphic to one of the following manifolds:*

- S^2
- $\underbrace{\Pi^2 \# \ldots \# \Pi^2}_{k \text{ times}}$
- $\underbrace{\mathbb{RP}^2 \# \ldots \# \mathbb{RP}^2}_{l \text{ times}}$ *(non-orientable)*

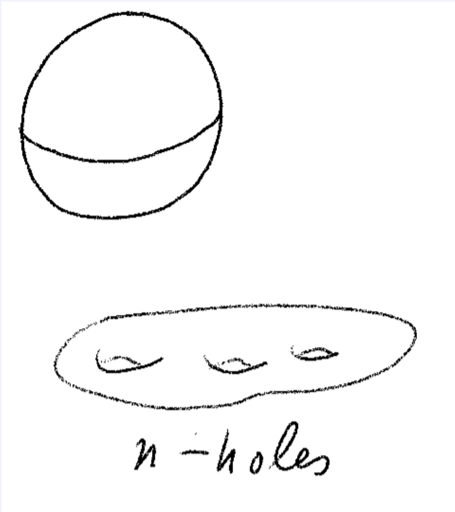

Figure 1.13: Sketch 1.15

Remark. *Surfaces are classified by the following invariants:*

(a) orientability

(b) Euler characteristic

For later: This classification also works in the smooth category.

1.3.3 Classification of high dimensional manifolds (not examinable at all)

Poincaré conjecture (now theorem of G. Perelman (2003), W. Thurston (1980s)): Any compact connected 3 dimensional manifold which is **simply connected** is homeomorphic to S^3. This paper is all about PDEs and Ricci flows.
Generalized Poincaré conjecture: Any n-manifold, which is homotopy equivalent to S^n is homeomorphic to S^n. This is true in all dimensions. for $n \geq 5$ Smale in the 1960s, for $n = 4$ Freedsen in the 1980s.
Unlike in dimension 1,2,3 the classification of $n \geq 3$-dimensional manifolds is complicated and not complete.

Example. *Any finitely presented group arises as the fundamental group of a compact connected* 4-*manifold(Which is provably too hard).*

Chapter 2:
Smooth manifolds

2.1 Basic theory

2.1.1 Charts and atlases

Definition. *Given $U \subset \mathbb{R}^n$ open, a function $f : U \to \mathbb{R}^m, f = (f_1, \dots, f_m)$ is called* ***smooth*** *(or* $\mathbb{C}^\infty$ *or* ***infinitely differentiable****), if the* ***component functions*** *f_i admit all partial derivatives of all orders and all these partial derivatives are continuous.*

In other words f smooth: $\iff \forall 1 \le i \le m, \alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n, \partial_\alpha f := \partial_{x_1}^{\alpha_1} \dots \partial_{x_n}^{\alpha_n} f$ exists.

Remark. *Given $k \ge 0$, we can similarly say hat f is* ***k-times continuously differentiable*** *and write ($f \in$) and write $f \in C^k(U, \mathbb{R}^m)$, if for all $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n, \sum \alpha_i \le k$ $\partial_x^\alpha f_i$ is continuous for all i.*

Definition. *Let M be a topological manifold. We say that two charts (U_1, ϕ_1), (U_2, ϕ_2) are* ***smoothly compatible*** *if the map $\phi_2 \circ \phi_1^{-1} : \phi_1(U_1 \cap U_2) \to \phi_2(U_1 \cap U_2)$ is smooth. We call $\phi_2 \circ \phi_1^{-1}$ a* ***transition function****.*

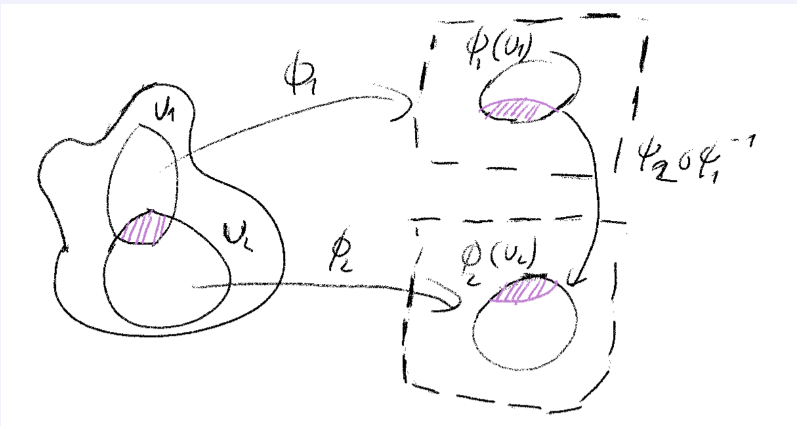

Figure 2.1: Sketch 2.01

Definition. *Let M be a topological manifold. An* ***(smooth) atlas*** *$\mathcal{A}$ of M is a collection of charts $\{U_\alpha, \phi_\alpha\}_{\alpha \in \mathcal{A}}$ such that*

- *the $\{U_\alpha\}$ cover M*
- *the charts are pairwise smoothly compatible (i.e. for all $\alpha, \beta \in \mathcal{A}(U_\alpha, \phi_\alpha), (U_\beta, \phi_\beta)$ are smoothly compatible).*

Definition. *We say that two atlases $\mathcal{A}, \mathcal{A}'$ (on a fixed topological manifold) are* ***equivalent****, if their union $\mathcal{A} \cup \mathcal{A}'$ is still an atlas.*

Fact(Sheet 03): This defines an equivalence relation.

Definition. *A* ***smooth manifold*** *$M = (M, [\mathcal{A}])$ consists of the following data:*

(i) a topological manifolds M

(ii) an equivalence class of smooth atlases

Remark.

- *typically, we will designate smooth manifolds by a capital letter, e.g. M. But we always mean $(M, [\mathcal{A}])$.* ***Note*** *being a smooth manifolds is* ***extra*** *structure on a topological space, while being a topological manifold is a property*

- *Using Zorn's lemma, it can be shown that any atlas is contained in a* ***unique maximal atlas****. Uniqueness here does not use Zorn's lemma, only existence needs that! Equally well define a smooth manifold to be a topological manifold and a maximal atlas.*

- *$\forall 0 \leq k \leq \infty$, we can define the notion of a C^k-atlas, simply by requiring that the transition functions are C^k functions. This yields the definition of C^k-Manifolds. Two extreme cases: C^0-manifold (topological manifolds) and C^∞-manifolds. Any $k \geq 1$ is not more interesting than C^∞!*

Typically we are given an atlas, since the maximal atlases have uncountably mani charts, which is why we work with equivalence classes, rather than maximal atlases

Start of lecture 04 (18.10.2024)

2.1.2 First examples of smooth manifolds

Example (Example 1: The cannoical smooth manifold)**.** *$\mathbb{R}^n, n \geq 0$ is* ***canonically*** *a smooth manifold. The* ***canonical atlas*** *is induced by the topological chart $U = \mathbb{R}^n, \phi : U \overset{id}{\to} \mathbb{R}^n$.*

Example (Example 2: Another canonical smooth manifold)**.** *Let V be a finite dimensional real vector space . Then V is canonically a smooth manifold. Pick a vector space basis $\mathcal{B}$. This basis induces a homeomorphism $\phi_{\mathcal{B}} : V \to \mathbb{R}^n$. If we had picked another basis $\mathcal{B}'$, then then the transition map $\phi_{\mathcal{B}'} \circ \phi_{\mathcal{B}}^{-1} \in GL(n, \mathbb{R})$. Hence $\phi_{\mathcal{B}'} \circ \phi_{\mathcal{B}}^{-1}$ is smooth.*

Example (Example 3: Spheres)**.** *We have $S^n_c \coloneqq \{(x_0, \ldots, x_n) \in \mathbb{R}^{n+1} \mid \sum_{i=0}^n x_i^2 = c^2\}$ for $c > 0$. Let $\phi_i^\pm : \underbrace{U_i^\pm}_{\coloneqq\{(x_0,\ldots,x_n)\in S^n_c \mid \pm x_i > 0\}} \to B^n_c$. Then*

$\phi_j^\pm \circ (\phi_i^{pm})^{-1} (y_1, \ldots, y_n) = \phi_j^\pm \left(y_1, \ldots, \pm\sqrt{c^2 - \sum y_i}, \ldots, y_n\right)$, *where $(y_1, \ldots, y_n) \in B^n_c$.*

$$= \begin{cases} (y_1, \ldots, y_n) & i = j \\ (y_1, \ldots, \sqrt{c^2 - \sum y_k}, \ldots, \hat{y_j}, \ldots, y_n) & j > i \\ (y_1, \ldots, \hat{y_{j+1}}, \ldots, \sqrt{c^2 - \sum y_k}, \ldots, y_n) & j < i \end{cases} \tag{1}$$

We conclude $\{U_i^\pm, \phi_i^\pm\}$ is a smooth atlas.

Example (Example 4: Level sets)**.** *Let $\Phi : \mathbb{R}^{n+1} \to \mathbb{R}$ be a smooth function. Fix $c \in \mathbb{R}$. Recall that the set $\Phi^{-1}(c) = \{x \in \mathbb{R}^{n+1} \mid \Phi(x) = c\}$ is called a* ***level set*** *of value c.* ***Suppose*** *that, $\forall p \in \Phi^{-1}(c) : D \underbrace{\Phi(p)}_{=(\partial_{x_0}\Phi(p), \ldots, \partial_{x_n}\Phi(p))} \neq 0$. This means that $\exists 0 \leq i \leq n$ s.t. $\partial_{x_i}\Phi(c) \neq 0$. By the* ***implicit function theorem*** *(Lee, Theorem C.40, Course website), there exists a neighborhood U of p such that $U \cap \Phi^{-1}(p) = \{(x_0, \ldots, f(x_0, \ldots, \hat{x_i}, \ldots, x_n), x_n)\}$.*

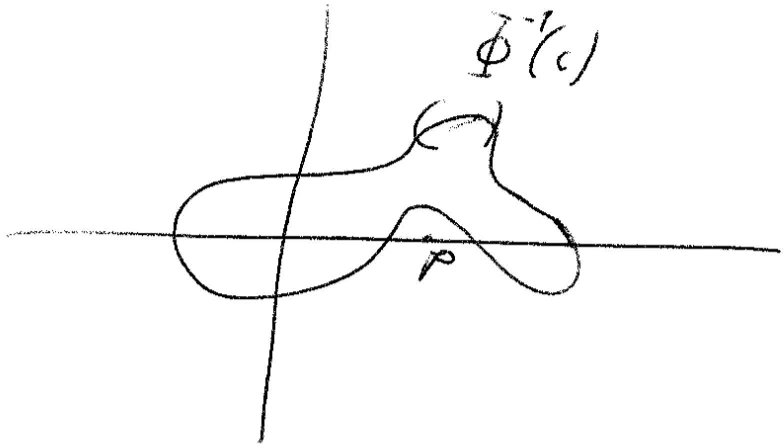

Figure 2.2: Sketch 2.02

Let $M = \phi^{-1}(c)$. We define $\hat{\pi}_i : \mathbb{R}^{n+1} \to \mathbb{R}^n, (x_0, \dots, x_n) \mapsto (x_0, \dots, \hat{x_i}, \dots, x_n)$.

$$\{(U, \hat{\pi}_i) \mid U \subset M, \hat{\pi}_i \mid_U \text{ homeomorphism, } \partial_{x_i}\Phi \neq 0 \text{ on } U\}$$

Remains to check the formula:

$$\hat{\pi_j} \circ \hat{\pi_i}^{-1}(y_1, \dots, y_n) = \begin{cases} (y_1, \dots, f, \dots, \hat{y_j}, \dots, y_n) & j > i \\ (y_1, \dots, \hat{y_{j+1}}, \dots, f, \dots, y_n) & i < j \\ (y_1, \dots, y_n) & i = j \end{cases}$$

Remark. *The condition $D\Phi \neq 0$ is very explicit! It is very easy to generate lots of manifolds. For example: $\Phi(x) = \sum \lambda_i x_i^2$*

Example (Example 5: Subset of smooth manifold)**.** *Let M be a smooth manifold. Then $U \subset M$ open, is also a smooth manifold. (Take charts of M and intersect / restrict each chart)*

Example (Example 6: Product of manifolds)**.** *Let M, N be smooth manifolds. Then $M \times N$ is also a smooth manifolds. Take as charts*

This takes care of the torus!

$$\{(U \times V, (\phi, \psi)) \mid (U, \phi), (V, \psi) \text{ charts of M,N respectively}\}$$

Example (Example 7:)**.** *Let's consider $\mathbb{R}$. We define a chart $\mathbb{R} \to \mathbb{R}, x \mapsto x^3$. Observe that*

*This is one to pay **attention** to!*

$$M = (U = \mathbb{R}, U \xrightarrow{id} \mathbb{R})$$

and

$$N = (U = \mathbb{R}, U \xrightarrow{x \mapsto x^3} \mathbb{R})$$

are smooth manifolds, which are different! Since the transition functions between them are not smooth:
Indeed $id \circ (x \mapsto x^3)^{-1} = (x \mapsto x^{\frac{1}{3}})$, which is not smooth!

2.1.3 Smooth maps

Definition. *Let M be a smooth manifold. A map $f : M \to \mathbb{R}^m$ is said to be **smooth**, if for all $p \in M$, there exists a chart (U, ϕ) containing p, such that*

$$f \circ \phi^{-1} : \underbrace{\phi(U)}_{\subset \mathbb{R}^n} \to \mathbb{R}^m$$

is smooth.

Definition. *Let M, N be manifolds. We say $f : M \to N$ is* ***smooth*** *if, for all $p \in M$ there exists charts (U, ϕ) with $p \in U \subset M$ and (V, ψ) with $V \subset N$ such that:*

- $V \supset f(U)$
- $\psi \circ f \circ \phi^{-1} : \underbrace{\phi(U)}_{\subset \mathbb{R}^n} \to \mathbb{R}^m$ *is smooth*

manifolds = smooth manifolds as always (unless otherwise stated)

Reality check.

Lemma 2.1. *Smooth maps are continuous.*

Proof. Enough to show that $\forall p \in M$, there exists a neighborhood of p on which $f : M \to N$ is continuous, for f smooth. By definition $\exists (U, \phi), p \in U, (V, \psi), V \subset N$ s.t.
$\psi \circ f \circ \phi^{-1} : \phi(U) \to \mathbb{R}^m$ smooth.
Observe $f = \psi^{-1} \circ (\psi \circ f \circ \phi^{-1}) \circ \phi$ on U. □

Lemma 2.2. *$f : M \to N$ is smooth if and only if each $p \in M$ has a neighborhood U such that $f\mid_U$ is smooth.*

Proof. Sheet 03. □

Lemma 2.3 (Properties of smooth maps)**.** *(i) Any constant map $c : M \to N$ is smooth*[a]

(ii) The identity map $id : M \to M$ is smooth

(iii) If $U \circ M$ open, then the inclusion $i : U \hookrightarrow M$ is smooth

(iv) Compositions of smooth functions are smooth

[a]Since it sends M to a point in N

Proof. Sheet 03. □

Definition. *Let M, N be manifolds. A* ***diffeomorphism*** *$f : M \to N$ is a smooth map, which is bijective and admits a smooth inverse.*

In particular, diffeomorphisms are homeomorphism!

Example. *$f : \mathbb{R} \to \mathbb{R}, x \mapsto x + 3$ is a diffeomorphism with inverse $x \mapsto x - 3$.*

Example. *Let $A \in GL(n, \mathbb{R})$. Define a map*

$$f_A : \mathbb{R}^n \to \mathbb{R}^n, x \mapsto Ax.$$

This is a diffeomorphism (smooth, since linear) with inverse $f_A^{-1} = f_{A^{-1}}$.

Example. *Let $S_c^n \coloneqq \{(x_0, \dots, x_n) \mid \sum_{i=0}^n x_i^2 = c^2\} \subset \mathbb{R}^{n+1}$. Given $d > c > 0$, we define a diffeomorphism.*

$$S_c^n \to S_d^n, (x_0, \dots, x_n) \mapsto \frac{d}{c}(x_0, \dots, x_n).$$

Example. *$M = (\mathbb{R}, id), N = (\mathbb{R}, x \mapsto x^3)$. The map $M \to N, x \mapsto x^{\frac{1}{3}}$ is a diffeomorphism. Indeed,*

$$(x \mapsto x^3) \circ (x \mapsto x^{\frac{1}{3}}) \circ id^{-1} = id$$

2.1.4 The category of smooth manifolds

Definition. *Let Man^∞ be the category of smooth manifolds. The objects are the smooth manifolds. The morphisms are the smooth maps.*

Exercise: M, N objects in Man^∞ are isomorphic if and only if they are diffeomorphic.
Observe that there is a forgetful functor: $\mathrm{Man}^\infty \to \mathrm{Man}^0$ by $(M, [\mathcal{A}]) \to M$ and $f : M \to N \mapsto f$.
In general:

- not full
- not essentially surjective

Remark (Hierarchy of categories). • *for $k = 0, \ldots, \infty$, we can consider the category Man^k with objects C^k-Manifolds, and morphisms C^k-maps. for $k \leq l$ there is a forgetful functor $Man^l \to Man^k$*

- *if $k \geq 1$,then the forgetful functor $Man^\infty \to Man^k$ is essentially surjective. This is different from the C^0 case. For this reason, we mainly focus on Man^0, Man^∞. This is a theorem by Whitney*
- *there are other interesting categories: $Man^{\text{Real-analytic}}, Man^{\text{Cplx-analytic}}, \ldots$, which both come with a forgetful functor to Man^∞*

Remark (Classification of manifolds (not examinable)). • *all topological manifolds of dimension ≤ 3 admit a unique smooth structure*

- *S^7, as a topological manifold, admits 15 pairwise non-diffeomorphic smooth structures. These are called **exotic spheres**. They also exist in higher dimensions (Milan-Kervaire?)*
- *$\mathbb{R}^4$ admits uncountably many pairwise non-diffeomorphic smooth structures (Taubes 1980s)*
- *Open problem(**Smooth 4 dimensional Poincaré conjecture**): Prove or disprove: any smooth 4-manifold, which is homeomorphic to S^4 is diffeomorphic to S^4. Most experts believe this is false!*

Start of lecture 05 (22.10.2024)

2.1.5 Smooth manifolds with boundary

Definition. *A function $f : \mathbb{H}^n \supset U \to \mathbb{R}^k$ is **smooth** if every $p \in U$ admits an open neighborhood $p \in U_p \subset \mathbb{R}^n$ on which f extends to a smooth function. (i.e. there exists $\tilde{f}_p : U_p \to \mathbb{R}^k, \tilde{f}_p$ smooth and $\tilde{f}_p |_{\mathbb{H}^n \cap U} = f$)*

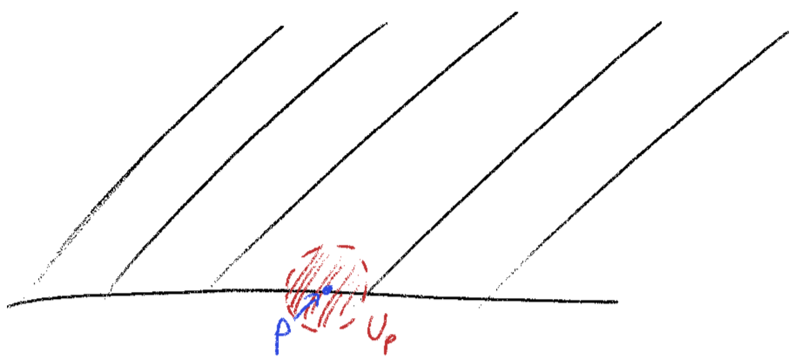

Figure 2.3: Sketch 2.03

Example. $n = 1, \mathbb{H}^1 = [0, \infty), f(x) = x^2$

Example (Non-Example). $n = 1, \mathbb{H}^1 = [0, \infty), f(x) = \sqrt{x}$ *has no smooth extension to* 0*, since the derivative goes to* ∞.

Give a topological manifold with boundary, we can define unproblematically the notions of

- smoothly compatible charts: $(U, \phi) : M \to \mathbb{H}^n$, $\phi_\alpha \circ \phi_\beta^{-1} : \phi_\beta(U_\alpha \cap u_\beta) \to \mathbb{H}^n$
- smooth atlases

Definition. *A smooth manifold with boundary $M = (M, [\mathcal{A}])$ is the data of*

- *a topological manifold with boundary*

- *an equivalence class of atlases*

Remark. *Every smooth manifold is a smooth manifold with boundary. This is an enlargement of* Man^∞.

Similarly we cna generalise even more to manifolds with corners ...

2.2 Partitions of unity

2.2.1 Preparatory lemmas

This section is technical, but also very important!

Lemma 2.4. *The function* $f : \mathbb{R} \to \mathbb{R}$,

$$f(t) = \begin{cases} e^{-\frac{1}{t}} & t > 0 \\ 0 & t \leq 0 \end{cases}$$

is smooth.

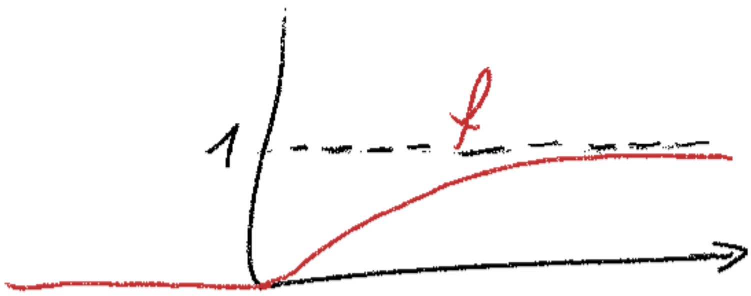

Figure 2.4: Sketch 2.04

Proof. It is enough to proof, that f has well defined derivatives of all orders, since f is a function on $\mathbb{R}$.
$f^0 = f$, for $k \geq 1$, assume

1. $f^{(k-1)}$ exists
2. $f^{(k-1)} \mid_{(-\infty,0]} = 0$
3. $f^{(k-1)} \mid_{(-\infty,0]} (t) = P_{k-1}(\frac{1}{t})e^{-\frac{1}{t}}$ for some polynomial $P_{(k-1)}$.

Clearly this holds for $k = 1$.
We have

$$\begin{aligned} \lim_{t \to 0^+} \frac{f^{(k-1)}(t) - f^{(k-1)}(0)}{t} &= \lim_{t \to 0^+} \frac{f^{(k-1)}(t)}{t} \\ &= \lim_{t \to 0^+} P_{(k-1)}(\frac{1}{t})\frac{1}{t}e^{-\frac{1}{t}} \\ &= \lim_{x \to \infty} P_{(k-1)}(x) \cdot x \cdot e^{-x} = 0 \end{aligned}$$

Therefore $f^{(k-1)}$ is differentiable at the origin, the derivative $f^{(k-1)'}(0) = 0$. and $f^{(k-1)} \mid_{(-\infty,0]} = 0$. Therefore $f^{(k-1)}$ is differentiable. Therefore we only have to check 3., which only takes place on $\mathbb{R}_+$!
Finally
$f^{(k-1)} \mid_{(0,\infty)} (t) = P_{(k-1)}(\frac{1}{t})e^{-\frac{1}{t}} \implies P'_{(k-1)}(\frac{1}{t})\left(\frac{-1}{t^2}e^{-\frac{1}{t}} + P_{(k-1)}(\frac{1}{t})e^{-\frac{1}{t}}\right) =: P_{(k)}(\frac{1}{t})e^{-\frac{1}{t}}$. □

Lemma 2.5. *Fix real numbers* $r_1 < r_2$. *Then there exists a smooth function* $h : \mathbb{R} \to \mathbb{R}$ *such that*

1. $h \equiv 1$ *on* $(-\infty, r_1]$

2. $0 < h < 1$ *on* r_1, r_2

3. $h \equiv 0$ *on* $[r_2, \infty)$

Proof. $h(t) := \frac{f(s_2-t)}{f(s_2-t)+f(t-s_1)}$, since the denominator never goes to 0. □

Lemma 2.6 (Existence of **cutoff functions**)**.** *Given* $0 < r_1 < r_2$*, there exists a smooth function* $H : \mathbb{R}^n \to \mathbb{R}$ *such that*

1. $H \equiv 1$ *on* $\overline{B_{r_1}}$

2. $0 < H < 1$ *on* $B_{r_2} \setminus \overline{B_{r_1}}$

3. $H \equiv 0$ *on* $\mathbb{R}^n \setminus B_{r_2}$

Proof. Set $H(x) := h(|x|)$, where h is defined as in lemma 2.5. (Recall: $|x| := \sqrt{x_1^2 + \cdots + x_n^2}$). Then H is smooth, since it is a composition of smooth functions on $\mathbb{R}^n \setminus \overline{B_{r_1}}$ and constant on $\overline{B_{r_1}}$. □

2.2.2 Partitions of unity

Definition. *Given a topological space* X *and a function* $f : X \to \mathbb{R}$*, the* ***support*** *of* f *is the set*

$$\mathit{supp}(f) := \overline{\{x \in X \mid f(x) \neq 0\}} \subset X$$

Example. *If* $f : \mathbb{R} \to \mathbb{R}$ *has the form* $f(x) = a_0 + a_1 x + \ldots, a_n x^n \implies \mathit{supp}(f) = \mathbb{R}$*. In fact, by Taylor's theorem, if* f *analytic, then* $\mathit{supp}(f)$ *either* $\mathbb{R}$ *or* $\emptyset$*. In contrast, the function* $h : \mathbb{R} \to \mathbb{R}$ *defined in lemma 2.5 has support* $(-\infty, r_2] \subsetneqq \mathbb{R}$*.*

Definition. *Let* M *be a smooth manifold. Let* $\{U_\alpha\}_{\alpha \in \mathcal{A}}$ *be an open cover. A* ***partition of unity subordinate to the cover*** *is the data of a collection of smooth functions* $\{\psi_\alpha\}_{\alpha \in \mathcal{A}}, \psi_\alpha : M \to \mathbb{R}$ *such that*

(1) $0 < \psi_\alpha < 1$

(2) $\mathit{supp}(\psi_\alpha) \subset U_\alpha$

(3) $\{\mathit{supp}(\psi_\alpha)\}_{\alpha \in \mathcal{A}}$ *is locally finite*

(4) $\sum_{\alpha \in \mathcal{A}} \psi_\alpha \equiv 1$

Remark. *There is an analogous notion in the category Top,*Man^0*,* Man^k*, etc.,...*

Example. $M = \mathbb{R}$*,* $U_1 = (-\infty, r_2 + 1), U_2 = (r_1 - 1, \infty)$*, where* $r_1 < r_2$ *as in lemma 2.5. Similarly let* h *as in lemma 2.5. and set* $\psi_1 = h, \psi_2 = 1 - h$

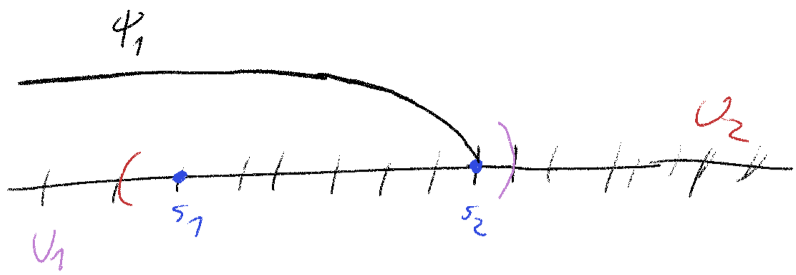

Figure 2.5: Sketch 2.05

Theorem 2.7 (Existence of partitions of unity)**.** *Let* M *be a smooth manifold. Let* $\{U_\alpha\}_{\alpha \in \mathcal{A}}$ *be an open cover. Then there exists a partition of unity subordinate to this cover.*

Remark. *The same theorem works in Top,* Man^0, Man^k*. It will not work in* $Man^{Analytic}$, $Man^{Cplx\text{-}Analytic}$*, Varieties* $/\mathbb{C}$*.*

Proof. **Step 1: Construction of the V_i** An open supset $U \subset M$ is called a **regular coordinate ball** if there exists $\overline{U} \subset \tilde{U}, (\tilde{U}, \tilde{\phi})$ a chart such that $\tilde{\phi}(U) = B_{r_1}, \tilde{\phi}(\tilde{U}) = B_{r_2}$.

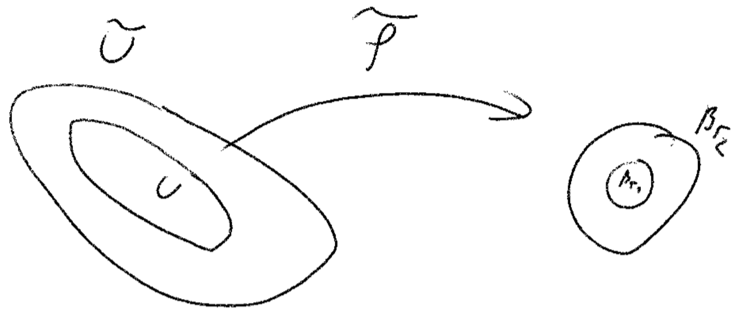

Figure 2.6: Sketch 2.06

By lemma 1.6 M admits an exhaustion by compact sets. By lemma 1.7, given any basis, any open cover, one can find a locally finite, countable basis refinement of this cover by basis elements.
Claim: {regular coordinate balls whose closure is contained in some U_α} basis of M
These tree points imply that $\{U_\alpha\}_{\alpha \in \mathcal{A}}$ admits a countable, locally finite refinement by regular coordinate balls $\{V_i\}_{i \in I}$.

The claim is easy to verify

By sheet 2, exercise 1 (a) $\{\overline{V_i}\}$ is still locally finite.
Step 2: Construction of the f_i For each $V_i \exists V_i \supset \tilde{V}_i, \tilde{\phi}_i : \tilde{V}_i \to \mathbb{R}^n$ such that $\tilde{\psi}_i(V_i) = B_{r_1^i}, \tilde{\psi}_i(\tilde{V}_i) = B_{r_2^i}$ with $0 < r_1^i < r_2^i$, $\tilde{V}_i \subset U_\alpha$ for some α. Using lemma 2.6, let $H_i : \mathbb{R}^n \to \mathbb{R}$ be a cutoff function, i.e. $H_i \mid_{B_{r_1}} > 0, H = 0$ on $\mathbb{R} \setminus B_{r_1^i}$. Let us set

$$f_i : M \to \mathbb{R}, f_i = \begin{cases} H_i \circ \tilde{\phi}_i & \text{on } \tilde{V}_i \\ 0 & M \setminus \overline{V_i} \end{cases}$$

Finging $\tilde{V}_i$ s.t. $\tilde{V}_i \subset U_\alpha$ is the reason we considered regular coordinate balls whose **closure is contained** in some U_α

Step 3: Construction of the g_i Let us set $f = \sum_{i \in I} f_i$. This is well defined by local finiteness of the $\overline{V_i}$ Note also that $f > 0$.. We set $g_i = f_i/f$. Then clearly we have $0 \leq g_i \leq 1, \sum_{i \in I} g_i \equiv 1$
Step 4: Reindexing and conformation Since $\tilde{V}_i \subset U_\alpha$, for some α, we can choose for each $i \in I, \alpha(i) \in \mathcal{A}$ s.t. $V_i \in U_{\alpha(i)}$. Let us set

Here the empty sum is 0

$$\psi_\alpha \coloneqq \sum_{i \mid \alpha = \alpha(i)} g_i$$

Observe for **(2)**:

$$\operatorname{supp}(\psi_\alpha) = \overline{\bigcup_{\alpha(i)=\alpha} V_i} \overset{\text{Exercise 2.1}}{=} \bigcup_{\alpha(i)\alpha} \overline{V_i} \subset U_\alpha$$

We still have $0 \leq \psi_\alpha \leq 1$, which is **(1)**
and $\operatorname{supp}(\psi_\alpha)$ are locally finite: for each $op \in M$, since $\{\overline{V_i}\}$ locally finite, there exists a neighborhood U_p of p which only intersects finitely many of the $\{\overline{V_i}\}$, call them $V_1, \ldots, V_k$. Then the only ψ_α which have a chance of being non-zero must satisfy $\alpha \in \{\alpha(1), \ldots, \alpha(k)\}$ (this is **(3)**).
Lastly

$$\sum_{\alpha \in \mathcal{A}} \psi_\alpha = \sum_\alpha \left(\sum_{i : \alpha = \alpha(i)} g_i \right) = \sum_{i \in I} g_i \equiv 1,$$

which confirms **(4)**.

□

Start of lecture 06 (25.10.2024)

2.2.3 Applications of partitions of unity

Definition. *Let X be a topological space. Let $A \subset X$ be closed, $U \subset X$, $A \subset U$ be open. A* ***bump function for** A* *supported in U is a function*

$$\phi : X \to \mathbb{R}$$

such that $\psi\mid_A \equiv 1$, $supp(\phi) \subset U$.

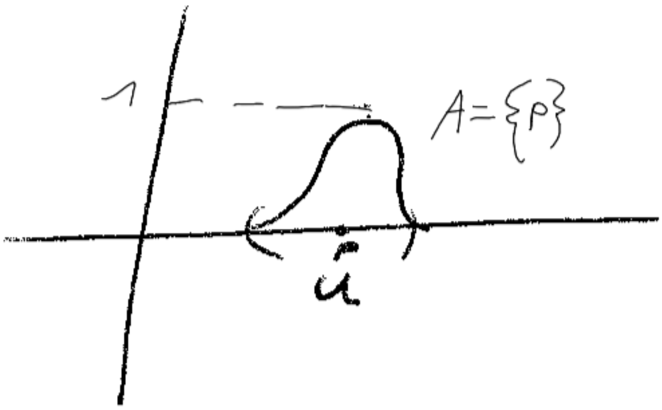

Figure 2.7: Sketch 2.07

Proposition 2.8. *Let M be a smooth manifold. Fix $A \subset M$ closed, $U \subset M, A \subset U \subset M$ open. Then there exists a smooth bump function for A supported in U*

Proof. Let $V = M \setminus A$. Then $\{U, V\}$ is a covering and by theorem 2.7, there exist $\{\Psi_U, \Psi_V\}$ partitions of unity subordinate to this cover. Now Ψ_U does the job. □

Definition. *Let M, N be smooth manifolds. Let $A \subset M$ be closed. We say that $f : A \to N$ is smooth if it admits a smooth extension in a neighborhood of each point $p \in A$.*

I.e. for any $p \in A$ there exists $U_p \ni p$, a smooth function $\tilde{f}_p : U_p \to N$ s.t. $\tilde{f}_p\mid_{U_p \cap A} = f\mid_{U_p \cap A}$

Proposition 2.9. *Let M be a smooth manifold. Let $A \subset M$ be closed and $f : A \to \mathbb{R}^k, k \geq 0$ be smooth. Then for any open $U \subset M, A \subset U$, there exists $\tilde{f} : M \to \mathbb{R}^k$, such that $\tilde{f}\mid_A = f$ and $supp(\tilde{f}) \subset U$*

Remark. *This would be* ***false*** *if we replaced $\mathbb{R}^k$ by an arbitrary smooth manifold N. E.g. take $\mathbb{R}^2 \hookleftarrow A = S^1 \overset{f=id}{\to} S^1$*

Proof. For each $p \in A$, choose a neighborhood $p \in W_p \subset U$, $\tilde{f}_p : W_p \to \mathbb{R}^k$ smooth extension of $f_{|A \cap W_p}$. Then observe that $\{W_p\}_{p \in A} \cup (M - A)$ forms an open cover of M. $\{\psi_p\}_{p \in A} \cup \psi_0$ be a partition of unity subordinate to the cover. Now we set $\tilde{f} = \sum_{p \in A} \psi_p \tilde{f}_p$. By local finiteness $\tilde{f}$ is smooth. Also

We maybe need $\overline{W_p} \subset U$? Prob. not?

$$\begin{aligned} \tilde{f}_{|_A} &= \sum_{p \in A} \psi_{p|_A} \underbrace{\tilde{f}_{p|_A}}_{=f} \\ &= f \sum_{p \in A} \psi_{p|_A} = f_{|_A} \cdot 1 = f_{|_A}. \end{aligned}$$

□

Definition. *Let X be a topological space. An* ***exhaustion function*** *$f : X \to \mathbb{R}$ is a continuous function such that $\forall C \in \mathbb{R}, f^{-1}(-\infty, c]$ is compact.*

If X is compact every f is an exhaustion function ...

Example. $X = \mathbb{R}, f : \mathbb{R} \to \mathbb{R}, x \overset{f}{\mapsto} x^2$

Example (NON-EXAMPLE). $X = \mathbb{R}, f(x) = x$

Proposition 2.10. *Every smooth manifold admits a smooth exhaustion function.*

Proof. Pick a countable partition of unity $\{U_i\}_{i\in N_+}$ by open subsets having compact closure[1].
Let $\{\Psi_i\}_{i\in\mathbb{N}_+}$ be a subordinate partition of unity. Let $f := \sum_{i\in\mathbb{N}_+} i\psi_i$.
Observe that for any $c\in\mathbb{R}$, $c<N\in\mathbb{N}$ that

$$f^{-1}(-\infty,c]\subset f^{-1}(-\infty,c]\subset\bigcup_{i=1}^{N}\overline{U_i}$$

Why $f^{-1}(-\infty,c]\subset\bigcup_{i=1}^{N}\overline{U_i}$? Let $q\notin\bigcup_{i=1}^{N}\overline{U_i}$. Then

$$\begin{aligned}
f(q) &= \underbrace{\sum_{i=1}^{N} i\psi_i(q)}_{=0} + \sum_{i=N+1}^{\infty} i\psi_i(q)\\
&\geq (N+1)\sum_{i=N+1}^{\infty}\psi_i(q) = (N+1)\underbrace{\sum_{i=1}^{\infty}\psi_i(q)}_{=1}\\
&= N+1
\end{aligned}$$

□

Proposition 2.11. *Let M be a smooth manifold. Let $A\subset M$ be a closed subset. Then there exists a smooth function*

$$f: M\to\mathbb{R}, f^{-1}(0)=A$$

In fact, the prove shows one can assume $f\geq 0$

E.g. take $M=\mathbb{R}, A=$ Cantor set, shows that this is non-trivial.

Proof. Assume $M=\mathbb{R}^n$ (general case: Sheet 04).
Choose a countable cover of $\mathbb{R}^n\setminus A$ by balls $\{B_{r_i}(x_i)\}_{i=1}^{\infty}$ with $r_i<1$. By Lemma 2.6 there exists a cutoff function

$$H:\mathbb{R}^n\to\mathbb{R}$$

s.t. $H\equiv 1$ on $\overline{B_{\frac{1}{2}}(0)}$ and $0<H<1$ on $B_1(0)\setminus\overline{B_{\frac{1}{2}}(0)}$ and $H\equiv 0$ on $R^n\setminus B_1(0)$. For each $i\geq 1$ let $C_i\gg 1$ be large enough so that

$$C_i>\sup\{\partial_x^\alpha H\mid \alpha=\overbrace{(\alpha_1,\ldots,\alpha_n)}^{\in\mathbb{N}^n}, |\alpha|\leq i\}$$

Let

$$f := \sum_{i=1}^{\infty}\frac{r_i^i}{2^i c_i}H\left(\frac{x-x_i}{r_i}\right).$$

We need to argue that f is smooth. Observe that, since $r_i<1$ $\frac{r_i}{2^i c_i}H\left(\frac{x-x_i}{r_i}\right)\leq\frac{1}{2^i}$ It follows from Analysis 2 that f is continuous. To prove that f is smooth assume for $k\geq 1$ that all partial of order $k<1$ exist and are continuous. If $|\alpha|=k$, then

$$\partial^\alpha\frac{r_i^i}{2^i C_i}H\left(\frac{x-x_i}{r_i}\right)=\frac{r_i^{i-k}}{2^i C_i}\partial^\alpha H\left(\frac{x-x_i}{r_i}\right)$$

If $i>k$, then

$$\left|\frac{r_i^{i-k}}{2^i C_i}\partial^\alpha H\left(\frac{x-x_i}{r_i}\right)\right|<\frac{1}{2^i}$$

Again follows by Analysis 2 that $\partial^\alpha f$ exists and equals $\sum\partial^\alpha\left(\frac{r_i^i}{2^i C_i}H\left(\frac{x-x_i}{r_i}\right)\right)$. □

[1] Like in the proof of 2.7

Chapter 3: Tangent Vectors

3.1 Motivation

Consider the following pictures

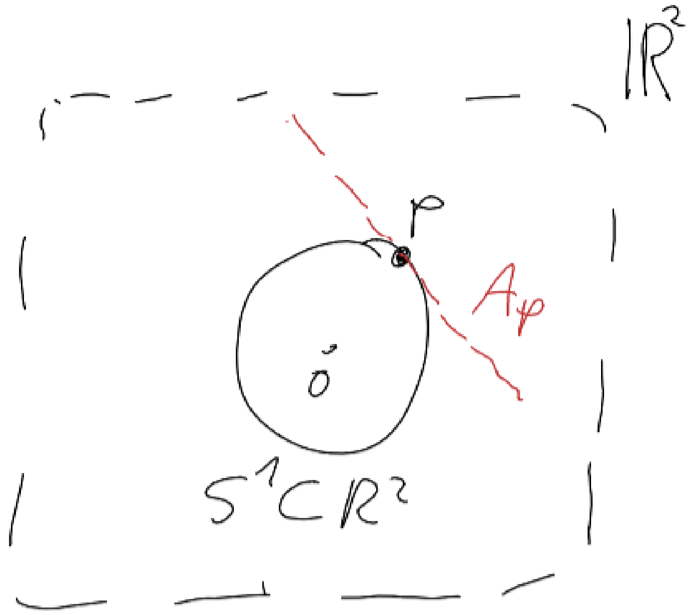

Figure 3.1: Sketch 3.01

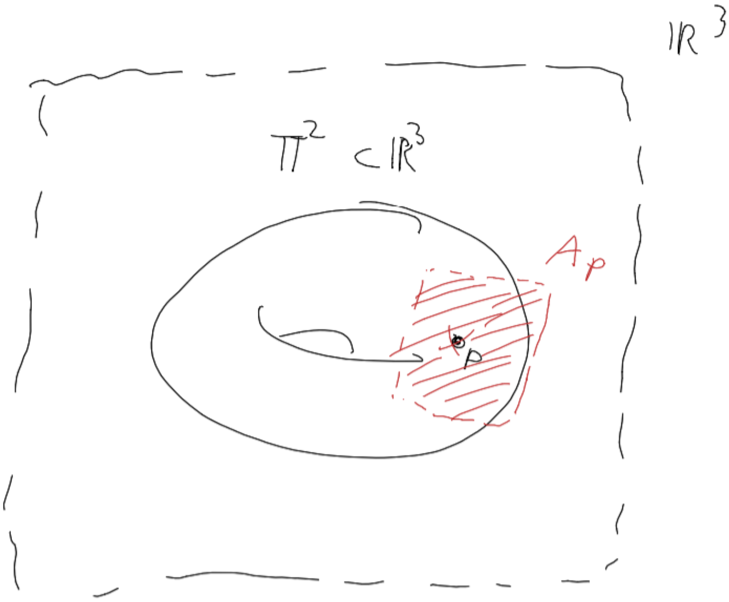

Figure 3.2: Sketch 3.02

A_p the affine hyperplane tangent to $S^1(\Pi^2)$ at the point p. Let $T_pM := A_p - p \subset \mathbb{R}^{n+1}$. This is a vector subspace of $\mathbb{R}^{n+1}$. It is called the **tangent space of M at p**. Consider

$$TM = \coprod_{p \in M} T_pM,$$

called the **tangent bundle**. Observe that there is a map

Think of π as a map of p, T_pM

$$\pi : TM \to M$$

by

$$x \in T_pM \mapsto p$$

the data $TM \xrightarrow{\pi}$ forms a **vector bundle**.
Problems with this approach:

- not very intrinsic (depends on $R^{n+1}\dots$)
- need to prove that manifolds can always embedded into R^N

This is really the picture / intuition we should have, but we will construct it in a different way.

3.2 Two (equivalent) theories of tangent vectors

3.2.1 Definition via equivalence classes of smooth curves

Let M be a smooth manifold. Fix $p \in M$.

I could not quite make out what he called this chapter, so I named it according to [3]

Definition. *The **tangent space** of M at p denoted by T_pM is the set of equivalence classes of smooth curves gamma : $[-\epsilon, \epsilon] \to M, \gamma(0) = p$ with $\gamma_1 \sim \gamma_2 \iff$ for any smooth function f defined near[a] p, we have $(f \circ \gamma_1)'(0) = (f \circ \gamma_2)'(0)$. Here the $\epsilon > 0$ is any positive real number, which depends on γ.*

[a] in a neighborhood of

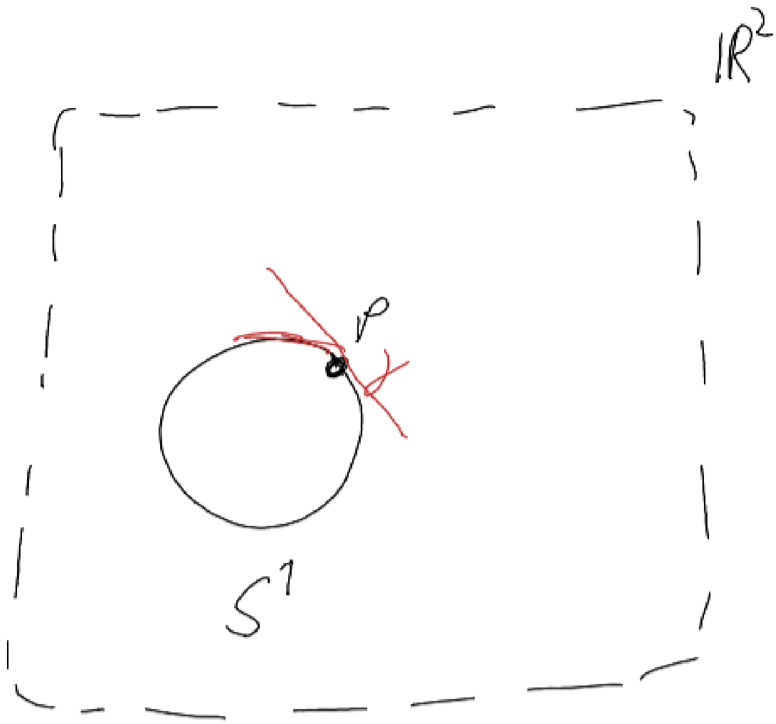

Figure 3.3: Sketch 3.03

Definition. *Given a smooth map $F : M \to N$, let*

$$dF_p : T_pM \to T_{F(p)}N$$

be given by

This is clearly well defined

$$[\gamma] \mapsto [F \circ \gamma].$$

This map dF_p is called the ***differential of F at p***.

Remark. *The map is also called the* ***tangent map of M at p*** *and the* ***total derivative***. *It is also denoted by*

$$DF_p, TF_p, \nabla F_p, F'_p, DF(p), TF(p), \dots$$

Lemma 3.1 (Fundamentality of the differential)**.** *Let $F^1 : M_1 \to M_2$, $F^2 : M_2 \to M_3$ smooth. Then:*

(i) $dF^2_{F^1(p)} \circ dF^1_p = d(F^2 \circ F^1)_p$

(ii) If $F : M \to M$ is the identity, then $dF_p = id$

Proof. Exercise. □

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Lemma 3.2. *Let $\gamma : [-\epsilon, \epsilon] \to \mathbb{R}^n$ and $\sigma : (-\delta, \delta) \to \mathbb{R}^n$ with $\gamma(0) = \sigma(0) = p \in \mathbb{R}^n$. Then $\gamma \sim \sigma \iff \underbrace{\gamma'(0)}_{(\gamma_1'(0), \dots \gamma_n'(0)) \in \mathbb{R}^n} = \sigma'(0)$*

Proof. By abusive notation, we denote by x_i the map $\mathbb{R}^n \to \mathbb{R}, (x_1, \dots, x_n) \mapsto x_i$.. If $\gamma \sim \sigma$, then ${\gamma^i}'(0) = (x_i \circ \gamma)'(0) \overset{\text{Def.}}{=} (x_i \circ \sigma)'(0) = {\sigma^i}'(0) \implies \gamma'(0) = \sigma'(0)$.

x^i might be better (in the sense of the dual space), but x_i is used in practice

Conversely, suppose $\sigma'(0) = \gamma'(0)$. Given any f smooth defined near p, we have

$$\begin{aligned}(f \circ \gamma)'(0) &= (\partial_{x_1} f(p), \dots, \partial_{x_n} f(p)) \cdot (\gamma^{1'}(0), \dots, \gamma^{n'}(0)) \\ &= (\partial_{x_1} f(p), \dots, \partial_{x_n} f(p)) \cdot (\sigma^{1'}(0), \dots, \sigma^{n'}(0)) \\ &= (f \circ \sigma')(0).\end{aligned}$$

□

Corollary 3.3. *Let V be a finite dimensional $\mathbb{R}$ vector space. Then, for any $p \in V$, the* ***canonical*** *map*

$$\begin{aligned}&V \to T_pV \\ &w \mapsto [t \mapsto p + tw]\end{aligned}$$

is a bijection.

Proof. If $V = \mathbb{R}^n$, then this is immediate from lemma 3.2. In general pick a basis to define an isomorphism[1] $F : V \to \mathbb{R}^n$. Then the following diagram commutes:

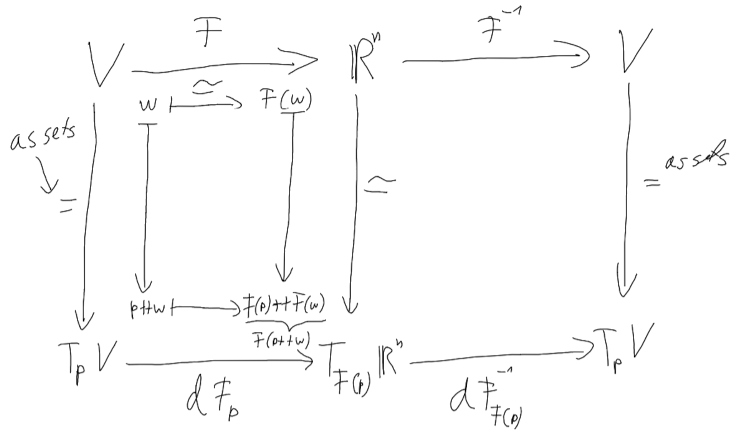

Figure 3.4: Sketch 3.04

using lemma 3.1. □

3.2.2 Definition via derivations

Definition. *Let M be a smooth manifold. A* ***derivation at*** $p \in M$ *is a linear map*

$$\nu : C^\infty(M) \to \mathbb{R}$$

satisfying the property

$$\nu(fg) = f(p)\nu(g) + \nu(f)g(p), \tag{1}$$

which is also called the ***Leibniz rule****.*

Remark. *Here $C^\infty(M)$ is the set of smooth functions from $f : M \to \mathbb{R}$. It is naturally an $\mathbb{R}$-vector space. Similarly we have $C^0(M)$ the space of continuous functions $f : M \to \mathbb{R}$ and $C^k(M)$ the space of k-times differentiable function $f : M \to \mathbb{R}$.*

Definition. *The set of derivations at p shall be also called the* ***tangent space*** *of M at p, denoted by T_pM.*

Lemma 3.4. *T_pM is naturally a vector subspace of $C^\infty(M)^\vee$*

$C^\infty(M)^\vee$ denotes the dual space of $C^\infty(M)$

[1] In particular a diffeomorphism

Proof. Given derivations $\nu_1, \nu_2 \in T_pM$ we must show that $a\nu_1 + \nu_2$ is still an element of $T_pM \forall a \in \mathbb{R}$. We compute we compute

$$\begin{aligned}(a\nu_1+\nu_2)(fg) &= a\nu_1(fg)+\nu_2(fg) = a[\nu_1(f)g(p)+f(p)\nu_1(g)]+[\nu_2(f)g(p)+f(p)\nu_2(g)] \\ &= f(p)[a\nu_1+\nu_2]+[a\nu_1+\nu_2](f)g(p)\end{aligned}$$

□

Definition. *Given a smooth map $F : M \to N$, we let $dF_p : T_pM \to T_{F(p)}N$ be the map*

$$\nu \mapsto dF_p(\nu) := C^\infty(N) \ni f \mapsto \nu(f \circ F)$$

Lemma 3.5. *(i) the previous definition gives a derivation*

(ii) $dF^2_{F^1(p)} \circ dF^1_p = d(F^2 \circ F^1)_p$

By (ii) and (iii) d is a Functor

(iii) If $F : M \to M$ is the identity, then $dF_p = id$

Lemma 3.6. *Let ν be a derivation at $p \in M$. Then*

(a) $f \equiv C$, then $\nu(f) = 0$. That is ν annihilates constant functions.

(b) if $f(p) = g(p) = 0$, then $\nu(fg) = 0$

Proof. **(a)**: Since ν is linear, it is enough to prove $\nu(f) = 0$ for $f \equiv 1$. But then

$$\nu(f) = \nu(f^2) = f(p)\nu(f) + \nu(f)f(p) = 2\nu(f).$$

(b) is obvious by the Leibniz rule (1). □

Lemma 3.7. *Let V be a finite dimensional vector space over $\mathbb{R}$. A derivation $\nu \in T_pV$ is entirely determined by its action on any dual basis $\{\xi^1, \dots, \xi^n\}$..*

This should remind us of lemma 3.2

Proof. Fix a basis $(\{e_1, \dots, e_n\})$ to identify $V \equiv \mathbb{R}^n$. It is enough to show that $\nu(f) = 0$ if $\{\partial_{x_1} f(p), \dots, \partial_{x_n} f(p)\}$ all vanish(Indeed, consider $f \to f - \sum_{k=1}^n \partial_{x_i} f(p)\xi_i)$. By Taylor's formula (Appendix C.15, Lee), we have

with $\xi_i : \mathbb{R}^n \to \mathbb{R}$ as before

$$f(x) = \underbrace{f(p)}_{\text{constant}} + \underbrace{\sum_{i=1}^n \partial_{x_i} f(p)(x_i - p_i)}_{=0} + \sum_{i,j=1}^n \underbrace{(x_i - p_i)}_{\text{constant at } p} \underbrace{(x_j - p_j)\int_0^1 (1-t)\partial_{x_i x_j} f(p + t(x-p))dt}_{\text{constant at } p}.$$

Then by lemma 3.6 $\nu(f) = 0$. □

Corollary 3.8. *The canonical map $V \to T_pV$, $p \in V$ defined by*

$$w \mapsto (C^\infty(V) \ni f \mapsto \frac{d}{dt}_{|t=0} f(p + tw))$$

is an isomorphism of vector spaces.

This should remind us of corollary 3.3

Proof. We define

These are really canonically equal! No choice needed

$$\begin{aligned}T_pV &\to V \\ \nu &\mapsto \sum_{i=1}^n \nu(\xi^i)e_i, \xi^i : V \to \mathbb{R}\end{aligned}$$

By lemma 3.7 this map is injective and hence $\dim T_pV \leq \dim V$. So it is enough to show that $V \mapsto T_pV$ is also injective. Suppose for contradiction that $V \ni w \neq 0$, that maps to the zero derivation.

$$\begin{aligned}0 &= \frac{d}{dt}_{|t=0} f(p + tw) \forall f \\ \implies 0 &= \frac{d}{dt} w^\vee(p + tw) = \frac{d}{dt}_{|t=0} t = 1\end{aligned}$$

□

3.2.3 Both definitions agree

Temporary notation: Let $T_pM^{(1)}, dF_p^{(1)},\ldots,$ be those objects defined in section 3.2.1 and $T_pM^{(2)}, dF_p^{(2)},\ldots,$ the analogous objects defined in 3.2.2
Key observation: There is a **canonical** map, for any $p \in M$,

$$K_P : T_pM^{(1)} \to T_pM^{(2)}$$
$$\gamma \mapsto (C^\infty(M) \ni f \mapsto (f \circ \gamma)'(0)).$$

Note that this commutes with $dF^{(i)}$, i.e. $dF^{(2)} \circ K_p = K_{F^{(1)}(p)} \circ dF_p^{(1)}$ (exercise).

Proposition 3.9. *K_p is a bijection.*

Proof. Choose a chat $(U, \varphi), p \in U$. Then we have a map

$$U \to \varphi(U) \subset R^n$$

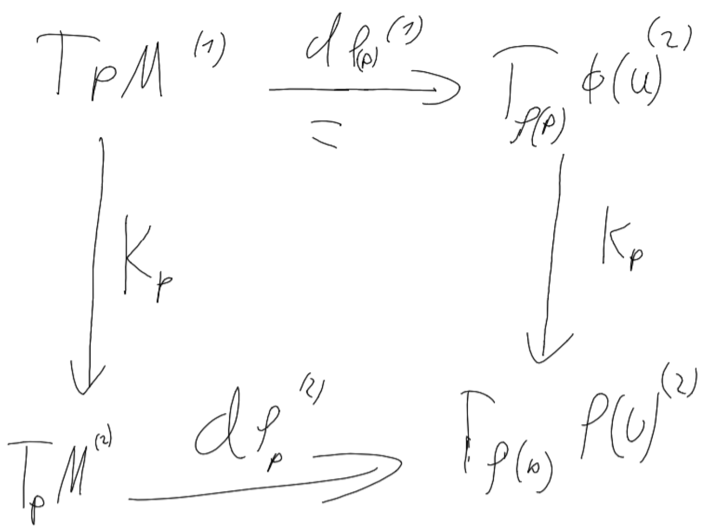

Figure 3.5: Sketch 3.05

Finally, we have

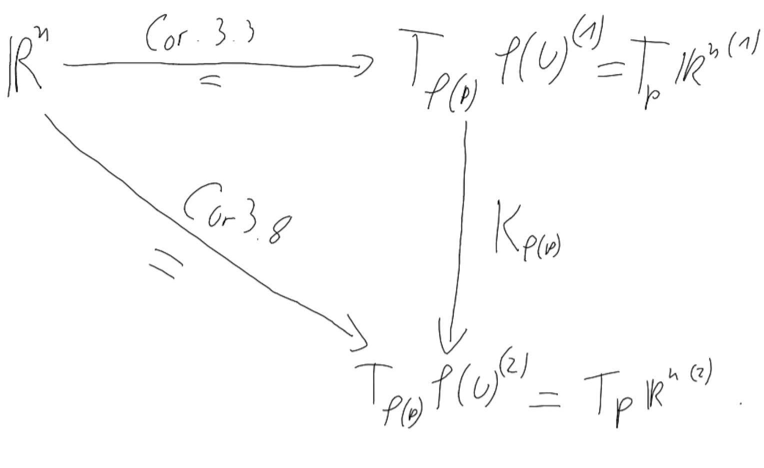

Figure 3.6: Sketch 3.06

□

3.3 Coordinates

Definition. *(1) Given a point $p \in \mathbb{R}^n$ let $(\partial_{x_i})_p \in T_p\mathbb{R}^n$ be the vector represented by the curve $t \mapsto p + t\underbrace{(0, \dots, 1, \dots, 0)}_{e_i}$.*

(2) Given $p \in M$, we shall abusenotation by writing $(\partial_{x_i})_p \coloneqq d\varphi^{-1}_{\varphi_p}(\partial x_i)_p$ for some chart $((U, \phi))$

Remark. 1. *Various authors also write $\partial_{x_i}(p)$*

2. *$\{(\partial_{x_1})_p, \dots, (\partial_{x_n})_p\}$ form a basis for T_pM, by construction*

3. *$\{\partial_{x_1}, \dots, \partial_{x_n}\}$ very much depend on the chart (U, φ)*

Suppose now that $F : M \to N$ smooth map. Let $(U, \varphi), (V, \psi)$ be charts, $F(U) \subset V$. Let $\hat{p} \coloneqq \phi(p) \in \mathbb{R}^m$. Then we have

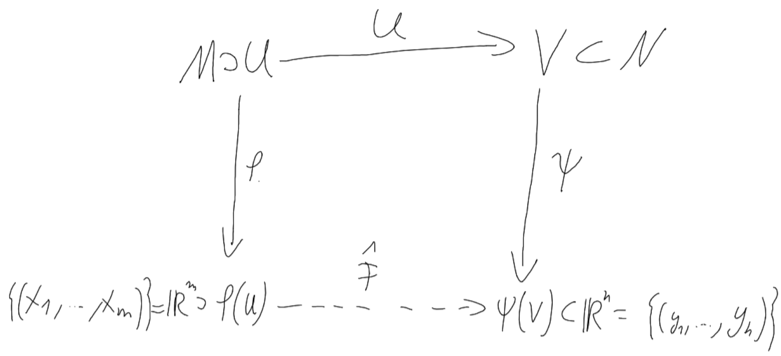

Figure 3.7: Sketch 3.07

where $\hat{F} = \psi \circ F \circ \varphi^{-1}$.
Note that $d\hat{F}_{\hat{p}} : T_{\hat{p}}\mathbb{R}^m \to T_{\hat{F}(\hat{p})}\mathbb{R}^n$ is a linear map. We want to find an expression ofr the matrix $d\hat{F}_{\hat{p}}$ w.r.t the basis $\{\partial_{x_1}, \dots, \partial_{x_m}\}$ and $\{\partial_{y_1}, \dots, \partial_{y_k}\}$.
Well, by definition

$$\begin{aligned} d\hat{F}_{\hat{p}}((\partial_{x_i})_{\hat{p}}) &\coloneqq [\hat{F}(\hat{p} + (0, \dots, 1, 0, \dots 0))] \\ &= \sum_{j=1}^{n} \partial_{x_i} F^j(\hat{p})(\partial_{y_j})_{\hat{F}(\hat{p})} \end{aligned}$$

and therefore

$$d\hat{F}_{\hat{p}} = \begin{pmatrix} \partial_{x_1}\hat{F}^1(\hat{p}) & \cdots & \partial_{x_m}\hat{F}^1(\hat{p}) \\ \vdots & & \vdots \\ \partial_{x_1}\hat{F}^n(\hat{p}) & \cdots & \partial_{x_m}\hat{F}^n(\hat{p}) \end{pmatrix}.$$

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Remark. *By abuse of notation we often write $F \equiv \hat{F}, p \equiv \hat{p}, \partial_{x_i} f \equiv \partial_{x_i}\hat{F}, dF_p \equiv d\hat{F}_{\hat{p}}$*

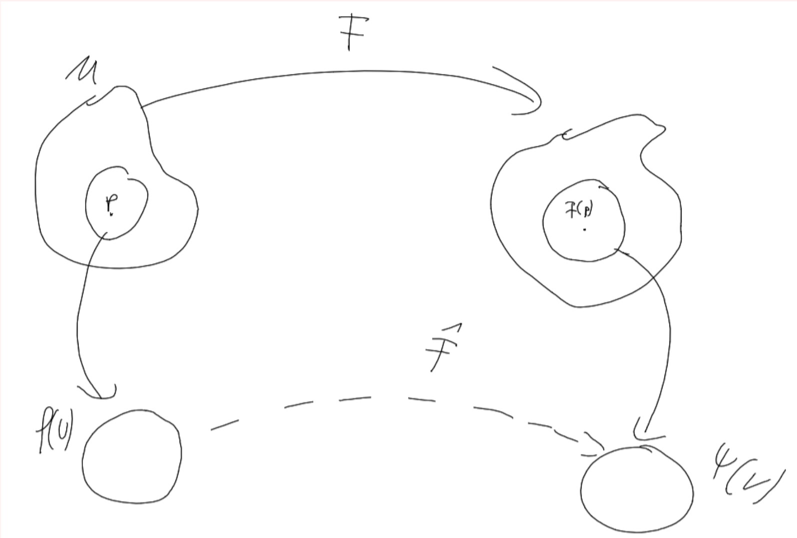

Figure 3.8: Sketch 3.08

Remark. $d\hat{F}.: \underbrace{x}_{\in\phi(U)\subset\mathbb{R}^m} \mapsto d\hat{F}_x \in Mat(n\times m) \equiv \mathbb{R}^{n\times m}$. *This it clearly a smooth map.*

3.4 The tangent bundle

Definition. *Given a smooth manifold M, let $TM := \coprod_{p\in M} T_pM$. We write elements of TM as pairs (p,v), where $v \in T_pM$. Note that we have a map*

$$\pi : TM \to M, (p,v) \mapsto p.$$

Remark (Added by Manuel, was an answer to my question)**.** *For $p \in M$ the preimage of p under π is called a **fiber**. He also highlighted, the condition that $\pi^{-1}(p)$ is a vector space (namely T_pM), which seems to be important in our context, but not generally required for fibers.*

A priori, TM is just a set. We will exhibit natural smooth manifold structure.
Special case: $M \subset U\mathbb{R}^n$. Then

$$TU := \coprod_{p\in U} T_pU \equiv U \times \mathbb{R}^n$$
$$(t \mapsto p + tv) \mapsto (p,v)$$

Remember that this is a canonical identification!

General construction Given a smooth chart (U,ϕ) for a smooth manifold M, we have a map $d\phi$

$$\begin{tikzcd} TM \supset TU \arrow[r, "d\phi"] \arrow[d] & T\phi(U) \equiv \phi(U)\times\mathbb{R}^n \arrow[d] \\ U \arrow[r, "\phi"] & \phi(U) \end{tikzcd}$$

Figure 3.9: Sketch 3.09

where

$$d\phi(p,v) := (\phi(p), d\phi_p(v)).$$

Define a subset $S \subset$ TM to be open, if, for any chart U, ϕ, $d\phi(S \cap TU)$ open in $T\phi(U) \equiv \phi(U) \times \mathbb{R}^n$.

This is a pullback

Lemma 3.10. *This prescription defines a topological space on TM. Moreover, TM is a topological manifold.*

Proof. Omitted. Check transition maps

$$d\psi \circ d\phi^{-1} : \phi(U \cap V) \times \mathbb{R}^n \to \psi(U \cap V) \times \mathbb{R}^n$$

is it an elementary, but tedious proof. ☐

Remark. *Alternatively define the same topology on TM by taking the basis the union over all charts (U, ϕ) in your atlas of $\{d\phi^{-1}(V) \mid V \subset T(\psi(U))$ open$\}$.*

To make TM into a **smooth** manifold, we take as our atlas the set $\{(TU, d\phi)\}_{(U,\phi)}$, where (U, ϕ) runs over the smooth charts of M.

Lemma 3.11. *this is a smooth atlas.*

Proof. Fix charts $(U, \phi), (V, \psi)$. Then the transition functions take the form

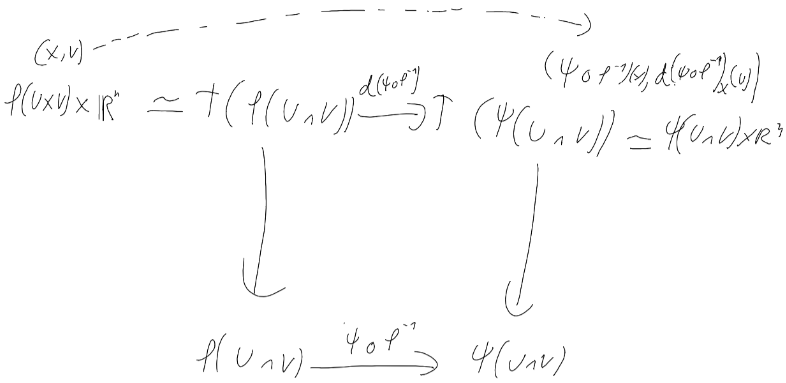

Figure 3.10: Sketch 3.11

Check if both components are smooth:

- The first component $x \mapsto \psi \circ \phi^{-1}(x)$ is smooth, since M is a smooth manifold an $(U, \phi), (V, \psi)$ are smooth
- For the second component can be fractured as follows:

$$(x, v) \mapsto (d(\underbrace{\psi \circ \phi_x^{-1}}_{\in \mathrm{Man}(n\times n) \equiv \mathbb{R}^{2n}}, v)) \mapsto d(\psi \circ \phi^{-1})_x v$$

Since we can write the second component as a concatination of maps, it is smooth

Exercise: the map $\mathrm{Mat}(m \times n) \times \mathrm{Mat}(n \times p) \to \mathrm{Mat}(m \times p)$ by $A, B \mapsto AB$ is smooth. ☐

Remark. *We will see later that $(\phi : TM \to M)$ forms a vector bundle. It can be shown that given $F : M \to N$ the map $dF : TM \to TN, (p, v) \mapsto (F(p), dF_p(v))$ is smooth..*
In fact, we have

This is the exact same computation as in the proof of lemma 3.11

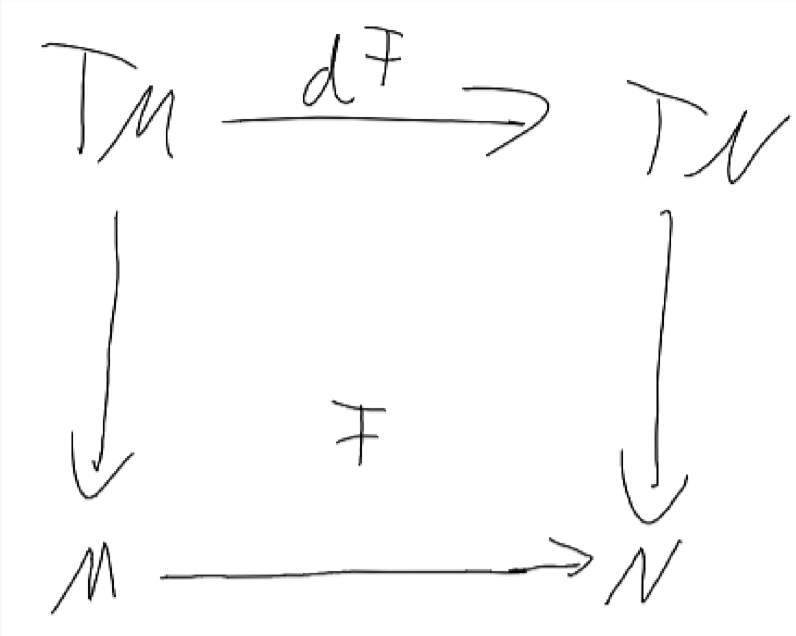

Figure 3.11: Sketch 3.12

commutes. This can be restated as follows: There is a functor $Man^{\infty} \to$ *Smooth vector bundles by*

$$M \mapsto (\pi : TM \to M)$$

$$F : M \to N \mapsto dF : TM \to TN$$

Chapter 4: Submersions, immersions and embeddings

4.1 Basic definitions

Definition. *Let $F : M \to N$ be smooth. The* ***rank*** *of F at $p \in M$ is the rank of the linear map $dF_p : T_pM \to T_{F(p)}M$.*

Smooth maps, which have full rank (highest possible rank, i.e. $\text{rank}F = \max(m, n)$) are particularly important:

Definition. *Let $F : M^m \to N^n$ be smooth. We say*

- *F is a* ***submersion*** *if dF_p is surjective, for all $p \in M$ $(m \geq n)$*
- *F is an* ***immersion*** *if dF_p is injective, for all $p \in M$ $(m \leq n)$*

M^m, N^n means M, N are m, n dimensional manifolds

Lemma 4.1. *Given $(m, n) \in \mathbb{N}_+ \times \mathbb{N}_+$, let $Mat(m \times n) \equiv \mathbb{R}^{m \times n}$. The subset $Mat(m \times n)^{full\ rank} := \{A \in Mat(m \times n) \mid A \text{ has full rank}\}$ is open in $Mat(m \times n)$.*

Proof. Fix $M \in \text{Mat}(m \times n)^{\text{full rank}}$. Without loss of generality $m \leq n$, otherwise apply $\text{Mat}(m \times n) \to \text{Mat}(n \times m), A \mapsto A^T$. By definition there exists a submatrix M', obtained by deleting $n - m$ columns, which is invertible. Now the map

M is fixed and F depends on M, but it does not matter here!

$$\text{Mat}(m \times n) \overset{F:M \mapsto M'}{\to} \text{Mat}(m \times m) \overset{\det(\cdot)}{\to} \mathbb{R}$$

is continuous, since booth the forgetful F and det is smooth.

$$M \in (\det \circ F)^{-1}(\underbrace{\mathbb{R} \setminus \{0\}}_{\text{open}}) \subset \text{Mat}(m \times n)^{\text{full rank}}$$

since M was arbitrary this completes the proof.

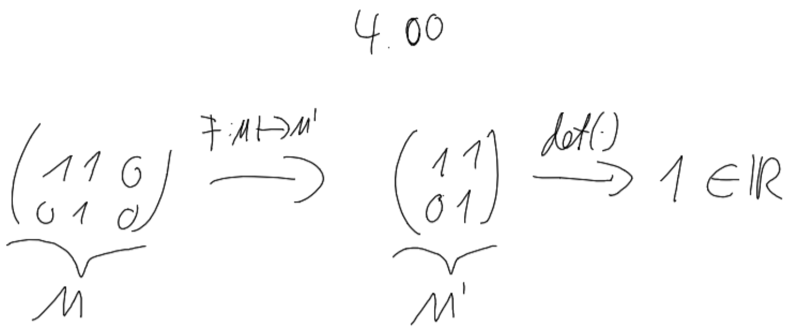

Figure 4.1: Sketch 4.00

□

Lemma 4.2. *Fix* $F : M^m \to N^n, p \in M$.

1. *If* dF_p *is injective, then there exists a neighborhood of* p *on which* $dF.$ *is injective.*
2. *If* dF_p *is surjective, then there exists a neighborhood of* p *on which* $dF.$ *is surjective.*

The property of full rank is stable under small pertubation!

Proof. This is a local statement. We can therefore assume that M, N are open subsets of $\mathbb{R}^m, \mathbb{R}^n$ respectively. Then

$$dF_{(\cdot)} : M \to \mathrm{Mat}(n \times m)$$

is smooth, hence continuous. By assumption $dF_p \in \mathrm{Mat}(n \times m)^{\text{full rank}}$. But $\mathrm{Mat}(n \times m)^{\text{full rank}}$, so the preimage is open (by lemma 4.1) and contains p. □

Remark.

1. *If* $F : M \to N$ *is both an immersion and a submersion, then we say that* F *is a* ***local diffeomorphism****. We will see (by the rank theorem 4.3) that* F *is a local diffeomorphism* $\iff \forall p \in M \exists p \in U : F_{|U}$ *is a diffeomorphism.*
2. *be warned. local diffeomorphism need not be global:*

$$\begin{aligned} \mathbb{R}^2 \equiv \mathbb{C} \supset \quad S^1 = &\{|z| = 1\} \to S^1 \\ (x, y) \mapsto x + iy \qquad &z \longmapsto \quad z^2 \end{aligned}$$

important: contains both a definition and a counterexample!

Definition. *An immersion is an* ***embedding*** *if it is a homeomorphism onto its image with the subspace topology.*

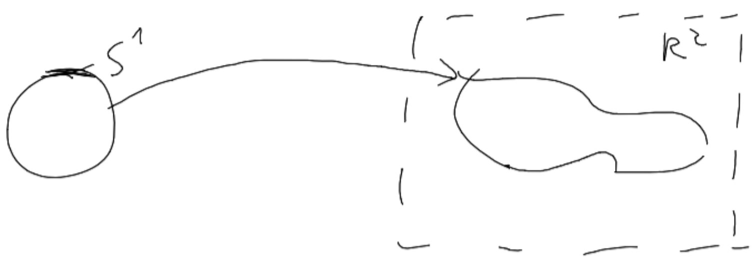

Figure 4.2: Sketch 4.01

Example. *Another example:*

$$S^n = \{(x_0, \ldots, x_n) \in \mathbb{R}^{1+n} \mid \sum x_i^2 = 1\} \subset \mathbb{R}^{1+n}$$

with

$$i : S^n \hookrightarrow \mathbb{R}^{1+n}$$

Non-examples

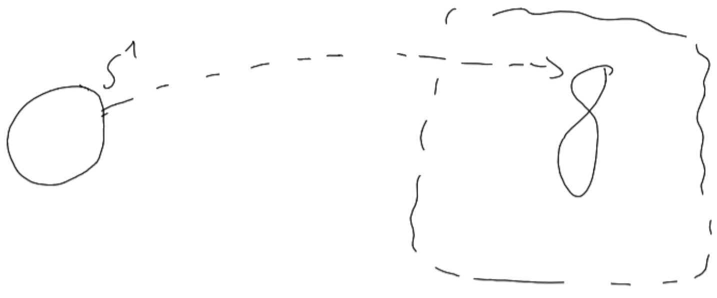

Figure 4.3: Sketch 4.02

parametrized by

$$t \mapsto (\sin t, \sin 2t)$$

and

$$\mathbb{R} \mapsto \mathbb{R}^2/\mathbb{Z}^2 = S^1 \times S^1$$
$$t \mapsto (t, \alpha t),\ \alpha \in \mathbb{R} \setminus \mathbb{Q}$$

Can show[1] *that the image is dense. It is an immersion, but no a homeomorphism!*

Start of lecture 09 (08.11.2024)

4.2 The rank theorem

Theorem 4.3 (rank theorem)**.** *Let $F : M^m \to N^n$ be a smooth map of constant rank r. For each $p \in M$, there exist charts $(U, \varphi) : p \in U$ and $(V, \psi) : F(U) \subset V$, such that*

$$\hat{F} := \psi \circ F \circ \varphi^{-1} :$$

Figure 4.4: Sketch 4.03

$\hat{F}$ takes the form

$$\hat{F}(x_1, \ldots, x_r, x_{r+1}, \ldots, x_m) = (x_1, \ldots, x_r, 0, \ldots, 0)$$

This is arguably the most important result of the first half of the course. There is a lot of results in [2], what is actually useful? Implied answer: Rank theorem

Remark. *By lemma 4.2, if F has full rank at $p \in M$, then*

- *if $m = r \geq n$, then F is an submersion near p and*
$$\hat{F}(x_1, \ldots, x_n, x_{n+1}, \ldots, x_m) = (x_1, \ldots, x_n)$$
- *$m = r \leq n$, then F is an immersion near p, and*
$$\hat{F}(x_1, \ldots, x_m) = (x_1, \ldots, x_m, 0, \ldots, 0)$$
- *$m = n \implies$ up to the diffeomorphism, $\hat{F}$ is just the identity*

Up to diffeomorphism there is only one map of constant, full, rank

Remark. *This theorem is a non-linear generalization of the following linear algebra fact: $L : V^m \to W^n$, then there are linear maps $\varphi : V^m \xrightarrow{\simeq} \mathbb{R}^m, \psi : W^n \xrightarrow{\simeq} \mathbb{R}^n$, such that $\hat{L} := \psi \circ L \circ \phi^{-1}$ takes the form*

$$\hat{L}(x_1, \ldots, x_r, x_{r+1}, \ldots, x_m) = (x_1, \ldots, x_r, 0, \ldots, 0),$$

where $r = rank(L)$.

[1] not obvious, non-examable

Proof of theorem 4.3. **Step 0:** We might as well assume that $M = U \subset \mathbb{R}^m, N = V \subset \mathbb{R}^n$, since we only make a local statement up to diffeomorphism. We may also assume, up to reordering the coordinates, that the matrix $(\partial_{x_i} F^j(p))_{1\le i,j\le r}$ is **invertible** for $p \in U$. We label our coordinates: see [2]

source coordinates in U

$$(x_1, \dots, x_r, y_1, \dots, y_{m-r})$$

Tarkget coordiantes

$$(v_1, \dots, v_r, \dots, w_1, \dots, w_{n-r})$$

and wlog $F(0,0) = (0,0)$.
We write $F(x,y) = \underbrace{Q(x,y)}_{v\text{-coordinates}}, \underbrace{R(x,y)}_{w\text{-coordinates}}$. Notice that $(\partial_{x_i} Q^j)$ is non-singular.
Step 1: Define $\varphi : U \to \mathbb{R}^m, \varphi(x,y) = (Q(x,y), y)$. Then

$$d\varphi_{(0,0)} = \begin{pmatrix} \overbrace{\partial_{x_i} Q^j}^{\in \mathrm{Mat}(r\times r)} & \partial_{y_i} Q^j \\ 0 & \underbrace{1}_{\in \mathrm{Mat}((n-r)\times(n-r))} \end{pmatrix}$$

$\implies$ by the inverse function theorem, there exist connected neighborhoods $U_0 \subset U, \tilde{U_0} \subset\in \mathrm{Mat}((n-r)\times(n-r))\varphi(U)$, such that $\varphi_{|U_0} : U_0 \to \tilde{U_0}$. We may as well assume that $\tilde{U_0}$ is a cube, i.e. $(-\epsilon, \epsilon)^n$.

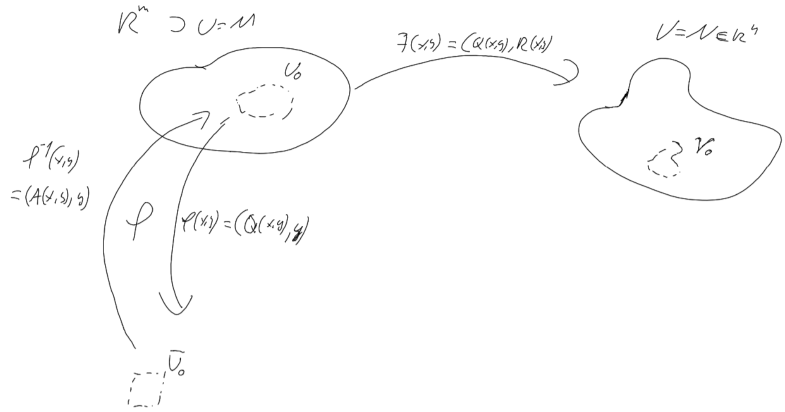

Figure 4.5: Sketch 4.04

While $\varphi^{-1}(x,y) = (A(x,y), B(x,y))$, for some $A : \tilde{U_0} \to \mathbb{R}^r$, $B : \tilde{U_0} \to \mathbb{R}^{m-r}$. We compute

$$(x,y) = \varphi \circ \varphi^{-1}(x,y) = \varphi(A(x,y), B(x,y)) = (Q(A(x,y), B(x,y)), B(x,y)) \implies \substack{x = Q(A(x,y),B(x,y)) \\ y = B(x,y)}$$

Hence $\varphi^{-1}(x,y) = (A(x,y), y)$.
Step 2: Observe that

$$F \circ \varphi^{-1}(x,y) = (Q(\varphi^{-1}(x,y)), R(\varphi^{-1}(x,y))) = (x, \tilde{R}(x,y)),$$

where

$$\tilde{R}(x,y) = R(\varphi^{-1}(x,y)).$$

Then

$$d(F \circ \varphi^{-1}) = \begin{pmatrix} \overbrace{1}^{\in \mathrm{Mat}(r\times r)} & 0 \\ \partial_{x_i} \tilde{R}(x,y)^j & \underbrace{\partial_{y_i} \tilde{R}^j}_{\in \mathrm{Mat}((m-r)\times(m-r))} \end{pmatrix}$$

But the rank of $d(F \circ \varphi^{-1})$ is r, because φ^{-1} is a diffeomorphism and F has rank r

- Since $1_{r\times r}$ has rank r, we must have $\partial_{y_i}\tilde{R} \equiv 0$

We write $S(x) \coloneqq \tilde{R}(x,y)$, we now have

$$F \circ \varphi^{-1}(x,y) = (x, S(x)) \tag{1}$$

.

to make clear $\tilde{R}$ does not really depend on y

Step 3: Recall

$$\begin{aligned} F : U \to V \subset \mathbb{R}^n \\ F(0,0) = (0,0) \end{aligned}$$

Let $V_0 \subset V$ be defined as follows:

$$V_0 \coloneqq \{(v,w) \in V \mid (v,0) \in \tilde{U}_0\}$$

By (1), $F \circ \varphi^{-1}(\tilde{U}_0) \subset V_0$. Hence $F(U_0) \subset V_0$. Set $\psi : V_0 \to \mathbb{R}^n, \psi(v,w) = (v, w - S(v))$. Clearly ψ is a diffeomorphism, since

$$(v,w) \mapsto (v, w + S(w))$$

is am inverse. $\implies$ (V_0, ψ) is a smooth chart.

$S(v)$ makes perfect sense, since both x, v have r entries

$$\hat{F} \coloneqq \psi \circ F \circ \phi^{-1} = \Psi(x, S(x)) = (x, S(x) - S(x)) = (x, 0) \qquad \square$$

Remark. *This is one theorem you should really not forget! If you continue to think about Manifolds in your life, this is really useful! Do not remember the proof, remember the statement!*

Chapter 5: Submanifolds

5.1 Basic definitions

Definition. *Let M be a topological manifolds. A subset $S \subset M$ is a* ***topological submanifold****, if S is a topological manifold with the subspace topology.*

Example. $S^n = \{(x_0, \dots, x_n) \mid \sum x_i^2 = 1\} \subset \mathbb{R}^{1+n}$

Example (Non-example)**.** $\{(x, y) \mid x = 0 \vee y = 0\} \subset \mathbb{R}^2$*, since this is not a manifold (see sheet 01).*

Definition. *Let M be a smooth manifold. A topological submanifold $S \subset M$ is a* ***smooth submanifold****, if it is equipped with a smooth structure, s.t. the embedding $i : S \hookrightarrow M$ is smooth.*

Example. *If M is a smooth manifold and $U \subset M$ open, then $U \subset M$ is a smooth manifold.*

With the restricted smooth structure of M

Remark. *Some authors (including Lee's textbook) use the term* ***embedded submanifold*** *to distinguish from* ***immersed submanifolds****. For use "submanifolds"≡"embedded submanifold".*

Lemma 5.1. *Suppose that $f : M \to N$ smooth embedding. Let $S := F(M) \subset N$. Then S admits a unique smooth structure making it a smooth submanifold, with the property that f is a diffeomorphism onto its image.*

Proof. By definition of f being an embedding, f is a homeomorphism onto it's image, with the subspace topology. $\implies S$ is a topological manifold.
We define a smooth atlas on S by taking $\{(f(U), \varphi \circ f^{-1})\}$, as (U, φ) ranges over the set of charts for M.
Clearly f is a diffeomorphism, since $\varphi \circ f \circ f^{-1} \circ \psi^{-1}$, for $(U, \varphi), (V, \psi)$ smooth charts, this follows from the fact that $(U, \varphi), (V, \psi)$ are smoothly compatible on M.
This is the only smooth at with the property that f is a diffeomorphism, if $\mathcal{B}$ is an other such atlas, then the fact that f is a diffeomorphism for $(S, \mathcal{B}) \iff (S, \mathcal{A})$ compatible.
Finally

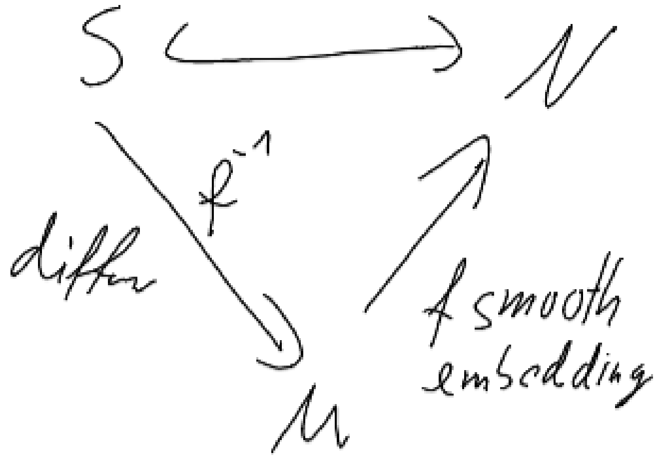

Figure 5.1: Sketch 5.01

so i is a smooth embedding. □

Definition. *A embedded submanifold S is called* ***properly embedded****, if the inclusion map $i \hookrightarrow N$ is proper (i.e. the preimage of a compact set is compact).*

Example. $S^n \hookrightarrow R^{n+1}$ *properly embedded.*

Example (Non-example)**.** $S^n \setminus \{pt\} \subset \mathbb{R}^{n+1}$

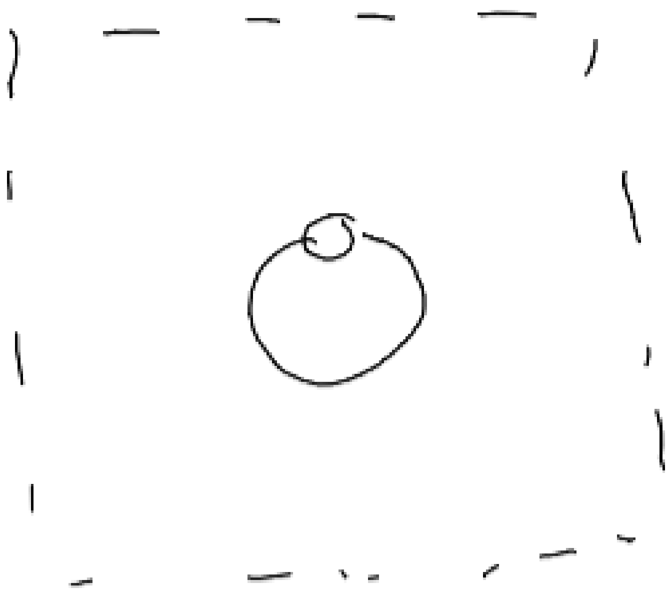

Figure 5.2: Sketch 5.02

Lemma 5.2. *A topological submanifold $S \subset N$ is properly embedded iff S is closed.*

Proof. Exercise. □

Elementary exercise in point set topology

5.2 The "slice lemma"

Theorem 5.3 (Slice lemma[a]). *(a) Suppose $S^k \subset M^n$ is a submanifold of codimension $n-k$. Then, for all $p \in S$, there exists a chart $(V, \psi), p \in U \subset N$, such that*

this is also a definition of codimension: $\dim M - \dim S$

$$\psi(V \cap S) = \{(x_1, \dots, x_k, x_{k+1}, \dots, x_n) \in \psi(V) \mid x_{k+1} = c_{k+1}, \dots, x_n = c_n\}.$$

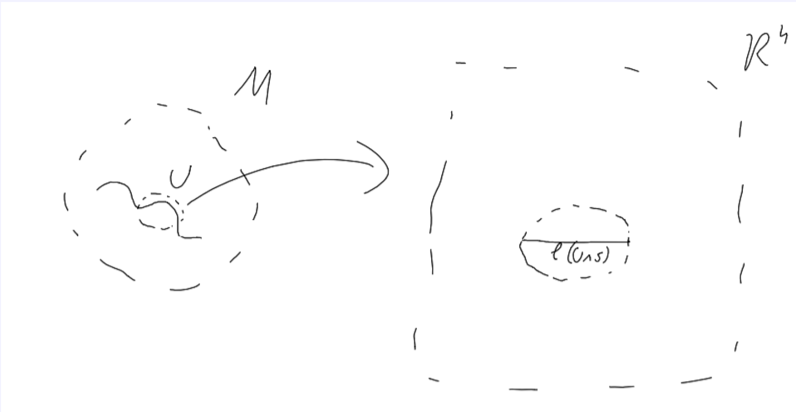

Figure 5.3: Sketch 5.03

Start of lecture 10 (12.11.2024)

The converse of (a)

(b) Suppose that $S \subset N$ is a subset with the property that, for all $p \in S$, there exists a slice chart $(V, \psi), p \in V \subset N$, such that

$$\psi(V \cap S) = \{(x_1, \dots, x_k, x_{k+1}, \dots, x_n) \in \psi(V) \mid x_{k+1} = c_{k+1}, \dots, x_n = c_n\},$$

then S admits a smooth manifold structure making it a smooth submanifold of N.

[a] Lee [2] calls it a theorem

Remark.
- *We get an equivalent theorem by requiring $c_{k+1} = \cdots = c_n = 0$*
- *Part (b) of theorem 5.3 tells us, that being a smooth submanifold $S \subset N$ of ambient smooth manifold N is a property property of the subset. It suffices to check, pointwise, the local property described above!*

Proof. **(a):** By assumption $S \hookrightarrow N$ is an immersion. By theorem 4.3 (rank theorem), there exists charts $(U, \varphi), (V, \psi)$ such that $i(U) \subset V$ and

Locally, all immersions look the same

$$\hat{i} = \psi \circ i \circ \varphi^{-1} : \varphi(U) \to \psi(V)$$
$$(x_1, \dots, x_k) \mapsto (x_1, \dots, x_k, 0, \dots, 0)$$

Up to shrinking ψ (restricting the image of φ), we find that

$$\psi(V \cap S) = \{(x_1, \dots, x_k, x_{k+1}, \dots, x_n) \mid x_{k+1} = \cdots = x_n = 0\}$$

Warning: What can go wrong here? Consider

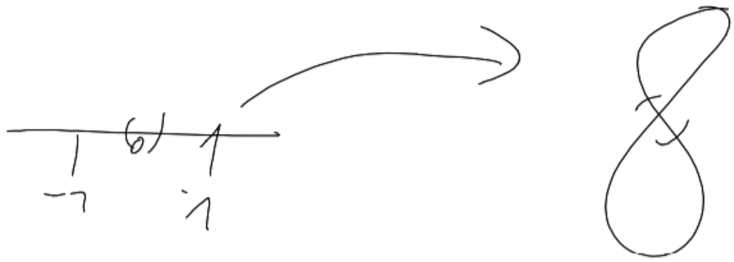

Figure 5.4: Sketch 5.04

Show that there is no more stuff in the set!
(b): We have to check that the local charts given form an atlas. Which is almost a tautology and quite tedious, as we can use $\{S \cap V, \psi_{|S}\}$ as the atlas. $\square$

Remark (+Exercise). *In section 2.1.2, example 4, we considered $\Phi : \mathbb{R}^{1+n} \to \mathbb{R}$. We assumed $d\Phi$ is nonzero on the set $\Phi^{-1}(0) \subset \mathbb{R}^{1+n}$. Under this assumption, we proved that $\Phi^{-1}(0)$ is a naturally smooth manifold. Using theorem 5.3 (or by hand) $\Phi^{-1}(0)$ is a smooth submanifold.*

A priori, $S \subset N$ could admit multiple smooth structures making it a submanifold. We know seek to show that this is not the case.

Lemma 5.4. *Let $S \subset N$ be a submanifold. If $F : M \to N$ is a smooth map which factors through $S \hookrightarrow N$ as a continuous map, then F is smooth as a map $M \to S$.*

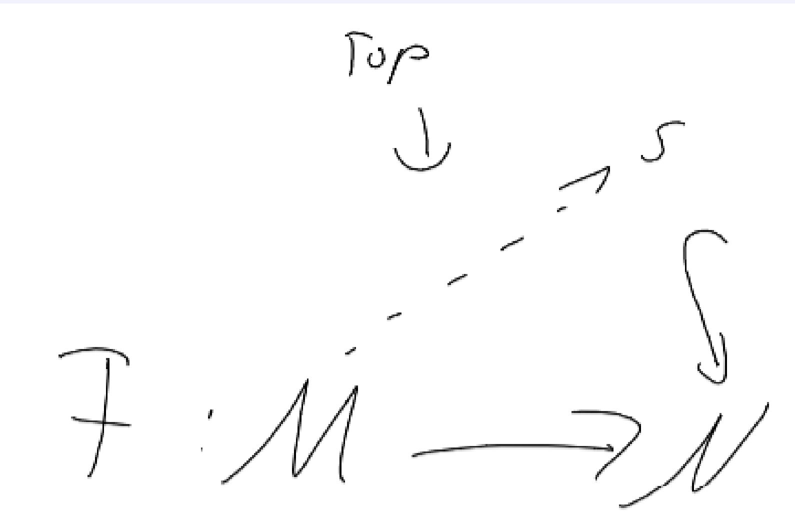

Figure 5.5: Sketch 5.05

Proof. By theorem 5.3, there exists $U \subset S \hookrightarrow N \supset V$

More by the proof of the theorem ...

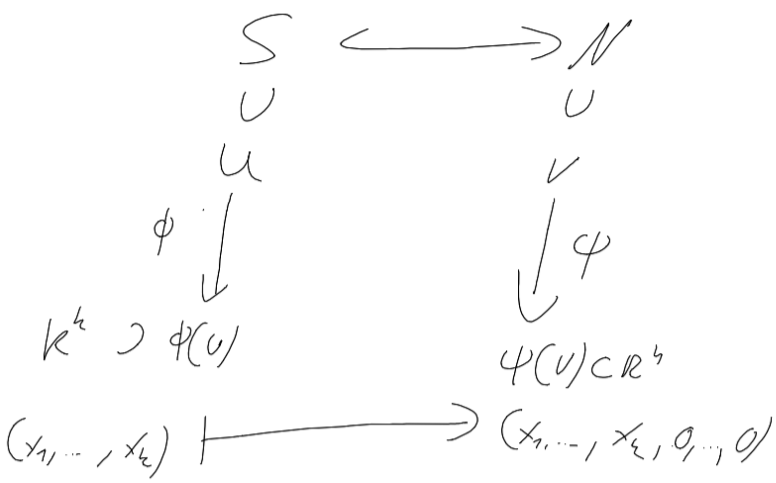

Figure 5.6: Sketch 5.06

Let us call $\overset{\vee}{F}: M \to S, \overset{\vee}{F}(x) = F(x)$. Since $\overset{\vee}{F}$ is continuous, $\overset{\vee}{F}^{-1}(U) \subset M$ open. So, we can write, for (W, U), $W \subset \overset{\vee}{F}^{-1}(U)$

$$\begin{tikzcd}
F^{-1}(U) \arrow[rr, "F^{\vee}"] \arrow[d, "\cup"] & & S \arrow[d, "\cup"] \\
W \arrow[rr] & & U
\end{tikzcd}$$

$$(x_1, \ldots, x_m) \longrightarrow (F^{\vee 1}(x_1, \ldots, x_m), \ldots, F^{\vee k}(x_1, \ldots, x_m))$$

Figure 5.7: Sketch 5.07

were, a priori, $\overset{\vee}{F}^i$ are continuous.
Concatenating the two diagrams, we find that
$F(x_1, \ldots, x_m) = i \circ \overset{\vee}{F}(x_1, \ldots, x_m) = (\overset{\vee}{F}^1(x_1, \ldots, x_m), \ldots, \overset{\vee}{F}^k(x_1, \ldots, x_m), 0, \ldots, 0)$. But then each $\overset{\vee}{F}^i$ has to be smooth and therefore $\overset{\vee}{F}$ is smooth. □

Lemma 5.5. *Let $S \subset M$ be a subset satisfying the conditions of theorem 5.3 (b), then the smooth structure produced by the theorem is the **unique** smooth structure, such that $S \hookrightarrow M$ is a smooth submanifold.*

Proof. Let $\tilde{S}$ be a copy of S, but endowed with some possibly different smooth structure s.t. $\tilde{S} \hookrightarrow M$ is an embedding.

Ergo it is a smooth submanifold of M.

$\tilde{S} \hookrightarrow M$ factors through S, so $\tilde{S} \overset{\text{id}}{\to} S$ smooth. Similarly $S \overset{\text{id}}{\to} \tilde{S}$ smooth. □

This uses lemma 5.4

5.3 The (weak) Whitney embedding theorem

Theorem 5.6 (Whitney)**.** *Every compact n-dimensional smooth manifold admits an embedding into $\mathbb{R}^N$ for $N \gg 1$ large enough.*

Remark. *Later (probably this month), we will remove the compactness assumption and also argue that one can take $N = 2n + 1$.*
Whitney proofed that one can take $N = 2n$.

Don't sue him, if he is off by one :)

Added remark. *This is a very philosophically pleasing statement, since we recover our intuition of embedded manifold from the abstract theory. It is also true, that there is only one embedding (up to isotopy).*

Proof of theorem 5.6. Fix a finite cover of M $\{B_1, \dots, B_k\}, B_i \subset M$ open. We may as well assume that there exist charts $(B_i', \phi_i), \overline{B_i} \subset B_i', \varphi_i(B_i') = B_1(0) \subset \mathbb{R}^m$.
Let $\rho_i : M \to \mathbb{R}$ be a cutoff function for $(\overline{B}_i \subset B_i')$, i.e. $\rho_{i|_{B_i}} = \equiv 1, \mathrm{supp}(\rho_i) \subset B_i', 0 \leq \rho_i \leq 1$. The existence of the ρ_i follows from proposition 2.8.
We now define

Notice the k comes from compactness, i.e. we have no control over it, as it its non-constructive

$$\begin{aligned} F : M &\to \mathbb{R}^{mk+k} \\ p &\mapsto (\rho_1(p) \underbrace{\varphi_1(p)}_{\in \mathbb{R}^m}, \dots, \rho_k(p)\varphi_k(p), \rho_1(p), \dots, \rho_k(p)) \end{aligned}$$

We will now see that F is an embedding. First, we will argue F is an injective immersion.
If $F(p) = F(q) \implies \rho_i(p) = \rho_i(q) \forall i = 1, \dots, k$. Let i_0 be such that $p \in B_{i_0}$. Then $\rho_{i_0}(p) = 1 = \rho_{i_0}(q) \implies q \in \mathrm{supp}(\rho_{i_0}) \subset B_{i_0}'$. But now
$\underbrace{\varphi_{i_0}(p)}_{\in \mathbb{R}^m} = \rho_{i_0}(p)\varphi_{i_0}(p) = \rho_{i_0}(q)\varphi_{i_0}(q) = \varphi_{i_0}(q)$. Hence $p, q \in B_{i_0}' \implies p = q$.
F is an immersion: Choose $p \in M$. Then p $p \in B_{i_0}$, for some i_0. Hence $\rho_{i_0} \equiv 1$ for some neighborhood of p.

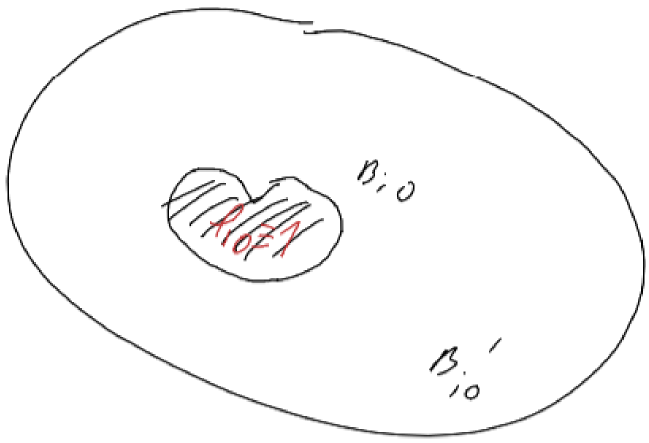

Figure 5.8: Sketch 5.08

Hence $d(\rho_{i_0}\varphi_{i_0}) = \underbrace{d\rho_{i_0}}_{\text{invertible } m \times m}$ near $p \implies dF$ is injective near p, but p was arbitrary.
Finally, since M is compact, the theorem follows from the following lemma 5.7.

Kind of cheating ...

I.e. it is enough to show that $F^{-1} : F(M) \to M$ is continuous, i.e. $F : M \to F(M)$ is a closed map. But since M is compact, F is proper $\overset{\text{lemma 5.7}}{\implies}$ F closed.
Please add to your notes: (Said in lecture 11)

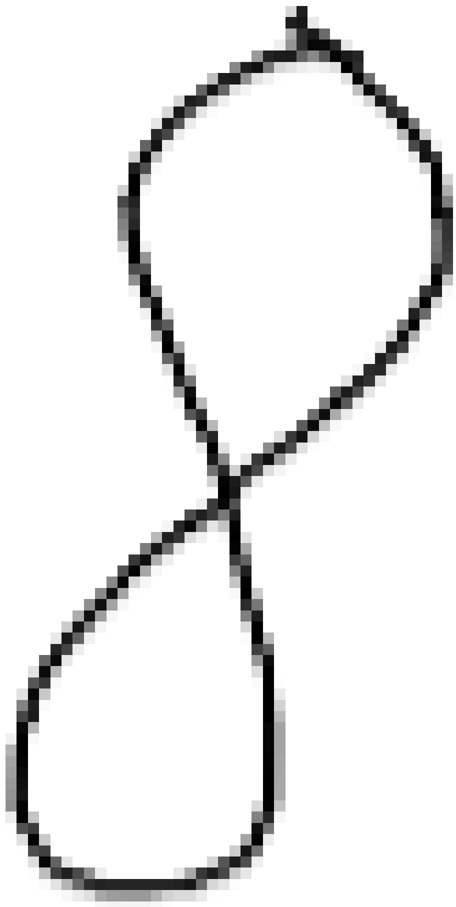

Figure 5.9: Sketch 6.04

Since $S \hookrightarrow N$ is an embedding, $i(U)$ is open in the subspace topology, so there exists $W \subset N$ such that $i(U) = S \cap W$.

$\square$

Lemma 5.7 (Lee Appendix A: 57)**.** *Let X be a topological space. Let Y be locally compact (e.g. a topological manifold), then any proper continuous map is closed.*

Chapter 6: Transversality

6.1 Basic definition

6.1.1 Motivation

Let $l_1, l_2 \subset \mathbb{R}^2$ be (linear) lines. We will say that l_1, l_2 are **transverse**, if $\underbrace{T_0 l_1}_{l_1} \oplus \underbrace{T_1 l_2}_{l_2} = T_0\mathbb{R}^2 \equiv \mathbb{R}^2$

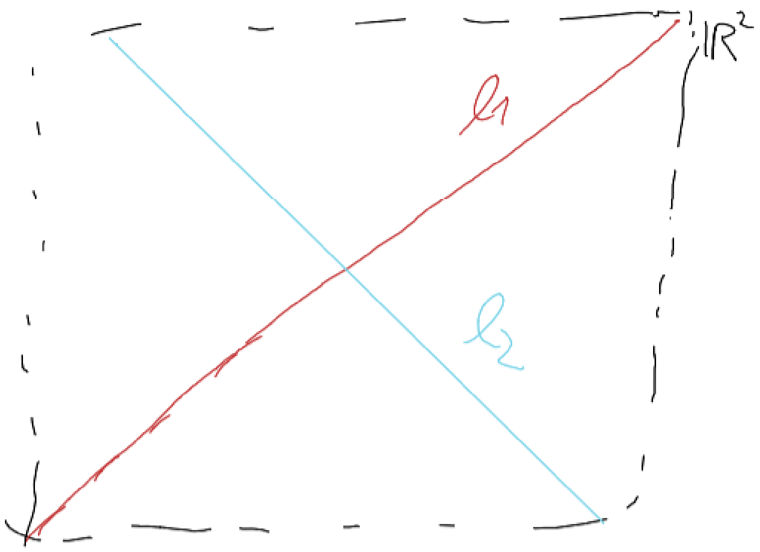

Figure 6.1: Sketch 6.01

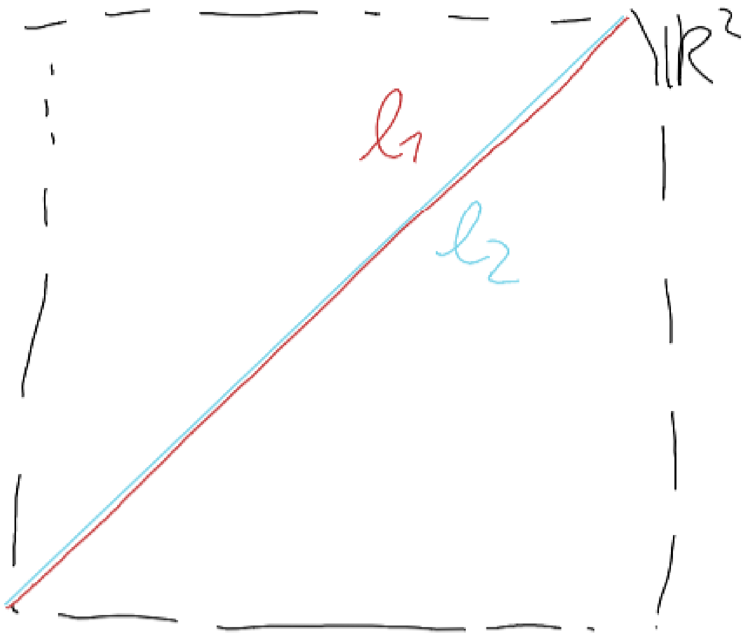

Figure 6.2: Sketch 6.02

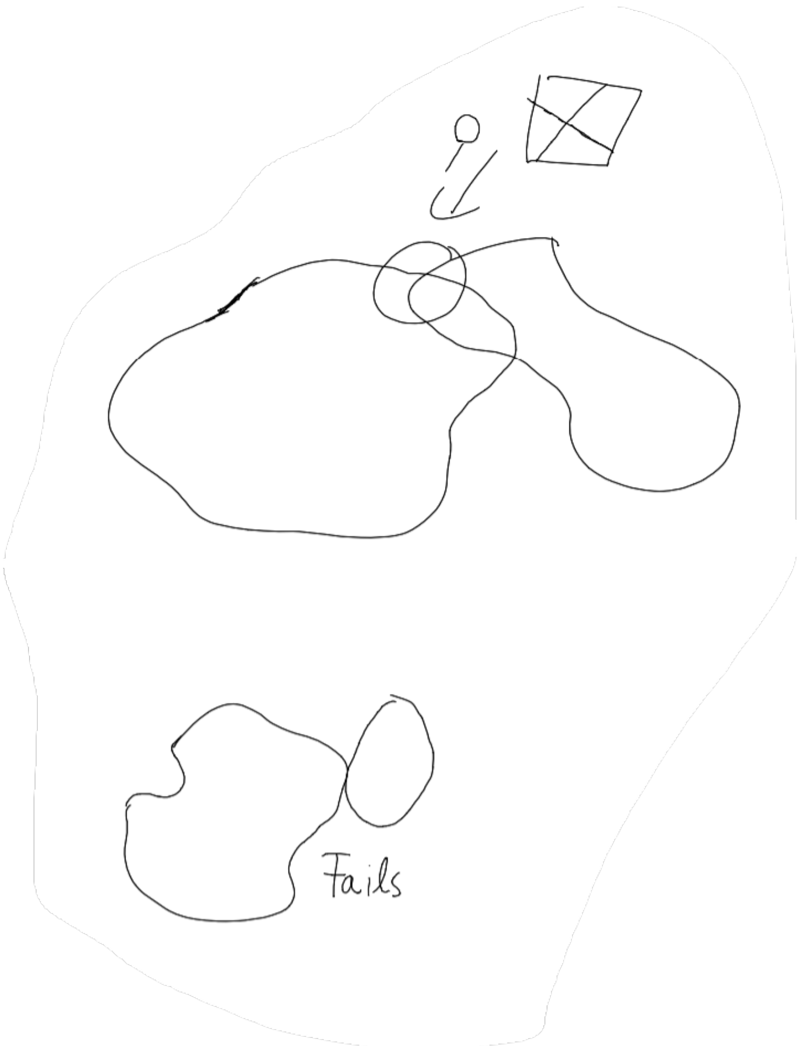

Figure 6.3: Sketch 6.03

Observations:

1. transversality is stable (slight changes to the lines don't change transversality)
2. transversality is generic(for pretty much any lines l_1, l_2 they are transverse)

Similarly to being full rank

One goal: Develop non-linear theory of transversality. I.e. replace $l_1, l_2 \subset \mathbb{R}^2$ by manifolds. Both of the above observations will still be true.

Announcement On Tuesday, November 26, there will be a course evaluation.

Start of lecture 11 (15.11.2024)

- Please show up that day!
- Bring a phone / computer

6.1.2 Transversality for submanifolds

Let M be a smooth manifold.

Definition. *We say that a pair of submanifolds $K, L \subset M$ are* ***transverse*** *at $p \in K \cap L$ if*

$$T_pK + T_pL = T_pM.$$

We say that K, L are ***transverse*** *and write $K \pitchfork L$.*

Here the sum is a gain the span of both of them

Remark. *In the literature, we also see "transversal", "transversally intersecting".*

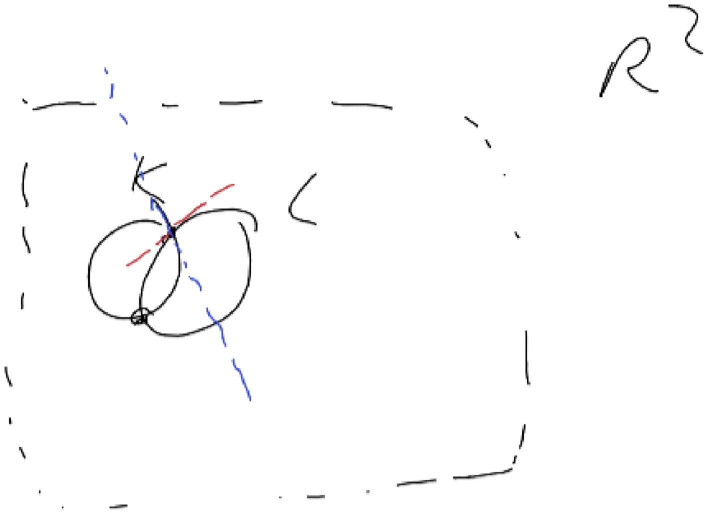

Figure 6.4: Sketch 6.05

Example. *K, L are transverse.*

Figure 6.5: Sketch 6.06

$T_pK = T_PL$, *transversality fails.*

Lemma 6.1. *Let K^k, L^l be submanifolds of M. If K, L are transversal, then $K \cap L \subset M$ is a submanifold.*

Key lemma for transversality

Remark. *In general, if S, T are submanifolds of N, then $S \cap T$ need not be a topological submanifold. For example: $f : \mathbb{R}^2 \to R$*

$$f(x, y) = x^2 - y^2.$$

Let $g : \mathbb{R}^2 \to \mathbb{R}$

$$g(x, y) = 0.$$

Let $S = \{(x,y,z) \mid z = f(x,y)\} \subset \mathbb{R}^{2+1}$ *and* $T = \{(x,y,z) \mid z = g(x,y)\} \subset \mathbb{R}^{2+1}$. *But*

$$S \cap T = \{(x,y,z) \mid z = 0, x^2 - y^2 = 0\}$$

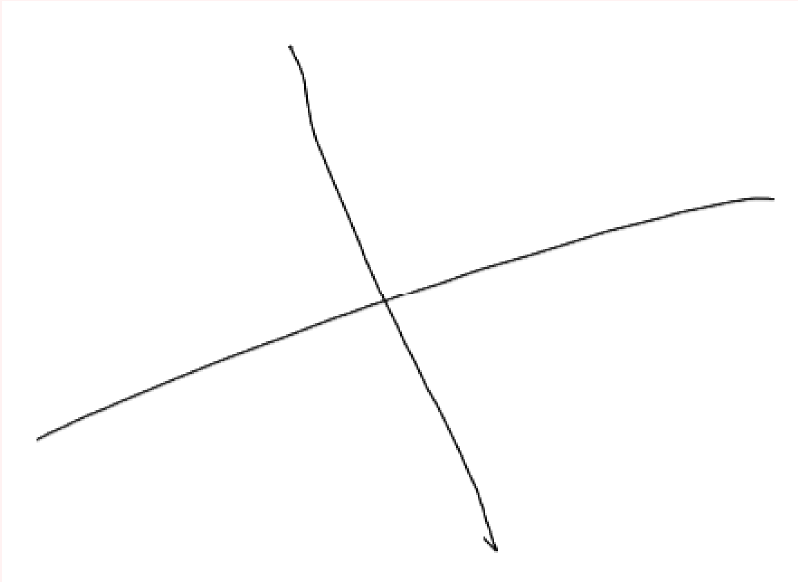

Figure 6.6: Sketch 6.07

Look at the derivative at 0 ....

Proof. This is a local question, e.g. by theorem 5.3. So we may as well assume that $M = U \subset \mathbb{R}^n$. We can also assume that $0 \in U$.
It is enough to check that $K \cap L$ smooth submanifold in a neighborhood of $p = 0$. By rank theorem (4.3), we may assume (after possibly further shrinking $U \ni 0$) that $K = f^{-1}(0), f : U \to \mathbb{R}^{n-k}$, $L = g^{-1}(0), g : U \to \mathbb{R}^{n-l}$ where f, g have full rank.

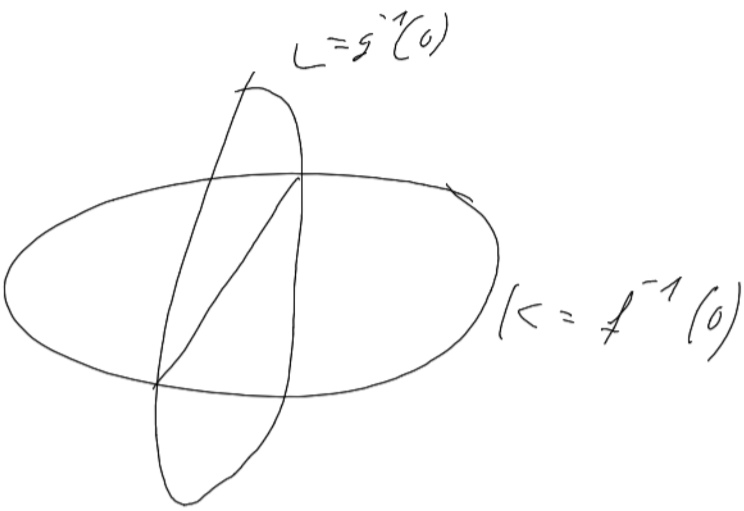

Figure 6.7: Sketch 6.08

Now we consider $H = (f,g) : U \to \mathbb{R}^{n-k} \oplus \mathbb{R}^{n-l}$. It is enough to prove that dH_0 is surjective (by the rank theorem). Note that $H^{-1}(0) = f^{-1}(0) \cap g^{-1}(0) = K \cap L$.
To see surjectivity of dH_0, we consider the exact sequences:

$$\begin{tikzcd}
T_0L + T_0K \arrow[r] \arrow[d, "\parallel"', "\text{transversality}"] & T_0L/(T_0L \cap T_0K) \oplus T_0K/(T_0L \cap T_0K) \arrow[d, "(df_0, dg_0)"] \\
\mathbb{R}^m \equiv T_0U \arrow[r, "dH_0 = (df_0, dg_0)"] & R^{n-k} \oplus \mathbb{R}^{m-l}
\end{tikzcd}$$

Figure 6.8: Sketch 6.09

The horizontal map $T_0L + T_0K \to T_L/(T_0L \cap T_0K) \oplus T_K/(T_0L \cap T_0K)$ sends $v + w$ to (v, w). This is well defined, because if $v + w = v' + w' \implies v - v' = w - w' \in T_0L \cap T_0K$. (Equivalently, this map is just quotient by $T_0L \cap T_0K$)
Clearly the R.H vertical arrow is injective: the kernel of $df_0 = T_0K$, so $(df_0)_{|T_0L/(T_0L \cap T_0K)}$ and similarly for dg_0. To prove the R.H. vertical arrow is an isomorphism, do a dimension count: Exact sequence

$$0 \longrightarrow T_0K \cap T_0L \xrightarrow{v \mapsto (v,v)} T_0K + T_0L \xrightarrow{(u,w) \mapsto u - w} T_0U \equiv \mathbb{R}^n \longrightarrow 0$$

$\implies \dim(T_0K \cap T_0L) + n = k + l \implies \dim(T_0L/_{(T_0K \cap T_0L)}) = l - (k + l - n) = n - k$ and $\dim(T_0K/_{(T_0K \cap T_0L)}) = k - (k + l - n) = n - l$. We conclude that the R.H. vertical arrow is an isomorphism. $\square$

Remark. *We have*

$$\begin{tikzcd}
T_0L \cap T_0K \arrow[r, hook] \arrow[d, "\wr"] & T_0L + T_0K \arrow[d, "\wr"] \\
\ker(dH_0) \arrow[r, hook] & T_0U \equiv \mathbb{R}^3
\end{tikzcd}$$

Figure 6.9: Sketch 6.10

where the left vertical arrow is an isomorphism, due to the five lemma or diagram chasing. Hence $\ker(dH_0) = T_0L \cap T_0K = T_0(L \cap K)$.

6.1.3 Transversality of maps

Definition. *Let*

$$\begin{tikzcd}
 & Y \arrow[d, "g"] \\
X \arrow[r, "f"] & Z
\end{tikzcd}$$

Figure 6.10: Sketch 6.11

be a diagram in Top (the category of topological spaces). We let $X \times_Z Y := \{(x, y) \mid f(x) = g(y)\} \subset X \times Y$*, endowed with the subspace topology. We call* $X \times_Z Y$ *the* ***fiber product (of the diagram)****.*

Remark (for enthusiasts only)**.** *It can be shown that given any topological space* $W \in$ *Top and maps*

$$\begin{tikzcd}
W \arrow[r] \arrow[d] & Y \arrow[d] \\
X \arrow[r] & Z
\end{tikzcd}$$

$$\begin{tikzcd}
W \arrow[dr, dashed, "\exists!"] \arrow[drr, bend left] \arrow[ddr, bend right] & & \\
& X \times_Z Y \arrow[r] \arrow[d] & Y \arrow[d] \\
& X \arrow[r] & Z
\end{tikzcd}$$

Figure 6.11: Sketch 6.12

there exists a unique map $W \to X \underset{z}{\overset{\times}{}} Y$ *commutes.(Universal property)*

Lots of categories admit fiber products! This is a good property for categories to have.
Bad news: The (not-full) subcategory $\mathrm{Man}^\infty \subset \mathrm{Top}$ does not admit fiber products (nor does $\mathrm{Man}^0 \subset \mathrm{Top}$).

Example (Non-example)**.** $Z = \mathbb{R}^{2+1}, X = \mathit{graph}(x^2 - y^2), Y = \mathit{graph}(0)$.

Definition. *Let*

$$\begin{tikzcd}
& Y \arrow[d, "g"] \\
X \arrow[r, hook, "f"] & Z
\end{tikzcd}$$

Figure 6.12: Sketch 6.13

be a diagram in Man^∞*. We say that* f, g *are* ***transverse*** *at* $z = f(x) = g(y)$ *if*

$$im\ df_x + im\ dg_y = T_z Z.$$

We say that f, g *are* ***transverse*** *and say* $f \pitchfork g$ *if this holds for all such* z.

Remark. *Transversality for maps generalizes transversality for submanifolds. Take the diagram*

$$\begin{tikzcd}
& Y \arrow[d] \\
X \arrow[r, hook] & Z
\end{tikzcd}$$

Figure 6.13: Sketch 6.14

Proposition 6.2. *If* $f \pitchfork g$*, then* $X \times_Z Y \xrightarrow{i} X \times Y$ *is a smooth embedding.*

The diagonal arrows are the obvious projections

$$\begin{tikzcd}
& Y & \\
X \times_Z Y \arrow[ur] \arrow[rr, hook] & & X \times Y \arrow[ul] \\
& X \arrow[ul] \arrow[ur] &
\end{tikzcd}$$

Figure 6.14: Sketch 6.15

Proof. Some observations:

- exercise sheet 07: $X \times_Z X \times Y$ is proper.
- similarly to the proof of theorem 5.6, it is enough to prove that i is an injective immersion. By definition i is injective. Therefore we need to check that i is smooth and the differential is injective.

Consider

$$\begin{tikzcd}
\Delta \coloneqq (X,Y,Z,Z) \arrow[d, hook] & \\
X \times Y \times Z \times Z \arrow[r, "\pi"] & X \times Y \\
W = \operatorname{graph}(f,g) \arrow[u, hook] &
\end{tikzcd}$$

Figure 6.15: Sketch 6.16

where

$$\operatorname{graph}(f,g) =\coloneqq \{(x,y,x_2,z_1,z_2) \mid z_1 = f(x), z_2 = g(y)\}.$$

Then

$$W \cap \Delta = \{(x,y,z_1,z_2) \mid z_1 = z_2 = f(x) = g(y)\} = X \times_Z Y.$$

We have:

$$\begin{tikzcd}
W \cap \Delta \arrow[rr, hook, "j"] \arrow[d, "\alpha", "\wr"'] \arrow[dr, hook, "i"] & & X \times X \times Z \times Z \arrow[dl, "\pi"] \\
X \times_Z Y \arrow[r, hook] & X \times Y &
\end{tikzcd}$$

Figure 6.16: Sketch 6.17

α is clearly bijective and continuous. It is elementary that α is a closed map. That means we have to check the limit points. $W \cap \Delta$ is closed, i.e. contains the same limit points... Therefore α is a homeomorphism.

By lemma 6.1, if we can show that $W \pitchfork \Delta$, then $W \cap \Delta \overset{j}{\hookrightarrow} X \times Y \times Z \times Z$ is smooth embedding. Hence $i \coloneqq \pi \circ j$ smooth. Let us now check that $W \pitchfork \Delta$ at some arbitrary point $p = (x,y,z,z) \in W \cap \Delta \subset X \times Y \times Z \times Z$. Note that $z = f(x) = g(y)$. We have

$$T_pW = \{(v,w,df_x(v),dg_y(w))\}$$

and

$$T_p\Delta = \{v',w',u,u\},$$

where $v,v' \in T_xX, w,w' \in T_yY, u \in T_zZ$. We need to check: $T_pW + T_p\Delta = T_p(X \times Y \times Z \times Z)$. We must show that for an arbitrary $(a,b,c,d) \in T_p(X \times Y \times Z \times Z) = T_xX \oplus T_yY \oplus T_zZ \oplus T_zZ$. We must solve:

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$$\begin{aligned}
a &= v + v' \\
b &= w + w' \\
c &= u + df_x(v) \\
d &= u + dg_y(w)
\end{aligned}$$

for some $\underbrace{(v,w,df_x(v),dg_y(w))}_{\in T_pW}, (v',w',u,u) \in T_p\Delta$. The above is equivalent to

we solve this, since we want to show $f \pitchfork g \iff \forall z \in X \times_Z Y : \operatorname{im} df + \operatorname{im} dg = T_zZ$

$$\begin{aligned}
c - d &= df_x(v) - dg_y(w) \in T_zZ && \text{By assumption there exists } v,w \text{ s.t. equation holds} \\
c + d &= 2u + df_x(v) + dg_y(w) && \text{can solve by picking suitable } u \\
a - v &= v' && \\
b - w &= w' && \text{choose } v', w' \text{ s.t. this holds}
\end{aligned}$$

Follows from Lemma 6.1 that

$$\begin{tikzcd} \Delta \cap W \arrow[r, hook] \arrow[rr, bend right, "i"'] & X \times Y \times Z \times Z \arrow[r, "\pi"] & X \times Y \end{tikzcd}$$

is a smooth submanifold. Finally, d_i is injective. This is clear, because $T_pW \longrightarrow T_{(x,y)}X \times Y$ is injective. Indeed, if $(v, w, df_x(v), dg_y(w)) \mapsto 0$, then $(v, w) = (0, 0)$, but then $(v, w, df_x(v), dg_y(w)) = (0, 0, 0, 0)$. $\square$

6.2 Sard's theorem

6.2.1 Measure theory on manifolds

Definition. *A subset $S \subset \mathbb{R}^n$ has* ***measure zero*** *if, for any $\epsilon > 0$, there exists a family $\{C_i\}_{i=1}^{\infty}$ of rectangles:*

$$\mathbb{R}^n \supset C_i = (a_1^i - \epsilon_1^i, a_1^i + \epsilon_1^i) \times \cdots \times (a_n^i - \epsilon_n^i, a_n^i + \epsilon_n^i),$$

where $(a_1^i, \ldots, a_n^i) \in \mathbb{R}^n$ and $(\epsilon_1^i, \ldots, \epsilon_n^i) \in \mathbb{R}^n_{>0}$, s.t.

$$S \subset \bigcup_{i=1}^{\infty} C_i \wedge \sum_{i=1}^{\infty} vol(C_i) < \epsilon.$$

Remark. *We would get an equivalent definition, if we replaced rectangles with balls, cubes, parallelograms,. . . .*

Example. *Suppose $S \subset \mathbb{R}^1$ and $|S| < \infty$, clearly S now has measure zero:*
$a_i \in S \implies (a_i - \epsilon, a_i + \epsilon)$ has finite volume $2n\epsilon$.

- *$S \subset \mathbb{R}$, S countable. Then S has measure zero: Take $(a_i - \frac{\epsilon}{2^i}, a_i + \frac{\epsilon}{2^i})$*

Lemma 6.3. *(i) If $A \subset B \subset \mathbb{R}^n$ and B has measure zero, then A has measure zero.*

(ii) if $A \subset \mathbb{R}^n$ is a countable union of measure zero subsets, then A also has zero measure.

Proof. Emitted. $\square$

Lemma 6.4. *Let $A \subset \mathbb{R}^n$ be compact. Suppose that for all $c \in \mathbb{R} : A \cap \{c\} \times \mathbb{R}^{n-1}$ has $(n-1)$-dimensional measure zero. Then A has n-dimensional measure zero.*

This is misleading . . .

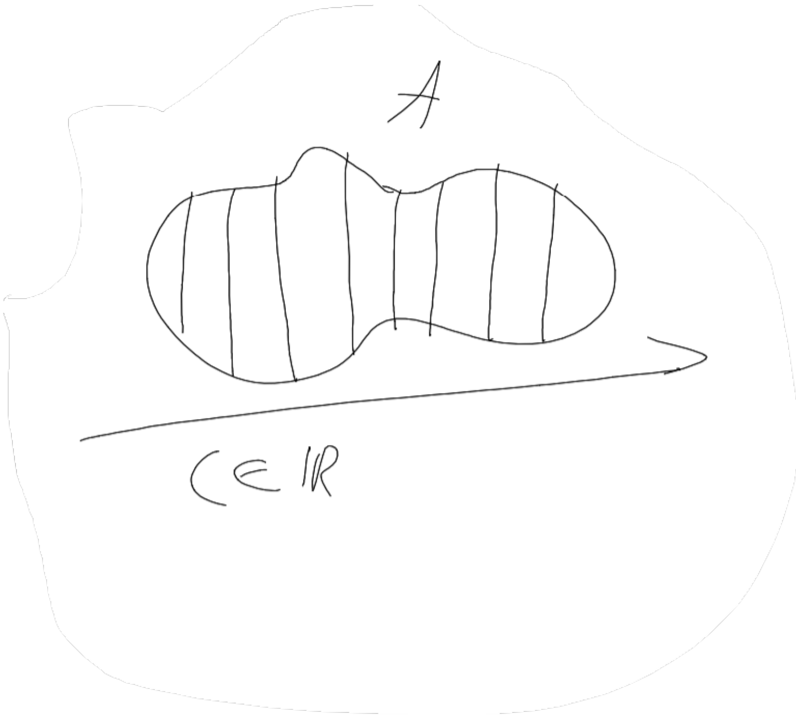

Figure 6.17: Sketch 6.18

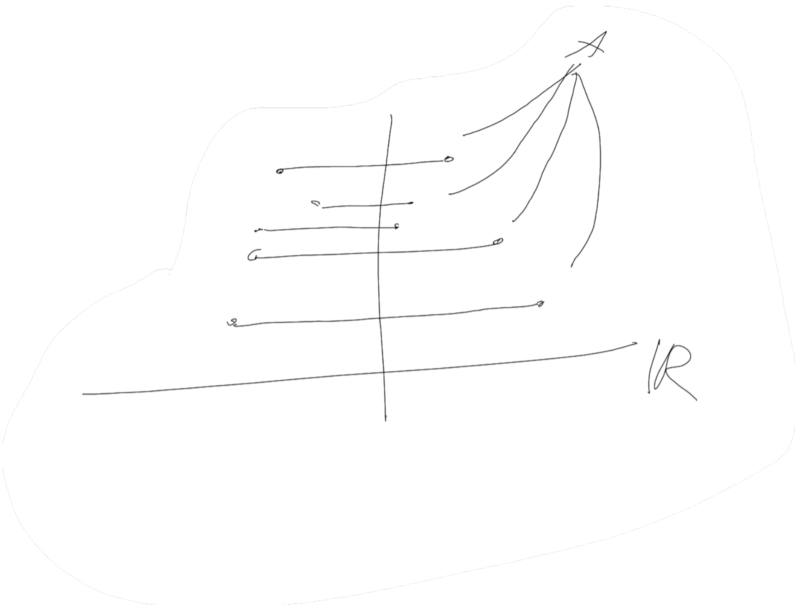

Figure 6.18: Sketch 6.19

Proof. Choose $a < b, a, b \in \mathbb{R}$ so that $A \subset (a, b) \times \mathbb{R}^{n-1}$. Let $A_c \coloneqq \{x \in \mathbb{R}^{n-1} : (c, x) \in A\}$. Fix $\epsilon > 0$. By assumption, we can cover A_c by a union of rectangles $U_c \coloneqq \bigcup_{i=1}^{\infty} C_c^i$ such that $\sum_{i=1}^{\infty} \mathrm{vol}(C_i) < \epsilon$.
By compactness there exists an open interval J_c such that $A \cap J_c \times \mathbb{R}^{k-1} \subset J_c \times U_c$.

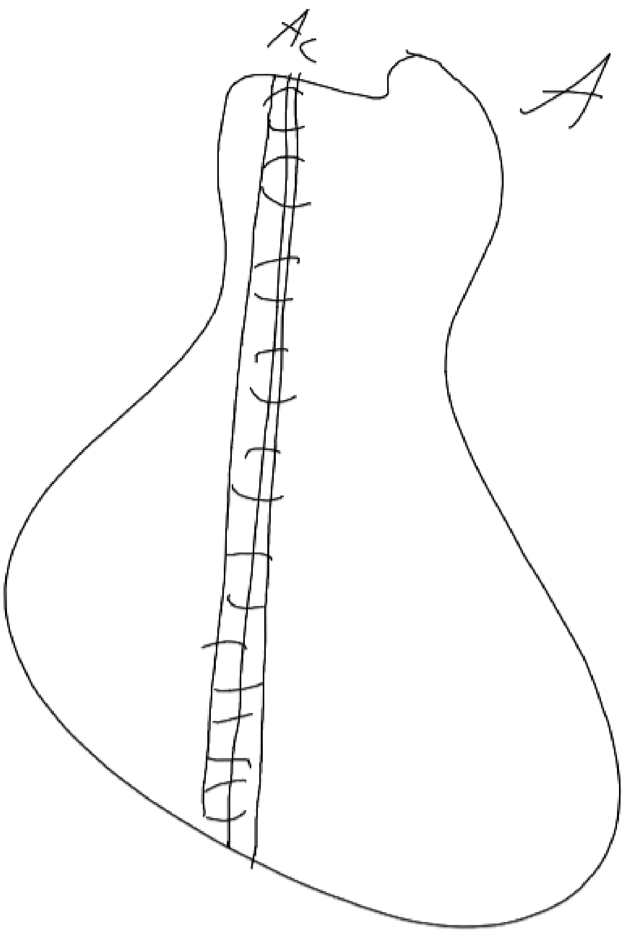

Figure 6.19: Sketch 6.20

Otherwise, there exists a sequence $(c_i, x_i), c_i \to c \wedge x_i \notin U_c \wedge (c_i, x_i) \in A$. By compactness one can extract a convergent subsequence $\to (c, x) \in A$, $x \in U_c^C$. This is impossible, since $A \subset U_c$. By compactness of $[a, b]$, there is a finite sequence $a = c_1 < c_2 < \cdots < c_l = b$ such that

Since A compact

$$\bigcup_{i=1}^{l} J_{c_i} \text{ covers } [a, b].$$

We can freely assume up to deleting certain J_{c_i} that $\sum \text{vol}(J_{c_i}) < 2|b-a|$. Finally: $A \subset \bigcup_{i=1}^{l} J_{c_i} \times U_{c_i}$. But

He writes $|J_{c_i}| \ldots$

$$\text{vol}(J_{c_i} \times U_{c_i}) \leq \sum |J_{c_i}| \times |U_{c_i}| \leq \epsilon \sum |J_{c_i}| = 2\epsilon|b-a|$$

$\square$

Corollary 6.5. *Let $f : \underbrace{A}_{\subset \mathbb{R}^n} \to \mathbb{R}^1$, where A is a countable union of compact subsets (e.g. A could be open or closed) and f continuous. Then the graph of f:*

$$\mathit{graph}(f) = \{(x, y) \mid y = f(x)\}$$

has measure zero as a subset of $\mathbb{R}^{n+1}$.

$\mathbb{R}^n \times \{c\} \subset \mathbb{R}^{n+1}$ *is a measure zero set*

Proof. Assume A compact. Argue by induction. If $n = 0$, trivial. Assume that the result holds for $\leq n+1$. Observe that $\forall c \in \mathbb{R}$, $\text{graph}(f) \cap \{c\} \times \mathbb{R}^{(n-1)+1} = \text{graph}\left(f_{|_{\{c\} \times \mathbb{R}^{n-1}}}\right)$, which by induction has measure zero. Hence follows from Lemma 6.4. For general A, write $A = \bigcup_{i=1}^{\infty} K_i$. Then

Holds by Lemma 6.3

$$\operatorname{graph}(f) = \bigcup_{i=1}^{\infty} \underbrace{\operatorname{graph}\left(f_{|\{K_i\}}\right)}_{\text{measure zero}}$$

□

Lemma 6.6. *Let $A \subset \mathbb{R}^n$, let $F : A \to \mathbb{R}^n$ be smooth. If A has measure zero, so does $F(A)$.*

Remark. *Smoothness is important. The lemma would be false if we only assume F to be continuous. Example: F the cantor function. Smoothness is way to strong. Absolutely continuous functions are the correct class.*

Proof of lemma 6.6. By definition, for any $p \in A$, F extends to a smooth map on a neighborhood of p. Up to shrinking this neighborhood U_p that F extends to $\overline{U_p}$. We can also assume that U_p is a ball. Note that $A \subset \bigcup_{p \in A} U_p$. By lemma 1.5, we can extract a countable subcover. Hence it is enough to prove that $F(A) \cap U_p$ has measure zero for all $p \in A$.
By Taylor's theorem, F is uniformly continuous on $\overline{U_p}$, and we have

Here we use smoothness

$$|F(x) - F(y)| < Q|x - y| \tag{1}$$

for all $x, y \in \overline{U_p}$. Fix $\delta > 0$. Since $A \cap \overline{U_p}$ has measure zero, can cover $A \cup \overline{U_p}$ by a countable union of balls C_i, such that $\sum_i \operatorname{vol}(C_i) < \delta$. By (1),

$$\operatorname{diam}(F(\overline{U_p} \cap C_i)) < Q' \operatorname{diam}(C_i)$$

, where $Q' \leq 100Q$. $\implies$ $F(A \cap \overline{U_p})$ is contained in a countable union of balls D_i of diameter $\leq Q' \operatorname{diam}(C_i)$. Hence

$$\sum_{i=1}^{\infty} \operatorname{vol}(D_i) < Q' \sum \operatorname{vol}(C_i) < 100^n Q' \delta.$$

□

Definition. *Let M be a manifold. A subset $S \subset M$ has measure zero, if, for all charts (U, ϕ), $\varphi(S \cap U)$ has measure zero in $\mathbb{R}^n$.*

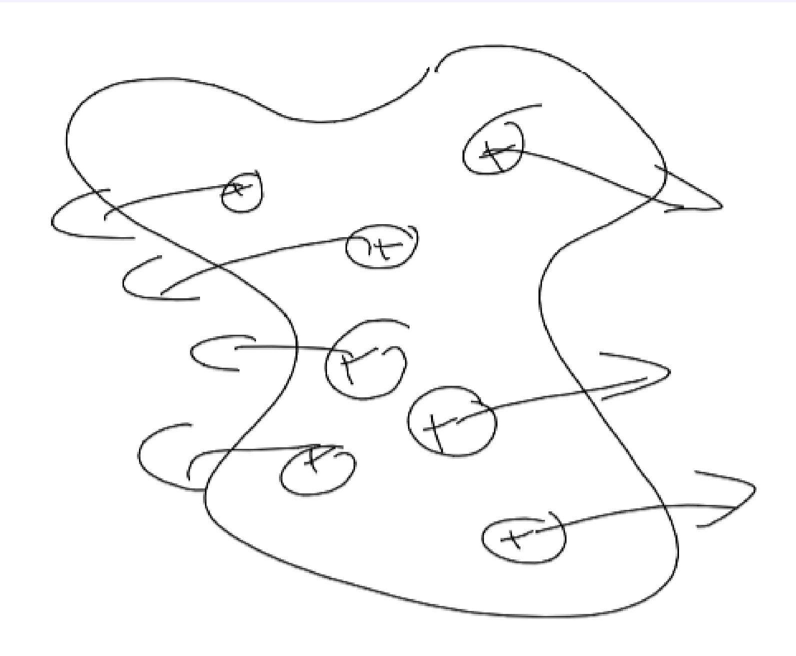

Figure 6.20: Sketch 6.21

Lemma 6.7. *If $\mathcal{A} \subset \mathcal{A}'$ is an inclusion of atlases. Then S has measure zero w.r.t. $\mathcal{A} \iff S$ has measure zero w.r.t. $\mathcal{A}'$.*

Proof. Assume that S has measure zero w.r.t. $\mathcal{A}$, i.e. $\phi_\alpha(S \cap U_\alpha)$ has measure zero for all charts (U_α, ϕ_α). Assume (V, ψ) is a chart for $\mathcal{A}'$. Then

$$\begin{aligned}
\psi(S \cap V) &= \psi\left(\bigcup_{\alpha \in \mathcal{A}} (U_\alpha \cap S) \cap V\right) \\
&= \psi\left(\bigcup_{\alpha \in \mathcal{A}} (U_\alpha \cap S \cap V)\right) \\
&= \psi\left(\bigcup_{\alpha \in \mathcal{A}} \phi_\alpha^{-1} \circ \phi_\alpha(U_\alpha \cap S \cap V)\right) \\
&= \bigcup_{\alpha \in \mathcal{A}} \underbrace{\psi \circ \phi_\alpha^{-1}\left(\phi_\alpha(U_\alpha \cap S \cap V)\right)}_{\text{measure by smoothness}}
\end{aligned}$$

because the U_α form a cover of M, up to replacing $\mathcal{A}$ by a countable cover. □

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Lemma 6.8. *Let M, N be smooth manifolds and $f : M \to N$ a smooth map. If $A \subset M$ has measure zero, then $F(A) \subset N$ also has measure zero.*

Compare lemma 6.6

Proof. Fix $\{(U_\alpha, \varphi_\alpha)\}$ a countable atlas for M. We need to show that given any chart (V, ψ) on N, $\psi(V \cap F(A))$ has measure zero. We may as well assume that $F(A) \subset V$ (otherwise replace A with $F^{-1}(A) \cap V$). Observe that $\psi(F(A))$ is the countable union of these sets $\psi(F(\phi_i^{-1}(\phi_i(A \cap U_i))))$:

$$\psi(F(A)) = \bigcup_i \psi(F(\phi_i^{-1}(\phi_i(A \cap U_i)))).$$

But $\phi_i(A \cap U)$ has measure zero and $\psi \circ F \circ \phi_i^{-1}$ is a smooth function, which is applied to a subset of measure zero of $\mathbb{R}^n$. Therefore the set has measure zero by lemma 6.6 along with the fact that countable unions of measure zeros subsets have measure zero (lemma 6.3). □

6.2.2 Sard's theorem

Definition. *Let $F : M \to N$ be smooth. Given a point $x \in M$, we say that x is a **critical point** of F, if the differential $dF_x : T_xM \to T_{F(x)}N$ fails to be surjective. Otherwise we say that x is a **regular point**.*
*A point $y \in N$ is a **critical value** if $F^{-1}(y)$ contains a critical point. Otherwise we say y is a **regular value**.*

This coincides with the analyis 1 definition

Remark. *If $F^{-1}(y) = \emptyset \implies y$ is a regular value, but not the image of a regular point!*

Theorem 6.9 (Sard)**.** *Let M, N be smooth manifolds. Let $F : M \to N$ be a smooth map. Then the set of critical values of $F \subset N$ has measure zero.*

Very important theorem

Example. *$M \to \mathbb{R}, M \ni x \mapsto 0 \in \mathbb{R}$. Here the set of **critical points** has full measure (since it is M), But the set of **critical values** is $\{0\} \subset \mathbb{R}$.*

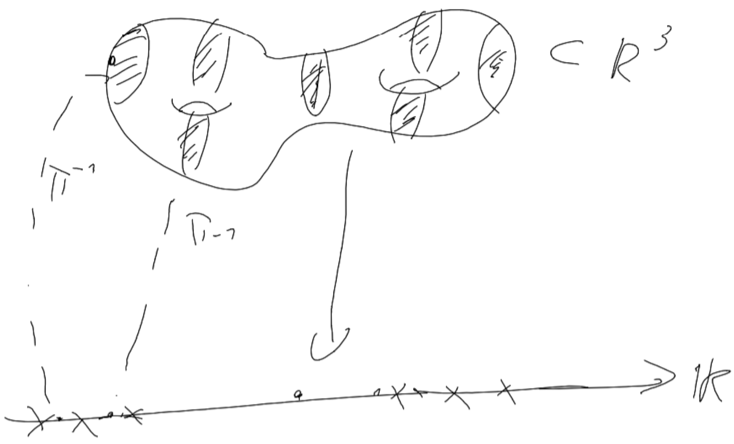

Figure 6.21: Sketch 6.22

Example. *Morse theory: study the topology of manifolds by studying functions on them.*

Corollary 6.10. *Let $F : M^m \to N^n$ be a smooth map. If $m < n$, then $im(F) \subset N$ has measure zero.*

Proof. Clear for dimensional reasons. □

Corollary 6.11. *Let $M^m \subset \mathbb{R}^N$ be a submanifold. Write $\mathbb{R}^{N-1} = \{(x_1, \dots, x_{N-1}, 0)\} \subset \mathbb{R}^N$. Given $v \in \mathbb{R}^N - \mathbb{R}^{N-1}$, we set $\pi_v : \mathbb{R}^N \to \mathbb{R}^{N-1}$ to be the projection with kernel $\mathbb{R} \cdot v$.*

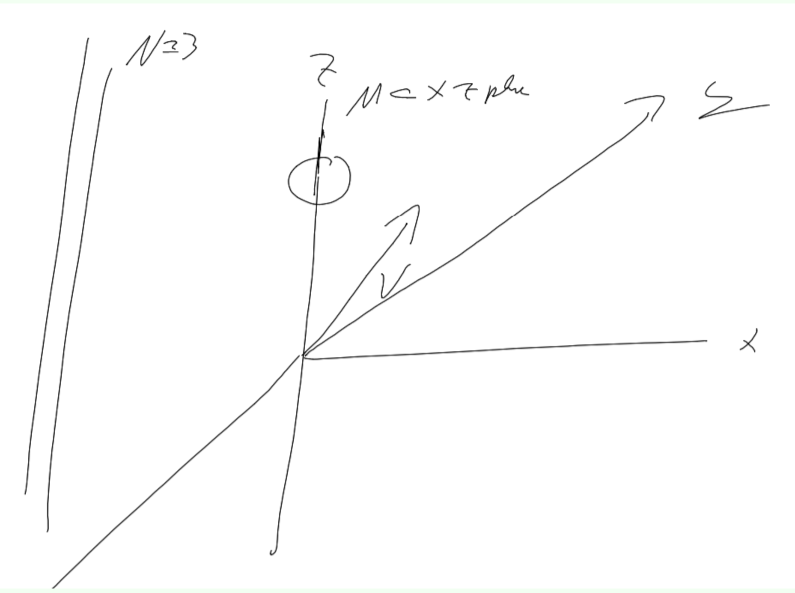

Figure 6.22: Sketch 6.23

Assume that $N > 2m + 1$. Then the set of $v \in \mathbb{R}^N \setminus \mathbb{R}^{N-1}$ such that $\pi_{v|_M} : M \to \mathbb{R}^{N-1}$ is an injective immersion is non-empty. It is, in fact, dense[a].

[a] In $\mathbb{RP}^{N-1}, \mathbb{R}^N$

Example. *Take $v = (0, 0, 1)$. Then $\pi_{(0,0,1)}(M = S^1) = [-1, 1]$, and not injective.*

Example. $v = (1, 1, 1), \pi_v(M = S^1) = S^1$*, up to scaling of the axis.*

Proof. Firstly, $\pi_{v|_M}$ is injective iff for all $p \in M$, $(p + tv)_{t \in \mathbb{R}} \cap M = \{p\}$.

Secondly, $\pi_{v|_M}$ is an immersion $\iff$ for all $p \in M$, $T_pM \cap \ker d\pi_v = 0$[1] $\iff$ $\overbrace{T_pM}^{\subset \mathbb{R}^N}$ does not contain v.
Let $\Delta \subset M \times M$ be the diagonal (i.e. $\Delta = \{(x,x) \mid x \in M\} \subset M \times M$). Let $0_M \subset TM$ be the **zero section**:

$$0_M := \{(p,0) \in TM\} \subset TM$$

where

$$TM = \bigcup_{p \in M} T_pM.$$

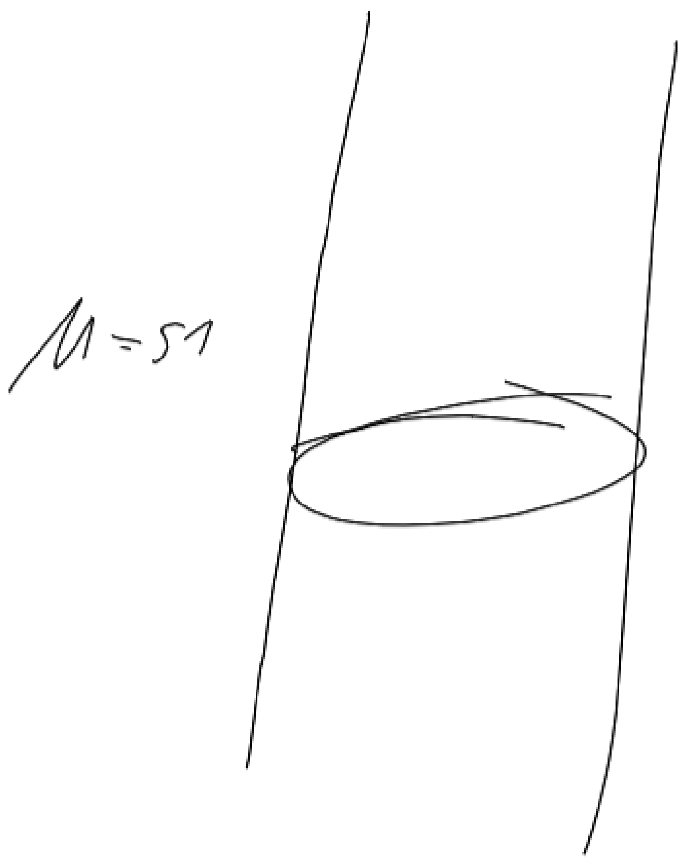

Figure 6.23: Sketch 6.24

Define

$$\begin{aligned} \alpha :& M \times M \setminus \Delta \to \mathbb{RP}^{N-1} \\ & (p,q) \mapsto [p-q] \\ \beta :& TM \setminus O_M \to \mathbb{RP}^{N-1} \\ & (p,w) \mapsto [w] \end{aligned}$$

It is easy to check that α, β are smooth. Check α

$$(p,q) \mapsto \underbrace{p-q}_{\in \mathbb{R}^N - \{0\}} \mapsto \underbrace{[p-q]}_{\in \mathbb{R}^N \setminus \{0\}/\mathbb{R}^\times} \equiv \mathbb{RP}^{N-1}.$$

[1] i.e. the zero vector space

Note that $N-1 > 2m$, and dimension of $M \times M \setminus \Delta$ and $TM - O_M$ is $2m$. It follows by corollary 6.10 that $\mathrm{im}(\alpha) \cup \mathrm{im}(\beta) \subset \mathbb{RP}^{N-1}$ has measure zero. Finally the conclusion follows from sheet 08. $\square$

To see that quotient maps are smooth is a good exercise for the exam

Corollary 6.12 (Strong Whitney embedding)**.** *Suppose that M^m (compact) manifold. Then M admits an embedding into $\mathbb{R}^{2m+1}$.*

Remark. *Compactness is not a necessary assumption. But our prof. assumes compactness. If we use this, we don't have to use compactness.*

Proof. By theorem 5.6, M admits an embedding into $\mathbb{R}^N$, $N \gg 1$. If $N > 2m+1$, then by corollary 6.11 there exists $v \in \mathbb{R}^N \setminus \mathbb{R}^{N-1}$, such that $\pi_{v|_M} : M \to \mathbb{R}^{N-1}$ is an injective immersion.

By repeatedly applying corollary 6.11, we get an injective immersion from $M \overset{i}{\hookrightarrow} \mathbb{R}^{2m+1}$. As in the proof of theorem 5.6, i must be an embedding, because M is compact. $\square$

Corollary 6.13. *Let I, X, Y, Z be manifolds. Let $f : X \times I \to Z, g : Y \to Z$ be smooth maps. Suppose that $f \pitchfork g$. Then for almost all $s \in I$*

i.e. away from a set of measure zero

$$f_s(\cdot) = f(\cdot, s) \pitchfork g.$$

Remark. *Let $f_0 : X \to \mathbb{R}^n, g : Y \to \mathbb{R}^n$ be any maps. Consider*

$$f : X \times \mathbb{R}^n \to \mathbb{R}, (x, s) \mapsto f_0(x) + s$$

. Then f is clearly a submersion. Hence $f \pitchfork \psi \implies f_s \pitchfork g$ for almost all s.

Proof. By assumption and proposition 6.2:

$$\begin{tikzcd} W = (X \times I) \times_Z Y \arrow[rr, hook, "\text{smooth embedding}"] \arrow[dr, "\pi"'] & & (X \times I) \times Y \arrow[dl] \\ & I & \end{tikzcd}$$

We will show that if $s \in I$ is a regular value of π, then $f_S \pitchfork g$. This implies the corollary by Sard's theorem 6.9.
So suppose that $s \in I$ is a regular value. Then either

(i) $s \notin \mathrm{im}(\pi)$. In this cae $\mathrm{im}(f_s) \cap g = \emptyset$

(ii) $s \in \mathrm{im}(\pi)$. In this case d_π is surjective on π^{-1}.

Let's assume case (ii). Suppose that $z = f_s(x) = g(y)$. Since $f \pitchfork g$, we have

$$\mathrm{im} df_x + \mathrm{im} dg_y = T_z Z.$$

FOr any $a \in T_z Z$, there exists a pair $b = (w, e) \subset T_{x,s}(X \times I) = T_x X \oplus T_s I$, such that $df_{(x,s)}(w, e) - a \in \mathrm{im} dg_y$.
Since $d\pi$ is surjective, there exist an element $(w', e, c') \in T_{(x,s,y)} W = T_{(x,s,y)}(X \times I) \times_Z Y$. But now

$$(df_s)_x(w - w') - a = df_{(x,s)}((w, e) - (w', e)) - a = \underbrace{df(\overbrace{\ b\ }^{=(w,e)}) - a}_{\in \mathrm{im} dg_y} - \underbrace{\overbrace{df(w', e)}^{dg_y(c')}}_{\in \mathrm{im} dg_y}$$

$$\begin{tikzcd} (X \times I) \times_Z Y \arrow[r] \arrow[d] & Y \arrow[d] \\ X \times I \arrow[r] & Z \end{tikzcd}$$

$\implies (df_s)_x(w - w') - a \in \mathrm{im} dg_y.$

$\square$

In this lecture we will try to prove theorem 6.9 using three intermediate lemmas.

Start of lecture 14 (26.11.2024)

Notation (auxiliaray): Consider $U \subset \mathbb{R}^m$ open, $F : U \to \mathbb{R}^n$. We let $C \subset U$ be the set of critical points of F. More generally, for $k \geq 1$ we let

$$C \supset C_k := \{x \in C \mid \forall 1 \leq i \leq k : \text{All ith partial derivatives of } F \text{ vanish at } x\}.$$

Clearly $C \supset C_1 \subset C_2 \subset \ldots$. Note also C, C_k are all closed.

Because being zero is a closed condition

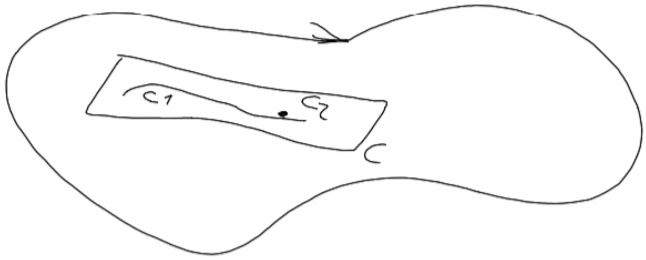

Figure 6.24: Sketch 6.26

Lemma 6.14. *Suppose that $k > \frac{m}{n} - 1$. Then $F(C_k)$ has measure zero.*

Proof. For each $a \in U$, there exists a closed cube $a \in E \subset U$. By second countability we can cover C_k by countability many such cubes. Hence it is enough to prove, for arbitrary such E that $F(C_k \cap E)$ has measure zero. Now fix $a \in C_k$ and cube $E \ni a$. Also fix $A > \sup_{y \in E} |\partial_x^\alpha F(y)|$ for $\alpha = (\alpha_1, \ldots, \alpha_m) \in \mathbb{N}^m, |\alpha| \leq k + 1$.
Let $L > 0$ be the side length of E. Let $K \gg 1$ be a natural number. We now subdivide E by K^m cubes of side length L/K. Let $E_1, \ldots, E_{K^m}$ be an enumeration of these subcubes.

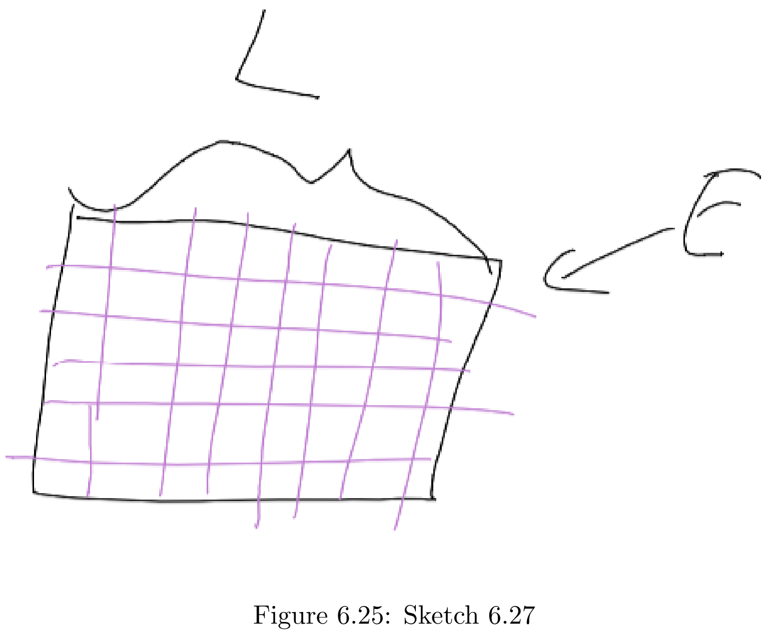

Figure 6.25: Sketch 6.27

Since $a \in E$ there exists some i_0 such that $a \in E_{i_0}$. Since $a \in C_k$, Taylor's theorem finishes the following inequality:

$$|F(x) - F(a)| \leq A'|x - a|^{k+1}$$

for all $x \in E_{i_0}$, where A' depends only on A.

$\implies F(E_{i_0})$ is contained in a ball centered at $F(a)$ of radius $A'(L/K)^{k+1}$. Now

$$F(C_k \cap E) = \bigcup_{i|C_k\cap E_i\neq\emptyset} F(C_k \cap E_i).$$

But each $F(C_k \cap E_i)$ is contained in a union of balls of volume $\leq \Lambda\left[A'(L/K)^{k+1}\right]^n$. Therefore at most K^m cubes E_i which intersect C_k non-emptily. Hence $F(C_k \cap E)$ is contained in a union of balls of total volume at most

$$\Lambda {A'}^n K^m \left[(L/K)^{k+1}\right]^n = \lambda {A'}^n L^{(k+1)n} K^{m-(k+1)n}.$$

Since $k > \frac{m}{n} - 1$ the exponent of K is negative and hence increasing K forces the equation above to go to zero. □

Restricting to the cubes which intersect C_k is a very important step, because otherwise we can't Taylor and have no control over the measure!

Lemma 6.15. *Assume that Sard's theorem holds for domains of dimension $< m$. Then $F(C \setminus C_1)$ has measure zero.*

Proof. Since C_1 is closed in U, we can assume after replacing U by $U \setminus C_1$, that $C_1 = \emptyset$. Then we just prove that $F(C)$, under that assumption, has measure zero.
Fix $a \in C$. By assumption that $C_1 = \emptyset$. Up to reordering coordinates in the source and in the target, we can assume that $\partial_{x_1} F^1(a) \neq 0$. Set $\begin{cases} u(x) = F^1(x) \\ v^i(x) = x_i & 2 \leq i \leq m \end{cases}$. By the inverse function theorem $(u, v) = (u, v^1, \dots, v^m)$ forms a coordinate system in some neighborhood V_a of a. Since the transition matrix is

$$\begin{bmatrix} \partial_{x_1} F^1 & \star & \star & \star \\ 0 & & 1 & \end{bmatrix}.$$

We can assume that (u, v) extend to $\overline{V_a}$. With respect to these new coordinates (u, v), we have $F(u, v) = (u, F^2(u, v), \dots, F^n(u, v))$. So we have: $dF(u, v) = \begin{bmatrix} 1 & 0 & \dots & 0 \\ \star & & & \\ \vdots & & \frac{\partial F^i}{\partial v^j} & \\ \star & & & \end{bmatrix}$ where $2 \leq i \leq n, 2 \leq j \leq m$. Therefore $C \cap \overline{V_a}$ is precisely the set of points such that $\operatorname{rank}\left(\frac{\partial F^i}{\partial v^j}\right) < n - 1$.
Note that $F(C \cap \overline{V_a})$ is compact. By lemma 6.4, if we can show that $F(C\cap) \cap \{y^1 = d\}$ has measure zero, then $F(C \cap \overline{V_a})$ has measure zero. Since C is covered by countably many such V_a (by second countability), we could conclude that $F(C)$ has measure zero.
For $d \in \mathbb{R}$, $B_d \coloneqq \{v \mid (d, v) \in \overline{V_\alpha}\} \subset \mathbb{R}^{n-1}$. Set $F_d(v) \coloneqq (F^2(d, v), \dots, F^n(d, v))$. Since $F(d, v) = (d, F_d(v))$, we have that the critical values of $F_{|\overline{V_a}}$ that lie in $\{y^1 = d\}$ are precisely the points (d, q), where q are critical values of F_d. By assumption that Sard's theorem 6.9 holds for dimension $< m$, since the domain of F_d has dimension $m - 1 < m$,
$\{\text{critical values of } F_d\} = \{y_1 = d\} \cap F(C \cap \overline{V_a})$ has measure zero. □

Bird's eye view: Change coordinates, consider modified functions

Lemma 6.16. *Assume that Sard's theorem holds for domains of dimension $< m$. For all $k \geq 1$, $F(C_k \setminus \{F(C_{k+1})\})$ has measure zero.*

Proof. As in the proof of the previous lemma 6.15, we can assume $C_{k+1} = \emptyset$. We will prove under that assumption that $F(C_k)$ has measure zero.
Let $a \in C_k$ be arbitrary. Let $\sigma : U \to \mathbb{R}$ be a k-th partial derivative of F, with the property that σ has at least one non-vanishing partial at a. I.e. $\begin{cases} \sigma = \partial_x^\alpha F & |\alpha| = k \\ \partial_{x_i}\sigma(a) \neq 0 & \forall i \end{cases}$. Let V_a be a neighborhood of a consisting of regular points of σ. Let $\Sigma \coloneqq \{\sigma^{-1}(0)\} \cap V$. Then Σ is a smooth submanifold in V_a. By definition of C_k, we have $(C_k \cap V_a) \subset \sigma^{-1}(0) \cap V_a$.
Moreover $F(C_k \cap V_a)$ is contained in the set of critical values of $F_{|\Sigma}$ (that's because $\partial_{x_i} F^j = 0 \implies dF_{|T\Sigma} \equiv 0$). But $\dim(\Sigma) = \dim(U) - 1 = m - 1$. Hence $\{$ critical values of $F_{|\Sigma}\}$ has measure zero, by assumption. □

Proof of Sard's theorem 6.9. We prove it by induction on the dimension of the source. If $F : M^m \to N^n$, and $m = 0$ the statement is true.
Let's assume that Sard's theorem has been proven for all manifolds $F : M^m \to N^n$, where $m < \tilde{m}$. We need to prove it for maps $\tilde{F} : \tilde{M} \to \tilde{N}$, where $\dim(\tilde{M}) = \tilde{m}$.

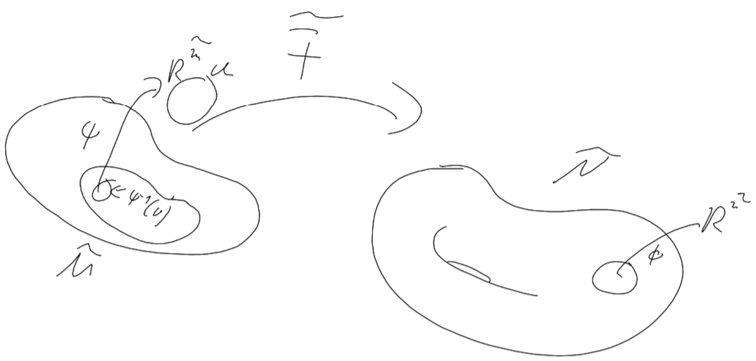

Figure 6.26: Sketch 6.28

By covering source and target by charts, we can assume

- $\tilde{M} = U \subset \mathbb{R}^m$
- $\tilde{N} \subset \mathbb{R}^n$.

If the intersection is non-empty, we reall need lemma 6.14

Apply lemma 6.14,6.15,6.16 to get the claim. ☐

Chapter 7: Vector fields

7.1 Basics

Start of lecture 15 (29.11.2024)

Let M be a smooth manifold. Recall that we have

$$\pi : TM \to M$$

where $TM = \coprod_{p \in M} T_pM$. A typical point in TM is $(p, \underbrace{v}_{\in T_pM})$ and

$$\pi((p, v)) = p.$$

Definition. *A (smooth)* ***vector field*** *X on M is a section of $\pi : TM \to M$. In other words*

1. *$X : M \to TM$ smooth map*
2. *$\pi \circ X = id$*

We let $\mathcal{X}(M)$ be the set of vector fields on M.

Concretely: To every point $p \in M$, we associate a vector

$$X(p) = X_{\in} T_pM.$$

Visually

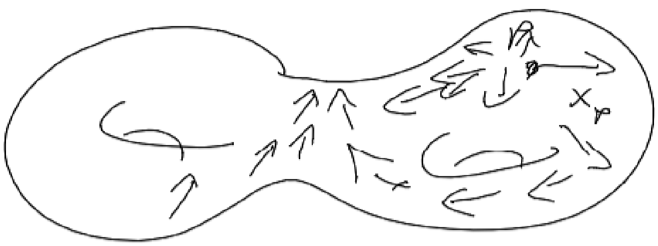

Figure 7.1: Sketch 7.01

Another picture:

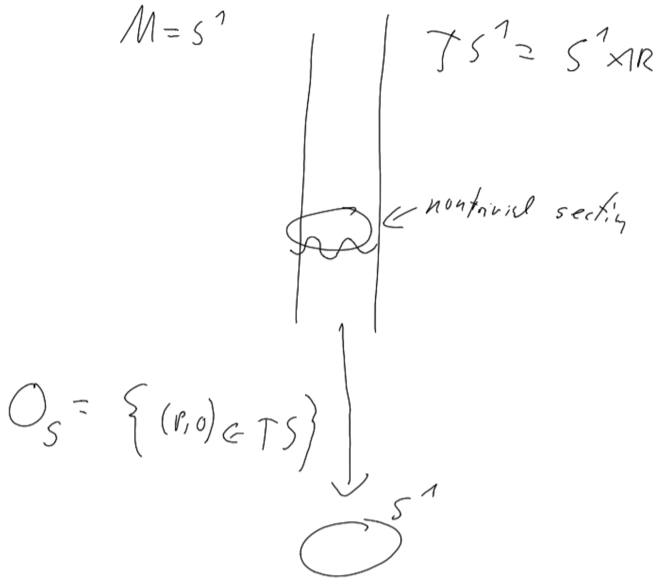

Figure 7.2: Sketch 7.02

Lemma 7.1. *Let M be a smooth manifold.*

(a) $\mathcal{X}(M)$ is a $\mathbb{R}$ vector space

(b) $\mathcal{X}(M)$ is a module over the ring $C^\infty(M)$ of smooth functions on M:

$$(f, X) \mapsto fX$$

$$fX(p) = \underbrace{f(p)}_{\in\mathbb{R}}\,\underbrace{X(p)}_{\in T_pM}$$

Proof. Exercise. □

Remark. *In this class, we only consider smooth vector fields. If you drop the smoothness condition on the map $X : M \to TM$, you get a* ***rough vector field****.*

We are not gonna study those, but it is useful to know they exist

Example. *Recall that $T_p\mathbb{R}^n \equiv \mathbb{R}^n$, hence $T\mathbb{R}^n \equiv \mathbb{R}^n \times \mathbb{R}^n$. A vector field $X \in \mathcal{X}(\mathbb{R}^n)$ is just a map*

$$X : \mathbb{R}^n \longrightarrow R^n \times \mathbb{R}^n$$

$$p \longrightarrow (p, v(p))$$

Equivalently X is a map $\mathbb{R}^n \to \mathbb{R}^n$, since the first coordinate is just fixed to be the identity. This agrees with the notion from Analysis 2.

A map $\mathbb{R}^n \ni p \mapsto (X^1(p), \ldots, X^n(p))$

Remark. *$T_p\mathbb{R}^n$ has a canonical basis $\{(\partial_{x_1})_p, \ldots, (\partial_{x_n})_p\}$. This identifies $(\partial_{x_i})_p \equiv (0, \ldots, 0, \overbrace{1}^{i\text{th component}}, 0 \ldots, 0)$. We can equivalently write a vector field on $\mathbb{R}^n$ as*

$$p \mapsto (X^1(p), \ldots, X^n(p))$$

or

$$p \mapsto X^1(p)(\partial_{x_1})_p + \cdots + X^1(p)(\partial_{x_n})_p.$$

Notation: We write $\partial_{x_i} \in \mathcal{X}(\mathbb{R}^n)$ for the vector field

$$p \mapsto (\partial_{x_i})_p \in T_p\mathbb{R}^m \equiv (0, \ldots, 0, \overbrace{1}^{i\text{th component}}, 0 \ldots, 0)$$

In the literature another common notation for the same thing is $\frac{\partial}{\partial x_i}$.

Example (Vector field on S^3)**.** *Let* $M = \{(x_0, \dots, x_3) \mid \sum x_i^2 = 1\} \subset \mathbb{R}^{1+3}$*. Let* $X = x_0\partial_{x_1} - x_1\partial_{x_0} + x_2\partial_{x_3} - x_3\partial_{x_2} \in \mathcal{X}(\mathbb{R}^{1+3})$*. Observe that* $X \perp S^3 \iff \underbrace{X \cdot v}_{X_v \cdot v} = 0, v \in S^3$*.*

Hence $X \in \mathcal{X}(S^3)$*.*

$$\begin{tikzcd}
TS^3 \arrow[r, hook] \arrow[d] & T\mathbb{R}^{1+3} \arrow[d, "\pi"', shift right] \\
S^3 \arrow[r, hook] \arrow[u, dotted, bend left, "X_{|_{S^3}}"] & \mathbb{R}^{1+3} \arrow[u, bend right]
\end{tikzcd}$$

where the map $X_{|_{S^3}}$ *is implied by composition.*

Example. *For any* M *smooth, the map* $p \mapsto 0 \in T_pM$ *is a vector field called the* ***zero section****.*

This is the only canonical vector field. “There is no 1”

Let $F : M \to N$ be a smooth map. Let $X \in \mathcal{X}(M), Y \in \mathcal{X}(N)$.

Definition. *We say that* X, Y *are* ***F-related*** *if the following diagram commutes*

$$\begin{tikzcd}
TM \arrow[r, "dF"] \arrow[d] & TN \arrow[d] \\
M \arrow[r, "F"] \arrow[u, bend left, "X"] & N \arrow[u, bend right, "Y"']
\end{tikzcd}$$

Be warned! Given $F : M \to N, X \in \mathcal{X}(M)$, there need not exist a $Y \in \mathcal{X}(N)$ s.t. X, Y are F-related. Vector fields do not push forward.

They push back!

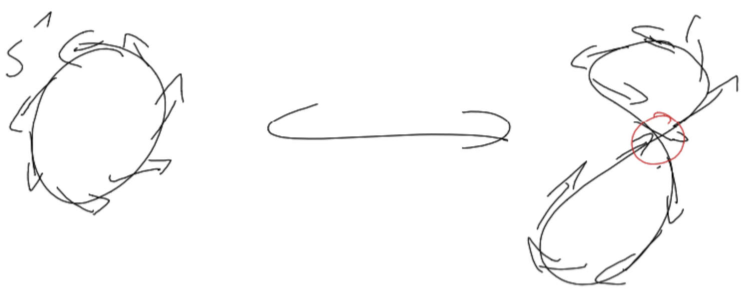

Figure 7.3: Sketch 7.04

Definition. *Let* $F : M \to N$ *be a diffeomorphism. Let* $X \in \mathcal{X}(M)$*, we define the* ***pushforward*** *of* X $F_\star X \in \mathcal{X}(N)$ *by*

$$(F_\star X)_p = dF_{F^{-1}(p)}(X_{F^{-1}(p)}),$$

i.e.:

$$\begin{tikzcd}
TM \arrow[r, "dF"] \arrow[d] & TN \arrow[d] \\
M \arrow[u, bend left, "X"] & N \arrow[l, "F^{-1}"] \arrow[u, dotted, bend right, "F_\star X"']
\end{tikzcd}$$

Lemma 7.2. *Given* $F : M \to N$*,* $G : N \to P$ *diffeomorphisms,*

(i) $(G \circ F)_\star = G_\star \circ F_\star : \mathcal{X}(M) \to \mathcal{X}(P)$

(ii) if $F = id, M = N$*, then* $F_\star = id : \mathcal{X}(M) \to \mathcal{X}(M)$

Proof. Exercise. □

7.2 Vector fields as derivations

Recall: a tangent vector $V \in T_pM$, $p \in M$ can be viewed as a **derivation at** p, i.e.

$$V : C^\infty(M) \to \mathbb{R}, V(fg) = f(p)V(g) + V(f)g(p).$$

Notation: Let $X \in \mathcal{X}(M)$. Given a smooth function on $f \in C^\infty(M)$, we let Xf be the map $M \ni p \mapsto X_p f \in \mathbb{R}$.

Lemma 7.3. *(i) If $X \in \mathcal{X}(M)$, i.e. X is a smooth vector field, then Xf is a smooth function*

(ii) Suppose that $X : M \to TM$ is an ***arbitrary*** *section (this is also known as a rough vector field). If Xf is smooth for all $f \in C^\infty(M)$, then X is a* ***smooth*** *vector field.*

Proof. Sheet 09. Hint: Test against coordinate functions. □

Check in $\mathbb{R}^n$

Definition. *An $\mathbb{R}$ linear map $X : C^\infty(M) \to C^\infty(M)$ is called a* ***derivation*** *if, for all $f, g \in C^\infty(M)$:*

$$X(fg) = f \cdot Xg + Xf \cdot g$$

The $\cdot$ are multiplications of functions

Lemma 7.4. *1. If $X \in \mathcal{X}(M)$, then the map*

$$C^\infty(M) \ni f \mapsto Xf \in C^\infty(M)$$

is a derivation.

2. every derivation is of this form.

Upshot of the lemma:

$$\mathcal{X}(M) \equiv \{\text{derivations } C^\infty(M) \to C^\infty(M)\}$$

just as we identified before

$$T_pM \equiv \{\text{derivations at } p\}.$$

Proof. (1) By definition, $\forall p \in M$, we have

All of this follows basically by applying point wise definitions

$$\begin{aligned} X(fg)(p) = X_p(fg) &= f(p)X_p g + X_p f g(p) \\ &= f(p)Xg(p) + Xf(p)g(p). \end{aligned}$$

Suppose that $\nu : C^\infty \to C^\infty$ is a derivation. Define a (possibly discontinuous) vector field X by setting

$$X_p f = \underbrace{\nu f}_{\in C^\infty(M)}(p).$$

By lemma 7.3 (ii) X is smooth, because $\nu f \in C^\infty$. □

Definition. *Let $X, Y \in \mathcal{X}(M)$. We let $[X, Y] \in \mathcal{X}(M)$ defined by the rule*

$$C^\infty(M) \ni f \mapsto XYf - YXf \in C^\infty(M). \tag{1}$$

We call $[X, Y]$ the ***Lie bracket*** *of X, Y.*

Lemma 7.5. *Equation 1 defines a derivation, hence $[X, Y]$ is a smooth vector field (by Lemma 7.4).*

Proof. For $f, g \in C^\infty(M)$:

$$\begin{aligned} [X, Y](f, g) &= XY(fg) - YX(fg) \\ &= X[f \cdot Yg + Yf \cdot g] - Y[f \cdot Xg + Xf \cdot g] \\ &= Xf \cdot Yg + f \cdot XYg + XYf \cdot g + Xf \cdot Xg \\ &\quad - Yf \cdot Xg - f \cdot YXg - YXf \cdot g - Xf \cdot Yg \\ &= f(XY - YX)(g) - g(XY - YX)f \\ &= f[X, Y]g + g[X, Y]f \end{aligned}$$ □

Remark (Properties of Lie bracket). *The Lie bracket* $[\cdot, \cdot] : \mathcal{X}(M) \times \mathcal{X}(M) \to \mathcal{X}(M)$ *satisfies:*

(i) bilinearity:

$$\begin{aligned}[aX + bY, Z] &= a[X, Z] + b(Y, Z) \\ [X, aY + bZ] &= a[X, Y] + b(X, Z)\end{aligned}$$

(ii) anti-symmetry

$$[X, Y] = -[Y, X]$$

(iii) Jacobi identity:

$$[X, [Y, Z]] + [Y, [Z, X]] + [Z, [X, Y]]$$

Thus $(\mathcal{X}(M), [\cdot, \cdot])$ *is a Lie algebra (an* ∞*-dimensional one).*

Warning:

$$C^\infty(M) \ni f \mapsto XYf \in C^\infty(M)$$

does not define a vector field in general!

Start of lecture 16 (03.12.2024)

Lemma 7.6 (Naturality of Lie brackets). *Given* $F : M \to N$ *smooth,* $X_1, X_2 \in \mathcal{X}(M), Y_1, Y_2 \in \mathcal{X}(N)$*. Assume* (X_i, Y_i) *are* F *related for* $i = 1, 2$*. Then* $[X_1, X_2], [Y_1, Y_2]$ *are* F*-related.*

Proof. For $f \in C^\infty(N)$

$$X_1 X_2(f \circ F) = X_1((Y_1 f) \circ F) = (Y_1 Y_2 f) \circ F$$

SImilarly swapping the order of X_1, X_2. Hence

$$\begin{aligned}[X_1, X_2](f \circ F) &= (X_1 X_2 - X_2 X_1)(f \circ F) \\ &= (Y_1 Y_2 - Y_2 Y_1)(f) \circ F \\ &= [Y_1, Y_2](f) \circ F\end{aligned}$$

□

7.3 Coordinate vector fields

Let M be a smooth manifold. Let (U, φ) be a smooth chart.
Recall that we abuse notation by writing $x_i \equiv x_i \circ \varphi$, where $\underbrace{x_i}_{x^i}(x) = x_i = \pi_i(x)$. w.r.t the chart

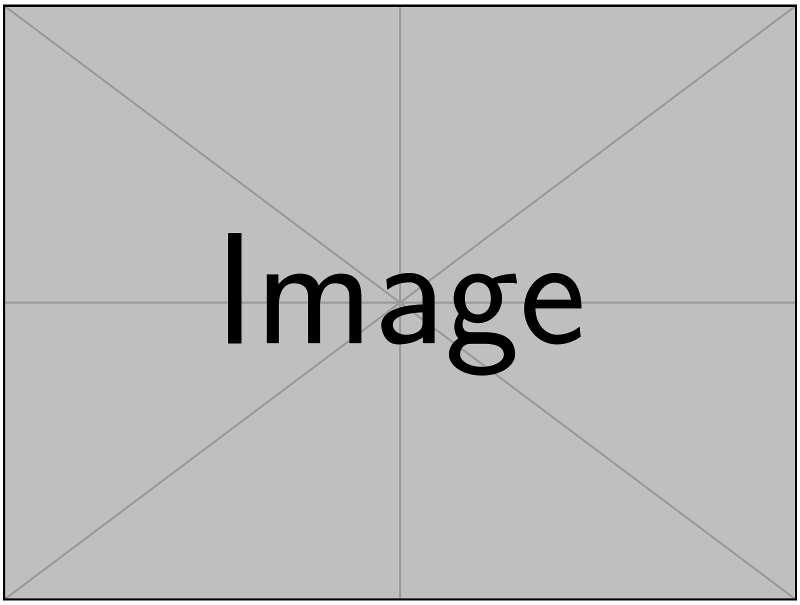

Figure 7.4: Sketch 7.05

If $p \in U$, we also have been writing $(\partial_{x_i})_p = d\varphi^{-1}_{\varphi(p)}((\partial_{x_i})_{\varphi(p)})$.

Section of the tangent bundle, a vector field ...

Lemma 7.7. *The map $U \ni p \mapsto (\partial_{x_i})_p \in T_pM$ is a smooth vector field on U, i.e. an element of $\mathcal{X}(U)$.*

Proof. Recall from last week 7 $M = \mathbb{R}^n$m then the map

$$(x_1, \ldots, x_n) \mapsto (x_1, \ldots, x_n, 0, \ldots, 0, 1, 0 \ldots, 0)$$

We often ommit the identity, i.e. the first n entries of the following

Then section 7.1 ,we have this is true, when M is an open subset of $\mathbb{R}^n$.
In general, $d\varphi^{-1}_{\varphi(p)}((\partial_{x_i})_{\varphi(p)}) = (\varphi)^{-1}_\star \partial_{x_i}$, where the pushfoward is

$$\varphi^{-1}_\star : \mathcal{X}(\varphi(u)) \to \mathcal{X}(U).$$

The lemma follows from the fact the fact that pushforwards of diffeomorphism send smooth vector fields to smooth vector fields. □

Notation: The vector field $U \ni p \mapsto (\partial_{x_i})_p$ shall be denoted by ∂_{x_i}. Other sources / authors write $\frac{\partial}{\partial x_i}$.

It is important to understand the difference between vector fields and tangent vectors, like the difference between functions and elements of the target of those functions

Does this commute?

Definition. *Let M be smooth of dimension m.*

*(i) Given a point $p \in M$, an m-tuple of vector fields $(X^1, \ldots, X^m) \in \mathcal{X}(M)^m$ is called a **local frame at p**, if $(X^1_p, \ldots, X^m_p) \in T_pM^m$*

*(ii) We say that $(X^1, \ldots, X^m) \in \mathcal{X}(M)^m$ is a **global frame** if $(X^1_p, \ldots, X^m_p)$ spans T_pM for all $p \in M$.*

Remark. *We take $X^i \in \mathcal{X}(M)$ and not $\mathcal{X}(U)$ for local frames, since (similar to functions), we can always extend them!*

Lemma 7.8. *If $(X^1, \ldots, X^m)$ is a local frame at $p \in M$, then there exists $p \in U \subset M$ s.t. $(X^1_{|_U}, \ldots, X^m_{|_U}) \in \mathcal{X}(U)^m$ is a global frame on U.*

This uses the fact that being full rank is an open condition

Proof. Exercise using lemma 4.1. □

Key example: If (U, φ) is a chart on M, then $(\partial_{x_1}, \ldots, \partial_{x_m}) \in \mathcal{X}(M)^m$ form a global frame on U.

Remark (Warning)**.** *It is not the case that all frames are of this form, i.e. there exists frames* $(X^1 \dots, X^m) \in \mathcal{X}(M)^m$ *local frames at some* $p \in M$*, such that* $(X^1_{|_U}, \dots, X^m_{|_U})$ *is not a coordinate vector field for any chart* $(V, \psi), V \subset U$*. E.g.* $[\partial_{x_i}, \partial_{x_j}] \equiv 0$.

It turns our the condition $[\partial_{x_i}, \partial_{x_j}] \equiv 0$ *is necessary and sufficient*

7.4 Integral curves

Let $\gamma : (a, b) \to M$ be a smooth map (a curve). We write $\dot{\gamma}(t) = d\gamma_t(\partial_t) \in T_{\gamma(t)}M$

$$\begin{tikzcd}
T\mathbb{R} \arrow[r, "d\gamma"] \arrow[d] & TM \arrow[d] \\
\mathbb{R} \arrow[u, bend left, "\partial_t"] \arrow[ur, dotted, "\dot{\gamma}(t)"] \arrow[r, "\gamma"] & M
\end{tikzcd}$$

In coordinates,
$gamma(t) = (\gamma^1(t), \dots, \gamma^n(t)) \in \mathbb{R}^n \implies \dot{\gamma}(t) = (\dot{\gamma}^1(t), \dots, \dot{\gamma}^n(t)) = \gamma^1(t)\partial_{x_1} + \dots + \gamma^n(t)\partial_{x_n}$,
where $\dot{\gamma}^i(t) = \frac{d}{dt}\gamma^i(t)$.

Definition. *Let* M *be a manifold and let* $V \in \mathcal{X}(M)$*. An* ***integral courve*** *for* V *is a curve* $\gamma : (a, b) \to M$ *such that*

$$\dot{\gamma}(t) = V_{\gamma(t)}.$$

We typically assume $0 \in (a, b)$*, we say that the* ***starting point*** γ*, is the point* $\gamma(0) \in M$*.*

Example. $M = \mathbb{R}^2, V = \partial_x = (1, 0)$.

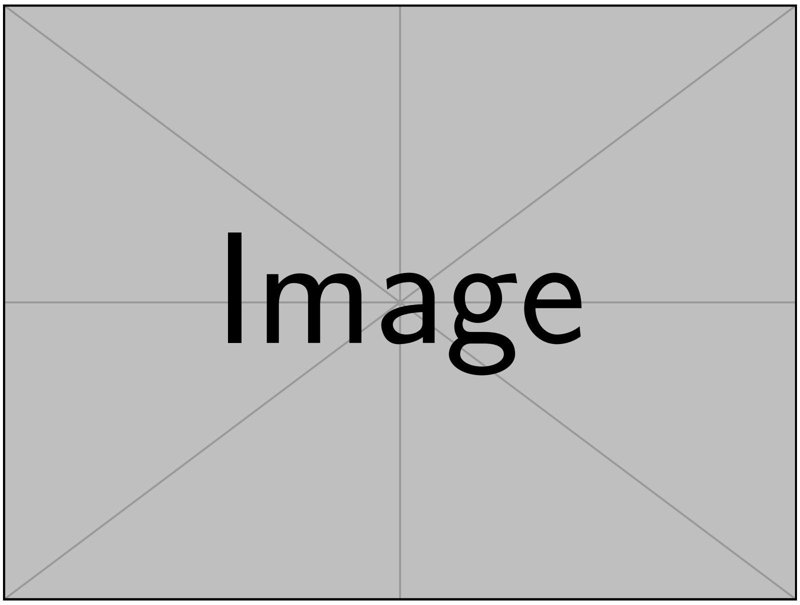

Figure 7.5: Sketch 7.06

The integral curves are precisely the curves

$$(t \mapsto p + t(1, 0))$$

where $p \in \mathbb{R}^2$ *is the starting point.*

Example. $M = \mathbb{R}^2, V = x\partial_y - y\partial_x \equiv (-y, x)$-

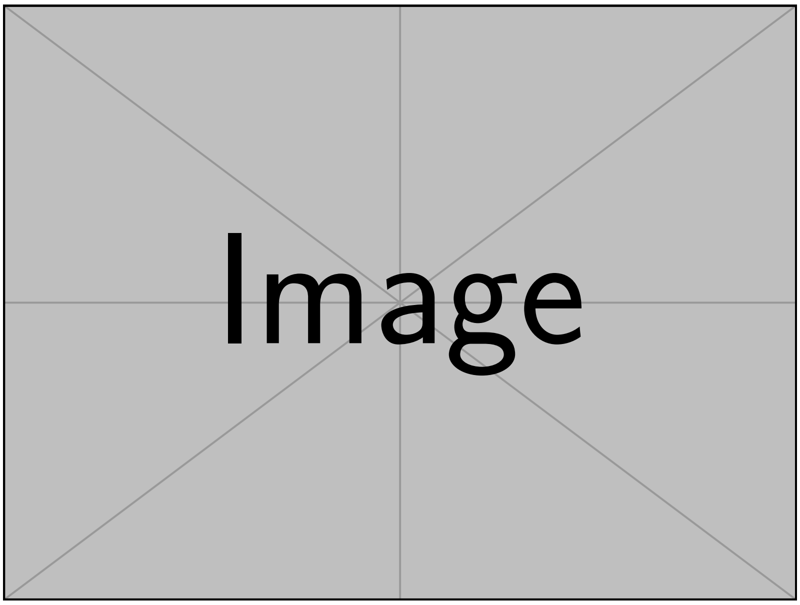

Figure 7.6: Sketch 7.07

Suppose that $\gamma : \mathbb{R} \to \mathbb{R}^2$ *is an integral curve*

$$t \mapsto (\gamma^1(t), \gamma^2(t))$$

Then we need

$$\begin{aligned} \dot{\gamma}(t) &= -\gamma^2(t) \\ \dot{\gamma}^2(t) &= \gamma^1 \end{aligned}$$

which is an ODE, with the following unique solution:

$$\gamma^1(t) = a\cos t - bsin(t), \gamma^2(t) = a\sin t + b\cos(t).$$

Hence

$$\gamma(t) = (a\cos t - bsin(t), a\sin t + b\cos(t)),\ a, b \in \mathbb{R}$$

integral curve with starting point (a, b)*.*

Proposition 7.9. *Let* M *be a smooth manifold. Let* $V \in \mathcal{X}(M)$*.*

(a) ***Existence:*** *Given any point* $p \in M$*, there exists an open interval* $0 \in J \subset \mathbb{R}$ *and an integral curve* $\gamma : J \to M$ *starting at* p

(b) ***Uniqueness:*** *If* $\sigma, \gamma : J \to M$ *starting at the same point* $p = \sigma(0) = \gamma(0)$*, then* $\sigma = \gamma$

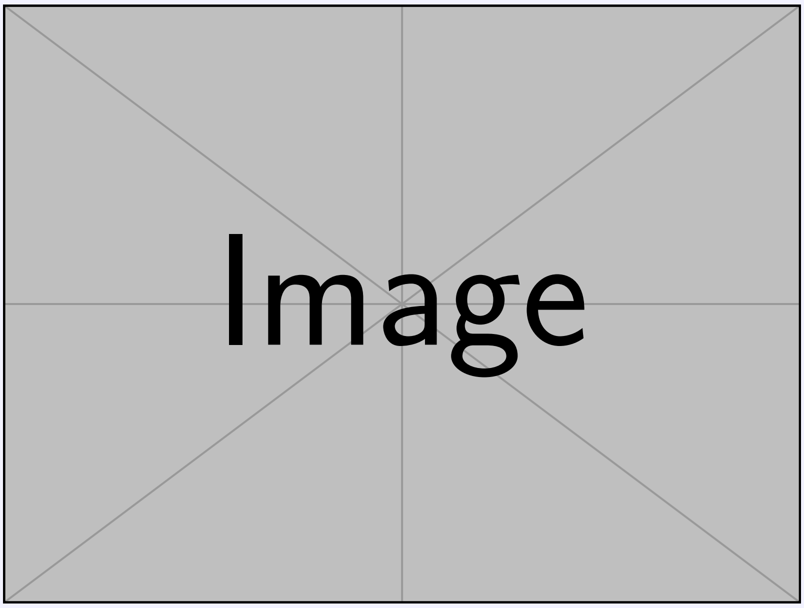

Figure 7.7: Sketch 7.08

Remark. *It follows from the proposition that,* $\forall p \in M$ *there is a largest interval* $0 \in J \subset \mathbb{R}$ *admitting an integral curve* $\gamma : J \to M$. *We call* $\gamma : J \to M$ *the* ***maximal integral curve****.*

This probably needs Zorn's lemma.

Proof of proposition 7.9. (a): This is a local statement, hence we can assume open $M \subset \mathbb{R}^n$. Then we must solve

$$\dot{\gamma}(t) = V_{\gamma(t)},$$

$\gamma(t) = (\gamma^1(t), \dots, \gamma^n(t))$.

$$\begin{cases} \dot{\gamma}^1(t) & = V^1_{\gamma(t)} \\ \vdots & \vdots \\ \dot{\gamma}^n(t) & = V^n_{\gamma(t)} \end{cases}$$

This is a system of ordinary differential equations (ODEs). Hence by Theorem D.1 in the appendix of [2][1], the system admits a unique solution with $\gamma(0) = p \in M \subset \mathbb{R}^n$.
(b): Let $\mathcal{E} \subset J$ be a subset of points $t \in J$ such that $\sigma(t) = \gamma(t)$. Observe that $0 \in \mathcal{E}$ by assumption. Observe also that $\mathcal{E}$ is closed, since σ, γ are continuous functions. Moreover $\mathcal{E}$ is open by the uniqueness part of theorem D1. $\implies \mathcal{E} = J$. □

We need this, because the uniqueness part of the theorem is local, but our statement in (b) is not

Lemma 7.10. *If* $F : M \to N, X \in \mathcal{X}(M), Y \in \mathcal{X}(N), X, Y$ *are* F *related, then* F *takes integral curves of* X *to integral curves of* Y.

Proof. Suppose $\gamma : J \to M$ integral curve of X.

$$(F \circ \gamma)'(t) = dF_{\gamma(t)} \dot{\gamma}(t) \overset{F\text{-related}}{=} Y_{F \circ \gamma(t)} \qquad \square$$

Remark. *There is also a converse. (exercise)*

Definition. *We say that a vector field* $V \in \mathcal{X}(M)$ *is* ***complete*** *if for all* $p \in M$*, the maximal integral curve starting at* $p \in M$ *is defined on* $\mathbb{R}$.

Example (Example of a non-complete vector field)**.** $M = \mathbb{R} \setminus \{0\}, V = \partial_x$. *Pick* $p = -1 \in \mathbb{R}$. *Then the integral curve starting at* p *is the map*

$$t \mapsto -1 + t.$$

This is only defined on $-\infty, 1$.

[1] On the course website

Journal

- Lecture 01: Covering: Introduction, locally Euclidean, Hausdorff, second countable spaces, their covers and exhaustions by compact sets .
  Starting in 'Organization' on page 3 and ending in 'Basis and covers' on page 9. Spanning 6 pages
- Lecture 02: Covering: Local finiteness, refinements, paracompactness, introduction to topological manifolds and examples .
  Starting in 'Basis and covers' on page 9 and ending in 'Manifolds with boundary' on page 14. Spanning 5 pages
- Lecture 03: Covering: Topological properties of topological manifolds, classification of topological manifolds, introduction to smooth manifolds .
  Starting in 'Manifolds with boundary' on page 14 and ending in 'Charts and atlases' on page 18. Spanning 4 pages
- Lecture 04: Covering: Examples of smooth manifolds, smooth maps, the category of smooth manifolds, hierarchy of categories of manifolds .
  Starting in 'Charts and atlases' on page 18 and ending in 'The category of smooth manifolds' on page 21. Spanning 3 pages
- Lecture 05: Covering: Smooth manifolds with boundary, partitions of unity .
  Starting in 'The category of smooth manifolds' on page 21 and ending in 'Partitions of unity' on page 24. Spanning 3 pages
- Lecture 06: Covering: Applications of partitions of unity, motivation of tangent vectors, definition of tangent vectors via equivalence classes of smooth curves, definition of differentials, fundamentality of the differential .
  Starting in 'Partitions of unity' on page 24 and ending in 'Definition via equivalence classes of smooth curves' on page 29. Spanning 5 pages
- Lecture 07: Covering: Definition of tangent vectors via derivations, equivalence of both definitions, coordinates .
  Starting in 'Definition via equivalence classes of smooth curves' on page 29 and ending in 'Coordinates' on page 33. Spanning 4 pages
- Lecture 08: Covering: Coordinates (continued), tangent bundles, submersions, immersions and embeddings .
  Starting in 'Coordinates' on page 33 and ending in 'Basic definitions' on page 39. Spanning 6 pages
- Lecture 09: Covering: The rank theorem as a generalization of a linear algebra fact and it's proof, basic definitions of submanifolds .
  Starting in 'Basic definitions' on page 39 and ending in 'Slice lemma[2]' on page 44. Spanning 5 pages

[2]Lee [2] calls it a theorem

- Lecture 10: Covering: Slice lemma (continued), weak Whitney embedding theorem, introduction to transversality .
  Starting in 'Slice lemma[3]' on page 44 and ending in 'Motivation' on page 51. Spanning 7 pages
- Lecture 11: Covering: Transversality for submanifold and maps, fiber products .
  Starting in 'Motivation' on page 51 and ending in 'Transversality of maps' on page 56. Spanning 5 pages
- Lecture 12: Covering: Measure zero sets on manifolds .
  Starting in 'Transversality of maps' on page 56 and ending in 'Measure theory on manifolds' on page 61. Spanning 5 pages
- Lecture 13: Covering: Sard's theorem and applications .
  Starting in 'Measure theory on manifolds' on page 61 and ending in 'Sard's theorem' on page 65. Spanning 4 pages
- Lecture 14: Covering: Proof of Sard's theorem using three intermediate lemmas .
  Starting in 'Sard's theorem' on page 65 and ending in 'Sard's theorem' on page 67. Spanning 2 pages
- Lecture 15: Covering: Vector fields, rough vector fields, F-related vector fields, vector fields as deviations, Lie brackets .
  Starting in 'Vector fields' on page 68 and ending in 'Vector fields as derivations' on page 72. Spanning 4 pages
- Lecture 16: Covering:

  .
  Starting in 'Vector fields as derivations' on page 72 and ending in 'Integral curves' on page 76. Spanning 4 pages

[3]Lee [2] calls it a theorem

Bibliography

[1] David Gale. “The Classification of 1-Manifolds: A Take-Home Exam”. In: (). URL: https://www.math.uni-bonn.de/~lcote/1_man_classification.pdf.

[2] John M. Lee. *Smooth Manifolds*. New York, NY: Springer New York, 2012. ISBN: 978-1-4419-9982-5. DOI: 10.1007/978-1-4419-9982-5. URL: https://doi.org/10.1007/978-1-4419-9982-5.

[3] Alex Taylor. “Equivalent definitions of the tangent space”. en. In: (). URL: https://art-math.github.io/files/tangentspace.pdf.

[4] Marco Zambon and Gilles Castel. *Differential Geometry*. 2020. URL: https://castel.dev/notes.