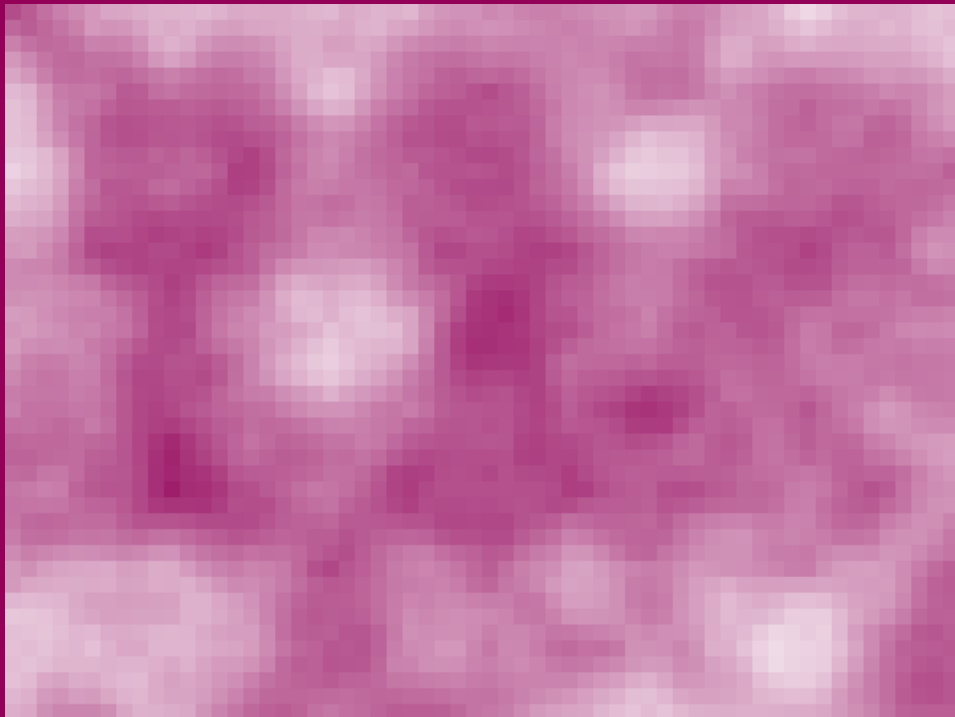

Lecture notes on Stochastic Analysis

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Based on the lectures of
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Chapter 0:

Manuel's notes

Warning

These are unofficial lecture notes written by a student. They are messy, will almost surely contain errors, typos and misunderstandings and may not be kept up to date! I do however try my best and use these notes to prepare for my exams. Feel free to email me any corrections to mh@mssh.dev or s6mlhinz@uni-bonn.de.
Happy learning!

General Information

- Ecampus: [Ecampus link](#)
- Basis: [Basis link](#)
- Website: None
- Time slot(s): Tuesday 12-14 and Thursday 12-14
- Exams: Oral: 23-25 July, 30 Sept. maybe 27. Sept
- Deadlines: ?
- Exercises: One of Tue 16-18(for now this is preferred), Friday 10-12. Starting 16.04.

- First halve based on Eberle and / or Gubinelli (be careful with Notation of dimensions!)

Start of lecture 01
(11.04.23)

Overview of the content

- Weak solutions of SDE
 - Martingale problem (characterization)
 - Time change (Dubin-Schwarz)
 - Change of measure (Girsonov)
- How to condition a diffusion to stay in a given domain forever (reflected BM, local time, ...)
- Lévy processes (a bit)
- Multiplicative stochastic heat-equation
 - relations with Kardar-Pavisi-Zhang class of growth models

Chapter 1:

Weak solutions of SDEs

SDE:

$$\begin{cases} dX_t = b(t, X_t)dt + \sigma(t, X_t)dB_t \\ X_0 = x_0 \text{ Initial condition} \end{cases} \quad (1.1)$$

- $X_t \in \mathbb{R}^d, B : n\text{-dim BM}$
- $b(t, x) : [b_k(t, x)]_{1 \leq k \leq d}$: **drift vector**
- $\sigma(t, x) = [\sigma_{k,l}(t, x)]_{\substack{1 \leq k \leq d \\ 1 \leq l \leq n}}$: **dispersion matrix**
- $a(t, x) = \sigma(t, x) \cdot \sigma(t, x)^\top$: **diffusion matrix**

1.1 Strong solutions

Definition 1.1. Let $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$ be a filtered probability space with $\mathcal{F}_t = \sigma(x_0, (B_s)_{0 \leq s \leq t})$

- a d -dim process X_t is a **strong solution** of equation 1.1 if:

- $X_t = x_0$ a.s.
- X_t is adapted to $\mathcal{F}_t \forall t \geq 0$
- X is a continuous semimartingale s.t. $\forall t \geq 0$:

$$\int_0^t (\|b(s, X_s)\| + \|\sigma(s, X_s)\|^2) ds < \infty \text{ a.s.}$$

- $X_t = x_0 + \int_0^t b(s, X_s) ds + \int_0^t \sigma(s, X_s) dB_s$

In the last semester we proved:

Theorem 1.2. Assume that b, σ are globally lipschitz with at most linear growth at ∞ (in space)
 $\implies \exists!$ strong solution of SDE.

Foundations of Stochastic Analysis Thm 8.6

Added remark. There exists $K > 0$ s.t. for all $x, y \in \mathbb{R}^d$: Globally Lipschitz:

$$\|b(t, x) - b(t, y)\| + \|\sigma(t, x) - \sigma(t, y)\| \leq K\|x - y\|$$

Linear growth condition:

$$\|b(t, x)\| + \|\sigma(t, x)\| \leq K(1 + \|x\|)$$

Remark. For strong solutions, \mathcal{F}_t is given by the driving BM, which is given to us.
 $\implies X_t(\omega) = \Phi(x_0(\omega), (B_s)_{0 \leq s \leq t})$

1.2 Weak solutions

- For weak solutions we do not fix the driving brownian motion.

Definition 1.3. A **weak solution** of equation 1.1 is a **pair** of adapted processes (X, B) to a $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$ s.t.

- B is a n -dim BM
- X is a d -dim continuous semimartingale with
 1. $X_0 = x_0$ a.s.
 2. $\forall t \geq 0$

$$\int_0^t (\|b(s, X_s)\| + \|\sigma(s, X_s)\|^2) ds < \infty \text{ a.s.}$$

$$3. X_t = x_0 + \int_0^t b(s, X_s) ds + \int_0^t \sigma(s, X_s) dB_s$$

Remark. • The filtration $(\mathcal{F}_t)_{t \geq 0}$ is not necessarily the one generated by B

- If X is adapted to the filtration generated by the BM \implies we have strong solutions
- \exists weak solution which are not strong solutions
- Warning: To give a weak solution we really need to provide $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P}, X, B)$

Definition 1.4 (Uniqueness in law). An SDE 1.1 has **uniqueness in law** if given any two weak solutions $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P}, X, B)$ and $(\tilde{\Omega}, \tilde{\mathcal{F}}, (\tilde{\mathcal{F}}_t)_{t \geq 0}, \tilde{\mathbb{P}}, \tilde{X}, \tilde{B})$ satisfy:

$$Law_{\mathbb{P}}(X) = Law_{\tilde{\mathbb{P}}}(\tilde{X})$$

They agree on any set in the sigma algebra

Definition 1.5 (Pathwise uniqueness). The SDE 1.1 has pathwise uniqueness if, whenever the filtered space $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$ and $(B_t)_{t \geq 0}$ are fixed, then two solutions X, \tilde{X} with $X_0 = \tilde{X}_0$ are indistinguishable.

Example 1.6 (No strong solutions, no pathwise uniqueness, \exists weak solution & uniqueness in law by Tanaka).

$$\begin{cases} dX_t = \text{sgn}(X_t) dB_t \\ X_0 = 0 \end{cases} \quad (1.2)$$

or more generally $X_0 = Y$, where

$$\text{sgn}(x) = \begin{cases} 1 & x > 0 \\ -1 & x \leq 0 \end{cases}$$

Let W be a BM with $W_0 = Y$. Define

$$B_t := \int_0^t \text{sgn}(W_s) dW_s \text{ or } dB_t = \text{sgn}(W_t) dW_t$$

$$\implies dW_t = \text{sgn}(W_t) dB_t$$

$$\implies W_t = y + \int_0^t \text{sgn}(W_s) dB_s$$

B_t is a local martingale with

$$\langle B \rangle_t = \int_0^t \underbrace{(\text{sgn}(W_s))^2}_{=1} \underbrace{d\langle W \rangle_s}_{=ds} = t$$

Also $B_0 = 0$, therefore B is a BM (see Lévy characterization) $\implies W$ solves the SDE. For $Y = 0$, W **and** $-W$ solves the same SDE.

\implies

- exists weak solutions
- For $Y = 0$: no pathwise uniqueness
- Uniqueness in law (because the law is determined by X_t being a BM)
- No strong solution, because: $\mathcal{F}^B = \mathcal{F}^{|W|} \subsetneq \mathcal{F}^W$

Not a proof just yet, just the reason!

Example 1.7 (No solutions).

$$\begin{cases} dX_t = -\frac{1}{2X_t} 1_{X_t \neq 0} dt + dB_t \\ X_0 = 0 \end{cases} \quad (1.3)$$

Assume there exists a solution. Use Itô formula for X_t^2 , then:

$$\begin{aligned} X_t^2 &= 2 \int_0^t X_s dX_s + \int_0^t 1 ds \\ &= - \int_0^t 1_{X_s \neq 0} ds + 2 \int_0^t x_s dB_s + t \\ &= \int_0^t 1_{X_s = 0} ds + 2 \int_0^t X_s dB_s \end{aligned}$$

We will prove $\int_0^t 1_{X_s = 0} ds = 0 \implies X_t^2$ is a local martingale, $X_t^2 \geq 0$ (and therefore a supermartingale) and $X_0 = 0$ ($\implies \mathbb{E}(X_t^2) = 0$). If $X_t = 0 \implies \int_0^t 1_{X_s = 0} ds = t \implies 0 = dB_t$ which are contradictions!

Remark. If $X = \underbrace{M}_{\in \mathcal{M}_{loc}} + \underbrace{A}_{\in \mathcal{A}}$

$$\implies \forall b \in \mathbb{R} \int_0^t 1_{X_s = b} d\langle M \rangle_s = 0$$

Sheet 0:

- Mail: Alexander.Becker@uni-bonn.de
- Exercise sheet handed in Fr 10 am via eCampus
- Groups of 3

Motivation:

in the last semester: Introduction to stochastic analysis

- Diffusion processes & SDEs

Here: Deepen the knowledge & have fun

- Learn SDE techniques and get other results
- Modify diffusion processes to behave in a certain way
- Ex. diffusion bridge (Brownian bridge)
- Condition a diffusion to stay in a domain
 - Ex. Condition BM to stay positive
 - Old SDE: $dB_t = dB_t$

- New SDE: $dX_t = \frac{1}{X_t} dx + dB_t \rightarrow P(X_t \in \cdot) = P(B_t \in \cdot | B > 0 \text{ forever})$
- $D \subset \mathbb{R}^d$ open domain, X diffusion process, with generator $L = \Sigma b \partial_i + \frac{1}{2} \sum a^{ij} \partial_i \partial_j$

$$Y := (X | X \in D \text{ forever})$$

get drift term $\nabla \log \phi_0$, where ϕ_0 is the lowest eigenfunction of $-L$ on D with dirichlet boundary.

Recap:

Brownian motion:

Added definition. $B_0 = 0$, independent $\mathcal{E} \mathcal{N}(0, t_i - t_{i-1})$ increments, $t \mapsto B_t(\omega)$ continuous.

Regularity of path $t \mapsto B_t(\omega)$:

- nowhere differentiable
- α -locally Hölder continuous $\iff \alpha < \frac{1}{2}$
- Quadratic variation $\langle B \rangle_t = t$
- Generator $\frac{\Delta}{2}$
- Recurrent $\iff ds^2?$

Itô-Integral:

1. If X simple process \implies RS-Integral
2. Itô isometry $\mathcal{E} \rightarrow \{L^2 - \text{local martingale}\}, \mathcal{E} \subset L^2(d[M])$ dense
3. general $X : \int X dM$ as L^2 -limit

Added remark (Itô formula). •

$$df(t, X_t) = \partial_t f(t, X_t) dt + \partial_x f(t, X_t) dX_t + \frac{1}{2} f''(t, X_t) d\langle X \rangle_t$$

- associative $\int X d(\int Y dZ) = \int XY dZ$
- If M local martingale $\implies \int X dM$ local martingale

SDEs:

$$dX_t = b(t, X_t) dt + \sigma(t, X_t) dB_t$$

- ex./ uniqueness: b, σ locally Lipschitz \implies strong ex.+pathwise uniqueness until explosion time
- globally Lipschitz (in space) and linear growth ($|b(t, x)| + |\sigma(t, x)| \leq C(1 + |x|)$), $e = \infty$.

Problem 00.1: SDE

Let B be a one-dimensional Brownian motion (starting from 0) and let $X_t = \sin(B_t)$.

1. Determine the SDE of X_t
2. Discuss the existence and/or uniqueness of strong solutions of the SDE
3. Determine whether the local martingale term is a martingale (Hint: for the integrability condition, think about the Itô isometry for instance)

Solution 00.1

1.:

Idea: Use Itô formula: $X_t = \sin(B_t) = f(B_t)$

$$dX_t = df(B_t) \stackrel{\text{Itô}}{=} \underbrace{\partial_x \cos(B_t)}_{\sqrt{1-X_t^2}} dB_t - \frac{1}{2} \underbrace{\sin(B_t)}_{X_t} dt$$

Careful: $\sqrt{1-X_t^2}$ is not inverse mapping, because it is always positive while $\cos(B_t)$ is not

2.:

Consider the SDE

$$dX_t = \begin{cases} -\frac{1}{2}X_t dt + \sqrt{1-X_t^2} dB_t \\ X_0 = x \in (-1, 1) \end{cases}$$

Coefficients: $b : [-1, 1] \rightarrow \mathbb{R}, b(x) = -\frac{1}{2}x$ and $\sigma : [-1, 1] \rightarrow \mathbb{R}, \sigma(x) = \sqrt{1-x^2}$

$$[\sigma]_{1,2} = \sup \frac{|\sigma(x) - \sigma(y)|}{|x - y|^{1/2}} < \infty$$

Probably σ^2 Lipschitz $\implies \sigma$ Hölder $\frac{1}{2}$

3.:

Problem 00.2: Time change

Let B be a one-dimensional Brownian motion (starting from 0). Let $Y_t = \int_0^t s^2 dB_s$.

1. Determine the SDE of Y_t
2. Find A_t such that Y_{A_t} is a (stopped) Brownian motion

Solution 00.2

1.: By Definition

$$dY_t = t^2 dB_t$$

2.: We use the Dubin-Schwarz theorem:

$$X_{\infty} \in \mathcal{M}_{\text{loc}}^0, \langle X \rangle_{\infty} = \infty, T_t := \inf\{s \geq 0 | \langle X \rangle_s \geq t\} = X_t^{[-1]}$$

$$\implies B_t := X_{T_t} \text{ 1 d BM w.r.t. } (F_{T_t})_{t \geq 0}, X_t = B_{\langle B \rangle_t}$$

$$\text{here: use } X_t = b(X_t)dt + \sigma(X_t)dB_t \implies d[X]_t = \sigma^2(X_t)dt$$

Problem 00.3: SDE and PDE

Let f be a function supported on $[0, 1]$, u the solution of

$$\frac{1}{2}u(t, x) = \frac{1}{2}x(1-x) + \frac{d^2}{dx^2}u(t, x), \quad u(0, x) = f(x).$$

Consider also the one-dimensional SDE (also known as Wright-Fisher diffusion)

$$dX_t = \sqrt{X_t(1-X_t)}dB_t$$

with $X_0 = x \in (0, 1)$.

1. For any fixed $t > 0$, define $M_s = u(t-s, X_s)$ for $s \in [0, t]$. Use Itô formula to show that M_s is a local martingale
2. Assume that f is bounded and there is a bounded solution of u . Show that $u(t, x) = \mathbb{E}_x(f(X_t))$.

Solution 00.3

1.:

$$\begin{aligned}
dM_s &= du(t-s, X_s) \\
&= -\partial_s u(t-s, X_s)ds + \partial_x u(t-s, X_s) \underbrace{dX_s}_{b(X_s)ds + \sigma(X_s)dB_s \text{ by asso.}} + \frac{1}{2}\partial_x^2 u(t-s, X_s) \underbrace{d[X]_s}_{=\sigma^2(X_s)ds} \\
&= \underbrace{(-\partial_s u + b\partial_x u + \frac{1}{2}\sigma^2\partial_x^2 u)(t-s, X_s)}_{=0}ds + \partial_x u(t-s, X_s)\sigma(X_s)dB_s \\
&\implies dM_s = \partial_x u(t-s, X_s)\sigma(X_s)dB_s
\end{aligned}$$

(i.e.: $M_t - M_0 = \int_0^t \dots dB_s$)This is a purely stochastic integral against a (local) martingale \implies martingale.

2.:

- M_s true martingale:

1. $\forall t : \mathbb{E}(\sup_{[0,t]} |M|) < \infty$, for example: M bounded
2. $\forall t : \mathbb{E}(\sup_{[0,t]} [M]_t) < \infty$

 $M_s := u(t-s, X_s), u$ bounded $\implies M$ bounded $\implies M$ true martingale $w(s, x) := u(t-s, x)$

$$u(t, x) = w(0, x) = \mathbb{E}_x[w(0, X_0)] \stackrel{\text{martingale}}{=} \mathbb{E}_x[w(t, X_t)] = \mathbb{E}_x[(u(0, X_t))] \stackrel{\text{PDE}}{=} \mathbb{E}_x[f(X_t)]$$

Feynman-Kac formula (later more general).

Also solvable by Kolmogorov Backward / forward equation

Start of lecture 02
(16.04.24)**Example 1.8** (Non-uniqueness of law, non pathwise uniqueness, with solutions).

$$\begin{cases} dX_t &= 1_{X_t \neq 0} dB_t \\ x_0 &= 0 \end{cases}$$

Then

$$X_t = 0 \forall t \geq 0$$

and

$$X_t = B_t \forall t \geq 0$$

both are solutions:

$$X_t - B_t = -\int_0^t 1_{X_s=0} dB_s \implies \langle X - B \rangle_t = \int_0^t 1_{X_s=0} d\langle B \rangle_s = 0$$

Let $\eta \sim \text{Ber}(\frac{1}{2})$ independent of $(B_t)_{t \geq 0}$ and define

$$\tilde{X}_t = \begin{cases} 0 & \eta = 0 \\ B_t & \eta = 1 \end{cases}$$

 $\implies \tilde{X}_t$ is adapted to $\sigma(\eta(B_s)_{0 \leq s \leq t})$, but not to $\sigma((B_s)_{0 \leq s \leq t})$ and therefore not a **strong solution**.

$$\begin{aligned} X_t &= \int_0^t 1_{X_s \neq 0} dB_s \\ &= \int_0^t (1 - 1_{X_s=0}) dB_s \\ B_t - \int_0^t 1_{X_s=0} dB_s \end{aligned}$$

Example 1.9 (No strong solution, weak solution, no pathwise uniqueness, no uniqueness in law).

$$\begin{cases} dX_t &= 1_{X_t \neq 1} \operatorname{sgn}(X_t) dB_t \\ X_0 &= 0 \end{cases}$$

Let Y_t be a solution of

$$\begin{cases} dY_t &= \operatorname{sgn}(Y_t) dB_t \\ Y_0 &= 0 \end{cases}$$

$\implies X_t := Y_{t \wedge \tau}$, where $\tau = \inf\{s \geq 0 \mid Y_s = 1\}$ is also a solution.

Theorem 1.10 (Yamada-Watanabe). *If both existence of weak solutions and pathwise uniqueness hold, uniqueness in law also holds.*

Moreover, \forall choices of $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$ and $(B_t)_{t \geq 0}$ then there exists a **strong solution**.

1.3 Lévy characterization

Example 1.11. Consider the SDE

$$\begin{cases} dX_t &= O_t dB_t \\ X_0 &= x_0 \end{cases}$$

where both X_t and B_t are d -dimensional and O_t is an adapted process (matrix) s.t. $O_t^\top O_t = 1 \forall t \geq 0$ i.e. O_t is a rotation

$$\begin{aligned} \implies X_t^k &= X_0^k + \sum_{l=1}^d \int_0^t O_s^{k,l} dB_s^l \\ \implies \langle X^k, X^{\bar{k}} \rangle_t &= \sum_{l, \bar{l}} \int_0^t O_s^{k,l} O_s^{\bar{k}, \bar{l}} d\langle B^l, B^{\bar{l}} \rangle_s = \sum_{l=1}^d \int_0^t O_s^{k,l} O_s^{\bar{k}, l} ds \\ &= \int_0^t \underbrace{(O_s O_s^\top)^{k, \bar{k}}}_{=1} ds = \delta_{k, \bar{k}} t \xrightarrow{\text{Lévy}} (X_t)_{t \geq 0} \text{ is also a } d\text{-dim BM starting from } x_0 \end{aligned}$$

Theorem 1.12 (Yamada, Watanabe). *Let $dX_t = b(X_t)dt + \sigma(X_t)dB_t$ and assume that there exist both a increasing function $\rho(u) \geq 0$ s.t. $|\sigma(x) - \sigma(y)| \leq \rho(|x - y|) \forall x, y \in \mathbb{R}$ s.t.*

$$\int_0^\infty \frac{1}{\rho(u)} du = \infty \implies 0 < u < C_1 \implies \rho(u) \leq C_2 u^{0.5}$$

and some increasing concave function $\gamma_1(u) \geq 0$ s.t.

$$|b(x) - b(y)| \leq \gamma_1(|x - y|) \forall x, y \in \mathbb{R}$$

and

$$\int_0^\infty \frac{1}{\gamma_1(u)} du = \infty.$$

Then pathwise uniqueness holds.

Theorem 1.13 (Storokhod). *Assume that σ, b are continuous bounded functions*

\implies *there exist weak solutions to the SDE $dX_t = b(X_t)dt + \sigma(X_t)dB_t$.*

1.4 Weak solutions and martingale problems

Let $(X_t)_{t \geq 0}$ be a weak solution of the SDE

$$\begin{cases} dX_t = b(t, X_t)dt + \sigma(t, X_t)dB_t \\ X_0 = 0 \end{cases}$$

on $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$.

$\implies X_t$ is a semimartingale s.t. $X_t^k = X_0^k + \int_0^t b(s, X_s)ds + \sum_{l=1}^n \int_0^t \sigma_{k,l}(s, X_s)dB_s^l$ and

$$\langle X^i, X^j \rangle_t = \int_0^t \underbrace{\sum_{l=1}^n \sigma_{i,l}(s, X_s) \sigma_{j,l}^T(s, X_s)}_{=a_{i,j}(s, X_s)} ds$$

1.4.1 Itô-Doeblin formula

Itô formula leads to

Proposition 1.14. For $f \in C^{1,2}(\mathbb{R}_+ \times \mathbb{R}^d)$, then

$$f(t, X_t) = f(0, X_0) + \int_0^t (\sigma^T \nabla f)(s, X_s) dB_s + \int_0^t \left[\left(\frac{\partial}{\partial s} + \mathcal{L} \right) f \right](s, X_s) ds$$

where $(\mathcal{L}f)(t, x) = \frac{1}{2} \sum_{k,l=1}^n a_{k,l}(t, x) \frac{\partial^2}{\partial x_k \partial x_l} f(t, x) + \sum_{k=1}^n b_k(t, x) \frac{\partial}{\partial x_k} f(t, x)$.

\mathcal{L} is called the **generator**

Remark. The Itô-Doeblin formula provides a connection between SDEs and PDEs as we have seen in the last part **Foundations of stochastic analysis**.

Example 1.15. Let $f \in C^{1,2}(\mathbb{R}_+ \times \mathbb{R}^d)$ be a solution of the PDE

$$\begin{aligned} \frac{\partial}{\partial t} f(t, x) + (\mathcal{L}f)(t, x) &= -g(t, x) & t \geq 0, x \in U \subseteq \mathbb{R}^d \\ f(t, x) &= \varphi(t, x) & t \geq 0, x \in \partial U. \end{aligned}$$

then $M_t := f(t, X_t) + \int_0^t g(s, X_s)ds \in \mathcal{M}_{loc}$ by proposition 1.14 and if f, g are bounded $M_t \in \mathcal{M}$.

$$T := \inf\{s \geq 0 | X_s \notin U\} \implies M_t^T := M_{t \wedge T} \in \mathcal{M}.$$

Furthermore, if we assume $T < \infty$ a.s. :

$$\mathbb{E}[M_t] = \mathbb{E}[\varphi(T, X_T)] + \mathbb{E}\left[\int_0^T g(s, X_s)ds\right] = \varphi(0, X_0)$$

where $X_0 = x_0$.

There are two special cases:

$g = 0 \implies$ yields the exit distributions, while

$\varphi = 0, g = 1$ yields the mean exit times.

Example 1.16 (Feynman-Kac formula). Let $t \in \mathbb{R}_+$ be finite. Assume $f : \mathbb{R}^d \rightarrow \mathbb{R}$ and $K : [0, t] \times \mathbb{R}^d \rightarrow \mathbb{R}_+$ be continuous functions. Assume that u is a $C^{1,2}$ -solution (bounded, for simplicity) of

$$\begin{cases} \frac{\partial u}{\partial s}(s, x) = \frac{1}{2} \Delta u(s, x) - K(s, x)u(s, x) & s \in [0, t], x \in \mathbb{R}^d \\ u(0, x) = f(x) & x \in \mathbb{R}^d \end{cases}$$

Then u has the stochastic representation $u(t, x) = \mathbb{E}_x \left[f(X_t) \exp \left(- \int_0^t K(t-s, X_s) ds \right) \right]$, where X_t is BM starting from $X_0 = x$.

Sketch. 1. Define $r(s, x) := u(t-s, x)$ for $s \in [0, t]$

2. Show: $M_s := \exp(-A_s)r(s, x)$ with $A_s = \int_0^s K(u, X_u)du$ is a local martingale. □

Remark. *This is a reformulation of the formula from the last semester.*

1.4.2 Martingale problem

A solution of an SDE is generically defined up to some **explosion time** ξ , where it either diverges or it exists a given domain $U \subset \mathbb{R}^d$ (open).

\implies For $k \in \mathbb{N}$ define $U_k := \{x \in U \mid |x| < k \wedge \text{dist}(x, U^c) \geq \frac{1}{k}\}$ with $U = \bigcup_{k \geq 1} U_k$ and

$$T_k := \{t \geq 0 \mid x_t \notin U_k\}.$$

A solution of the SDE $b(t, X_t)dt + \sigma(t, X_t)dB_t$ is defined up to $\xi = \sup_{k \geq 1} T_k$.

Start of lecture 03
(18.04.24)

Added remark. *uniqueness of solution to the heat equation $\frac{1}{2}\Delta u - Ku$: not unique! Stochastic calculus: Paolo Baldi: 10.3-10.4*

Define (\star) :

$$dX_t b(t, X_t)dt + \sigma(t, X_t)dB_t \text{ with } X_0 = x_0$$

Theorem 1.17 (Martingale problem). *If X is a solution of (\star) up to time ζ , then $\forall f \in C^{1,2}(\mathbb{R}_+ \times U)$*

$$M_t = f(t, X_t) - \int_0^t \left(\frac{\partial}{\partial s} + \mathcal{L} \right) f(s, x_s) ds, t < s$$

is a local martingale up to ζ and $M_t^{T_k}$ are localizing martingales.

Definition 1.18 (Martingale solutions). *$(X_t)_{t \geq 0}$ is a **martingale solution** of (\star) if $\forall f \in C^2(\mathbb{R}^d)$*

$$M_t^f = f(X_t) - f(X_0) - \int_0^t (\mathcal{L}f)(X_s) ds$$

is a continuous local martingale.

Theorem 1.19 (Equivalent definitions). *The following are equivalent (for X_t being a solution of (\star)):*

(a) $\forall f \in C^2(\mathbb{R}^d)$,

$$M_t^f := f(X_t) - f(X_0) - \int_0^t (\mathcal{L}f)(X_s) ds$$

is a local martingale

(b) *The process in \mathbb{R}^d given by*

$$M_t := X_t - X_0 - \int_0^t b(s, X_s) ds$$

is a d -dimensional local martingale with $\langle M^i, M^j \rangle_t = \int_0^t a_{i,j}(s, X_s) ds = \langle X^i, X^j \rangle_t$

(c) $\forall f \in C^{1,2}(\mathbb{R}_+ \times \mathbb{R}^d)$

$$\tilde{M}_t^f := f(t, X_t) - f(0, X_0) - \int_0^t \left(\frac{\partial}{\partial s} + \mathcal{L} \right) f(s, X - s) ds$$

is a local martingale

ds

Proof. $c \implies a$: by choosing f independent of t .

$a \implies b$: 1.: Choosing $f(X) = X_i$ implies

$$M_t^f = X_t^i - X_0^i - \int_0^t b_i(s, X_s) ds \in \mathcal{M}_{\text{loc}}$$

2.: $f(X) = X_i X_j$:

$$\begin{aligned} (\mathcal{L}f)(x) &= \frac{1}{2}a_{ij} + \frac{1}{2}a_{ji} + b_i X_j b_j X_i \\ a &= a^\top \implies a_{ij} b_i X_j b_j X_i \\ \implies M_t^f X_t^i X_t^j - X_0^i X_0^j - \int_0^t [a_{ij}(s, X_s) + b_i(s, X_s) X_s^j + b_j(s, X_s) X_s^i] ds \end{aligned}$$

$$\begin{aligned} X_t^i X_t^j - X_0^i X_0^j &\stackrel{\text{Integration by parts}}{=} \int_0^t X_s^i dX_s^j + \int_0^t X_s^j dX_s^i + \langle X^i, X^j \rangle_t \\ &= M_t^f + \int_0^t [a_{ij} + b_i X_s^j + b_j X_s^i] ds \end{aligned}$$

We can maybe also proof this by calculating X^2 ?

Here dX_s^i is the same as $b_i X_s^j$ is the same up to a local martingale term and $\langle X^i, X^j \rangle_t = \int_0^t a_{ij}(s, X_s) ds = \langle M^i, M^j \rangle_t$

$b \implies c$: By Proposition 1.14 If (use the next theorem) X was a weak solution $\implies \tilde{M}_t^f$ is a local martingale. \square

Theorem 1.20. Let $n = d$, assume $\sigma(t, x)$ is invertible $\forall t, x$ and $\sigma^{-1}(t, x)$ is uniformly bounded. T.f.a.e.:

- (a) $(X_t)_{t \geq 0}$ is a weak solution of the SDE (\star) on $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P}; B)$
- (b) $(X_t)_{t \geq 0}$ is a martingale solution of the SDE (\star)

This also works for $n \neq d$, but with a different proof

Proof. $a \implies b$: True

$b \implies a$: Goal construct a BM for the weak solution.

By proposition ?? $a \implies b$ $dM_t = dX_t - b(t, X_t)dt \in \mathcal{M}_{\text{loc}}$ and $d\langle M^i, M^j \rangle_t = a_{k,l}(t, X_t)dt$

$$\begin{aligned} \implies dX_t &= dM_t + b(t, X_t)dt \\ &= \sigma(t, X_t) d\tilde{B}_t + b(t, X_t)dt \end{aligned}$$

where $\tilde{B}_t := \sigma(s, X_s)^{-1} dM_s$

To see: \tilde{B}_t is a brownian motion.

$$\begin{aligned} \langle \tilde{B}^i, \tilde{B}^j \rangle_t &= \sum_{k,l} \int_0^t \sigma_{ij}^{-1} \sigma_{jl}^{-1} d\langle M^k, M^l \rangle_s \\ &\quad = \underbrace{a_{ij}}_{(\sigma^\top \sigma)_{kl}} ds \\ &= \sum_{k,l,p} \int_0^t \sigma_{ik}^{-1} \sigma_{kp} \sigma_{pl}^\top \sigma_{lj}^{-1} ds \\ &= \delta_{ij} \int_0^t 1 ds = \delta_{ij} t \end{aligned}$$

Then by the Lévy characterization \tilde{B} is a brownian motion. \square

Added remark. This is the first way to construct a weak solution: Solve a martingale problem! This is used a lot in practice.

1.5 Weak solutions and time change

1.5.1 Time change

For $d = 1$:

Theorem 1.21. [Dubins-Schwarz]

- Let $M \in \mathcal{M}_{loc}^0$ and $\langle M \rangle_\infty = \infty$ a.s.
- Let $T_t := \inf\{s \geq 0 \mid \langle M \rangle_s \geq t\}$

This implies

1. $t \mapsto M_{T_t}$ is a (\mathcal{F}_{T_t}) brownian motion
2. $M_t = B_{\langle M \rangle_t}$ for some standard brownian motion B

$$X_t = X_0 + \int_0^t b(s, X_s) ds + \underbrace{\int_0^t \sigma(s, X_s) dB_s}_{=M_t}. \text{ If } \langle M \rangle_\infty = \infty \text{ a.s.:}$$

$$X_t = X_0 + \int_0^t b(s, X_s) ds + \tilde{B}_{\int_0^t \sigma^2(s, X_s) ds}$$

1.5.2 Time change in a martingale problem

Consider $d = 1 = n$.

$$dY_t = \tilde{\sigma}(Y_t) dB_t \quad (\star\star)$$

and $\tilde{\sigma}$ strictly positive continuous function.

$$\langle Y \rangle_t = \int_0^t \tilde{\sigma}(Y_s)^2 ds =: A_t$$

By theorem 1.21 $\implies Y_t = W_{A_t}$ for some brownian motion W .

Assume $A_t \rightarrow \infty$ a.s.

$$T_t := \inf\{s \geq 0 \mid \langle Y \rangle_s \geq t\}$$

$$\implies T_{A_t} = \inf\{s \geq 0 \mid \langle Y \rangle_s \geq \langle Y \rangle_t\} = t$$

$$1 = \frac{d}{dt} (T_{A_t}) = T'_{A_t} \cdot A_t$$

$$\implies \underbrace{T'_u}_{=\frac{dT_u}{du}} = \frac{1}{A'_u} \implies T_u = \int_0^u \frac{1}{\tilde{\sigma}(Y_s)^2} ds = \int_0^u \frac{1}{\tilde{\sigma}(W_s)^2} ds$$

\implies to construct a solution of $(\star\star)$: Given $W \rightarrow$ compute $T_u \rightarrow$ determine $A - t = T_t^{-1} \implies Y_t = W_{A_t}$

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Theorem 1.22. Let $(X_u)_{u \geq 0}$ on $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$ be a weak solution of

$$dX_u = b(X_u) du + \sigma(X_u) dB_u$$

where $b : \mathbb{R}^d \rightarrow \mathbb{R}^d$, the drift and $\sigma : \mathbb{R}^d \rightarrow \mathbb{R}^d \times \mathbb{R}^d$ are locally bounded, σ^{-1} exists for a.e. x and is locally bounded.

Consider a **time change** $T_u := \int_0^u \rho(X_s) ds$, where $\rho : \mathbb{R}^d \rightarrow \mathbb{R}_+$ s.t.

$$T_u < \infty \forall u \geq 0 \text{ and } T_\infty = \infty \text{ a.s.}$$

\implies Then $Y_t := X_{A_t}$, where $A_t = T_t^{-1}$ is a weak solution of the SDE

$$dY_t = \frac{b(Y_t)}{\rho(Y_t)}dt + \frac{\sigma(Y_t)}{\sqrt{\rho(Y_t)}}dB_t$$

Remark. Special case: $d = 1, b = 0, \sigma = 1$: Then X is a BM and $\rho = \frac{1}{\tilde{\sigma}^2(x)} \implies Y_t = X_{T_t^{-1}}$ solves

$$dY_t = \tilde{\sigma}(Y_t)dB_t$$

Proof. By theorem 1.20, it is enough to see how the martingale problem after change of time becomes:

$$\mathcal{L} = \mathcal{L}_{X_t} \xrightarrow{\text{time change}} \mathcal{L}_{Y_t} = \tilde{\mathcal{L}}$$

$Y_t = X_{A_t}; Y_0 = X_{A_0}$. For $f \in C^2$: $M_t^f = f(X_t) - f(X_0) - \int_0^t (\mathcal{L}f)(X_s)ds$ is a local martingale w.r.t. $(\mathcal{F}_t)_{t \geq 0}$.

$$\implies N_t^f := M_{A_t}^f = f(\underbrace{X_{A_t}}_{=Y_t}) - f(\underbrace{X_{A_0}}_{Y_0}) - \int_{A_0}^{A_t} (\mathcal{L}f)(X_s)ds$$

is also a local martingale w.r.t. $(\mathcal{F}_{A_t})_{t \geq 0}$.

Change of variable (to get rid of the X_s in the integral):

$$\begin{aligned} \tau = T_s &\leftrightarrow A_t = s \implies X_s = X_{A_t} = Y_\tau \\ d\tau &= \rho(X_s)ds \end{aligned}$$

$$\implies N_t^f = f(Y_t) - f(Y_0) - \int_0^t (\mathcal{L}f)(Y_t) \frac{1}{\rho(Y_t)} d\tau$$

Since $\mathcal{L}f(x) = \sum_k b_k(x) \frac{\partial}{\partial x_k} f(x) + \sum_{k,l} a_{k,l}(x) \frac{\partial^2}{\partial x_k \partial x_l} f(x)$

$$\implies (\tilde{\mathcal{L}}f)(x) = \sum_k \frac{b_k(x)}{\rho(x)} \frac{\partial}{\partial x_k} f(x) + \sum_{k,l} \frac{\overbrace{a_{k,l}}^{(\sigma\sigma^\top)_{k,l}}}{\sqrt{\rho(x)\rho(x)}}(x) \frac{\partial^2}{\partial x_k \partial x_l} f(x)$$

\implies It is a martingale problem for the SDE where the drift $\rightarrow \frac{\text{drift}}{\rho}$ and $\sigma \rightarrow \frac{\sigma}{\sqrt{\rho}}$

□

1.5.3 Weak solutions in d=1

We will do both time and “space” changes.

- 1-d SDE:

$$\begin{cases} dX_t &= b(X_t)dt + \sigma(X_t)dB_t \\ X_0 = x_0 \in (\alpha, \beta) \end{cases} \quad (1.4)$$

- X_t a process in (α, β)
- Assume $b, \sigma : (\alpha, \beta) \rightarrow \mathbb{R}$ continuous, $\sigma(x) > 0 \forall x \in (\alpha, \beta)$
- Do a change of coordinates $Y_t := s(X_t)$ where $s : (\alpha, \beta) \rightarrow (s(\alpha), s(\beta))$, C^2 with $s'(x) > 0, x \in (\alpha, \beta)$.
- $s(x)$ is called the **scale function** and it is given by

$$s(x) = \int_{x_0}^x \exp\left(-\int_{x_0}^y \frac{2b(z)}{\sigma(z)^2} dz\right) dy$$

- s satisfies $\frac{1}{2}\sigma^2(x)s''(x) + b(x)s'(x) = 0 \iff (\mathcal{L}s)(x) = 0$

The A_0 in the integral is probably 0, but it does not matter, we do a change of variables anyway.

Remark. If $b(z) = 0 \implies s(x) = x - x_0 \implies s'(x) = 1$. If $s'(x) = 1$, we say that the process is in its “natural scale”

By proposition 1.14: $\mathcal{L}s = 0, \dot{s} = 0$.

$\implies Y_t = s(X_t)$ is a local martingale satisfies $dY_t = s'(X_t)\sigma(X_t)dB_t$.

the other terms cancel

$\iff Y_t$ is a solution of

$$\begin{cases} dY_t &= \tilde{\sigma}(Y_t)dB_t \\ Y_0 &= s(X_0) \end{cases} \quad (1.5)$$

where $\tilde{\sigma}(y) = s'(s^{-1}s(y))\sigma(s^{-1}(y))$.

Therefore we can write the original SDE in terms of a BM

Theorem 1.23. The following are equivalent:

1. The process $(X_t)_{t < \xi}$, where ξ is the explosion time, on $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P}; (B_t)_{t \geq 0})$ is a solution of (1.4) up to the stopping time ξ
2. The process $Y_t = s(X_t)_{t < \xi}$ on $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P}; (B_t)_{t \geq 0})$ is a solution of (1.5) up to ξ
3. The process $(Y_t)_{t < \xi}$ has the representation $Y_t = \tilde{B}_{A_t}$, where \tilde{B} is a BM starting at $\tilde{B}_0 = s(X_0)$ and $A_t = T_t^{-1}$ and $T_t = \int_0^t \frac{1}{\tilde{\sigma}^2(\tilde{B}_u)} du$

s and A_t have the same definition as before

A degenerate case:

Let $\sigma(x) = |x|^\alpha$ for some $\alpha \in (0, \frac{1}{2})$. \implies

$$\begin{cases} dY_t &= |Y_t|^\alpha dB_t \\ Y_0 &= y \end{cases} \quad (1.6)$$

$\implies T_t = \int_0^t \frac{1}{\sigma(\tilde{B}_u)^2} du$, $A_t = \int_0^t \sigma(Y_s)^2 ds$ and $Y_t = \tilde{B}_{A_t} \implies \tilde{B}_0 = y$.
 $T_t < \infty$ a.s. ?

$$\begin{aligned} \mathbb{E}(T_t) &= \int_0^t \mathbb{E} \left(\frac{1}{\sigma(\tilde{B})^2} \right) du \\ &= \int_0^t \mathbb{E} \left(\frac{1}{|\tilde{B}|^{2\alpha}} \right) du \\ &= \int_0^t \int_{\mathbb{R}} dx \frac{1}{|x|^{2\alpha}} \frac{\exp(-\frac{(x-y)^2}{2u})}{\sqrt{2\pi u}} \quad 0 < 2\alpha < 1 < \infty \end{aligned}$$

$\implies A_t = T_t^{-1}$, then $Y_t = \tilde{B}_{A_t}$ is a solution of (1.6), i.e. $\forall y \in \mathbb{R} \exists$ a non-trivial solution of (1.6).

For $Y=0, Y_t = 0$ is also a solution \implies

- No uniqueness in law of (1.6)
- No pathwise uniqueness as well

Remark. In general: uniqueness in law of 1-d SDEs is not to be expected if $\sigma(x) = 0$ somewhere (and σ continuous ...) (i.e. if σ is degenerate).

By theorem 1.12 as soon as $\sigma(x) = |x|^\alpha$ for some $\alpha \geq \frac{1}{2}$, then one has pathwise uniqueness.

Hitting times and scale functions Bessel process:

$$\begin{cases} dR_t &= \frac{d-1}{2R_t} dt + dW_t \\ R_0 &= r_0 \in (0, \infty) \end{cases}$$

$\implies b(x) = \frac{d-1}{2x}, \sigma(x) = 1$.

The scale function satisfies $\mathcal{L}s(x) = \frac{1}{2}s''(x) + \frac{d-1}{2x}s'(x) = 0$

$$\implies s(x) = \begin{cases} \frac{x^{2-d}}{2-d} & d \neq 2 \\ \ln(x) & d = 2 \end{cases}$$

and therefore

$$(s_0, s_\infty) = \begin{cases} (0, \infty) & d < 2 \\ (-\infty, \infty) & d = 2 \\ (-\infty, 0) & d > 2 \end{cases}$$

Define the stopping time

$$T_a^R := \inf\{t \geq 0 \mid R_t = a\}$$

Choose an $\alpha < r_0 < \beta$

$$\implies \mathbb{P}(T_\alpha^R < T_\beta^R) \stackrel{s' \geq 0}{=} \mathbb{P}(T_{s(\alpha)}^{s(R)} < T_{s(\beta)}^{s(R)})$$

One computes

$$\mathbb{P}(T_a^R < T_\beta^R) = \frac{s(\beta) - s(r_0)}{s(\beta) - s(\alpha)} = \mathbb{P}(T_{s(\alpha)}^{s(R)} < T_{s(\beta)}^{s(R)})$$

This is generic, for Itô diffusions, provides that \exists no killing in (α, β) .

WS exercises

unlike in 1.16
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1.5.4 Uniqueness of martingale solution

SDE $dX_t = b(t, X_t)dt + \sigma(t, X_t)dB_t$ with generator

$$\mathcal{L} = \sum_k b_k \frac{\partial}{\partial x_k} + \frac{1}{2} \sum_{k,l} (\sigma \sigma^\top)_{k,l} \frac{\partial^2}{\partial x_k \partial x_l}$$

Definition 1.24. Let $\mathcal{C} = C(\mathbb{R}_+, \mathbb{R}^d)$ with σ -algebra \mathcal{F} , canonical filtration $(\mathcal{F}_t)_{t \geq 0}$, canonical process $Z_t(\omega) := \omega$.

We say that \mathbb{P} on $(\mathcal{C}, \mathcal{F})$ is a martingale solution for the generator $\mathcal{L} \iff \forall f \in C^{1,2}(\mathbb{R}_+ \times \mathbb{R}^d \rightarrow \mathbb{R})$

$$M_t^f := f(t, Z_t) - f(0, Z_0) - \int_0^t \left(\frac{\partial}{\partial s} + \mathcal{L} \right) f(s, Z_s) ds \quad (1.7)$$

is a martingale w.r.t. \mathbb{P} .

Definition 1.25. A martingale problem (1.7) has a unique solution if for any two martingale solutions $\mathbb{P} = \mathbb{Q}$ s.t. $\text{Law}_{\mathbb{P}}(Z_0) = \text{Law}_{\mathbb{Q}}(Z_0)$

$$\implies \mathbb{P} = \mathbb{Q}$$

Remark. Uniqueness of martingale solutions corresponds to uniqueness in law of the weak solutions.

Backwards Kolmogorov Equation (BKE):

$$\frac{\partial}{\partial t} \varphi(t, x) = \mathcal{L} \varphi(t, x) \forall x \in \mathbb{R}^d, t \geq 0 \quad (1.8)$$

Theorem 1.26. Assume that \forall initial condition

$$\varphi(0, x) = \Psi(x), \Psi \in C_0^\infty(\mathbb{R}^d)$$

the (1.8) has a solution and φ bounded for all finite time intervals. We have uniqueness of martingale solutions and therefore uniqueness of weak solutions!

The Kolmogorov forward equation is (related to) the Fokker-Planck equation!

Proof. Prove that $\forall 0 \leq t_1 < t_2 < \dots < t_n$:

$$\text{Law}_{\mathbb{P}}(Z_{t_1}, Z_{t_2}, \dots, Z_{t_n}) = \text{Law}_{\mathbb{Q}}(Z_{t_1}, Z_{t_2}, \dots, Z_{t_n})$$

1. One-time distribution:

$\forall 0 \leq s \leq r$:

$$\left(\frac{\partial}{\partial s} + \mathcal{L} \right) \varphi(r-s, x) \stackrel{(1.8)}{=} 0$$

take $t \in [0, r]$:

$$\begin{aligned} M_t^r &:= \varphi(r-t, Z_t) - \varphi(r, Z_0) - \int_0^t \underbrace{(\partial_s + \mathcal{L})\varphi(r-s, Z_s)}_{=0} ds \\ &= \varphi(r-t, Z_t) - \varphi(r, Z_0) \text{ is a martingale} \end{aligned}$$

for any solution \mathbb{P} .

$$\begin{aligned} 0 &= \mathbb{E}_{\mathbb{P}}(M_t^r - M_0^r \mid \mathcal{F}_t) = \mathbb{E}(\varphi(0, Z_r) - \varphi(r-t, Z_t) \mid \mathcal{F}_t) \\ \implies \forall 0 \leq t \leq r : \mathbb{E}_{\mathbb{P}}(\varphi(0, Z_r) \mid \mathcal{F}_t) &= \mathbb{E}_{\mathbb{P}}(\varphi(r-t, Z_t) \mid \mathcal{F}_t) \\ &\stackrel{\text{a.s.}}{=} \varphi(r-t, Z_t) \\ \underbrace{\mathbb{E}(\varphi(0, Z_r))}_{\Psi(Z_r)} &\stackrel{t=0}{=} \mathbb{E}_{\mathbb{P}}(\varphi(r, Z_0)) \end{aligned}$$

\forall other martingale solutions \mathbb{Q} :

$$\mathbb{E}_{\mathbb{Q}}(\Psi(Z_r)) = \mathbb{E}_{\mathbb{Q}}(\varphi(r, Z_0))$$

By assumption this implies $\text{Law}_{\mathbb{P}}(Z_r) = \text{Law}_{\mathbb{Q}}(Z_r)$.

2. Multi-time distributions:

For $\Psi \in C_0^\infty$, denote φ_Ψ the solution of (1.8) with initial condition Ψ :

$$\mathbb{E}_{\mathbb{P}}(\Psi(Z_r) \mid \mathcal{F}_t) = \varphi_\Psi(r-t, Z_t)$$

$0 \leq r_2 \leq r_1$ test for $g \in C_0^\infty$:

$$\begin{aligned} \mathbb{E}_{\mathbb{P}}(\Psi(Z_{r_1})g(Z_{r_2})) &= \mathbb{E}(\underbrace{\mathbb{E}(\varphi_\Psi(Z_{r_1}) \mid \mathcal{F}_{r_2})}_{\varphi_\Psi(r_1-r_2, Z_{r_2})} g(Z_{r_2})) \\ &= \mathbb{E}_{\mathbb{P}}(\varphi_\Psi(r_1-r_2, Z_{r_2})g(Z_{r_2})) \\ &\stackrel{1.}{=} \mathbb{E}_{\mathbb{Q}}(\varphi_\Psi(r_1-r_2, Z_{r_2})g(Z_{r_2})) \\ &= \mathbb{E}_{\mathbb{Q}}(\Psi(Z_{r_1})g(Z_{r_2})) \end{aligned}$$

Iterating yields the statement. □

This needs the boundedness of φ , otherwise it might only be a local martingale. There are softer conditions we can put on the coefficients to achieve the same result. This might not be needed, because φ is C^1 in time anyways

Chapter 2:

SDE techniques

Goal: Study process by changing the measure.
 E.g.: $X_t = B_t$. $\underbrace{\text{Condition } X_t \geq 0 \forall t \geq 0}_{=: Y_t}$.

2.1 Girsanov theorem

Given $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0})$ and two measures \mathbb{P}, \mathbb{Q}
 Assume $\mathbb{P} \ll \mathbb{Q}$ and $\mathbb{Q} \ll \mathbb{P}$ and let $H = \frac{d\mathbb{Q}}{d\mathbb{P}}$

The notes of Eberle switches the roles of \mathbb{P}, \mathbb{Q} !

$$\implies Z_t := \mathbb{E}_{\mathbb{P}}(H \mid \mathcal{F}_t) = \frac{d\mathbb{Q}}{d\mathbb{P}} \Big|_{\mathcal{F}_t}$$

is a martingale.

From last semester: $\forall Y \in L^1(\mathbb{Q}) \cap L^1(\mathbb{P}), \mathcal{F}_t$ measurable:

$$\mathbb{E}_{\mathbb{Q}}(Y \mid \mathcal{F}_s) = \frac{bE_{\mathbb{P}}(Y \cdot Z_t \mid \mathcal{F}_s)}{Z_s} \forall s < t$$

If $Z > 0$ is \mathcal{M}_{loc} , $\exists L \in \mathcal{M}_{\text{loc}}$ s.t.:

$$Z_t = e^{L_t - \frac{1}{2} \langle L \rangle_t} \rightarrow L_t = \ln(Z_0) + \int_0^t \frac{dZ_s}{Z_s}$$

There might be a problem, because $\ln(Z_0)$ might not be integrable, and therefore not a local martingale!

Theorem 2.1 (Girsanov). Assume $Z > 0$ is a martingale. If M is a local martingale w.r.t. \mathbb{P} , then

$$\tilde{M}_t := M_t - \langle M, L \rangle_t$$

is a local martingale w.r.t. \mathbb{Q} and

$$\langle M \rangle_t = \langle \tilde{M} \rangle_t.$$

Moreover, if M is a BM w.r.t. to \mathbb{P} , then \tilde{M} is a BM w.r.t. \mathbb{Q} .

Remark. In applications, given $\mathbb{P}, (Z_t)_{t \geq 0}$ a positive continuous martingale, define \mathbb{Q} on $\mathcal{F}_{\infty} = \bigcup_{t \geq 0} \mathcal{F}_t$ s.t.

$$\frac{d\mathbb{Q}}{d\mathbb{P}} \Big|_{\mathcal{F}_t} = Z_t$$

Z is uniformly integrable $\iff \mathbb{Q} \ll \mathbb{P}$. **Problem:** In applications, Z is not necessarily uniformly integrable.

\implies restrict to $[0, T] \implies$ all fine.

$\mathbb{Q} \rightarrow \mathbb{Q}_T$ as in the last semester.

Added example. Let $\gamma \in \mathbb{R}^d$, $(B_t)_{t \geq 0}$ standard BM.
Let $L_t := \gamma \cdot B_t$ and $Z_t = \exp(L_t - \frac{1}{2}\langle L, L \rangle_t) = \exp(\gamma \cdot B_t - \frac{1}{2}|\gamma|^2 t)$

Remark. $\lim_{M \rightarrow \infty} \sup_{t \geq 0} \mathbb{E}(|Z_t| 1_{|Z_t| > M}) \neq 0$.
Define \mathbb{Q} on \mathcal{F}_∞ s.t. $\tilde{B}_t^k = B_t^k - \langle L, B^k \rangle = B_t^k - \gamma^k t$ is a BM with drift. Show: $\mathbb{Q} \ll \mathbb{P}$.

Construct \mathbb{Q} via Z

$$A = \left\{ \lim_{t \rightarrow \infty} \frac{\tilde{B}_t + \gamma t}{t} = \gamma \right\} \in \mathcal{F}_\infty$$

but: \tilde{B} is a BM w.r.t. $\mathbb{Q} \implies \mathbb{Q}(A) = 1$, \tilde{B} is a BM with drift $-\gamma$ w.r.t. $\mathbb{P}(A) = 0$.

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2.1.1 Drift transformation of SDE

We once again start with

$$\star = \begin{cases} dX_t &= b(t, X_t) \\ X_0 &= x_0 \end{cases}$$

with drift b continuous.

Goal: Get a weak solution of \star .

Let $(X_t)_{t \geq 0}$ be a BM in $(\Omega, \mathcal{F}(\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$, $X_0 = x_0$.

Assume: $Z_t := \exp \left(\underbrace{\int_0^t b(s, X_s) dX_s}_{=L_t} - \frac{1}{2} \int_0^t |b(s, X_s)|^2 ds \right)$ is a martingale w.r.t. \mathbb{P} .

Remark. The assumption holds if

$$|b(t, x)| \leq C(1 + \|x\|) \text{ for some } C.$$

$$\implies \mathbb{E}_{\mathbb{P}}(Z_t) = 1 \forall t \geq 0$$

By Girsanov

$$\tilde{X}_t = X_t - \langle L, X \rangle_t$$

is a \mathbb{Q} -BM.

But

$$d\langle L, X \rangle_t = b \cdot dX_t \cdot dX_t = b \cdot dt$$

$$\implies \tilde{X}_t = X_t - \int_0^t b(s, X_s) ds$$

$$\text{w.r.t. } \mathbb{Q} : dX_t = b(t, X_t) dt + \underbrace{d\tilde{B}_t}_{d\tilde{X}_t}$$

Generalization: Start with

$$\star \star dX_t = b(t, X_t) dt + \sigma(t, X_t) dB_t$$

where X, B are d -dimensional.

Proposition 2.2. Assume (X, B) is a weak solution of $\star \star$ on $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$. If

$$Z_t = \exp \left(\int_0^t c(s, X_s) dB_s - \frac{1}{2} \int_0^t c(s, X_s)^2 ds \right)$$

is a martingale w.r.t. \mathbb{P} , $\mathbb{Q} \ll \mathbb{P}$ and \mathcal{F}_t s.t. $Z_t = \frac{d\mathbb{Q}_t}{d\mathbb{P}} \text{Vert}_{\mathcal{F}_t}$.

In practice this is
surprisingly useful in
practice!

this is an implicit
condition for c

Then $(X_t)_{t \geq 0}$ on $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{Q})$ is a weak solution of

$$dX_t = [b(t, X_t) + \sigma(t, X_t)c(t, X_t)dt] + \sigma(t, X_t)d\tilde{B}_t$$

where \tilde{B} is a d -dim BM.

Proof.

$$\begin{aligned} d\langle L, B \rangle_t &\stackrel{L_t = \int_0^t c(s, X_s)dB_s}{=} c(t, X_t)dt \\ \implies \tilde{B}_t &:= B_t - \langle L, B \rangle_t \text{ is a } \mathbb{Q}\text{-BM} \\ \implies dB_t &= c(t, X_t)dt + d\tilde{B}_t \end{aligned}$$

From $\star\star$: $dX_t = b(t, X_t)dt + \sigma(t, X_t)c(t, X_t)dt + \sigma(t, X_t)d\tilde{B}_t = \star\star\star$ □

Measure	SDE	Generators
\mathbb{P}	$dX_t b \cdot dt + \sigma \cdot dB_t$	$\mathcal{L} \sum_k b_k \frac{\partial}{\partial x_k} + \frac{1}{2} \sum_{k,l} (\sigma \sigma^\top)_{k,l} \frac{\partial^2}{\partial x_k \partial x_l}$
\mathbb{Q}	$[b + \sigma \cdot c]dt + \sigma d\tilde{B}_t$	$\tilde{\mathcal{L}} = \mathcal{L} + \sum_k \sum_l \sigma_{k,l} c_l \frac{\partial}{\partial x_k} = \mathcal{L} + c \sigma^\top \nabla$

$t \leq T$ for \mathbb{Q}_t .

2.2 Doob-h transform

1. From $B_t \rightarrow B_t$ conditioned on $\{B_1 = 0\}$ (measure zero set)
2. From $B_t \rightarrow B_t$ conditioned on $\{B_t \geq 0 \forall t \geq 0\}$ (measure zero set)
3. From $B_t \rightarrow B_t$ conditioned on $\{B_t \geq 0 \forall t \in [0, 1], B_1 = 0\}$

Essentially three cases in 1d

Let $(X_t, B_t)_{t \geq 0}$ be a weak solution of

$$(\star) = \begin{cases} dX_t &= b(t, X_t)dt + \sigma(t, X_t)dB_t \\ X_0 &= x_0 \text{ fixed} \end{cases}$$

Assume there exists $h \in C^{1,2}(\mathbb{R}_+ \times \mathbb{R}^d)$ s.t. $h > 0$ satisfying

$$\left(\frac{\partial}{\partial t} + \mathcal{L}\right)h = 0 \forall t \in [0, T], x \in \mathbb{R}^d$$

where \mathcal{L} is the generator of the SDE (\star) .

By theorem 1.14 $Z_t := h(t, X_t) = h(0, X_0) + \int_0^t (\sigma \nabla h)(s, X_s)dB_s$.

Z_t is a positive local martingale. Assume Z_t is a martingale.

W.l.o.g. $Z_0 = 1$ (if not $h \mapsto \frac{h}{h(0, X_0)}$).

$\implies d\mathbb{Q}_T = Z_T \cdot d\mathbb{P}$. Let L_t s.t. $Z_t = \exp(L_t - \frac{1}{2}\langle L \rangle_t)$.

Girsanov, since B_t is a \mathbb{P} -BM,

$\tilde{B}_t := B_t - \langle L, B \rangle_t$ is a \mathbb{Q}_T -BM, where

$$\langle L, B \rangle_t = \sigma^\top \cdot \nabla \ln h \cdot dB_t$$

because of

$$dL_t = \frac{dZ_t}{Z_t} = \frac{\sigma^\top \cdot \nabla h \cdot dB_t}{h(t, X_t)} = \sigma^\top \cdot \nabla \ln h \cdot dB_t$$

And therefore $dB_t = d\tilde{B}_t + \sigma^\top \nabla \ln h dt$.

From $(\star) \implies dX_t = \underbrace{(b(t, X_t) + \sigma(t, X_t)\sigma^\top(t, X_t)\nabla h(t, X_t))}_{:= \tilde{b}}dt + \sigma(t, X_t)d\tilde{B}_t$

Proposition 2.3. Let X be a weak solution of $dX_t = b(t, X_t) + \sigma(t, X_t)dB_t$ on $[0, T]$ under \mathbb{P} . Then under \mathbb{Q}_T , X is a weak solution of the SDE

$$\begin{cases} dX_t &= \tilde{b}(t, X_t)dt + \sigma(t, X_t)d\tilde{B}_t \\ X_0 &= x_0 \end{cases}$$

where $\tilde{b} = b + \sigma\sigma^\top \nabla \ln h$.

Remark. In applications, often $h(x) \not\equiv 0$ for all x !

E.g.: $h(t, x) = x \implies (\frac{\partial}{\partial t} + \mathcal{L})h = 0$ ($X_t = B_t + x_0$), but $h(x) \leq 0$ for $x \leq 0$.

In this case first do the construction on $[0, \tau]$, where $\tau := \inf\{t > 0 \mid B_t = 0\}$

\implies ok for $B_t^\tau \xrightarrow{\text{magically}}$ the new SDE has drift:

$$\frac{\partial}{\partial x} \ln(h(x)) = \frac{1}{h(x)} \frac{\partial h(x)}{\partial x} = \frac{1}{x}$$

We realize there is no problem in the new measure

Added example. If $X_t = B_t$ and $h(t, \cdot) = e^{\gamma x - \frac{1}{2}|\gamma|^2 t}$

$$\begin{aligned} \implies dX_t &= \nabla \ln h(t, X_t)dt + dB_t \\ &= \nabla(\gamma \cdot x)dt + dB_t \\ &= \gamma dt + dB_t \end{aligned}$$

$\implies X_t$ is a BM with drift γ w.r.t \mathbb{Q} .

2.3 Diffusion Bridges

Consider a Markov process $(X_t)_{t \geq 0}$ which is a diffusion starting from $X_0 = x_0 \in \mathbb{R}^d$.

We want to condition on the event $\{X_T = y\}$ for some given $T > 0, y \in \mathbb{R}^d$.

Goal: Find, $\forall y \in \mathbb{R}^d, \mathbb{Q}^y$ which is the conditional measure on $\{X_T = y\}$.

Assume: $(X_t)_{t \geq 0}$ has transition density P s.t.

$$\forall 0 \leq s \leq t \leq T, \mathbb{P}(X_t \in dz \mid X_s = x) = p(s, x; t, z)dz.$$

X_t solves

$$\begin{cases} dX_t &= b(t, X_t)dt + \sigma(t, X_t)dB_t \\ X_0 &= x_0 \end{cases}.$$

Define $h^y(s, x) := \frac{p(s, x; T, y)}{p(0, x_0; T, y)}$ for $s \in [0, T), x \in \mathbb{R}^d$.

Remark. $s < T$ since otherwise we get ingeneral singularities.

Lemma 2.4. Let $Z_t^y := h^y(t, X_t)$ is a martingale.

Proof. Let $0 \leq t < T$:

$$\begin{aligned} \mathbb{E}(Z_t^y \mid \mathcal{F}_s) &= \mathbb{E}(h^y(t, X_t) \mid \mathcal{F}_s) \\ &\stackrel{\text{MP}}{=} \mathbb{E}(h^y(t, X_t) \mid X_s) \\ &= \int_{\mathbb{R}^d} h^y(t, x) p(s, X_s; t, x) dx \\ &= \int_{\mathbb{R}^d} \frac{p(t, x; T, y)}{p(0, x_0; T, y)} p(s, X_s; t, x) dx \\ &= \frac{1}{p(0, x_0; T, y) \int_{\mathbb{R}^d} p(s, X_s; t, x) p(t, x; T, y) dx} \\ &\stackrel{\text{Chapman-Kolmogorov}}{=} Z_s^y = \end{aligned}$$

$$\square \quad h^y(0, x_0) = 1$$

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Added remark. *Goal:* Find a family $(\mathbb{Q}^y)_{y \in \mathbb{R}^d}$ s.t. for $A \in \mathcal{F}_T$:

$$\mathbb{P}(A) = \mathbb{E}(\mathbb{P}(A|X_T)) \stackrel{?}{=} \mathbb{E}(\mathbb{Q}^{X_T}(A))$$

and $\mathbb{Q}^y(\lim_{t \uparrow T} X_t = y) = 1$

Lemma 2.5. We can take

$$\mathbb{Q}^y(A) = \mathbb{E}(1_A \cdot h^y(s, X_s)) \forall A \in \mathcal{F}_s$$

for $s \in [0, T]$.

Proof. For all $A \in \mathcal{F}_s$, g bounded measurable:

$$\begin{aligned} \mathbb{E}(1_A g(X_T)) &= \mathbb{E}(1_A \mathbb{E}(g(X_T) | \mathcal{F}_s)) \\ &\stackrel{\text{MP}}{=} \mathbb{E}(1_A \mathbb{E}(g(X_T) | X_s)) \\ &= \mathbb{E} \left(1_A \int_{\mathbb{R}^d} p(s, X_s; T, x) g(x) dx \right) \\ &= \int_{\mathbb{R}^d} dx g(x) \mathbb{E}(1_A p(s, X_s; T, x)) \end{aligned}$$

In particular,

$$\mathbb{P}(A) = \mathbb{E}(1_A) = \int_{\mathbb{R}^d} dx \mathbb{E}(1_A \cdot p(s, X_s; T, x))$$

But

$$\begin{aligned} \int_{\mathbb{R}^d} dx p(0, X_0; T, x) \mathbb{Q}^x(A) &= \int_{\mathbb{R}^d} p(0, x_0; T, x) \underbrace{\mathbb{E}(1_A h^x(s, X_s))}_{= \int dz p(0, x_0; s, z) h^x(s, z) 1_A} \\ &= \int_{\mathbb{R}^d} \mathbb{E}(1_A p(s, X_s; T, x)) \\ &= \mathbb{P}(A). \end{aligned}$$

□

Remark. $Z_t^y = h^y(t, X_t) = h(0, X_0) + \underbrace{\text{martingale}}_{=0} + \int_0^t (\partial_t + \mathcal{L})h^y(s, X_s) ds.$

One can verify: $(\partial_t + \mathcal{L})h^y(t, X_t) = 0 \iff (\partial_t + \mathcal{L})H^y(t, X_t) = 0$ for $H^y(t, x) = p(t, x; T, y).$

$$\begin{aligned} \frac{\partial}{\partial t} H^y(t, x) &= \lim_{\epsilon \downarrow 0} \frac{p(t, x; T, y) - p(t - \epsilon, x; T, y)}{\epsilon} \\ &= \lim_{\epsilon \downarrow 0} \frac{p(t, x; T, y) - \int \underbrace{p(t - \epsilon, x; t, z)}_{= e^{\epsilon \mathcal{L}}(x, z) = \delta_{x-z} + \epsilon \mathcal{L}(x, z)} p(t, z; T, y) dz}{\epsilon} \\ &= -(\mathcal{L}H^y)(t, x) \end{aligned}$$

\implies this is a Doob-h transform with $h = h^y$.

$$\frac{d\mathbb{Q}^y}{d\mathbb{P}}|_{\mathcal{F}_t} = Z_t^y.$$

Corollary 2.6. Assume $(t, x) \mapsto p(t, x; T, y)$ is $C^{1,2}([0, T] \times \mathbb{R}^d)$

\implies The Doob h-transform of the original process under \mathbb{Q}^y satisfies the SDE:

$$dX_t = \tilde{b}(t, X_t)dt + \sigma(t, X_t)d\tilde{B}_t$$

where \tilde{B}_t is a \mathbb{Q}^y -BM and $\tilde{b}(t, X_t) = b(t, X_t) + (\sigma \sigma^\top \nabla \ln h^y)(t, X_t).$

Remark. Take $z \neq y$ and $\forall 0 < \epsilon < |z - y|$:

$$\begin{aligned}\mathbb{Q}^y(\{|X_t - z| \leq \epsilon\}) &= \mathbb{E}\left(1_{|X_t - z| \leq \epsilon} \frac{p(t, X_t; T, y)}{p(0, x_0; T, y)}\right) \\ &= \int dx 1_{|x - z| \leq \epsilon} p(0, x_0, t, x) \frac{p(t, x; T, y)}{p(0, x_0; T, y)} \\ &\xrightarrow{t \rightarrow T} 0\end{aligned}$$

$\Rightarrow \mathbb{P}(\lim_{t \uparrow T} X_t = y) = \mathbb{P}(X_t = y) = 0$, but $\mathbb{Q}^y(\lim_{t \uparrow T} X_t = y) = 1$
 $\Rightarrow \mathbb{Q}^y$ is singular w.r.t. \mathbb{P} .

Added example. $b = \gamma \in \mathbb{R}^d, \sigma = 1, X_0 = 0$ and $T = 1$. Under \mathbb{P} :

$$\begin{cases} dX_t = \gamma dt + dB_t \\ X_0 = 0 \end{cases}$$

Under \mathbb{Q}^y ?

$$h^y(t, x) = \frac{p(t, x; 1, y)}{p(0, x_0, 1, y)} = fct(\gamma, y) \cdot \exp\left(-\frac{(y-x)^2}{2(1-t)}\right) \exp((y-x)\gamma)$$

$$\Rightarrow \ln(h^y(t, x)) = \ln f(\gamma, y) - \frac{(y-x)^2}{2(1-t)} + (y-x)\gamma \Rightarrow \nabla \ln h^y(t, x) = \frac{y-x}{1-t} - \gamma.$$

Under \mathbb{Q}^y :

$$\begin{aligned}dX_t^k h^y &= \left(\gamma_k + \frac{y_k - X_t^k}{1-t}\right) dt + d\tilde{B}_t^k \\ &= \frac{Y_k - X_t^k}{1-t} dt + d\tilde{B}_t^k\end{aligned}$$

Independent of γ !

for $k = 1, \dots, d$

Lemma 2.7. Let p be the transition density of X w.r.t. \mathbb{P} and p^h the transition density of X w.r.t. \mathbb{Q}^y .

Let $h^y(t, x) = \frac{p(t, x; T, y)}{p(0, x_0; T, y)}$.

Useful in practice to sample!

$$\Rightarrow p^h(s, x; t, z) = \frac{1}{h^y(s, x)} p(s, x; t, z) h^y(t, z)$$

Notice how the normalizations inside of h^y cancel!

Added remark. This is the first time my numbering is different from the handwritten notes, as they contain two environments numbered 2.5.

Proof.

$$\begin{aligned}p^h(s, x; t, z) dz &= \mathbb{P}(X_t \in dz \mid X_s = x, X_T = y) \\ &\stackrel{0 \leq s \leq t}{=} \frac{p(0, x_0; s, x) p(s, x; t, z) p(t, z; T, y) dz}{p(0, x_0; s, x) p(s, x; T, y)} \\ &= p(s, x; t, z) \frac{p(t, z; T, y)}{p(0, x_0; T, y)} \frac{1}{\frac{p(s, x; T, y)}{p(0, x_0; T, y)}} dz\end{aligned}$$

□

2.4 Brownian motion conditioned to stay positive forever

Goal: $(B_t)_{t \geq 0}$ with $B_0 = x_0 \geq 0$ and condition on

$$\{B_t \geq 0 \forall t \geq 0\}$$

$T_x = \inf\{t \geq 0 \mid B_t = x\}$ and take $0 < x_0 < R$.

$T_0 \wedge T_R = T_R$.

Let $\tilde{T}_R := T_0 \wedge T_R$. Define the event $E_R = \{B_{\tilde{T}_R} = R\} = \{T_0 \wedge T_R = T_R\}$.

One verifies $\mathbb{P}(E_R) = \frac{x_0}{R} \in (0, 1)$.

$\mathbb{P}(E_R) = \mathbb{E}(1_{B_{\tilde{T}_R}^{x_0}}) = \underbrace{\mathbb{E}(f(B_{\tilde{T}_R}^{x_0}))}_{u(x_0)}$, where

$$f(x) = \begin{cases} 1 & x = R \\ 0 & x = 0 \end{cases}.$$

u has a link to the PDE:

$$\begin{cases} \frac{1}{2} \frac{\partial^2}{\partial x^2} u(x) = 0 & x \in (0, R) \\ u(x) = f(x) & x \in \{0, R\} \end{cases}$$

By Theorem 11.6 of the last semester

Define the conditional probability

later $R \rightarrow \infty$

$$Q^R(A) := \frac{\mathbb{P}(A \cap E_R)}{\mathbb{P}(E_R)}$$

Lemma 2.8. Let $h(x) := \frac{\mathbb{P}_x(E_R)}{\mathbb{P}_{x_0}(E_R)} = \frac{x}{x_0}$, where \mathbb{P}_x is the unconditional law for $B_0 = x$.

$$Z_t = h(B_{t \wedge \tilde{T}_R})$$

is a non-negative martingale.

Proof.

$$\begin{aligned} \mathbb{Q}^R(A) &\stackrel{A \in \mathcal{F}_s}{=} \frac{\mathbb{E}(1_A \mathbb{E}(1_{E_R} \mid \mathcal{F}_s))}{\mathbb{P}(E_R)} = \frac{\mathbb{E}(1_A \mathbb{E}(1_{E_R} \cdot 1_{\tilde{T}_R > s} \mid \mathcal{F}_s)) + \mathbb{E}(1_A \mathbb{E}(1_{E_R} 1_{\tilde{T}_R \leq s} \mid \mathcal{F}_s))}{\mathbb{P}(E_R)} \\ &= \frac{1}{\mathbb{P}(E_R)} \left[\mathbb{E}(1_A 1_{\tilde{T}_R > s} \underbrace{\mathbb{E}(1_{E_R} \mid \mathcal{F}_s)}_{\mathbb{P}_{B_s}(E_R)}) + \mathbb{E}(1_A \underbrace{1_{E_R}}_{1_{B_{\tilde{T}_R} = R}} 1_{\tilde{T}_R \leq s}) \right] \\ &= \mathbb{E}(1_A 1_{\tilde{T}_R > s} h(B_s)) + \mathbb{E}(1_A 1_{\tilde{T}_R \leq s} h(B_{\tilde{T}_R})) \\ &= \mathbb{E}(1_A h(B_{s \wedge \tilde{T}_R})) \end{aligned}$$

$$\implies \forall A \in \mathcal{F}_s : \mathbb{Q}^R(A) = \mathbb{E}_{\mathbb{P}}(1_A h(B_{s \wedge \tilde{T}_R}))$$

$$\implies h(B_{s \wedge \tilde{T}_R}) = \frac{d\mathbb{Q}^R}{d\mathbb{P}} \Big|_{\mathcal{F}_s} \implies h \in (0, \frac{R}{x_0}) \text{ is a martingale (See construction of Girsanov)}$$

□

Note that we can write $Z_t^R := h(B_{s \wedge \tilde{T}_R}) = \exp(L_t - \frac{1}{2} \langle L \rangle_t)$ by choosing

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$$L_t = \int_0^{\tilde{T}_R} \frac{h'(B_s)}{h(B_s)} dB_s$$

since

$$dL_t = \frac{dZ_t^R}{Z_t^R} = \begin{cases} \frac{h'(B_t)dB_t}{h(B_t)} & t < \tilde{T}_R \\ 0 & t \geq \tilde{T}_R \end{cases}$$

Proposition 2.9. Under the measure \mathbb{Q}^R , $(B_t)_{t \geq 0}$ solves the SDE

$$dB_t = \frac{1_{t \leq \tilde{T}_R}}{B_t} dt + dW_t$$

for some $(W_t)_{t \geq 0}$ a \mathbb{Q}^R -BM.

Proof. Apply Girsanov in which

$$d\langle B, L \rangle_t = dB_t \cdot dL_t \stackrel{h'(x)=\frac{1}{x_0}}{=} \frac{1}{B_t} dt \quad \square$$

Our goal was to condition the BM to stay positive forever. So far we have conditioned it to reach the level R before the level 0.

Remark.

$$\begin{aligned} \mathbb{Q}^R(T_0 < T_R) &= \mathbb{E}(1_{T_0 < T_R} h(B_{T_R \wedge T_0})) \\ &= \mathbb{E}(1_{T_0 < T_R} h(B_{T_0})) \\ &= \mathbb{E}(1_{T_0 < T_R} \underbrace{h(0)}_{=0}) = 0 \end{aligned}$$

\implies under the new measure \mathbb{Q}^R , the BM indeed does not reach 0 before R as we wanted.

Finally we want to take $R \rightarrow \infty$. It should

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Added example. Discrete time M.C. with transition probability P aperiodic and irreducible: $\exists n_0 \forall n > n_0 (P)_{i,j}^n > 0 \implies \exists |\lambda_0| \leq 1, |\lambda_1| > |\lambda_2| > |\lambda_3|$:

$$(P)^n \underbrace{\varphi_0(i)}_{>0} = \lambda_0 \varphi_0(i)$$

$$\lim_{n \rightarrow \infty} \underbrace{P^n}_{(1+L)} = (\varphi_0(1), \dots, \varphi_0(d))$$

where $(1+L) \rightarrow e^{tL}$, for which the real eigenvalues are positive.

2.5 Diffusion conditioned to stay in a domain

Domain $D \subset \mathbb{R}^d$: bounded, open, connected.

Diffusion with generator

$$L = \frac{1}{2} \sum_{i,j=1}^d a_{ij} \frac{\partial^2}{\partial x_i \partial x_j} + \sum_{i=1}^d b_i \frac{\partial}{\partial x_i}$$

\iff SDE

$$\begin{cases} dX_t = b(t, X_t)dt + \frac{1}{2}\sigma(t, X_t)dB_t \\ X_0 = x_0 \end{cases}$$

$a = \sigma\sigma^\top$.

Assume: b, σ are continuous, $\sigma \in C^1$ and let $\tau_D = \int \{t \geq 0 | X_t \notin D\}$

Key assumption in Pinsky's paper:

$$(a) \quad \mathbb{P}_x(\tau_D > t) \in \mathcal{C}^2(D)$$

(b)

$$\begin{cases} \mathbb{P}_x(\tau_D > t) \\ \nabla \mathbb{P}_x(\tau_D > t) = C_1 \nabla \varphi_0(x) e^{-\lambda_0 t} + o(e^{-\lambda_0 t}) \end{cases} = C_1 \varphi_0(x) e^{-\lambda_0 t} + o(e^{-\lambda_0 t})$$

where

$$\begin{cases} -L\varphi_0(x) = \lambda_0 \varphi_0(x) & x \in D \\ \varphi_0(x) = 0 & x \in \partial D \end{cases}$$

and λ_0 is the smallest eigenvalue of $-L$. Which means $\mathbb{P}(\tau_d > t) \xrightarrow{t \rightarrow \infty} 0$

in the non symmetric case
take the real part first

Want: Condition X to stay in D forever.

(1) Condition X_t to $\{X_t \in D : 0 \leq t \leq T\}$: For all $A \in \mathcal{F}_T$: define a measure

$$\mathbb{Q}^T(A) := \frac{\mathbb{P}_{x_0}(A \cap \{\tau_D > T\})}{\mathbb{P}_{x_0}(\tau_D > T)} = \frac{\mathbb{E}_{x_0}(1_A \cdot 1_{\tau_D > T})}{\mathbb{E}_{x_0}(1_{\tau_D > T})}$$

Lemma 2.10. $\forall s < T, A \in \mathcal{F}_s$,

$$\mathbb{Q}^T(A) = \mathbb{E}_{x_0}(1_A \cdot Z_s^T)$$

where $Z_s^T = \frac{g^{T-s}(X_{s \wedge \tau_D})}{g^T(x_0)}$ with $g^t(x) := \mathbb{P}_x(\tau_D > t)$.

Proof. Let $A \in \mathcal{F}_s, s < T$:

$$\begin{aligned} \mathbb{Q}^T(A) &= \frac{\mathbb{E}_{x_0}(1_A 1_{\tau_D > T})}{g^T(x_0)} = \frac{\mathbb{E}_{x_0}(1_A \mathbb{E}_{x_0}(1_{\tau_D > T} | \mathcal{F}_s))}{g^T(x_0)} \\ &\stackrel{\text{M.P.}}{=} \frac{\mathbb{E}_{x_0}(1_A \mathbb{E}_{x_0}(1_{\tau_D > T} | X_s))}{g^T(x_0)} \\ &= \frac{1}{g^T(x_0)} \left[\mathbb{E}_{x_0}(1_A \underbrace{\mathbb{E}_{x_0}(1_{\tau_D > T} 1_{\tau_D > s} | X_s)}_{g^{T-s}(X_s)}) + \mathbb{E}_{x_0}(1_A \underbrace{\mathbb{E}_{x_0}(1_{\tau_D > T} 1_{\tau_D < s} | X_s)}_{=0}) \right] \\ &= \frac{1}{g^T(x_0)} (1_A g^{T-s}(X_{s \wedge \tau_D})) \end{aligned}$$

□

Lemma 2.11. $Z_0^T = 1$ and $(Z_s^T)_{s \in [0, T]}$ is a martingale.

Proof. By lemma 2.10 $\implies Z_s^T = \frac{d\mathbb{Q}^T}{d\mathbb{P}} |_{\mathcal{F}_s} \rightarrow$ is a martingale. □

Remark. By construction, $\mathbb{Q}^T(\tau_D \leq T) = \frac{1}{g^T(x_0)} \mathbb{E}_{x_0}(1_{\tau_D \leq T} 1_{\tau_D > t}) = 0$

Assume that $g^t(x)$ is $C^{1,2}$ (1 in time, 2 in space) \implies apply Itô and doob transform gives:

Proposition 2.12. Let X be a weak solution of $dX_t = b(t, X_t)dt + \sigma(t, X_t)dB_t$ under \mathbb{P} .
 $\implies X$ is a weak solution of

$$dX_t = \left(b(t, X_t) + \frac{a(t, X_t) \nabla g^{T-t}(X_t)}{g^{T-t}(X_t)} \right) dt + \sigma(t, X_t) d\tilde{B}_t, 0 \leq t \leq T$$

under \mathbb{Q}^T provided $g^t(x) > 0 \forall x \in D, t \geq 0$.

What happens in the $T \rightarrow \infty$ limit?

By assumption (b)

$$\lim_{T \rightarrow \infty} \frac{\nabla g^{T-t}(x)}{g^{T-t}(x)} = \frac{\nabla \varphi_0(x)}{\varphi_0(x)}$$

Their operator is not the same as ours. The only difference is a drift term.

Remark. If $g \in C^{1,2}$, it satisfies the parabolic PDE

$$(\star) \begin{cases} \frac{\partial}{\partial t} g^t(x) = Lg^t(x) & x \in D \\ g^t(x) = 0 & x \in \partial D \end{cases}$$

Apply Theorem 11.5 from the WS with $A = L, u(t, x = g^t(x))$: $u(0, x) = \mathbb{E}_x(1_{\tau_D > 0}) = 0, u(t, x) = \mathbb{E}_x(1_{\tau_D > t}) = 0 \forall t, x \in \partial D$.

Pinsky proved that $\lim_{T \rightarrow \infty} \mathbb{Q}^T = Q$ weak and that under Q the process satisfies

$$dX_t = \left[b(t, X_t) + a(t, X_t) \frac{\nabla \varphi_0(X_t)}{\varphi_0(X_t)} \right] dt + \sigma(t, X_t) dW_t.$$

Why is $\mathbb{P}_x(\tau_D > t) = C_1 \varphi_0(x) e^{-\lambda_0 t} + o(e^{-\lambda_0 t})$

Added remark. This is not the case for BM conditioned to stay in $D = (0, \infty)$. Reason: Spectrum of $-L$ is \mathbb{R}_+

Since it satisfies the PDE (\star) , $g^t(x) = (e^{tL})g^0(x)$.

if the spectrum of $-L$ is discrete with eigenvalues $0 \leq \lambda_0 < \lambda_1 \leq \dots$, where there is a spectral gap between λ_0 and λ_1 : \exists eigenfunctions $\varphi_0(x), \varphi_1(x), \dots$, normalized as

$\|\varphi_n\|_{L^2(D)} = 1 \implies +L\varphi_n(x) = -\lambda_n\varphi_n(x) \implies$ we can choose $\varphi_0, \varphi_1, \dots$ to be orthonormal:
 $(\varphi_i, \varphi_j)_{L^2(D)} = \delta_{ij}$.

$\implies 1 = \sum_{n \geq 0} \varphi_n \varphi_n^*$, since $\varphi_n \varphi_n^*$ is the projection onto the space generated by φ_n :

$$\varphi_n \varphi_n^* f = \varphi_n (\varphi_n, f)_{L^2(D)}$$

$$f(L)\varphi_n = f(-\lambda_n)\varphi_n$$

$$\begin{aligned} g^t(x) &= (e^{tL})g^0(x) = e^{tL}1g^0(x) = \sum_{n \geq 0} e^{tL}\varphi_n(x)\varphi_n^*g^0 = \sum_{n \geq 0} e^{-\lambda_n t}\varphi_n(x)(\varphi_n, g^0) \\ &= (\varphi_0, g^0)\varphi_0(x)e^{\lambda_0 t} + \underbrace{e^{-\lambda_0 t} \sum_{n \geq 0} e^{(\lambda_0 - \lambda_n)t}\varphi_n(x)(\varphi_n, g^0)}_{o(e^{-\lambda_0 t})} \end{aligned}$$

Example 2.13. One dimension.

$L = \frac{1}{2} \frac{d^2}{dx^2}$ and $D = [0, R]$.

Solve $-L\varphi(n)(x) = \lambda_n\varphi_n(x)$ with $\varphi_n(x) = 0$ for $x \in \{0, R\}$.

Solutions $\varphi_n(x) = C_1 \sin\left(\frac{\pi x}{R} \cdot (n+1)\right)$ and $\lambda_n = \left(\frac{\pi(n+1)}{R}\right)^2 \implies \lambda_0 = \frac{\pi^2}{R^2}$.

For $x \in (0, R)$:

$$\mathbb{P}_x(\tau > t) \approx \tilde{C}_1 \varphi_0(x) e^{-\frac{\pi^2 t}{R^2}}$$

$$\implies dX_t = \frac{\pi \cos(\frac{\pi X_t}{R})}{R \sin(\frac{\pi X_t}{R})} dt + dW_t$$

as $X_t \rightarrow 0$ (or $X_t \rightarrow R$), drift $\approx \frac{1}{x_t}$ or $(\frac{-1}{R-X_t})$.

Also: formally $R \rightarrow \infty$ in the SDE, we get $dX_t = \frac{dt}{X_t} + dW_t$, which is the SDE we derived for BM conditioned to stay > 0 forever.

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Example 2.14 (Brownian Motion in a Weyl chamber). The **Weyl chamber** is defined as

$$W^d = \{x \in \mathbb{R}^d \mid x_1 < x_2 < \dots < x_d\}.$$

Given a d dim. Brownian motion $(B_t)_{t \geq 0}$ with $B_0 \in W^d$ what is the sde of this BM conditioned on staying in W^d forever.

What is the harmonic function vanishing at ∂W^d ?

Lemma 2.15. $h(x) := \prod_{1 \leq k < l \leq d} (x_l - x_k)$ is harmonic and satisfies

$$\frac{1}{2} \sum_{k=1}^d \frac{\partial^2}{\partial x_k^2} h(x) = 0, x \in W^d$$

and $h(x) = 0$ for $x \in \partial W^d$, $h(x) > 0$ for $x \in W^d$.

Remark. $h(x) = \det(x_k^{l-1})$

Proof. Last two properties are clear. h is a polynomial, antisymmetric in each pair $x_l - x_k$ and has lowest possible power.

$\Delta h(x)$ is still antisymmetric, but with lower power $\implies \Delta h(x) = 0$. □

The BM conditioned to stay in the Weyl chamber will satisfy the SDE:

$$dX_t^k = \sum_{l \neq k} \frac{dt}{X_t^l - X_t^k} + dB_t^k, \quad 1 \leq k \leq d$$

2.6 Stationary distribution for diffusions

let $dX_t = b(X_t)dt + \sigma(X_t)dB_t$, where b, σ are time independent with generator

$$L = \sum_{k=1}^d b_k(x) \frac{\partial}{\partial x_k} + \frac{1}{2} \sum_{k,l=1}^d a_{k,l}(x) \frac{\partial^2}{\partial x_k \partial x_l}$$

Definition 2.16. A probability measure μ stationary (or invariant) if for all $f \in C_0^\infty(\mathbb{R}^d)$

or only test schwarzfunctions

$$\int_{\mathbb{R}^d} (Lf)(x) \mu(dx) = 0$$

Assume that $\mu \ll \text{Lebesgue}$, i.e., $\mu(dx) = \rho(x)dx$ for some positive function $\rho(x) \in C^2$ with $\int \rho(x)dx = 1$.

Lemma 2.17. μ is stationary with density ρ

$$\iff L^* \rho(x) = 0 \text{ almost everywhere}$$

this also assumes b to be differentiable!

where L^* is the adjoint of L , given by

$$L^* \rho(x) = \frac{1}{2} \sum_{k,l=1}^d \frac{\partial^2}{\partial x_l \partial x_l} (a_{k,l}(x) \rho(x)) - \sum_{k=1}^d \frac{\partial}{\partial x_k} (b_k(x) \rho(x))$$

Proof.

$$\begin{aligned} \int_{\mathbb{R}^d} (Lf)(x) \rho(x) dx &= 0 \\ &= \int_{\mathbb{R}^d} dx_1, \dots, dx_d \rho(x) \left(\frac{1}{2} \sum_{k,l=1}^d \frac{\partial^2}{\partial x_k \partial x_l} f(x) + \sum_{k=1}^d b_k(x) \frac{\partial}{\partial x_k} f(x) \right) \\ &= \int_{\mathbb{R}^{d-1}} \prod_{l \neq k} dx_l \underbrace{\int_{\mathbb{R}} dx_k \rho(x) b_k(x) \frac{\partial}{\partial x_k} f(x)}_{\stackrel{\text{I.B.P.}}{=} - \int_{\mathbb{R}} dx_k \frac{\partial}{\partial x_k} (\rho(x) b_k(x)) \cdot f(x)} \end{aligned}$$

□

Example 2.18 (1-dim. diffusion). Let $L = b(x) \frac{\partial}{\partial x} + \frac{1}{2} \sigma^2(x) \frac{\partial^2}{\partial x^2}$ for all $x \in \mathbb{R}$.

$$\implies L^* \rho(x) = \frac{1}{2} \frac{\partial^2}{\partial x^2} (\rho(x) \sigma^2(x)) - \frac{\partial}{\partial x} (\rho(x) b(x)) \stackrel{\text{wanted}}{=} 0$$

$$\implies \exists c_1 \text{ s.t. } \underbrace{\frac{1}{2} \frac{\partial}{\partial x} (\rho(x) \sigma^2(x))}_{=g(x)} - \underbrace{\rho(x) b(x)}_{=g(x) \frac{b(x)}{\sigma^2(x)}} = c_1.$$

Let $s(x) = \int_{x_0}^x dy e^{-\int_{x_0}^y dz \frac{2b(z)}{\sigma^2(z)}}$ be the scale function.

The equation for c_1 is equivalent to

$$s'(x) \sigma^2(x) \rho(x) = c_2 + 2c_1 s(x)$$

for some constant $c_2, s'(x) e^{-\int_{x_0}^x dz \frac{2b(z)}{\sigma^2(z)}} = > 0$.

s satisfies $\frac{1}{2}\sigma^2(x)s''(x) + b(x)s'(x) = 0$, for the Bessel process $d = 2$, $s(x) = \ln(x)$
If $s(\mathbb{R}) = \mathbb{R}$, then $c_1 = 0$, which implies

$$\rho(x) = \frac{c_2}{\sigma^2(x)} \underbrace{e^{\int_{x_0}^x \frac{2b(y)}{\sigma^2(y)} dy}}_{\frac{1}{s'(x)}}$$

which satisfies positivity.

Lemma 2.19. If $S(\mathbb{R}) = \mathbb{R}$, then there exists stationary measure with density $\rho(x)$ as described above.

Counterexample:

- $\sigma = 1$, $x_0 = 0$, $b(z) = b > 0$.

$$\implies s(x) = \frac{1-e^{-2bx}}{2b} \rightarrow s'(x) = e^{-2bx}.$$

- $s(-\infty) = -\infty$
- $s(\infty) = \frac{1}{2b}$

\implies Argument for $c_1 = 0$ does not work.

$$\implies \rho(x) = \tilde{c}_1 + \tilde{c}_2 e^{2bx}$$

which can't be a density, because if at least \tilde{c}_1 or \tilde{c}_2 are $\neq 0 \implies$ it is not integrable.

Example 2.20. Let $Lf(x) = \frac{1}{2}\frac{\partial^2}{\partial x^2}f(x) + b(x)\frac{\partial}{\partial x}f(x)$ where $b(x) = \frac{\partial}{\partial x} \ln h(x)$ for some $h(x) > 0$. Assume h is normalized as $\int_{\mathbb{R}} (h(x))^2 dx = 1$. \implies **Claim:** The stationary density of the process with generator L is given by $\rho(x) = (h(x))^2$.
Verify the claim:

Implicitly assumes $h \in L^2(\mathbb{R})$

$$\begin{aligned} L^* \rho(x) &\stackrel{?}{=} 0 \\ &= \frac{1}{2} \frac{\partial^2}{\partial x^2} \rho(x) - \frac{\partial}{\partial x} (b(x) \rho(x)) \\ &= \frac{1}{2} \frac{\partial^2}{\partial x^2} (h(x))^2 - \frac{\partial}{\partial x} \left(\frac{h'(x)}{h(x)} h(x)^2 \right) \\ &= \frac{\partial}{\partial x} (h(x) h'(x)) - \frac{\partial}{\partial x} (h'(x) h(x)) = 0 \end{aligned}$$

Example ?? $\implies h(x) = c \sin(\frac{\pi x}{L})$

here $L \in \mathbb{R}$ is not the operator!

$$\begin{aligned} \int_0^L h(x)^2 dx &= c^2 \int_0^L \sin^2\left(\frac{\pi x}{L}\right) dx = 1 \\ \implies c &= \sqrt{\frac{2}{L}} \implies \rho(x) = \frac{2}{L} \sin^2\left(\frac{\pi x}{L}\right). \end{aligned}$$

2.7 Uniqueness in law and path integral formula

Consider the SDE

$$\begin{cases} dX_t = b(t, X_t)dt + dB_t & \text{in } \mathbb{R}^d \\ x_0 = x_0 \end{cases}$$

Assume

$$(\star) \forall T > 0 \int_0^T |b(s, X_s)|^2 ds < \infty \text{ a.s.}$$

.

Goal: Show uniqueness in law.

Consider any $(X, \mathcal{B}, \mathbb{P})$ weak solution satisfying (\star) and define

$$\tau_n := \inf\{t \geq 0 \mid \int_0^t |b(s, X_s)|^2 ds \geq n\}$$

which, by (\star) goes to infinity.

For each n , define \mathbb{Q}^n :

$$\frac{d\mathbb{Q}^n}{d\mathbb{P}} = e^{\underbrace{-\int_0^{\tau_n} b(s, X_s) dB_s - \frac{1}{2} \int_0^{\tau_n} |b(s, X_s)|^2 ds}_{L_{\tau_n}}}.$$

By Girsanov: $\tilde{B}_t := B_t - \langle B, L \rangle_t = B_t + \int_0^{t \wedge \tau_n} b(s, X_s) ds$ is BM w.r.t. \mathbb{Q}^n , which implies $X_t = \tilde{B}_t$ for all $t \leq \tau_n$ w.r.t. \mathbb{Q}^n .

Let events of (X, B) \mathcal{F}_T measurable for some time T : are in A_T .

$$\begin{aligned} \mathbb{E}_{\mathbb{P}}(1_{(X, B) \in A_T} 1_{T \leq \tau_n}) &= \mathbb{E}_{\mathbb{Q}^n} \left(1_{(X, B) \in A_T} 1_{T \leq \tau_n} e^{\underbrace{\int_0^{\tau_n} b(s, X_s) dB_s}_{=dX_s - b(s, X_s) ds} + \frac{1}{2} \int_0^{\tau_n} |b(s, X_s)|^2 ds} \right) \\ &= \mathbb{E}_{\mathbb{Q}^n} \left(1_{(X, B) \in A_T} 1_{T \leq \tau_n} e^{\int_0^{\tau_n} b(s, X_s) dX_s - \frac{1}{2} \int_0^{\tau_n} |b(s, X_s)|^2 ds} \right) \end{aligned}$$

B_s is adapted to $X_s \implies$ for some Φ : $B = \Phi(X) \implies$

$$\mathbb{E}_{\mathbb{Q}^n} \left(1_{(X, \Phi(X)) \in A_T} 1_{T \leq \tau_n} e^{\int_0^{\tau_n} b(s, X_s) dX_s - \frac{1}{2} \int_0^{\tau_n} |b(s, X_s)|^2 ds} \right)$$

But: Law of X w.r.t. \mathbb{Q}^n is the law of BM . Take $n \rightarrow \infty$, then $\mathbb{Q}^n \rightarrow$ Wiener measure, $T \rightarrow \infty \implies$ we look at every possible event, but the probability does only depend on X !

$$\mathbb{P}((X, B) \in \mathcal{B}(\mathcal{E}^d \times \mathcal{E}^d))$$

One case where the path integral formula is also numerically stable:

Assume that $b(x) = -\nabla V(x)$ for some smooth $V(x)$ (time independent). This is called drift of **gradient type**.

Apply Itô to $V(x)$:

$$V(\omega_T) = V(\omega_0) + \int_0^T \nabla V(\omega_s) d\omega_s + \frac{1}{2} \int_0^T \Delta V(\omega_s) ds$$

$$\implies \int_0^T b(s, \omega_s) d\omega_s = - \int_0^T \nabla V(\omega_s) d\omega_s$$

and therefore

$$\mathbb{P}(X \in \tilde{A}_T) = \int_{C^d} W(d\omega) \underbrace{e^{V(\omega_0) - V(\omega_T) + \frac{1}{2} \int_0^T [\Delta V(\omega_s) - (\nabla V(\omega_s))^2] ds}}_{=: \Psi(\omega)}$$

One application:

Let $X_0 = x, f : \mathbb{R}^d \rightarrow \mathbb{R}$

$$\underbrace{bE_x(f(X_T))}_{(T(t)f)(x)} = \int_{\mathbb{R}^d} f(\omega_T) \Psi(\omega) W_x(d\omega)$$

where W_x is the wiener measure starting from x and $T(t)$ is the semigroup of X .

$$|(T(t)f)(x)| \leq \|f e^{-V}\|_{\infty} e^{-\frac{1}{2} \int_0^t \inf_{x \in \mathbb{R}^d} (|\nabla V(x)|^2 - \Delta V(x)) ds}$$

If $\inf_{x \in \mathbb{R}^d} (|\nabla V(x)|^2 - \Delta V(x)) \geq 2\lambda > 0 \implies$

$$\|e^{-V(x)(T(t)f)}\| \leq \|e^{-V} f\|_{\infty} e^{-\lambda t} \rightarrow \text{exponential decay}$$

Chapter 3:

Local times, Itô-Tanaka formula, reflected Brownian Motion

3.1 Extension of Itô formula to convex functions

If $f \in C^2(\mathbb{R})$, $f(X_t) = f(X_0) + \int_0^t f'(X_s) dX_s + \frac{1}{2} \int_0^t f''(X_s) d\langle X \rangle_s$

Proposition 3.1. *Let f be a convex function on \mathbb{R} , X_t a (continuous) semimartingale, then $f(X_t)$ is a semimartingale: $\exists A_t^f$ such that $\forall t \geq 0$*

$$f(X_t) = f(X_0) + \int_0^t \underbrace{f'_-}_{\text{left derivative of } f}(X_s) dX_s + A_t^f$$

We make a choice for the left derivative, the same works for the right one, but with different processes

Remark. *This extends directly to the case that $f = f_1 - f_2$ with f_1, f_2 convex (But with bounded variation and not necessarily increasing A_t^f)*

Sketch of Proof. Consider a function $\rho(x)$ s.t.

- $\rho(x) \geq 0$, ρ smooth
- $\rho(x) = 0$ if $x \notin [0, 1]$
- $\int_0^1 \rho(x) dx = 1$

For any $n \in \mathbb{N}$ set

$$f_n(x) := \int_{\mathbb{R}} n\rho(ny) f(x-y) dy$$

Verify:

- f_n is $C^2(\mathbb{R})$; $f_n'' \geq 0$ (since f is convex)
- $f_n'(x) = \int_{\mathbb{R}} n\rho(ny) \cdot f'_-(x-y) dy$
- $f_n(x) \xrightarrow{n \rightarrow \infty} f(x)$
- $f_n'(x) \xrightarrow{n \rightarrow \infty} f'_-(x)$

Itô formula to $f_n(X_t)$:

$$f_n(X_t) = f_n(X_0) + \int_0^t f_n'(X_s) dX_s + \underbrace{\frac{1}{2} \int_0^t f_n''(X_s) d\langle X \rangle_s}_{A_t^{f_n} \in \mathcal{A}_+^0}$$

left derivative since we do convolution and not correlation with ρ

Using stopping times: If $X = \underbrace{M_+}_{\in \mathcal{M}_{\text{loc}}^0} + \underbrace{A}_{\in \mathcal{A}}$

$$\forall m \geq 1 : T_m = \inf\{t \geq 0 \mid |X_t| + \langle M \rangle_t + \int_0^t |dA_s| \geq m\}$$

$$f_n(X_{t \wedge T_m}) = f(X_0) + \underbrace{\int_0^{t \wedge T_m} f'_n(X_s) dX_s}_{\xrightarrow{n \rightarrow \infty, \mathbb{P}} \int_0^{t \wedge T_m} f'_-(X_s) dX_s} + \underbrace{\frac{1}{2} \int_0^{t \wedge T_m} f''_n(X_s) d\langle M \rangle_s}_{A_{t \wedge T_m}^{f_n}}$$

\implies set $A_t^{f,m} := f(X_{t \wedge T_m}) - f(X_0) - \int_0^{T_m} f'_-(X_s) dX_s$ and $A_{t \wedge T_m}^{f_n} \xrightarrow{n \rightarrow \infty, \mathbb{P}} A_t^{f,m} = A_{t \wedge T_m}^f$; Take $m \rightarrow \infty$ and get a process A_t^f since $f''_n \geq 0 \implies A_t^f$ is increasing and in \mathcal{A}_0 . \square

Let $f(x) = |x|$. Then

$$f'_-(x) = \begin{cases} -1 & x \leq 0 \\ 1 & x > 0 \end{cases}$$

we therefore define

$$\text{sgn}(x) := \begin{cases} -1 & x \leq 0 \\ 1 & x > 0 \end{cases}$$

as the left derivative of $|x|$.

Proposition 3.2 (Tanaka's formula). *Let X be a continuous semimartingale and $a \in \mathbb{R}$. Then there \exists increasing process $(L_t^a(X))_{t \geq 0}$ s.t.:*

$$(a) \quad |X_t - a| = |X_0 - a| + \int_0^t \text{sgn}(X_s - a) dX_s + L_t^a(X)$$

$$(b) \quad (X_t - a)^+ = (X_0 - a)^+ + \int_0^t 1_{X_s > a} dX_s + \frac{1}{2} L_t^a(X)$$

$$(c) \quad (X_t - a)^- = (X_0 - a)^- - \int_0^t 1_{X_s \leq a} dX_s + \frac{1}{2} L_t^a(X)$$

The process $L_t^a(X)$ is called the **local time of X at level a** . For any stopping time T :

$$L_t^a(X^T) = L_{t \wedge T}^a(X)$$

Proof. Taking $f(x) = |x - a|$ in proposition 3.1 yields (a). Therefore

$$L_t^a(X) := |X_t - a| - |X_0 - a| - \int_0^t \text{sgn}(X_s - a) dX_s$$

Applying prop. 3.1 to $f(x) = (x - a)^+$ and $f(x) = (x - a)^-$

$$\implies \exists A_t^{a,(+)}, A_t^{a,(-)} \in \mathcal{A}_0^+$$

such that

$$(X_t - a)^+ = (X_0 - a)^+ + \int_0^t 1_{X_s > a} dX_s + A_t^{a,(+)}$$

$$(X_t - a)^- = (X_0 - a)^- - \int_0^t 1_{X_s \leq a} dX_s + A_t^{a,(-)}$$

$$X_t - a \stackrel{\text{Itô}}{=} X_0 - a + \int_0^t dX_s$$

$$X_t - a = (X_t - a)^+ - (X_t - a)^- = X_0 - a + \int_0^t dX_s + A_t^{a,(+)} - A_t^{a,(-)}$$

which holds if and only if $A_t^{a,(+)} = A_t^{a,(-)}$. Furthermore

$$|X_t - a| = |X_0 - a| + \int_0^t \text{sgn}(X_s - a) dX_s + \underbrace{A_t^{a,(+)} + A_t^{a,(-)}}_{=L_t^a(X)} \quad \square$$

To see: $L_t^a(X) \rightarrow$ positive measure $dL_t^a(X)$, since $L_t^a(X)$ is increasing.

$$\int_0^t \underbrace{f(x)}_{\geq 0} dL_s^a(X) \stackrel{?}{=} 0 \text{ if } f(x) > 0 \text{ for } x \neq a$$

Proposition 3.3. Let $dL_t^a(X)$ be the measure associated with the increasing process $L_t^a(X)$. Then $dL_t^a(X)$ is supported on $\{s \geq 0 \mid X_s = a\}$.

But this is not necessarily the full support!

Proof. Let $Y_t = |X_t - a|$.

$$\begin{aligned} \Rightarrow Y_t^2 &= (X_t - a)^2 \stackrel{\text{Itô to } f(X_t) = (X_t - a)^2}{=} (X_0 - a)^2 + \int_0^t (X_s - a) dX_s + 2\langle X \rangle_t \\ Y_t^2 &\stackrel{\text{Itô to } f(Y_t) = Y_t^2}{=} (X_0 - a)^2 + 2 \int_0^t \underbrace{Y_s dY_s}_{= |X_s - a| \cdot (\text{sgn}(X_s - a) dX_s + dL_s^a(X))} + \underbrace{\langle Y \rangle_t}_{\langle X \rangle_t \text{ by prop 3.1}} \\ &= (X_0 - a)^2 + 2 \int_0^t (X_s - a) dX_s + 2 \int_0^t |X_s - a| dL_s^a(X) + \langle X \rangle_t \\ &\Rightarrow \int_0^t |X_s - a| dL_s^a(X) = 0 \end{aligned}$$

and therefore the support is indeed contained in $\{s \geq 0 \mid X_s = a\}$ \square

Remark. If f is convex $\Rightarrow f'_-(x)$ is increasing and left continuous. Therefore there exists a unique measure $f''(dx)$ on \mathbb{R}_+ such that

$$f''([a, b]) = f'_-(b) - f'_-(a)$$

If $f \in C^2(\mathbb{R})$, then $f''(dx) = f''(x)dx$, i.e. it has the density given by the second derivative. For all convex functions f with $f''(dx) = 0$ for all $|x| \geq K$

$$\Rightarrow \exists \alpha, \beta \in \mathbb{R} : f(x) = \alpha + \beta x + \frac{1}{2} \int_{\mathbb{R}} |x - a| f''(da)$$

and $f'_-(x) = \beta + \frac{1}{2} \int_{\mathbb{R}} \text{sgn}(x - a) f''(da)$ in a weak sense.

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Theorem 3.4 (Itô-Tanaka-formula). If f is a difference of convex functions, X is a continuous semimartingale

$$\Rightarrow f(X_t) - f(X_0) + \int_0^t f'_-(X_s) dX_s + \frac{1}{2} \int_{\mathbb{R}} L_t^a(X) f''(da)$$

, where $f''(da)$ is the measure associated with f'_- .

Sketch of proof. (Full proof: Thm 9.6 LeGall book)

Once localized \rightarrow assume $f''(da) = 0$ on $[-\kappa, \kappa]^c$

$$\begin{aligned} \Rightarrow f(X_t) &= \alpha + \beta X_t + \int_{-\kappa}^{\kappa} |X_s - a| f''(da) \\ &\stackrel{\text{prop. 3.2}}{=} \alpha + \beta X_t + \frac{1}{2} \int |X_0 - a| f''(da) + \frac{1}{2} \int \int_0^t \text{sgn}(X_s - a) dX_s f''(da) + \frac{1}{2} \int L_t^a(X) f''(da) \\ &= \underbrace{\alpha + \beta X_0 + \frac{1}{2} \int |X_0 - a| f''(da)}_{=f(X_0)} + \underbrace{\beta \int_0^t dX_s + \frac{1}{2} \int \int_0^t \text{sgn}(X_s - a) f''(da) dX_s}_{= \int_0^t f'_-(X_s) dX_s} + \frac{1}{2} \int L_t^a(X) f''(da) \end{aligned}$$

\square

Corollary 3.5 (Occupation time formula). Almost surely, $\forall t \geq 0$, non-negative measurable function φ

$$\int_0^t \varphi(X_s) d\langle X \rangle_s = \int_{\mathbb{R}} \varphi(a) L_t^a(X) da$$

Added example. $X = BM$, $\varphi(X) = 1_A(X)$, A Borel set in \mathbb{R}

$$\implies \int_0^t 1_A(X_s) ds$$

is the time spend by $(X_s, s \in [0, t])$ in A and the RHS is

$$\int_A L_t^a(X) da$$

$\implies L_t^a$ density of time spend by Brownian motion in a .

Think $A = [a, a + \epsilon]$

Proof. (For φ with bounded support)

Find $f \in C^2$ s.t. $f''(x) = \varphi(x)$.

\implies Itô-Tanaka-formula:

$$f(X_t) = f(X_0) + \int_0^t f'_-(X_s) dX_s + \frac{1}{2} \int L_t^a(X) \varphi(a) da$$

By Itô-formula:

$$f(X_t) = f(X_0) + \int_0^t f'(X_s) dX_s + \frac{1}{2} \int_0^t \varphi(X_s) d\langle X \rangle_s$$

The claim follows from comparing the terms. \square

Explicit representation of the local time:

Lemma 3.6. Let X be a continuous semimartingale

\implies a.s. $\forall a \in \mathbb{R}, t \geq 0$:

$$L_t^a(X) = \lim_{\epsilon \downarrow 0} \frac{1}{\epsilon} \int_0^t 1_{a \leq X_s \leq a+\epsilon} d\langle X \rangle_s$$

Proof. Take $\varphi(x) = \frac{1}{\epsilon} 1_{[a \leq x \leq a+\epsilon]}$ in corollary 3.5:

See Thm 9.4 in LeGall for more details

$$\implies \frac{1}{\epsilon} \int_0^t 1_{a \leq X_s \leq a+\epsilon} d\langle X \rangle_s = \frac{1}{\epsilon} \int_a^{a+\epsilon} L_t^{\tilde{a}}(X) d\tilde{a} \xrightarrow{\tilde{a} \rightarrow L_t^a} L_t^a(X) \quad \square$$

Similarly:

$$\begin{aligned} \lim_{\epsilon \downarrow 0} \frac{1}{\epsilon} \int_0^t 1_{[a-\epsilon \leq X_s < a]} d\langle X \rangle_s &= L_t^{a-}(X) \\ \implies \lim_{\epsilon \downarrow 0} \frac{1}{2\epsilon} \int_0^t 1_{[a-\epsilon \leq X_s \leq a+\epsilon]} d\langle X \rangle_s &= \frac{1}{2} (L_t^{a-}(X) + L_t^a(X)) \end{aligned}$$

$$\begin{aligned} L_t^a(X) - L_t^{a-}(X) &\stackrel{\text{prop 3.2}}{=} |X_t - a| - |X_0 - a| - \int_0^t \text{sgn}(X_s - a) dX_s - (|X_t - a_-| - |X_0 - a_-| - \int_0^t \text{sgn}(X_s - a_-) dX_s) \\ &= 2 \int_0^t 1_{X_s = a} dX_s \stackrel{X_t = M_t + A_t}{=} 2 \int_0^t 1_{X_s = a} dA_s \end{aligned}$$

where the first two terms are equal, since X is a continuous semimartingale. This then implies, if X is a martingale (and therefore $A_t = 0$) then

$$L_t^a(X) = L_t^{a-}(X) \implies L_t^a(X) = \lim_{\epsilon \downarrow 0} \frac{1}{2\epsilon} \int_0^t 1_{[a-\epsilon \leq X_s \leq a+\epsilon]} d\langle X \rangle_s.$$

In particular, if X is a BM:

$$L_t^{a-}(X) \implies L_t^a(X) = \lim_{\epsilon \downarrow 0} \frac{1}{2\epsilon} \int_0^1 1_{[a-\epsilon \leq X_s \leq a+\epsilon]} ds$$

3.2 Brownian motion and local time

Let B be a standard BM, then by Tanaka:

$$|B_t| = \underbrace{|B_0|}_{=0} + \int_0^t \operatorname{sgn}(B_s) dB_s + \underbrace{L_t}_{:=L_t^0(B)}$$

We want to define the process $R_t = |B_t|$ be the **BM reflected at 0**.
We want to study R_t and $S_t^B := \sup_{0 \leq s \leq t} B_s, L_t(B)$

3.2.1 No strong solution of the Tanaka SDE

$$(\star) = \begin{cases} dX_t &= \operatorname{sgn}(X_t) dB_t \\ X_0 &= 0 \end{cases}$$

We already know: $B_t := \int_0^t \operatorname{sgn}(W_s) dW_s$, where W is a BM $\implies BM$ is a BM (using Levy characterization) and

$$\int_0^t \operatorname{sgn}(W_s) dB_s = \int_0^t \operatorname{sgn}(W_s)^2 dW_s = W_t \rightarrow \operatorname{sgn}(W_t) dB_t = dW_t$$

and therefore (W, B) is a weak solution of (\star) .

Assume (X, B) is a strong solution of $(\star) \implies dX_t = \operatorname{sgn}(X_t) dB_t$ with X is a BM.

Itô-Tanaka-formula:

$$\begin{aligned} |X_t| &= \int_0^t \operatorname{sgn}(X_s) dX_s + L_t^0(X) \\ \implies \int_0^t \operatorname{sgn}(X_s) dX_s &= |X_t| - L_t^0(X) = |X_t| - \lim_{\epsilon \downarrow 0} \frac{1}{2\epsilon} \int_0^t 1_{|X_s| \leq \epsilon} ds \in \mathcal{F}_t^{|X|} \end{aligned}$$

But also:

$$\int_0^t \operatorname{sgn}(X_s) dX_s = \int_0^t (\operatorname{sgn}(X_s))^2 dB_s = B_t$$

$$B_t = |X_t| - \lim_{\epsilon \downarrow 0} \frac{1}{2\epsilon} \int_0^t 1_{|X_s| \leq \epsilon} ds$$

$\implies B_t$ is $\mathcal{F}_t^{|X|}$ -measurable and therefore B is $\mathcal{F}^{|X|}$ measurable.

If (X, B) is a strong solution, then X is measurable w.r.t. \mathcal{F}^B . $\implies \mathcal{F}^X \subset \mathcal{F}^B \subseteq \mathcal{F}^{|X|}$ which is wrong, since we can not recall the value of X knowing only its absolute value.

3.2.2 Reflected SDE

Definition 3.7. The family (X, l, W) is a weak solution of the **reflected SDE** (One-dimensional):

$$dX_t = dW_t + dl_t$$

if:

- W is a BM
- X is a positive continuous process
- l is a positive non-decreasing continuous process

s.t.

$$\int_0^\infty 1_{X_s} > 0 dl_s = 0$$

The solution is called **strong**, if (X, l) is adapted to W .

Added example. • $X_t := |B_t|$

- $W_t := \int_0^t \text{sgn}(B_s) dB_s$

- $l_t = L_t^0(B)$

This is a weak solution of the 1 dimensional reflected SDE.

List of Lectures

- **Lecture 01:** Introduction, reminder of strong solutions, definition of weak solutions, uniqueness in law, pathwise uniqueness, and some examples
- **Lecture 02:** Further examples, Yamata-Watanabe theorems and Skorohod theorem (no proof), reminder of Lévy characterization, Ito-Doebelin formula
- **Lecture 03:** The martingale problem and one-to-one relation with weak solutions (special case of $d = n$ proven); reminder of Dubins-Schwarz theorem
- **Lecture 04:** Transformation of SDE under time change, weak solutions for 1d SDEs, scale function and its relation to hitting times
- **Lecture 05:** Uniqueness of the solution of martingale problem, reminder of Girsanov theorem, changes of SDE under drift transformation
- **Lecture 06:** Drift transformation for SDE, Doob-h transform, start set-up for diffusion bridges
- **Lecture 07:** Diffusion bridges, set-up for Brownian motion conditioned to stay positive
- **Lecture 08:** Brownian motion conditioned to stay positive, Brownian excursion
- **Lecture 09:** Brownian motion conditioned to stay in a bounded domain
- **Lecture 10:** Brownian motion in the Weyl chamber, stationary measures for diffusions; Uniqueness in law via Girsanov
- **Lecture 11:** Path integral formula for drift of gradient type, extension of Ito to convex function, Tanaka formula and definition of local time
- **Lecture 12:**