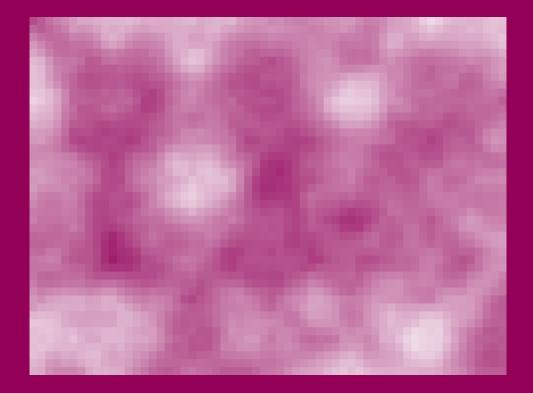
Lecture notes on Stochastic Analysis

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Contents

Chap	ter 0 Manuel's notes
Chap	ter 1 Weak solutions of SDEs
$1.\overline{1}$	Strong solutions
1.2	Weak solutions
1.3	Lévy characterization
1.4	Weak solutions and martingale problems
	1.4.1 Itô-Doeblin formula
	1.4.2 Martingale problem
1.5	Weak solutions and time change
	1.5.1 Time change
	1.5.2 Time change in a martingale problem

Chapter 0: Manuel's notes

Warning

These are unofficial lecture notes written by a student. They are messy, will almost surely contain errors, typos and misunderstandings and may not be kept up to date! I do however try my best and use these notes to prepare for my exams. Feel free to email me any corrections to mh@mssh.dev or s6mlhinz@uni-bonn.de. Happy learning!

General Information

• Ecampus: Ecampus link

• Basis: Basis link

• Website: None

• Time slot(s): Tuesday 12-14 and Thursday 12-14

• Exams: Oral: 23-25 July, 30 Sept. maybe 27. Sept

• Deadlines: ?

• Exercises: One of Tue 16-18(for now this is preferred), Friday 10-12. Starting 16.04.

• First halve based on Eberle and / or Gubinelli (be careful with Notation of dimensions!)

Start of lecture 01 (11.04.23)

Overview of the content

- Weak solutions of SDE
 - · Martingale problem (characterization)
 - · Time change (Dubin-Schwarz)
 - · Change of measure (Girsonov)
- How to condition a diffusion to stay in a given domain forever (reflected BM, local time, ...)
- Lévy processes (a bit)
- Multiplicative stochastic heat-equation
 - · relations with Kardar-Pavisi-Zhang class of growth models

Chapter 1: Weak solutions of SDEs

SDE:

$$\begin{cases} dX_t = b(t, X_t)dt + \sigma(t, X_t)dB_t \\ X_0 = x_0 \text{ Initial condition} \end{cases}$$
 (1.1)

- $X_t \in \mathbb{R}^d, B : n\text{-dim BM}$
- $b(t,x):[b_k(t,x)]_{1\leq k\leq d}$: drift vector
- $\sigma(t,x) = [\sigma_{k,l}(t,x)]_{\substack{1 \le k \le d \\ 1 \le l \le n}}$: dispersion matrix
- $a(t,x) = \sigma(t,x) \cdot \sigma(t,x)^{\mathsf{T}}$: diffusion matrix

1.1 Strong solutions

Definition 1.1. Let $(\Omega, \mathcal{F}, (\mathcal{F})_{t \geq 0}, \mathbb{P})$ be a filtered probability space with $\mathcal{F}_t = \sigma(x_0, (B_s)_{0 \leq s \leq t})$

- a d-dim process X_t is a **strong solution** of equation 1.1 if:
 - $\cdot X_t = x_0 \ a.s.$
 - · X_t is adapted to $\mathcal{F}_t \forall t \geq 0$
 - · X is a continuous semimartingale s.t. $\forall t \geq 0$:

$$\int_0^t (\|b(s, X_t)\| + \|\sigma(t, X_t)\|^2) ds < \infty \ a.s.$$

 $X_t = X_0 + \int_0^t b(s, X_s) ds + \int_0^t \sigma(s, X_s) dB_s$

In the last semester we proved:

Theorem 1.2. Assume that b, σ are globally lipschitz with at most linear growth at ∞ (in space) $\Rightarrow \exists !$ strong solution of SDE.

Foundations of Stochastic Analysis Thm 8.6

Added remark. There exists K > 0 s.t. for all $x, y \in \mathbb{R}^d$: Globally Lipschitz:

$$||b(t,x) - b(t,y)|| + ||\sigma(t,x) - \sigma(t,y)|| \le K||x - y||$$

Linear growth condition:

$$||b(t,x)|| + ||\sigma(t,x)|| \le K(1+||x||)$$

Remark. For strong solutions, \mathcal{F}_t is given by the driving BM, wich is given to us. $\Longrightarrow X_t(\omega) = \Phi(x_0(\omega), (B_s)_{0 \le s \le t})$

1.2 Weak solutions

• For weak solutions we do not fix the driving brownian motion.

Definition 1.3. A <u>weak solution</u> of equation 1.1 is a <u>pair</u> of adapted processes (X, B) to a $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t>0}, \mathbb{P})$ s.t.

- B is a n-dim BM
- X is a d-dim continuous semimartingale with
 - 1. $X_0 = x_0$ a.s.
 - $2. \ \forall t > 0$

$$\int_0^t (\|b(s, X_t)\| + \|\sigma(t, X_t)\|^2) ds < \infty \ a.s.$$

3.
$$X_t = x_0 + \int_0^t b(s, X_s) ds + \int_0^t \sigma(s, X_s) dB_s$$

Remark. • The filtration $(\mathcal{F}_t)_{t\geq 0}$ is not necessarily the one generated by B

- If X is adapted to the filtration generated by the $BM \implies$ we have strong solutions
- \exists weak solution which are not strong solutions
- Warning: To give a weak solution we really need to provide $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t\geq 0}, \mathbb{P}, X, B)$

Definition 1.4 (Uniqueness in law). An SDE 1.1 has <u>uniqueness in law</u> if given any two weak solutions $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t\geq 0}, \mathbb{P}, X, B)$ and $(\tilde{\Omega}, \tilde{\mathcal{F}}, (\tilde{\mathcal{F}}_t)_{t\geq 0}, \tilde{\mathbb{P}}, \tilde{X}, \tilde{B})$ satisfy:

$$Law_{\mathbb{P}}(X) = Law_{\tilde{\mathbb{P}}}(\tilde{X})$$

Definition 1.5 (Pathwise uniqueness). The SDE 1.1 has pathwise uniqueness if, whenever the filtered space $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t\geq 0}, \mathbb{P})$ and $(B_t)_{t\geq 0}$ are fixed, then two solutions X, \tilde{X} with $X_0 = \tilde{X}_0$ are indistinguishable.

Example 1.6 (No strong solutions, no pathwise uniqueness, \exists weak solution & and uniqueness in law by Tanaka).

$$\begin{cases} dX_t = sgn(X_t)dB_t \\ X_0 = 0 \end{cases}$$
 (1.2)

or more generally $X_0 = Y$, where

$$sgn(x) = \begin{cases} 1 & x > 0 \\ -1x \le 0 \end{cases}$$

Let W be a BM with $W_0 = Y$. Define

$$B_t := \int_0^t sgn(W_s)dW_s \text{ or } dB_t = sgn(W_t)dW_t$$

$$\implies dW_t = sgn(W_t)dB_t$$

$$\implies W_t = y + \int_0^t sgn(W_s)dB_s$$

 B_t is a local martingale with

$$\langle B \rangle_t = \int_0^t \underbrace{(sgn(W_s))^2}_{=1} \underbrace{d\langle W \rangle_s}_{=ds} = t$$

They agree on any set in the sigma algebra

Also $B_0 = 0$, therefore B is a BM (see Lévy characterization) \implies W solves the SDE. For Y = 0, W and -W solves the same SDE.

 \Longrightarrow

- exists weak solutions
- For Y = 0: no pathwise uniqueness
- Uniqueness in law (because the law is determined by X_t being a BM)
- No strong solution, because: $\mathcal{F}^B = \mathcal{F}^{|W|} \subsetneq \mathcal{F}^W$

Not a proof just yet, just the reason!

Example 1.7 (No solutions).

$$\begin{cases} dX_t = -\frac{1}{2X_t} 1_{X_t \neq 0} dt + dB_t \\ X_0 = 0 \end{cases}$$
 (1.3)

Assume there exists a solution. Use Itô formula for X_t^2 , then:

$$X_t^2 = 2 \int_0^t X_s dX_s + \int_0^t 1 ds$$

$$= -\int_0^t 1_{X_s \neq 0} ds + 2 \int_0^t x_s dB_s + t$$

$$= \int_0^t 1_{X_s = 0} ds + 2 \int_0^t X_s dB_s$$

We will prove $\int_0^t 1_{X_s=0} ds = 0 \implies X_t^2$ is a local martingale, $X_t^2 \ge 0$ (and therefore a supermartingale) and $X_0 = 0$ ($\implies \mathbb{E}(X_t^2) = 0$). If $X_t = 0 \implies \int_0^t 1_{X_s=0} ds = t \implies 0 = dB_t$ which are contradictions!

Remark. If
$$X = \underbrace{M}_{\in \mathcal{M}_{loc}} + \underbrace{A}_{\in \mathcal{A}}$$

$$\implies \forall b \in \mathbb{R} \int_0^t 1_{X_s = b} d\langle M \rangle_s = 0$$

Sheet 0:

- Mail: Alexander.Becker@uni-bonn.de
- Exercise sheet handed in Fr 10 am via eCampus
- Groups of 3

Motivation:

in the last semester: Introduction to stochastic analysis

• Diffusion processes & SDEs

Here: Deepen the knowledge & have fun

- Learn SDE techniques and get other results
- Modify diffusion processes to behave in a certain way
- Ex. diffusion bridge (Brownian bridge)
- Condition a diffusion to stay in a domain
 - · Ex. Condition BM to stay positive
 - · Old SDE: $dB_t = dB_t$

- · New SDE: $dX_t = \frac{1}{X_t} dx + dB_t \rightarrow P(X_t \in \cdot) = P(B_t \in \cdot | B > 0 \text{ forever})$
- $D \subset \mathbb{R}^d$ open domain, X diffusion process, with generator $L = \sum b \partial_i + \frac{1}{2} \sum a^{ij} \partial_i \partial_j$

$$Y := (X|X \in D \text{ forever})$$

get drift term $\nabla \log \phi_0$, where ϕ_0 is the lowest eigenfunction of -L on D with dirichlet boundary.

Recap:

Brownian motion:

Added definition. $B_0 = 0$, independent & $\mathcal{N}(0, t_i - t_{i-1})$ increments, $t \mapsto B_t(\omega)$ continuous.

Regularity of path $t \mapsto B_t(\omega)$:

- nowhere differentiable
- α -locally Hölder continuous $\iff \alpha < \frac{1}{2}$
- Quadratic variation $\langle B \rangle_t = t$
- Generator $\frac{\Delta}{2}$
- Recurrent $\iff ds2$?

Itô-Integral:

- 1. If X simple process \implies RS-Integral
- 2. Itô isometry $\mathcal{E} \to \{L^2 \text{local martingale}\}, \mathcal{E} \subset L^2(d[M])$ dense
- 3. general $X: \int XdM$ as L^2 -limit

Added remark (Itô formula).

$$df(t, X_t) = \partial_t f(t, X_t) dt + \partial_x f(t, X_t) dX_t + \frac{1}{2} f(t, X_t) d\langle X \rangle_t$$

- associative $\int Xd(\int YdZ) = \int XYdZ$
- If M local martingale $\implies \int XdM$ local martingale

SDEs:

$$DX_t = b(t, X_t)dt + \sigma(t, X_t)dB_t$$

- ex./ uniqueness: b, σ locally Lipschitz \implies strong ex.+pathwise uniqueness until explosion time
- globally Lipschitz (in space) and linear growth $(|b(t,x)| + |\sigma(t,x)| \le C(1+|x|)), e = \infty.$

Problem 00.1: SDE

Let B be a one-dimensional Brownian motion (starting from 0) and let $X_t = \sin(B_t)$.

- 1. Determine the SDE of X_t
- 2. Discuss the existence and/or uniqueness of strong solutions of the SDE
- 3. Determine whether the local martingale term is a martingale (Hint: for the integrability condition, think about the Itô isometry for instance)

Solution 00.1

1.:

Idea: Use Itô formula: $X_t = \sin(B_t) = f(B_t)$

$$dX_t = df(B_t) \stackrel{\text{It\^{o}}}{=} \partial_x \underbrace{\cos(B_t)}_{\sqrt{1 - X_t^2}} dB_t - \frac{1}{2} \underbrace{\sin(B_t)}_{X_t} dt$$

<u>2.:</u>

Consider the SDE

$$dX_t = \begin{cases} -\frac{1}{2}X_t dt + \sqrt{1 - X_t^2} dB_t \\ X_0 = x \in (-1, 1) \end{cases}$$

Coefficients: $b:[-1,1]\to\mathbb{R}, b(x)=-\frac{1}{2}x$ and $\sigma:[-1,1]\to\mathbb{R}.\sigma(x)=\sqrt{1-x^2}$

$$[\sigma]_{1,2} = \sup \frac{|\sigma(x) - \sigma(y)|}{|x - y|^{1/2}} < \infty$$

Probably σ^2 Lipschitz $\implies \sigma$ Hölder $\frac{1}{2}$ 3.:

Careful: $\sqrt{1-X_t^2}$ is not inverse mapping, because it is always positive while $\cos(B_t)$ is not

Problem 00.2: Time change

Let B be a one-dimensional Brownian motion (starting from 0). Let $Y_t = \int_0^t s^2 dB_s$.

- 1. Determine the SDE of Y_t
- 2. Find A_t such that Y_{A_t} is a (stopped) Brownian motion

Solution 00.2

1.: By Definition

$$dY_t = t^2 dB_t$$

2.: We use the Dubin-Schwarz theorem:

$$X_{\in}\mathcal{M}_{loc}^{0}, \langle X \rangle_{\infty} = \infty, T_{t} := \inf\{s \geq 0 | \langle X \rangle_{s} \geq t\} = X_{t}^{[-1]}$$

 $\Longrightarrow B_{t} := X_{T_{t}} \text{ 1 d BM w.r.t. } (F_{T_{t}})_{t \geq 0}, X_{t} = B_{\langle B \rangle_{t}}$
here: use $X_{t} = b(X_{t})dt + \sigma(X_{t})dB_{t} \Longrightarrow d[X]_{t} = \sigma^{2}(X_{t})dt$

Problem 00.3: SDE and PDE

Let f be a function supported on [0,1], u the solution of

$$\frac{1}{2}u(t,x) = \frac{1}{2}x(1-x) + \frac{d^2}{dx^2}u(t,x), \qquad u(0,x) = f(x).$$

Consider also the one-dimensional SDE (also known as Wright-Fisher diffusion)

$$dX_t = \sqrt{X_t(1 - X_t)dB_t}$$

with $X_0 = x \in (0, 1)$.

- 1. For any fixed t > 0, define $M_s = u(t s, X_s)$ for $s \in [0, t]$. Use Itô formula to show that M_s is a local martingale
- 2. Assume that f is bounded and there is a bounded solution of u. Show that $u(t, x) = \mathbb{E}_x(f(X_t))$.

Solution 00.3

<u>1.:</u>

$$\begin{split} dM_s &= du(t-s,X_s) \\ &= -\partial_s u(t-s,X_s) ds + \partial_x u(t-s,X_s) \underbrace{dX_s}_{b(X_s)ds + \sigma(X_s)dB_s \text{ by asso.}} + \frac{1}{2} \partial_x^2 u(t-s,X_s) \underbrace{d[X]_s}_{=\sigma^2(X_s)ds} \\ &= \underbrace{(-\partial_s u + b\partial_x u + \frac{1}{2}\sigma^2\partial_x^2 u)(t-s,X_s)ds + \partial_x u(t-s,X_s)\sigma(X_s)dB_s}_{=0} \\ &\implies dM_s &= \partial_x u(t-s,X_s)\sigma(X_s)dB_s \end{split}$$

(i.e.: $M_t - M_0 = \int_0^t \dots dB_s$) This is a purely stochastic integral against a (local) martingale \implies martingale.

- M_s true martingale:
 - 1. $\forall t : \mathbb{E}(\sup_{[0,t]} |M|) < \infty$, for example: M bounded
 - 2. $\forall t : \mathbb{E}(\sup_{[0,t]} [M]_t) < \infty$

 $M_s := u(t - s, X_s), u \text{ bounded} \implies M \text{ bounded} \implies M \text{ true martingale}$ $w(s,x) \coloneqq u(t-s,x)$

$$u(t,x) = w(0,x) = \mathbb{E}_x[w(0,X_0)] = \overset{\text{martingale}}{=} \mathbb{E}_x[w(t,X_t)] = \mathbb{E}_x[(u(0,X_t))] \overset{\text{PDE}}{=} \mathbb{E}_x[f(X_t)]$$

Feynman-Kac formula (later more general).

Also solvable by Kolmogorov Backward / forward equation

Start of lecture 02 (16.04.24)

Example 1.8 (Non-uniqueness of law, non pathwise uniqueness, with solutions).

$$\begin{cases} dX_t &= 1_{X_z} dB_t \\ x_0 &= 0 \end{cases}$$

Then

$$X_t = 0 \forall t > 0$$

and

$$X_t = B_t \forall t > 0$$

both are solutions:

$$X_t - B_t = -\int_0^t 1_{X_s=0} dB_s \implies \langle X - B \rangle_t = \int_0^t 1_{X_s=0} d\langle B \rangle_s = 0$$

Let $\eta \sim Ber(\frac{1}{2})$ independent of $(B_t)_{t>0}$ and define

$$\tilde{X}_t = \begin{cases} 0 & \eta = 0 \\ B_t & \eta = 1 \end{cases}$$

 $\implies \tilde{X}_t$ is adapted to $\sigma(\eta(B_s)_{0 \le s \le t})$, but not to $\sigma((B_s)_{0 \le s \le t})$ and therefore not a strong solution.

$$X_{t} = \int_{0}^{t} 1_{X_{s} \neq 0} dB_{s}$$

= $\int_{0}^{t} (1 - 1_{X_{s} = 0} dB_{s})$
 $B_{t} - \int_{0}^{t} 1_{X_{s} = 0} dB_{s}$

Example 1.9 (No strong solution, weak solution, no pathwise uniqueness, no uniqueness in law).

$$\begin{cases} dX_t = 1_{X_t \neq 1} sgn(X_t) dB_t \\ X_0 = 0 \end{cases}$$

Let Y_t be a solution of

$$\begin{cases} dY_t &= sgn(Y_t)dB_t \\ Y_0 &= 0 \end{cases}$$

 $\implies X_t \coloneqq Y_{t \wedge \tau}, \text{ where } \tau = \inf\{s \ge 0 \mid Y_s = 1\} \text{ is also a solution.}$

Theorem 1.10 (Yamada-Watanabe). If both existence of weak solutions and pathwise uniqueness hold, uniqueness in law also holds.

Moreover, \forall choices of $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t\geq 0}, \mathbb{P})$ and $(B_t)_{t\geq 0}$ then there exists a strong solution.

1.3 Lévy characterization

Example 1.11. Consider the SDE

$$\begin{cases} dX_t &= O_t dB_t \\ X_0 = x_0 \end{cases}$$

where both X_t and B_t are d-dimensional and O_t is an adapted process (matrix) s.t. $O_t^{\intercal}O_t = 1 \forall t \geq 0$ i.e. O_t is a rotation

$$\implies X_t^k = X_0^k + \sum_{l=1}^d \int_0^t O_s^{k,l} dB_s^l$$

$$\implies \langle X^k, X^{\tilde{k}} \rangle_t = \sum_{l,\tilde{l}}^d \int_0^t O_s^{k,l} O_s^{\tilde{k},\tilde{l}} d\langle B^l, B^{\tilde{l}} \rangle_s = \sum_{l=1}^d \int_0^t O_s^{k,l} O_s^{\tilde{k},l} ds$$

$$= \int_0^t \underbrace{(O_s O_s^\intercal)^{k,\tilde{k}}}_{=1} ds = \delta_{k,\tilde{k}} t \stackrel{Lévy}{\Longrightarrow} (X_t)_{t \geq 0} \text{ is also a } d\text{-dim } BM \text{ starting from } x_0$$

Theorem 1.12 (Yamada, Watanabe). Let $dX_t = b(X_t)dt + \sigma(X_t)dB_t$ and assume that there exist both a increasing function $\rho(u) \geq 0$ s.t. $|\sigma(x) - \sigma(y)| \leq \rho(|x - y|) \forall x, y \in \mathbb{R}$ s.t.

$$\int_{0}^{\infty} \frac{1}{\rho(u)} du = \infty \implies 0 < u < C_1 \implies \rho(u) \le C_2 u^{0.5}$$

and some increasing concave function $\gamma_1(u) \geq 0$ s.t.

$$|b(x) - b(y)| \le \gamma_1(|x - y|) \forall x, y \in \mathbb{R}$$

and

$$\int_0^\infty \frac{1}{\gamma_1(u)} = \infty.$$

Then pathwise uniqueness holds.

Theorem 1.13 (Storokhod). Assume that σ , b are continuous bounded functions \implies there exist weak solutions to the SDE $dX_t = b(X_t)dt + \sigma(X_t)dB_t$.

1.4 Weak solutions and martingale problems

Let $(X_t)_{t>0}$ be a weka solution of the SDE

$$\begin{cases} dX_t = b(t, X_t)dt + \sigma(t, X_t)dB_t \\ X_0 = 0 \end{cases}$$

on $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t\geq 0}, \mathbb{P})$.

 $\implies X_t$ is a semimartingale s.t. $X_t^k = X_0^k + \int_0^t b(s, X_s) ds + \sum_{l=1}^n \int_0^t \sigma_{k,l}(s, X_s) dB_s^l$ and

$$\langle X^i, X^j \rangle_t = \int_0^t \underbrace{\sum_{l=1}^n \sigma_{i,l}(s, X_s) \sigma_{j,l}^{\mathsf{T}}(s, X_s)}_{=a_{i,j}(s, X_s)} ds$$

1.4.1 Itô-Doeblin formula

Itô formula leads to

Proposition 1.14. For $f \in C^{1,2}(\mathbb{R}_+ \times \mathbb{R}^d)$, then

$$f(t,X_t) = f(0,X_0) + \int_0^t (\sigma^\intercal \nabla f)(s,X_s) dB_s + \int_0^t \left[\left(\frac{\partial}{\partial s} + \mathcal{L} \right) \right](s,x_s) ds$$

where $(\mathcal{L}f)(t,x) = \frac{1}{2} \sum_{k,l=1}^{n} a_{k,l}(t,x) \frac{\partial^2}{\partial x_k \partial x_l} f(t,x) + \sum_{k=1}^{n} b_k(t,x) \frac{\partial}{\partial x_k} f(t,x).$

 \mathcal{L} is called the **generator**

Remark. The Itô-Doeblin formula provides a connection between SDEs and PDEs as we have seen in the last part Foundations of stochastic analysis.

Example 1.15. Let $f \in C^{1,2}(\mathbb{R}_+ \times \mathbb{R}_d)$ be a solution of the PDE

$$\frac{\partial}{\partial t} f(t, x) + (\mathcal{L}f)(t, x) = -g(t, x) \qquad t \ge 0, x \in U \subseteq \mathbb{R}^d$$
$$f(t, x) = \varphi(t, x) \qquad t \ge 0, x \in \partial U.$$

then $M_t := f(t, X_t) + \int_0^t g(s, X_s) ds \in \mathcal{M}_{loc}$ by proposition 1.14 and if f, g are bounded $M_t \in \mathcal{M}$.

$$T \coloneqq \inf\{s \ge 0 | X_s \notin U\} \implies M_t^T \coloneqq M_{T \land t} \in \mathcal{M}.$$

Furthermore, if we assume $T < \infty$ a.s. :

$$\mathbb{E}[M_t] = \mathbb{E}[\varphi(T, X_T)] + \mathbb{E}[\int_0^T g(s, X_s) ds] = \varphi(0, X_0)$$

where $X_0 = x_0$.

There are two special cases:

 $g=0 \implies yields \ the \ exit \ distributions, \ while$

 $\varphi = 0, g = 1$ yields the mean exit times.

Example 1.16 (Feynman-Kac formula). Let $t \in \mathbb{R}_+$ be finite. Assume $f : \mathbb{R}^d \to \mathbb{R}$ and $K : [0,t] \times \mathbb{R}^d \to \mathbb{R}_+$ be continuous functions. Assume that u is a $C^{1,2}$ -solution (bounded, for simplicity) of

$$\begin{cases} \frac{\partial u}{\partial s}(s,x) = \frac{1}{2}\Delta u(s,x) - K(s,x)u(s,x) & s \in [0,t], x \in \mathbb{R}^d \\ u(0,x) = f(x) & x \in \mathbb{R}^d \end{cases}$$

Then u has the stochastic representation $u(t,x) = \mathbb{E}_x \left[f(X_t) \exp\left(-\int_0^t K(t-s,X_s)ds\right) \right]$, where X_t is BM starting from $X_0 = x$.

Sketch. 1. Define
$$r(s,x) := u(t-s,x)$$
 for $s \in [0,t]$

Page 10 of 13

2. Show: $M_s := \exp(-A_s)r(s,x)$ with $A_s = \int_0^s K(u,X_u)du$ is a local martingale.

Remark. This is a reformulation of the formula from the last semester.

1.4.2 Martingale problem

A solution of an SDE is generically defined up to some $\underline{\text{explosion time } \xi}$, where it either diverges or it exists a given domain $U \subset \mathbb{R}^d$ (open).

 \implies For $k \in \mathbb{N}$ define $U_k := \{x \in U \mid |x| < k \land \operatorname{dist}(x, U^c) \ge \frac{1}{k}\}$ with $U = \bigcup_{k \ge 1} U_k$ and

$$T_k := \{ t \ge 0 \mid x_t \notin U_k \}.$$

A solution of the SDE $b(t, X_t)dt + \sigma(t, X_t)dB_t$ is defined up to $\xi = \sup_{k>1} T_k$.

Start of lecture 03 (18.04.24)

Added remark. uniqueness of solution to the heat equation $\frac{1}{2}\Delta u - Ku$: not unique! Stochastic calculus: Paolo Baldi: 10.3-10.4

Define (\star) :

$$dX_t b(t, X_t) dt + \sigma(t, X_t) dB_t$$
 with $X_0 = x_0$

Theorem 1.17 (Martingale problem). If X is a solution of (\star) up to time ζ , then $\forall f \in C^{1,2}(\mathbb{R}_+ \times U)$

$$M_t = f(t, X_t) - \int_0^t \left(\frac{\partial}{\partial s} + \mathcal{L}\right) f(s, x_s) ds, t < s$$

is a local martingale up to ζ and $M_t^{T_k}$ are localizing martingales.

Definition 1.18 (Martingale solutions). $(X_t)_{t\geq 0}$ is a martingale solution of (\star) if $\forall f \in C^2(\mathbb{R}^d)$

$$M_t^f = f(X_t) - f(X_0) - \int_0^t (\mathcal{L}f)(X_s) ds$$

is a continuous local martingale.

Theorem 1.19 (Equivalent definitions). The following are equivalent (for X_t being a solution of (\star) :

(a) $\forall f \in C^2(\mathbb{R}^d)$.

$$M_t^f := f(X_t) - f(X_0) - \int_0^t (\mathcal{L}f)(X_s) ds$$

is a local martingale

(b) The process in \mathbb{R}^d given by

$$M_t := X_t - X_0 - \int_0^t b(s, X_s) ds$$

is a d-dimensional local martingale with $\langle M^i, M^j \rangle_t = \int_0^t a_{i,j}(s,X_s) ds = \langle X^i, X^j \rangle_t$

(c) $\forall f \in C^{1,2}(\mathbb{R}_+ \times \mathbb{R}^d)$

$$\tilde{M}_t^f := f(t, X_t) - f(0, X_0) - \int_0^t \left(\frac{\partial}{\partial s} + \mathcal{L}\right)(s, X - s) ds$$

is a local martingale

ds

Proof. $\underline{c} \Longrightarrow \underline{a}$: by choosing f independent of t. $\underline{a} \Longrightarrow \underline{b}$: 1.: Choosing $f(X) = X_i$ implies

 $M_t^f = X_t^i - X_0^i - \int_0^t b_i(s, X_s) ds \in \mathcal{M}_{loc}$

We can maybe also proof this by calculating X^2 ?

2.:
$$f(X) = X_i X_i$$
:

$$\begin{split} (\mathcal{L}f)(x) &= \frac{1}{2}a_{ij} + \frac{1}{2}a_{ji} + b_iX_jb_jX_i \\ a &= a^{\mathsf{T}} \implies = a_{ij}b_iX_jb_jX_i \\ \implies M_t^fX_t^iX_t^j - X_0^iX_0^j - \int_0^t \left[a_{ij}(s,X_s) + b_i(s,X_s)X_s^j + b_j(s,X_s)X_s^i\right]ds \end{split}$$

$$X_t^i X_t^j - X_0^i X_0^j \overset{\text{Integration by parts}}{=} \int_0^t X_s^i dX_s^j + \int_0^t X - s^j dX_s^i + \langle X^i, X^j \rangle_t$$
$$= M_t^f + \int_0^t [a_{ij} + b_i X_s^j + b_j X_s^i] ds$$

 $\underline{b} \Longrightarrow \underline{c}$: By Proposition 1.14 If (use the next theorem) X was a weak solution $\Longrightarrow \tilde{M}_t^f$ is a local martingale.

Theorem 1.20. Let n = d, assume $\sigma(t, x)$ is invertible $\forall t, x \text{ and } \sigma^{-1}(t, x)$ is uniformly bounded.

- (a) $(X_t)_{t\geq 0}$ is a weak solution of the SDE (\star) on $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t\geq 0}, \mathbb{P}; B)$
- (b) $(X_t)_{t\geq 0}$ is a martingale solution of the SDE (\star)

Proof. $a \implies b$: True

 $b \implies a$: Goal construct a BM for the weak solution.

By proposition ?? $a \implies b \ dM_t = dX_t - b(t, X_t)dt \in \mathcal{M}_{loc} \text{ and } d\langle M^i, M^j \rangle_t = a_{k,l}(t, X_t)dt$

$$\implies dX_t = dM_t + b(t, X_t)dt$$
$$= \sigma(t, X_t)d\tilde{B}_t + b(t, X - t)dt$$

where $\tilde{B}_t := \sigma(s, X_s)^{-1} dM_s$

To see: \tilde{B}_t is a brownian motion.

$$\langle \tilde{B}^{i}, \tilde{B}^{j} \rangle_{t} = \sum_{k,l} \int_{0}^{t} \sigma_{ij}^{-1} \sigma_{jl}^{-1} \underbrace{d\langle M^{k}, M^{l} \rangle_{s}}_{= \underbrace{\alpha_{ij}}_{(\sigma^{\mathsf{T}}\sigma)_{kl}} ds}$$

$$= \sum_{k,l,p} \int_{0}^{t} \sigma_{ik}^{-\mathsf{T}} \sigma_{kp} \sigma_{pl}^{\mathsf{T}} \sigma_{lj}^{-\mathsf{T}} ds$$

$$= \delta_{ij} \int_{0}^{t} 1 ds = \delta_{ij} t$$

Then by the Lévy characterization \tilde{B} is a brownian motion.

Added remark. This is the first way to construct a weak solution: Solve a martingale problem! This is used a lot in practice.

Here dX_s^i is the same as $b_iX_s^j$ is the same up to a local martingale term and $\langle X^i, X^j \rangle_t = \int_0^t a_{ij}(s, X_s)ds = \langle M^i, M^j \rangle_t$

This also works for $n \neq d$, but with a different proof

1.5 Weak solutions and time change

1.5.1 Time change

For d = 1:

Theorem 1.21. [Dubins-Schwarz]

- Let $M \in \mathcal{M}_{loc}^0$ and $\langle M \rangle_{\infty} = \infty$ a.s.
- Let $T_t := \inf\{s \ge |\langle M \rangle_s \ge t\}$

This implies

- 1. $t \mapsto M_{T_t}$ os a (\mathcal{F}_{T_t}) brownian motion
- 2. $M_t = B_{\langle M \rangle_t}$ for some standard brownian motion B

$$X_t = X_0 + \int_0^t b(s, X_s) ds + \underbrace{\int_0^t \sigma(s, X_s) dB_s}_{=M_t}$$
. If $\langle M \rangle_{\infty} = \infty$ a.s.:

$$X_t = X_0 + \int_0^t b(s, X_s) ds + \tilde{B}_{\int_0^t \sigma^2(s, X_s) ds}$$

1.5.2 Time change in a martingale problem

Consider d = 1 = n.

$$dY_t = \sigma(Y_t)dB_t \tag{**}$$

and σ strictly positive positive continuous function.

$$\langle Y \rangle_t = \int_0^t \sigma(Y_s)^2 ds =: A_t$$

By theorem 1.21 $\implies Y_t = W_{A_t}$ for some brownian motion W.

Assume $A_t \infty = \infty$ a.s.

 $T_t := \inf\{s \ge 0 \mid \langle Y \rangle_s \ge t\}$

$$\implies T_{A_t} = \inf\{s \ge 0 \mid \langle Y \rangle_s \ge \langle Y \rangle_t\} = t$$

$$1 = \frac{d}{dt} (T_{A_t}) = T'_{\underbrace{A_t}_u} \cdot A_t$$

$$\implies \underbrace{T'_u}_{=\frac{dT_u}{dt}} = \frac{1}{A'_{T_u}} \implies T_u = \int_0^u \frac{1}{\sigma(Y_{T_s})^2} ds = \int_0^u \frac{1}{\sigma(W_s)^2} ds$$

 \implies to construct a solution of $(\star\star)$: Given $W\longrightarrow$ compute $T_u\longrightarrow$ determine $A-t=T_t^{-1}\implies Y_t=W_{A_t}$