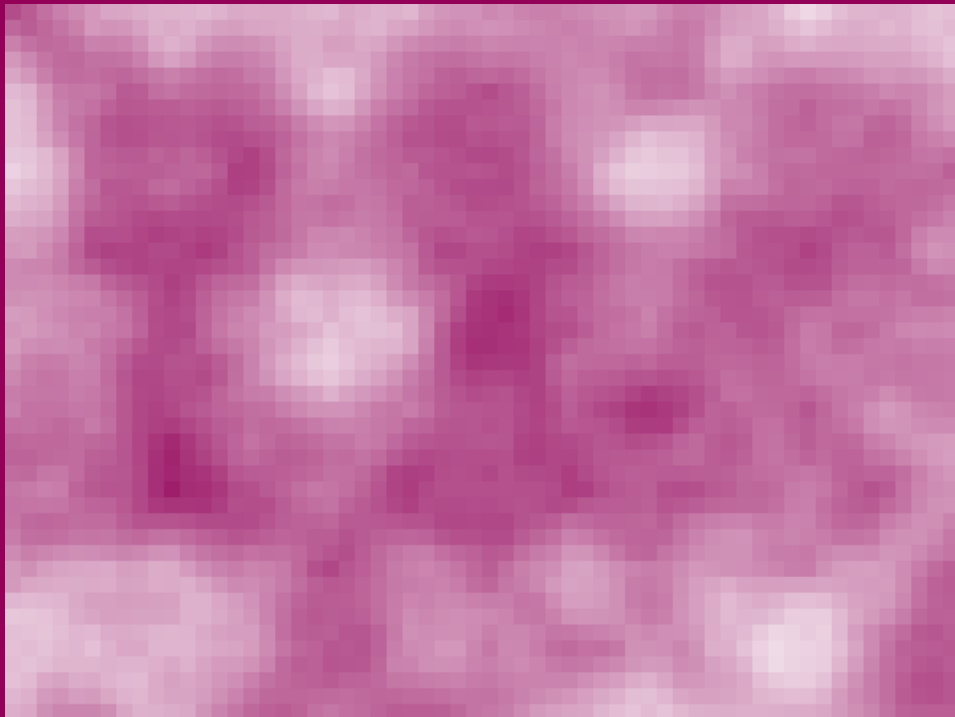

Lecture notes on Stochastic Analysis

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Based on the lectures of
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Chapter 0:

Manuel's notes

Warning

These are unofficial lecture notes written by a student. They are messy, will almost surely contain errors, typos and misunderstandings and may not be kept up to date! I do however try my best and use these notes to prepare for my exams. Feel free to email me any corrections to mh@mssh.dev or s6mlhinz@uni-bonn.de.
Happy learning!

General Information

- Ecampus: [Ecampus link](#)
- Basis: [Basis link](#)
- Website: None
- Time slot(s): Tuesday 12-14 and Thursday 12-14
- Exams: Oral: 23-25 July, 30 Sept. maybe 27. Sept
- Deadlines: ?
- Exercises: One of Tue 16-18(for now this is preferred), Friday 10-12. Starting 16.04.

- First halve based on Eberle and / or Gubinelli (be careful with Notation of dimensions!)

Start of lecture 01
(11.04.23)

Overview of the content

- Weak solutions of SDE
 - Martingale problem (characterization)
 - Time change (Dubin-Schwarz)
 - Change of measure (Girsanov)
- How to condition a diffusion to stay in a given domain forever (reflected BM, local time, ...)
- Lévy processes (a bit)
- Multiplicative stochastic heat-equation
 - relations with Kardar-Parisi-Zhang class of growth models

Chapter 1:

Weak solutions of SDEs

SDE:

$$\begin{cases} dX_t = b(t, X_t)dt + \sigma(t, X_t)dB_t \\ X_0 = x_0 \text{ Initial condition} \end{cases} \quad (1.1)$$

- $X_t \in \mathbb{R}^d, B : n\text{-dim BM}$
- $b(t, x) : [b_k(t, x)]_{1 \leq k \leq d}$: **drift vector**
- $\sigma(t, x) = [\sigma_{k,l}(t, x)]_{\substack{1 \leq k \leq d \\ 1 \leq l \leq n}}$: **dispersion matrix**
- $a(t, x) = \sigma(t, x) \cdot \sigma(t, x)^\top$: **diffusion matrix**

1.1 Strong solutions

Definition 1.1. Let $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$ be a filtered probability space with $\mathcal{F}_t = \sigma(x_0, (B_s)_{0 \leq s \leq t})$

- a d -dim process X_t is a **strong solution** of equation 1.1 if:

- $X_t = x_0$ a.s.
- X_t is adapted to $\mathcal{F}_t \forall t \geq 0$
- X is a continuous semimartingale s.t. $\forall t \geq 0$:

$$\int_0^t (\|b(s, X_s)\| + \|\sigma(s, X_s)\|^2) ds < \infty \text{ a.s.}$$

- $X_t = x_0 + \int_0^t b(s, X_s) ds + \int_0^t \sigma(s, X_s) dB_s$

In the last semester we proved:

Theorem 1.2. Assume that b, σ are globally lipschitz with at most linear growth at ∞ (in space)
 $\implies \exists!$ strong solution of SDE.

Foundations of Stochastic Analysis Thm 8.6

Added remark. There exists $K > 0$ s.t. for all $x, y \in \mathbb{R}^d$: Globally Lipschitz:

$$\|b(t, x) - b(t, y)\| + \|\sigma(t, x) - \sigma(t, y)\| \leq K\|x - y\|$$

Linear growth condition:

$$\|b(t, x)\| + \|\sigma(t, x)\| \leq K(1 + \|x\|)$$

Remark. For strong solutions, \mathcal{F}_t is given by the driving BM, which is given to us.

$$\implies X_t(\omega) = \Phi(x_0(\omega), (B_s)_{0 \leq s \leq t})$$

1.2 Weak solutions

- For weak solutions we do not fix the driving brownian motion.

Definition 1.3. A **weak solution** of equation 1.1 is a **pair** of adapted processes (X, B) to a $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$ s.t.

- B is a n -dim BM
- X is a d -dim continuous semimartingale with
 1. $X_0 = x_0$ a.s.
 2. $\forall t \geq 0$

$$\int_0^t (\|b(s, X_t)\| + \|\sigma(t, X_t)\|^2) ds < \infty \text{ a.s.}$$

$$3. X_t = x_0 + \int_0^t b(s, X_s) ds + \int_0^t \sigma(s, X_s) dB_s$$

Remark. • The filtration $(\mathcal{F}_t)_{t \geq 0}$ is not necessarily the one generated by B

- If X is adapted to the filtration generated by the BM \implies we have strong solutions
- \exists weak solution which are not strong solutions
- Warning: To give a weak solution we really need to provide $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P}, X, B)$

Definition 1.4 (Uniqueness in law). An SDE 1.1 has **uniqueness in law** if given any two weak solutions $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P}, X, B)$ and $(\tilde{\Omega}, \tilde{\mathcal{F}}, (\tilde{\mathcal{F}}_t)_{t \geq 0}, \tilde{\mathbb{P}}, \tilde{X}, \tilde{B})$ satisfy:

$$Law_{\mathbb{P}}(X) = Law_{\tilde{\mathbb{P}}}(\tilde{X})$$

They agree on any set in the sigma algebra

Definition 1.5 (Pathwise uniqueness). The SDE 1.1 has pathwise uniqueness if, whenever the filtered space $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$ and $(B_t)_{t \geq 0}$ are fixed, then two solutions X, \tilde{X} with $X_0 = \tilde{X}_0$ are indistinguishable.

Example 1.6 (No strong solutions, no pathwise uniqueness, \exists weak solution & uniqueness in law by Tanaka).

$$\begin{cases} dX_t = \text{sgn}(X_t) dB_t \\ X_0 = 0 \end{cases} \quad (1.2)$$

or more generally $X_0 = Y$, where

$$\text{sgn}(x) = \begin{cases} 1 & x > 0 \\ -1 & x \leq 0 \end{cases}$$

Let W be a BM with $W_0 = Y$. Define

$$B_t := \int_0^t \text{sgn}(W_s) dW_s \text{ or } dB_t = \text{sgn}(W_t) dW_t$$

$$\implies dW_t = \text{sgn}(W_t) dB_t$$

$$\implies W_t = y + \int_0^t \text{sgn}(W_s) dB_s$$

B_t is a local martingale with

$$\langle B \rangle_t = \int_0^t \underbrace{(\text{sgn}(W_s))^2}_{=1} \underbrace{d\langle W \rangle_s}_{=ds} = t$$

Also $B_0 = 0$, therefore B is a BM (see Lévy characterization) $\implies W$ solves the SDE. For $Y = 0$, W **and** $-W$ solves the same SDE.

\implies

- exists weak solutions
- For $Y = 0$: no pathwise uniqueness
- Uniqueness in law (because the law is determined by X_t being a BM)
- No strong solution, because: $\mathcal{F}^B = \mathcal{F}^{|W|} \subsetneq \mathcal{F}^W$

Not a proof just yet, just the reason!

Example 1.7 (No solutions).

$$\begin{cases} dX_t = -\frac{1}{2X_t} 1_{X_t \neq 0} dt + dB_t \\ X_0 = 0 \end{cases} \quad (1.3)$$

Assume there exists a solution. Use Itô formula for X_t^2 , then:

$$\begin{aligned} X_t^2 &= 2 \int_0^t X_s dX_s + \int_0^t 1 ds \\ &= - \int_0^t 1_{X_s \neq 0} ds + 2 \int_0^t x_s dB_s + t \\ &= \int_0^t 1_{X_s = 0} ds + 2 \int_0^t X_s dB_s \end{aligned}$$

We will prove $\int_0^t 1_{X_s = 0} ds = 0 \implies X_t^2$ is a local martingale, $X_t^2 \geq 0$ (and therefore a supermartingale) and $X_0 = 0$ ($\implies \mathbb{E}(X_t^2) = 0$). If $X_t = 0 \implies \int_0^t 1_{X_s = 0} ds = t \implies 0 = dB_t$ which are contradictions!

Remark. If $X = \underbrace{M}_{\in \mathcal{M}_{loc}} + \underbrace{A}_{\in \mathcal{A}}$

$$\implies \forall b \in \mathbb{R} \int_0^t 1_{X_s = b} d\langle M \rangle_s = 0$$